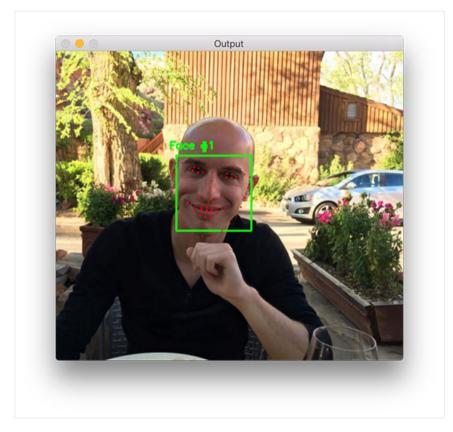
Navigation



Facial landmarks with dlib, OpenCV, and **Python**

by Adrian Rosebrock on April 3, 2017 in dlib. Faces, Facial Landmarks, Libraries, Tutorials



Last week we learned how to install and configure dlib on our system with Python bindings.

Today we are going to use dlib and OpenCV to detect facial landmarks in an image.

Facial landmarks are used to localize and represent salient regions of the face, such as:

- Eyes
- Eyebrows

01/07/2019

- Nose Mouth
- Jawline

Facial landmarks have been successfully applied to face alignment, head pose estimation, face swapping, blink detection and much more.

In today's blog post we'll be focusing on the basics of facial landmarks, including:

- 1. Exactly what facial landmarks are and how they work.
- 2. How to detect and extract facial landmarks from an image using dlib, OpenCV, and Python.

In the next blog post in this series we'll take a deeper dive into facial landmarks and learn how to extract specific facial regions based on these facial landmarks.

To learn more about facial landmarks, just keep reading.

Looking for the source code to this post? Jump right to the downloads section.

Facial landmarks with dlib, OpenCV, and Python

The first part of this blog post will discuss facial landmarks and why they are used in computer vision applications.

From there, I'll demonstrate how to detect and extract facial landmarks using dlib, OpenCV, and Python.

Finally, we'll look at some results of applying facial landmark detection to images.

What are facial landmarks?

https://www.pyimagesearch.com/2017/04/03/facial-landmarks-dlib-opencv-python/

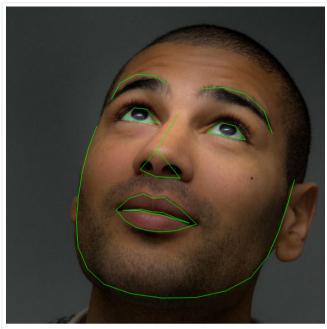


Figure 1: Facial landmarks are used to label and identify key facial attributes in an image (source)

Detecting facial landmarks is a subset of the shape prediction problem. Given an input image (and normally an ROI that specifies the object of interest), a shape predictor attempts to localize key points of interest along the shape.

In the context of facial landmarks, our goal is detect important facial structures on the face using shape prediction methods.

Detecting facial landmarks is therefore a two step process:

- Step #1: Localize the face in the image.
- Step #2: Detect the key facial structures on the face ROI.

Face detection (Step #1) can be achieved in a number of ways.

We could use OpenCV's built-in Haar cascades.

We might apply a pre-trained HOG + Linear SVM object detector specifically for the task of face detection.

Or we might even use deep learning-based algorithms for face localization.

In either case, the actual algorithm used to detect the face in the image doesn't matter. Instead, what's important is that through some method we obtain the face bounding box (i.e., the (x, y)coordinates of the face in the image).

Given the face region we can then apply Step #2: detecting key facial structures in the face region.

There are a variety of facial landmark detectors, but all methods essentially try to localize and label the following facial regions:

- Mouth
- Right eyebrow
- · Left eyebrow
- Right eye
- Left eve
- Nose
- Jaw

The facial landmark detector included in the dlib library is an implementation of the One Millisecond Face Alignment with an Ensemble of Regression Trees paper by Kazemi and Sullivan (2014).

This method starts by using:

- 1. A training set of labeled facial landmarks on an image. These images are manually labeled, specifying **specific** (x, y)-coordinates of regions surrounding each facial structure.
- 2. Priors, of more specifically, the probability on distance between pairs of input pixels.

Given this training data, an ensemble of regression trees are trained to estimate the facial landmark positions directly from the pixel intensities themselves (i.e., no "feature extraction" is taking place).

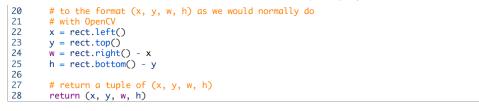
The end result is a facial landmark detector that can be used to detect facial landmarks in realtime with high quality predictions.

For more information and details on this specific technique, be sure to read the paper by Kazemi and Sullivan linked to above, along with the official dlib announcement.

Understanding dlib's facial landmark detector

The pre-trained facial landmark detector inside the dlib library is used to estimate the location of 68 (x, y)-coordinates that map to facial structures on the face.

The indexes of the 68 coordinates can be visualized on the image below:



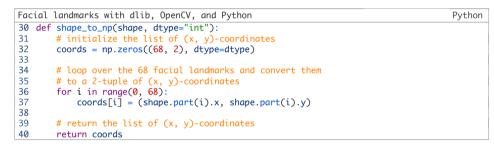
This function accepts a single argument, rect, which is assumed to be a bounding box rectangle produced by a dlib detector (i.e., the face detector).

The rect object includes the (x, y)-coordinates of the detection.

However, in OpenCV, we normally think of a bounding box in terms of "(x, y, width, height)" so as a matter of convenience, the rect_to_bb function takes this rect object and transforms it into a 4-tuple of coordinates.

Again, this is simply a matter of conveinence and taste.

Secondly, we have the shape_to_np function:



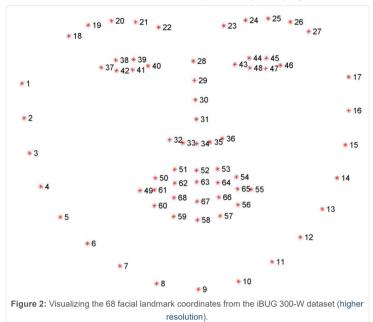
The dlib face landmark detector will return a shape object containing the 68 (x, y)-coordinates of the facial landmark regions.

Using the shape_to_np function, we cam convert this object to a NumPy array, allowing it to "play nicer" with our Python code.

Given these two helper functions, we are now ready to detect facial landmarks in images.

Open up a new file, name it facial_landmarks.py , and insert the following code:

Fac	ial landmarks with dlib, OpenCV, and Python	Python
1	# import the necessary packages	
2	from imutils import face_utils	
3	import numpy as np	
4	import argparse	
5	import imutils	
6	import dlib	
7	import cv2	
8		
9	# construct the argument parser and parse the arguments	
10	<pre>ap = argparse.ArgumentParser()</pre>	
11	ap.add_argument("-p", "shape-predictor", required=True,	
12	help="path to facial landmark predictor")	
13	<pre>ap.add_argument("-i", "image", required=True,</pre>	
14	help="path to input image")	



These annotations are part of the 68 point iBUG 300-W dataset which the dlib facial landmark predictor was trained on.

It's important to note that other flavors of facial landmark detectors exist, including the 194 point model that can be trained on the HELEN dataset.

Regardless of which dataset is used, the same dlib framework can be leveraged to train a shape predictor on the input training data — this is useful if you would like to train facial landmark detectors or custom shape predictors of your own.

In the remaining of this blog post I'll demonstrate how to detect these facial landmarks in images.

Future blog posts in this series will use these facