Problem Solutions

e-Chapter 9

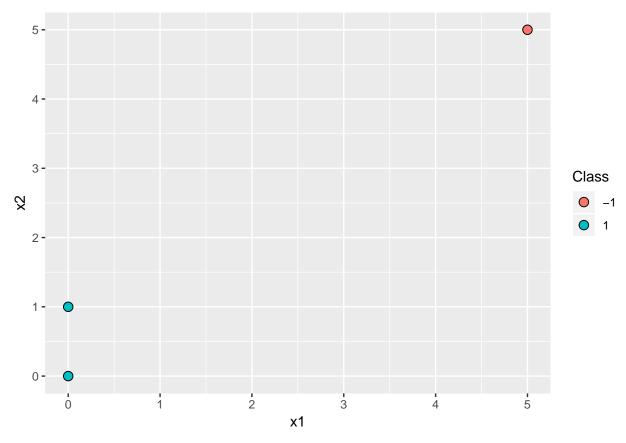
Pierre Paquay

Problem 9.1

(a) We begin by implementing the nearest neighbor method on the raw data.

```
data <- data.frame(x1 = c(0, 0, 5), x2 = c(0, 1, 5))
class <- as.factor(c(1, 1, -1))

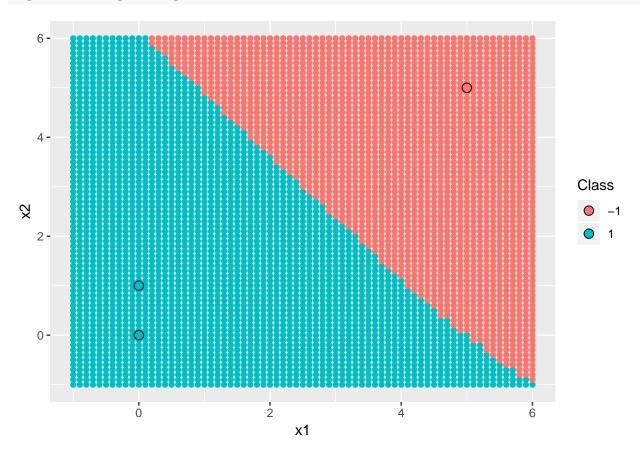
ggplot(data, aes(x = x1, y = x2, fill = class)) + geom_point(size = 3, shape = 21) +
    guides(fill = guide_legend(title = "Class"))</pre>
```



Below, we show the decision regions of the final hypothesis.

```
ggplot() + geom_point(data = grid, aes(x = x1, y = x2, col = knn_mod)) +
geom_point(data = data, aes(x = x1, y = x2, fill = class), size = 3, shape = 21) +
guides(fill = guide_legend(title = "Class")) +
```

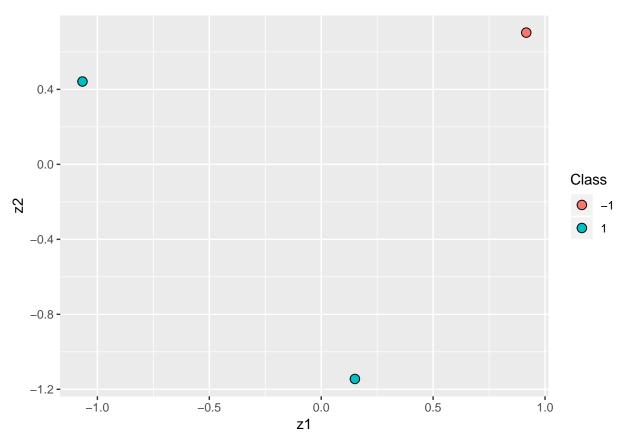
guides(col = guide_legend(title = "Class"))



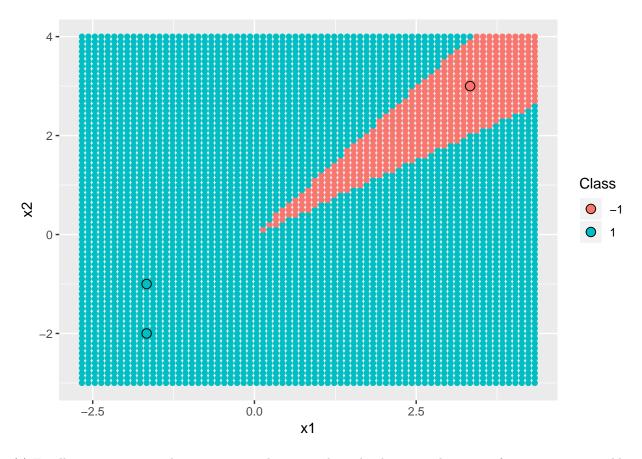
(b) Here, we transform to whitened coordinates and we run the nearest neighbor rule.

```
data_centered <- apply(data, 2, function(y) y - mean(y))
sigma <- t(data_centered) %*% as.matrix(data_centered) / 2
sigma_sqr <- sqrtm(sigma)
sigma_sqr_inv <- solve(sigma_sqr)
data_whitened <- as.matrix(data_centered) %*% sigma_sqr_inv
data_whitened <- as.data.frame(data_whitened)
colnames(data_whitened) <- c("z1", "z2")

ggplot(data_whitened, aes(x = z1, y = z2, fill = class)) + geom_point(size = 3, shape = 21) +
guides(fill = guide_legend(title = "Class"))</pre>
```



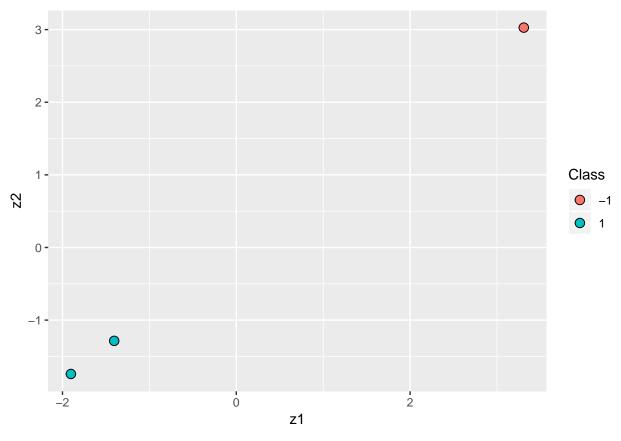
We show the decision region of the final hypothesis in the original space as well.



(c) Finally, we use principal component analysis to reduce the data to 1 dimension for our nearest neighbor classifier.

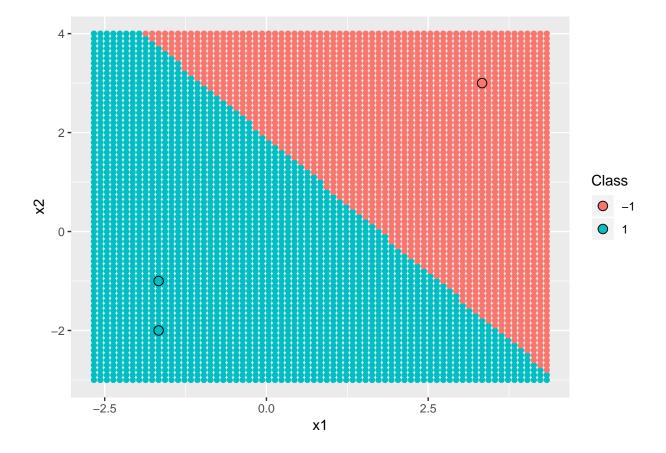
```
SVD_decomp <- svd(data_centered)
V1 <- SVD_decomp$v[, 1]
Z <- data_centered %*% V1
data_pca <- Z %*% t(V1)
data_pca <- as.data.frame(data_pca)
colnames(data_pca) <- c("z1", "z2")

ggplot(data_pca, aes(x = z1, y = z2, fill = class)) + geom_point(size = 3, shape = 21) +
    guides(fill = guide_legend(title = "Class"))</pre>
```



```
grid_pca <- (as.matrix(grid_centered) %*% V1) %*% t(V1)
knn_mod_pca <- knn(data_pca, grid_pca, class, k = 1, prob = TRUE)</pre>
```

Once again, we show the decision regions of the final hypothesis in the original space.



Problem 9.2

(a) Here, we have $x'_n = x_n + b$. Let us compute $\overline{x'}$, $\sigma_i'^2$ and Σ' . We have

$$\overline{x'} = \frac{1}{N} \sum_{n=1}^{N} x'_n = \frac{1}{N} \sum_{n=1}^{N} (x_n + b) = \overline{x} + b;$$

moreover, we have

$$\sigma_i^{\prime 2} = \frac{1}{N} \sum_{n=1}^{N} (x'_{ni} - \overline{x'}_i)^2 = \frac{1}{N} \sum_{n=1}^{N} (x_{ni} + b_i - \overline{x'}_i - b_i)^2 = \sigma_i^2;$$

and finally

$$\Sigma' = \frac{1}{N} \sum_{n=1}^{N} (x_n' - \overline{x'})(x_n' - \overline{x'})^T = \frac{1}{N} \sum_{n=1}^{N} (x_n + b - \overline{x} - b)(x_n + b - \overline{x} - b)^T = \Sigma.$$

• Centering. We may write that

$$z'_n = x'_n - \overline{x'} = x_n + b - \overline{x} - b = z_n.$$

• Normalization. Here, we have that

$$z_n' = D'(x_n' - \overline{x'})$$

where

$$D' = \operatorname{diag}(1/\sigma_1', \cdots, 1/\sigma_d') = \operatorname{diag}(1/\sigma_1, \cdots, 1/\sigma_d) = D.$$

In that case, we have

$$z'_n = D(x'_n - \overline{x'}) = D(x_n + b - \overline{x} - b) = z_n.$$

• Whitening. We have

$$z'_n = \Sigma'^{-1/2}(x'_n - \overline{x'}) = \Sigma^{-1/2}(x_n + b - \overline{x} - b) = z_n.$$

(b) Here, we have $x'_n = \alpha x_n$ with $\alpha > 0$. Let us compute $\overline{x'}$, σ'^2_i and Σ' . We have

$$\overline{x'} = \frac{1}{N} \sum_{n=1}^{N} x'_n = \frac{1}{N} \sum_{n=1}^{N} \alpha x_n = \alpha \overline{x};$$

moreover, we have

$$\sigma_i^{\prime 2} = \frac{1}{N} \sum_{n=1}^{N} (x'_{ni} - \overline{x'}_i)^2 = \frac{1}{N} \sum_{n=1}^{N} (\alpha x_{ni} - \alpha \overline{x'}_i)^2 = \alpha^2 \sigma_i^2;$$

and finally

$$\Sigma' = \frac{1}{N} \sum_{n=1}^{N} (x'_n - \overline{x'})(x'_n - \overline{x'})^T = \frac{1}{N} \sum_{n=1}^{N} (\alpha x_n - \alpha \overline{x})(\alpha x_n - \alpha \overline{x})^T = \alpha^2 \Sigma.$$

• Centering. We may write that

$$z'_n = x'_n - \overline{x'} = \alpha x_n - \alpha \overline{x} = \alpha z_n \neq z_n.$$

• Normalization. Here, we have that

$$z'_n = D'(x'_n - \overline{x'})$$

where

$$D' = \operatorname{diag}(1/\sigma_1', \dots, 1/\sigma_d') = \operatorname{diag}(1/(\alpha\sigma_1), \dots, 1/(\alpha\sigma_d)) = \frac{1}{\alpha}D.$$

In that case, we have

$$z'_n = \frac{1}{\alpha}D(x'_n - \overline{x'}) = \frac{1}{\alpha}D(\alpha x_n - \alpha \overline{x}) = D(x_n - \overline{x}) = z_n.$$

• Whitening. We have

$$z'_n = \Sigma'^{-1/2}(x'_n - \overline{x'}) = \frac{1}{\alpha} \Sigma^{-1/2}(\alpha x_n - \alpha \overline{x}) = z_n.$$

(c) Here, we have $x'_n = Ax_n$ with $A = \operatorname{diag}(a_1, \dots, a_d)$ $(a_i \neq 0)$. Let us compute $\overline{x'}$, $\sigma_i'^2$ and Σ' . We have

$$\overline{x'} = \frac{1}{N} \sum_{n=1}^{N} x'_n = \frac{1}{N} \sum_{n=1}^{N} A x_n = A \overline{x};$$

moreover, we have

$$\sigma_i^{\prime 2} = \frac{1}{N} \sum_{n=1}^{N} (x'_{ni} - \overline{x'}_i)^2 = \frac{1}{N} \sum_{n=1}^{N} (a_i x_{ni} - a_i \overline{x'}_i)^2 = a_i^2 \sigma_i^2;$$

and finally

$$\Sigma' = \frac{1}{N} \sum_{n=1}^{N} (x_n' - \overline{x'})(x_n' - \overline{x'})^T = \frac{1}{N} \sum_{n=1}^{N} (Ax_n - A\overline{x})(Ax_n - A\overline{x})^T = A\Sigma A^T.$$

• Centering. We may write that

$$z'_n = x'_n - \overline{x'} = Ax_n - A\overline{x} = Az_n \neq z_n.$$

• Normalization. Here, we have that

$$z'_n = D'(x'_n - \overline{x'})$$

where

$$D' = \text{diag}(1/\sigma'_1, \dots, 1/\sigma'_d) = \text{diag}(1/(a_1\sigma_1), \dots, 1/(a_d\sigma_d));$$

which means that D'A = D. In that case, we have

$$z'_n = D'(x'_n - \overline{x'}) = D'A(x_n - \overline{x}) = D(x_n - \overline{x}) = z_n.$$

• Whitening. We have

$$z'_{n} = \Sigma'^{-1/2}(x'_{n} - \overline{x'}) = (A\Sigma A^{T})^{-1/2}A(x_{n} - \overline{x}) \neq z_{n}.$$

(d) Here, we have $x'_n = Ax_n$ with $\det(A) \neq 0$. Let us compute $\overline{x'}$, σ'^2_i and Σ' . We have

$$\overline{x'} = \frac{1}{N} \sum_{n=1}^{N} x'_n = \frac{1}{N} \sum_{n=1}^{N} Ax_n = A\overline{x};$$

moreover, we have

$$\sigma_i^{\prime 2} = \frac{1}{N} \sum_{n=1}^{N} (x'_{ni} - \overline{x'}_i)^2 = \frac{1}{N} \sum_{n=1}^{N} (l_i^T x_n - l_i^T \overline{x})^2 = \frac{1}{N} \sum_{n=1}^{N} l_i^T (x_n - \overline{x})(x_n - \overline{x})^T l_i = l_i^T \Sigma l_i$$

where l_i is the *i*th row of A; and finally

$$\Sigma' = \frac{1}{N} \sum_{n=1}^{N} (x_n' - \overline{x'})(x_n' - \overline{x'})^T = \frac{1}{N} \sum_{n=1}^{N} (Ax_n - A\overline{x})(Ax_n - A\overline{x})^T = A\Sigma A^T.$$

• Centering. We may write that

$$z'_n = x'_n - \overline{x'} = Ax_n - A\overline{x} = Az_n \neq z_n.$$

• Normalization. Here, we have that

$$z_n' = D'(x_n' - \overline{x'})$$

where

$$D' = \operatorname{diag}(1/\sigma_1', \dots, 1/\sigma_d') = \operatorname{diag}(1/(l_1^T \Sigma l_1), \dots, 1/(l_d^T \Sigma l_d)).$$

In that case, we have

$$z'_n = D'(x'_n - \overline{x'}) = D'A(x_n - \overline{x}) = D'Az_n \neq z_n.$$

• Whitening. We have

$$z'_n = \Sigma'^{-1/2}(x'_n - \overline{x'}) = (A\Sigma A^T)^{-1/2}A(x_n - \overline{x}) \neq z_n.$$

Problem 9.3

We may write

$$\Gamma = \operatorname{diag}(\lambda_1, \cdots, \lambda_d)$$

where $\lambda_i > 0$. With this in mind, it is easy to describe $\Gamma^{1/2}$ and $\Gamma^{-1/2}$; we have

$$\Gamma^{1/2} = \operatorname{diag}(\sqrt{\lambda_1}, \cdots, \sqrt{\lambda_d}) \text{ and } \Gamma^{-1/2} = \operatorname{diag}(1/\sqrt{\lambda_1}, \cdots, 1/\sqrt{\lambda_d}).$$

To prove the first fact, we simply need to compute $\Gamma^{1/2}\Gamma^{1/2}$, we have

$$\Gamma^{1/2}\Gamma^{1/2} = \operatorname{diag}(\sqrt{\lambda_1}, \cdots, \sqrt{\lambda_d})\operatorname{diag}(\sqrt{\lambda_1}, \cdots, \sqrt{\lambda_d}) = \operatorname{diag}(\lambda_1, \cdots, \lambda_d) = \Gamma;$$

to prove the second fact, we need to compute $\Gamma^{1/2}\Gamma^{-1/2}$ (the same reasoning can be applied to $\Gamma^{-1/2}\Gamma^{1/2}$), we have

$$\Gamma^{1/2}\Gamma^{-1/2} = \operatorname{diag}(\sqrt{\lambda_1}, \cdots, \sqrt{\lambda_d})\operatorname{diag}(1/\sqrt{\lambda_1}, \cdots, 1/\sqrt{\lambda_d}) = I.$$

Now, to prove that $\Sigma^{1/2} = U\Gamma^{1/2}U^T$, we write that

$$\Sigma^{1/2}\Sigma^{1/2} = U\Gamma^{1/2}\underbrace{U^TU}_{=I}\Gamma^{1/2}U^T = U\Gamma U^T = \Sigma.$$

Then, to prove that $\Sigma^{-1/2} = U\Gamma^{-1/2}U^T$, we write that

$$\Sigma^{-1/2}\Sigma^{1/2} = U\Gamma^{-1/2}\underbrace{U^TU}_{-I}\Gamma^{1/2}U^T = UIU^T = I.$$

Problem 9.4

We know that $A = V\psi$, consequently we get

$$V^T A = \underbrace{V^T V}_{=I} \psi = \psi$$

because V is an orthogonal matrix. Moreover, we also have that

$$\psi^T \psi = A^T \underbrace{VV^T}_{-I} A = A^T A = I$$

since A is an orthogonal matrix as well; this means that ψ is also an orthogonal matrix.

Problem 9.5

(a) if A is a diagonal matrix (N=d), it suffices to define U, Γ and V as follows

$$U = V = I_N$$
 and $\Gamma = A$.

In this case, we have

$$A = U\Gamma V^T.$$

(c) If A is a matrix with pairwise orthogonal columns, we may write that

$$A^T A = \operatorname{diag}(a_1, \cdots, a_d)$$

where $a_i > 0$. Now if we define D as follows

$$D = \operatorname{diag}(1/\sqrt{a_1}, \cdots, 1/\sqrt{a_d}),$$

it is easy to see that U = AD is actually a matrix with orthonormal columns since

$$U^T U = D^T A^T A D = I_d.$$

In this case, we have

$$A = U\Gamma V^T$$

with
$$\Gamma = \operatorname{diag}(\sqrt{a_1}, \cdots, \sqrt{a_d})$$
 and $V = I_d$.

(d) If A has SVD $U\Gamma V^T$ and $Q^TQ=I$, we may write that

$$QA = (QU)\Gamma V^T$$

with QU a matrix with orthonormal columns since

$$(QU)^T(QU) = U^T \underbrace{Q^T Q}_{=I} U = I_d.$$

(e) If A has blocks A_i along the diagonal such that A_i has SVD $U_i\Gamma_iV_i^T$, we simply have to define U, Γ , and V as follows

$$U = \begin{pmatrix} U_1 & & \\ & \ddots & \\ & & U_m \end{pmatrix}, \ \Gamma = \begin{pmatrix} \Gamma_1 & & \\ & \ddots & \\ & & \Gamma_m \end{pmatrix} \text{ and } V = \begin{pmatrix} V_1 & & \\ & \ddots & \\ & & V_m \end{pmatrix}.$$

In that case, we immediately get that

$$A = U\Gamma V^T$$

with

$$U^{T}U = \begin{pmatrix} U_{1}^{T} & & \\ & \ddots & \\ & & U_{m}^{T} \end{pmatrix} \begin{pmatrix} U_{1} & & \\ & \ddots & \\ & & U_{m} \end{pmatrix} = I,$$

$$V^{T}V = \begin{pmatrix} V_{1}^{T} & & \\ & \ddots & \\ & & V_{m}^{T} \end{pmatrix} \begin{pmatrix} V_{1} & & \\ & \ddots & \\ & & V_{m} \end{pmatrix} = VV^{T} = I,$$

and Γ diagonal.

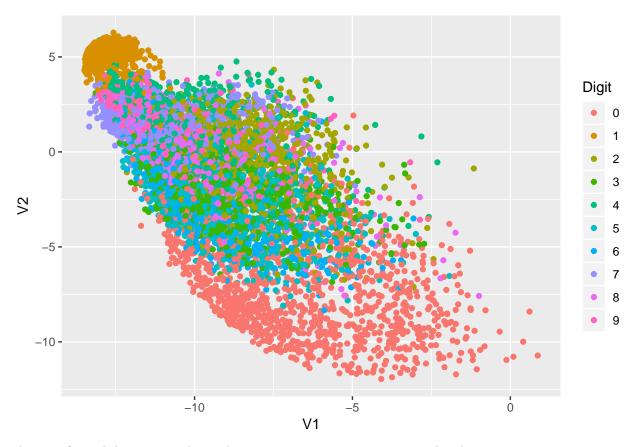
Problem 9.6

Here, we suppose that the digits data were not centered and we perform PCA to obtain a 2-dimensional feature vector.

```
digits <- read.delim("zip.train", header = FALSE, sep = " ")
digits$V258 <- NULL
colnames(digits) <- c("digit", 1:256)

X <- as.matrix(digits[, -1])
y <- digits[, 1]
SVD_decomp <- svd(X)
V2 <- SVD_decomp$v[, 1:2]
Z <- X %*% V2
digits_pca <- Z %*% t(V2)
digits_pca_proj <- digits_pca %*% V2
digits_pca_proj <- as.data.frame(digits_pca_proj)

ggplot(digits_pca_proj, aes(x = V1, y = V2, col = as.factor(y))) + geom_point() +
    guides(col = guide_legend(title = "Digit"))</pre>
```



The transformed data is not whitened since its covariance matrix is not the identity matrix.

cov(digits_pca_proj)

Problem 9.7

As we have that

$$z_n = \sqrt{N} \Gamma_k^{-1} V_k^T x_n,$$

we may let Z be

$$Z = \sqrt{N}X(\Gamma_k^{-1}V_k^T)^T = \sqrt{N}XV_k\Gamma_k^{-1}.$$

Moreover, since X is centered, it is easy to see that Z is centered as well because

$$\overline{z} = \frac{1}{N} Z^T \mathbf{1} = \frac{\sqrt{N}}{N} \Gamma_k^{-1} V_k^T \underbrace{X^T \mathbf{1}}_{=0} = 0.$$

To prove that the transformed data is actually whitened, we have to compute Z^TZ , if we use the SVD of $X = U\Gamma V^T$, we get

$$\begin{split} \frac{1}{N}Z^TZ &= \frac{1}{N}(\sqrt{N}XV_k\Gamma_k^{-1})^T(\sqrt{N}XV_k\Gamma_k^{-1}) \\ &= \Gamma_k^{-1}V_k^TX^TXV_k\Gamma_k^{-1} \\ &= \Gamma_k^{-1}V_k^TV\Gamma\underbrace{U^TU}_{=I_d}\Gamma V^TV_k\Gamma_k^{-1} \\ &= \Gamma_k^{-1}V_k^TV\underbrace{\Gamma_k^2U}_{=\operatorname{diag}(\gamma_1^2,\cdots,\gamma_d^2)} V^TV_k\Gamma_k^{-1}. \end{split}$$

We also have that

$$V_k^T V = \begin{pmatrix} v_1^T \\ \vdots \\ v_k^T \end{pmatrix} (v_1, \dots, v_k \mid v_{k+1}, \dots, v_d) = (I_k \mid 0)$$

and

$$V^T V_k = \left(\frac{I_k}{0}\right).$$

This means that

$$\Gamma_k^{-1}(I_k \mid 0) = (\Gamma_k^{-1} \mid 0),$$

and in the same way

$$\left(\frac{I_k}{0}\right)\Gamma_k^{-1} = \left(\frac{\Gamma_k^{-1}}{0}\right).$$

Consequently, we get that

$$\frac{1}{N}Z^TZ = (\Gamma_k^{-1} \mid 0)\Gamma^2 \left(\frac{\Gamma_k^{-1}}{0}\right)$$

$$= (\Gamma_k^{-1} \mid 0) \left(\frac{\Gamma_k^2 \mid 0}{0 \mid *}\right) \left(\frac{\Gamma_k^{-1}}{0}\right)$$

$$= I_k,$$

which means that Z is whitened.

Problem 9.8

We begin by constructing a two dimensional feature as described in the book and we apply the algorithm to the digits data giving us the features z_1 and z_2 .

```
digits <- read.delim("zip.train", header = FALSE, sep = " ")
digits$V258 <- NULL
colnames(digits) <- c("digit", 1:256)

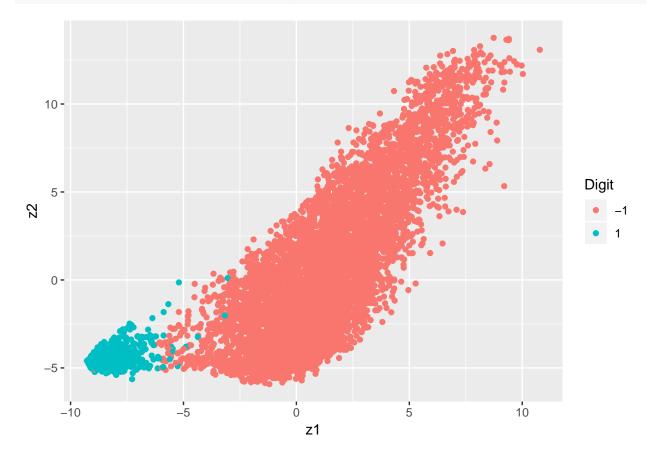
X <- as.matrix(digits[, -1])
y <- digits[, 1]
X_centered <- apply(X, 2, function(x) x - mean(x))
X_centered_1 <- X_centered[y == 1, ]
X_centered_not1 <- X_centered[y != 1, ]

SVD_decomp_1 <- svd(X_centered_1)
v1 <- SVD_decomp_1$v[, 1]</pre>
SVD_decomp_not1 <- svd(X_centered_not1)
v2 <- SVD_decomp_not1$v[, 1]
```

(a) We give below a scatter plot of our resulting two features.

```
z1 <- X_centered %*% v1
z2 <- X_centered %*% v2
y_1 <- ifelse(y == 1, +1, -1)
z <- data.frame(z1, z2, y_1)

ggplot(z, aes(x = z1, y = z2, col = as.factor(y_1))) + geom_point() +
    guides(col = guide_legend(title = "Digit"))</pre>
```



(b) No, the directions of v_1 and v_2 are not necessarily orthogonal.

[,1] ## [1,] FALSE

(c) Since $\hat{V} = [v_1, v_2]$ has full rank, we know that

$$\hat{V}^{+} = (\hat{V}^{T}\hat{V})^{-1}\hat{V}^{T}.$$

In this case, we have

$$\hat{X} = X\hat{V}(\hat{V}^T\hat{V})^{-1}\hat{V}^T.$$

(d) This method of constructing features is supervised since we need the target values to apply it.

Problem 9.9

(a) Since \hat{X} is a matrix whose rows are projected onto k basis vectors, it is pretty obvious that $\operatorname{rank}(\hat{X}) = k$.

(b) We may write that

$$||\Gamma - U^T \hat{X} V||_F^2 = ||U^T X V - U^T \hat{X} V||_F^2 = ||U^T (X - \hat{X}) V||_F^2.$$

Moreover, we may also write (see exercise 9.9) that

$$\begin{split} ||U^{T}(X - \hat{X})V||_{F}^{2} &= ||U(U^{T}(X - \hat{X})V)V^{T}||_{F}^{2} \\ &= ||UU^{T}(X - \hat{X})\underbrace{VV^{T}}_{=I}||_{F}^{2} \\ &= \operatorname{trace}[(UU^{T}(X - \hat{X}))^{T}(UU^{T}(X - \hat{X}))] \\ &= \operatorname{trace}[(X - \hat{X})^{T}U\underbrace{U^{T}U}_{=I}U^{T}(X - \hat{X})] \\ &= ||U^{T}(X - \hat{X})||_{F}^{2} \\ &\leq \underbrace{||U^{T}||_{F}^{2}}_{=\operatorname{trace}(U^{T}U) = d} \\ &\leq d||X - \hat{X}||_{F}^{2} \end{split}$$

where we used the fact that $||AB||_F^2 \le ||A||_F^2 ||B||_F^2$.

(c) Since the rank of a matrix product is less than each factor, we have that

$$\operatorname{rank}(\hat{\Gamma}) = \operatorname{rank}(U^T \hat{X} V) \le \operatorname{rank}(\hat{X}) = k.$$

(d) It is easy to see that

$$||\Gamma - \hat{\Gamma}||_F^2 = \sum_{i,j=1}^d (\gamma_{ij} - \hat{\gamma}_{ij})^2$$

$$= \sum_{i=1}^d (\gamma_{ii} - \hat{\gamma}_{ii})^2 + \sum_{i \neq j} (\gamma_{ij} - \hat{\gamma}_{ij})^2$$

$$\geq \sum_{i=1}^d (\gamma_{ii} - \hat{\gamma}_{ii})^2.$$

So, the optimal choice for $\hat{\Gamma}$ must have all off-diagonal elements equal to zero.

- (e) Since we know that $\operatorname{rank}(\hat{\Gamma}) \leq k$, we may conclude that the optimal $\hat{\Gamma}$ can have at most k non-zero diagonal elements.
- (f) We may write for our optimal $\hat{\Gamma}$ that

$$||\Gamma - \hat{\Gamma}||_F^2 = \sum_{i=1}^d (\gamma_{ii} - \hat{\gamma}_{ii})^2$$

$$= \sum_{i=1}^k (\gamma_{ii} - \hat{\gamma}_{ii})^2 + \underbrace{\sum_{i=k+1}^d (\gamma_{ii} - \hat{\gamma}_{ii})^2}_{\sum_{i=k+1}^d \gamma_{ii}^2}$$

$$\geq \sum_{i=k+1}^d \gamma_{ii}^2.$$

Consequently, the minimum reconstruction error is equal to $\sum_{i=k+1}^{d} \gamma_{ii}^2$.

(g) If $\hat{X} = XV_kV_k^T$, we choose our optimal $\hat{\Gamma}$ such that

$$\hat{\Gamma} = U^T \hat{X} V
= U^T X V_k V_k^T V
= \underbrace{U^T U}_{=I} \Gamma V^T V_k V_k^T V
= \Gamma (V^T V_k) (V_k^T V)$$

where

$$V_k^T V = (I_k \mid 0) \text{ and } V^T V_k = \left(\frac{I_k}{0}\right).$$

This means that

$$\hat{\Gamma} = \Gamma\left(\begin{array}{c|c} I_k & 0 \\ \hline 0 & 0 \end{array}\right) = \begin{pmatrix} \gamma_1 & & 0 \\ & \ddots & \vdots \\ \hline & \gamma_k & 0 \\ \hline 0 & \cdots & 0 & 0 \end{pmatrix}.$$

Thus, we finally have

$$\Gamma - \hat{\Gamma} = \begin{pmatrix} 0 & 0 & \cdots & 0 \\ \hline 0 & -\gamma_{k+1} & & \\ \vdots & & \ddots & \\ 0 & & & -\gamma_d \end{pmatrix},$$

and consequently

$$||\Gamma - \hat{\Gamma}||_F^2 = \sum_{i=k+1}^d \gamma_i^2.$$

So, for this choice of $\hat{\Gamma}$, we actually check eac of the conditions obtained in points (d), (e), and (f) to characterize the optimal choice of $\hat{\Gamma}$; so $\hat{X} = XV_kV_k^T$ is the optimal choice for the reconstructed vector. In this case, we know from point (a) that

$$||X - \hat{X}||_F^2 \ge ||\Gamma - \hat{\Gamma}||_F^2,$$

so for our optimal choice of \hat{X} , the minimum reconstruction error is $\sum_{i=k+1}^{d} \gamma_i^2$.

Problem 9.10

- (a) The main difference between Algorithm 1 and Algorithm 2 is that Algorithm 1 first performs SVD and then splits the data, and Algorithm 2 first splits the data and then performs SVD.
- (b) Here, we generate N random normally distributed d-dimensional inputs x_1, \dots, x_N with their respective targets $y_n = w_f^T x_n + \epsilon_n$ where w_f is normally distributed and ϵ_n is independent Gaussian noise with variance 0.5.

```
set.seed(10)
d <- 5
N <- 40
k <- 3

target <- function(w, x) {
   return(sum(w * as.matrix(x)) + rnorm(1, sd = sqrt(0.5)))
}</pre>
```

Now, we use Algorithms 1 and 2 to compute estimates of E_{out} .

```
E_cross_1 <- function(X, y) {</pre>
  SVD <- svd(X)
  Vk <- SVD$v[, 1:k]
  Z <- as.matrix(X) %*% Vk
  en <- numeric(N)
  for (n in 1:N) {
    Zn \leftarrow Z[-n,]
    yn \leftarrow y[-n]
    wn_minus <- solve(t(Zn) %*% Zn) %*% t(Zn) %*% yn
    en[n] \leftarrow (sum(Z[n, ] * wn_minus) - y[n])^2
  E1 <- mean(en)
  return(E1)
E_cross_2 <- function(X, y) {</pre>
  en <- numeric(N)
  for (n in 1:N) {
    Xn \leftarrow X[-n,]
    yn \leftarrow y[-n]
    SVD_minus <- svd(Xn)
    Vk_minus <- SVD_minus$v[, 1:k]</pre>
    Zn <- as.matrix(Xn) %*% Vk_minus</pre>
    wn_minus <- solve(t(Zn) %*% Zn) %*% t(Zn) %*% yn
    wn_minus2 <- Vk_minus ** wn_minus
    en[n] \leftarrow (sum(X[n, ] * wn_minus2) - y[n])^2
  }
  E2 <- mean(en)
  return(E2)
}
```

We compute E_{out} below.

```
E_out <- function(X, y, wf) {
    SVD <- svd(X)
    Vk <- SVD$v[, 1:k]
    Z <- as.matrix(X) %*% Vk
    w <- solve(t(Z) %*% Z) %*% t(Z) %*% y
    w2 <- Vk %*% w

    Ntest <- 1000
    X_test <- data.frame(x1 = rnorm(Ntest), x2 = rnorm(Ntest), x3 = rnorm(Ntest),</pre>
```

```
x4 = rnorm(Ntest), x5 = rnorm(Ntest))
y_test <- apply(X_test, 1, target, w = wf)

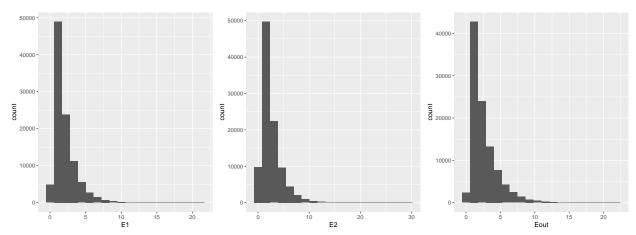
E_out <- mean((as.matrix(X_test) %*% w2 - y_test)^2)
return(E_out)
}</pre>
```

Finally, we repeat this process 10^5 times and we report the averages \overline{E}_1 , \overline{E}_2 , and \overline{E}_{out} .

```
iter <- 100000
E1 <- numeric(iter)
E2 <- numeric(iter)</pre>
Eout <- numeric(iter)</pre>
for (i in 1:iter) {
  data <- data_gen(d, N)
  X <- data$X</pre>
  y <- data$y
  wf <- data$wf
  E1[i] \leftarrow E_{cross_1}(X, y)
  E2[i] \leftarrow E_{cross_2}(X, y)
  Eout[i] <- E_out(X, y, wf)</pre>
}
E1_avg <- mean(E1)
E2_avg <- mean(E2)
Eout_avg <- mean(Eout)</pre>
```

We plot below the histograms of E_1 , E_2 and E_{out} .

```
results <- data.frame(E1 = E1, E2 = E2, Eout = Eout)
plot1 <- ggplot(results, aes(x = E1)) + geom_histogram(bins = 20)
plot2 <- ggplot(results, aes(x = E2)) + geom_histogram(bins = 20)
plot3 <- ggplot(results, aes(x = Eout)) + geom_histogram(bins = 20)
grid.arrange(plot1, plot2, plot3, nrow = 1)</pre>
```



We get $\overline{E}_1 = 2.0445914$, $\overline{E}_2 = 2.5364857$, and $\overline{E}_{out} = 2.5386052$.

- (c) As we may see, the average \overline{E}_1 is clearly not as close to \overline{E}_{out} as \overline{E}_2 is. This was to be expected since in cross-validation we have to compute every element of our hypothesis after the data split is done, not before.
- (d) As stated in point (c), the correct estimate of E_{out} is E_2 .

Problem 9.12

(a) We have

$$E_{out}^{\pi}(h) = \frac{1}{4} \mathbb{E}_{x,\pi} [(h(x) - f_{\pi}(x))^{2}]$$

$$= \frac{1}{4} \mathbb{E}_{\pi} [\mathbb{E}_{x|\pi} [(h(x) - f_{\pi}(x))^{2} | \pi]]$$

$$= \frac{1}{4} \mathbb{E}_{\pi} \left[\sum_{n=1}^{N} (h(x_{n}) - f_{\pi}(x_{n}))^{2} \underbrace{\mathbb{P}[x = x_{n} | \pi]}_{=1/N} \right]$$

$$= \frac{1}{4N} \sum_{n=1}^{N} \mathbb{E}_{\pi} [(h(x_{n}) - f_{\pi}(x_{n}))^{2}].$$

(b) We know from point (a) that

$$E_{out}^{\pi}(h) = \frac{1}{4N} \sum_{n=1}^{N} \mathbb{E}_{\pi}[(h(x_n) - f_{\pi}(x_n))^2];$$

so, we may write that

$$E_{out}^{\pi}(h) = \frac{1}{4N} \sum_{n=1}^{N} \mathbb{E}_{\pi} [(h(x_n) - \overline{y} + \overline{y} - f_{\pi}(x_n))^2]$$

$$= \frac{1}{4N} \sum_{n=1}^{N} (\mathbb{E}_{\pi} [(h(x_n) - \overline{y})^2] + \mathbb{E}_{\pi} [(\overline{y} - f_{\pi}(x_n))^2] + 2 \mathbb{E}_{\pi} [(h(x_n) - \overline{y})(\overline{y} - f_{\pi}(x_n))]).$$
(3)

Let us treat each term separately, we immediately get

$$(1) = \mathbb{E}_{\pi}[(h(x_n) - \overline{y})^2] = (h(x_n) - \overline{y})^2.$$

We also get

$$(2) = \mathbb{E}_{\pi}[(\overline{y} - f_{\pi}(x_n))^2] = \mathbb{E}_{\pi}[(\overline{y} - y_{\pi_n})^2] = \sum_{i=1}^{N} (\overline{y} - y_i)^2 \underbrace{\mathbb{P}[\pi_n = i]}_{-1/N} = \frac{1}{N} \sum_{i=1}^{N} (\overline{y} - y_i)^2.$$

And finally, we get

$$(3) = \mathbb{E}_{\pi}[(h(x_n) - \overline{y})(\overline{y} - f_{\pi}(x_n))] = (h(x_n) - \overline{y})\mathbb{E}_{\pi}[(\overline{y} - y_{\pi_n})]$$

$$= (h(x_n) - \overline{y})\sum_{i=1}^{N}(\overline{y} - y_i)\underbrace{\mathbb{P}[\pi_n = i]}_{=1/N}$$

$$= \frac{1}{N}(h(x_n) - \overline{y})\underbrace{\sum_{i=1}^{N}(\overline{y} - y_i)}_{=0} = 0.$$

In conclusion, we get that

$$E_{out}^{\pi}(h) = \frac{1}{4N} \sum_{n=1}^{N} (h(x_n) - \overline{y})^2 + \frac{1}{4N^2} \sum_{n=1}^{N} \sum_{i=1}^{N} (\overline{y} - y_i)^2$$

$$= \frac{1}{4N} \sum_{n=1}^{N} (h(x_n) - \overline{y})^2 + \underbrace{\frac{1}{4N} \sum_{i=1}^{N} (\overline{y} - y_i)^2}_{=\frac{1}{4} s_y^2}$$

$$= \frac{s_y^2}{4} + \frac{1}{4N} \sum_{n=1}^{N} (h(x_n) - \overline{y})^2.$$

(c) Similarly to E_{out}^{π} , we find that

$$E_{in}^{\pi}(h) = \frac{1}{4N} \sum_{n=1}^{N} (h(x_n) - y_{\pi_n})^2 = \frac{1}{4N} \sum_{n=1}^{N} (h(x_n) - \overline{y} + \overline{y} - y_{\pi_n})^2$$

$$= \frac{1}{4N} \sum_{n=1}^{N} [(h(x_n) - \overline{y})^2 + (\overline{y} - y_{\pi_n})^2 + 2(h(x_n) - \overline{y})(\overline{y} - y_{\pi_n})]$$

$$= \frac{1}{4N} \sum_{n=1}^{N} (h(x_n) - \overline{y})^2 + \frac{1}{4N} \sum_{n=1}^{N} (\overline{y} - y_{\pi_n})^2 + \frac{1}{2N} \sum_{n=1}^{N} (h(x_n) - \overline{y})(\overline{y} - y_{\pi_n})$$

$$= \frac{s_y^2}{4} + \frac{1}{4N} \sum_{n=1}^{N} (h(x_n) - \overline{y})^2 + \frac{1}{2N} \sum_{n=1}^{N} (h(x_n) - \overline{y})(\overline{y} - y_{\pi_n}).$$

(d) We are now able to compute the permutation optimism penalty, we have

$$E_{out}^{\pi}(g_{\pi}) - E_{in}^{\pi}(g_{\pi}) = -\frac{1}{2N} \sum_{n=1}^{N} (g_{\pi}(x_n) - \overline{y})(\overline{y} - y_{\pi_n})$$

$$= -\frac{1}{2N} \sum_{n=1}^{N} g_{\pi}(x_n)(\overline{y} - y_{\pi_n}) + \frac{1}{2N} \overline{y} \underbrace{\sum_{n=1}^{N} (\overline{y} - y_{\pi_n})}_{=0}$$

$$= \frac{1}{2N} \sum_{n=1}^{N} (y_{\pi_n} - \overline{y}) g_{\pi}(x_n).$$

(e) It is easy to see that the permutation optimism penalty is proportional to the covariance between y_{π_n} and $g_{\pi}(x_n)$.

Problem 9.13

For the Bootstrap, we also have that

$$\mathbb{P}[x = x_n] = \frac{1}{N},$$

consequently we may proceed in the same fashion as in Problem 9.12 to obtain the conclusions.

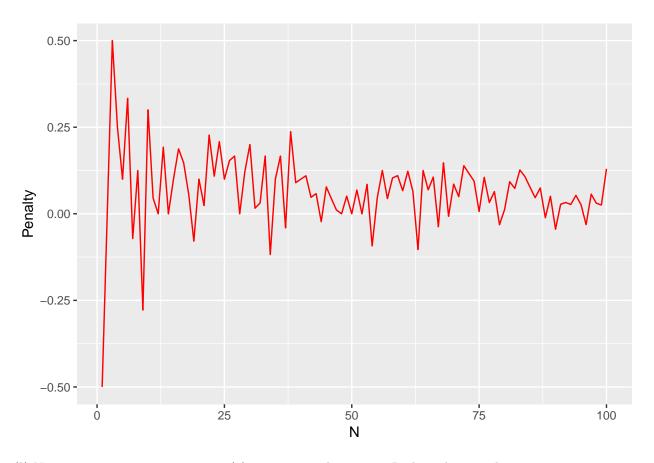
Problem 9.14

(a) Below, we estimate the Rademacher optimism penalty for $N = 1, 2, \dots, 100$.

```
set.seed(10)
h <- function(D, w0) {
  return(sign(D$x - w0))
data_gen <- function(N) {</pre>
  x \leftarrow runif(N, min = -1, max = 1)
  r \leftarrow sample(c(-1, 1), size = N, replace = TRUE)
  D_prime \leftarrow data.frame(x = x, r = r)
  return(D_prime)
penalty <- numeric()</pre>
for (N in 1:100) {
  iter <- 10000
  D_prime <- data_gen(N)</pre>
  w0 <- 0
  w0_prime <- w0</pre>
  Ein <- mean(D_prime$r != h(D_prime, w0))</pre>
  Ein_prime <- Ein</pre>
  for (i in 1:iter) {
    D_mis <- subset(D_prime, r != h(D_prime, w0))</pre>
    if (nrow(D_mis) == 0)
      break
    xt <- D_mis[sample(nrow(D_mis), 1), ]</pre>
    w0 <- w0 + xt$x * xt$r
    Ein <- mean(D_prime$r != h(D_prime, w0))</pre>
    if (Ein < Ein_prime) {</pre>
      w0_prime <- w0</pre>
    Ein_prime <- mean(D_prime$r != h(D_prime, w0_prime))</pre>
  penalty <- c(penalty, 0.5 - Ein_prime)</pre>
```

Below, we plot the penalty versus N.

```
ggplot(data.frame(N = 1:100, Penalty = penalty), aes(x = N, y = Penalty)) +
geom_line(col = "red") +
coord_cartesian(xlim = c(1, 100))
```



(b) Now, we repeat 1000 times point (a) to compute the average Rademacher penalty.

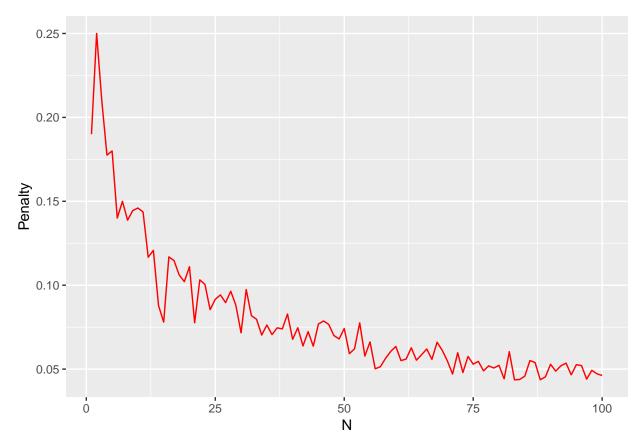
```
penalty_matrix <- matrix(NA, nrow = 100, ncol = 100)</pre>
for (row in 1:100) {
  penalty <- numeric()</pre>
  for (N in 1:100) {
    iter <- 1000
    D_prime <- data_gen(N)</pre>
    w0 <- 0
    w0_prime <- w0
    Ein <- mean(D_prime$r != h(D_prime, w0))</pre>
    Ein_prime <- Ein</pre>
    for (i in 1:iter) {
      D_mis <- subset(D_prime, r != h(D_prime, w0))</pre>
      if (nrow(D_mis) == 0)
         break
      xt <- D_mis[sample(nrow(D_mis), 1), ]</pre>
      w0 <- w0 + xt$x * xt$r
      Ein <- mean(D_prime$r != h(D_prime, w0))</pre>
       if (Ein < Ein_prime) {</pre>
         w0_prime <- w0
      Ein_prime <- mean(D_prime$r != h(D_prime, w0_prime))</pre>
    }
    penalty <- c(penalty, 0.5 - Ein_prime)</pre>
  penalty_matrix[row, ] <- penalty</pre>
```

}

Below, we give a plot of the average penalty versus N.

```
penalty_avg <- apply(penalty_matrix, 2, FUN = mean)

ggplot(data.frame(N = 1:100, Penalty = penalty_avg), aes(x = N, y = Penalty)) +
    geom_line(col = "red") +
    coord_cartesian(xlim = c(1, 100))</pre>
```



(c) We may see that the Rademacher penalty is $\mathcal{O}(1/\sqrt{N})$, which is similar to the order of the VC penalty in this case.

```
one_square <- function(N) {
    return(1 / sqrt(N))
}

ggplot(data.frame(N = 1:100, Penalty = penalty_avg), aes(x = N, y = Penalty)) +
    geom_line(aes(colour = "Average Rademacher penalty")) +
    stat_function(fun = one_square, geom = "line", aes(colour = "1 / sqrt(N)")) +
    guides(colour = guide_legend(title = "Function")) +
    coord_cartesian(xlim = c(1, 100))</pre>
```

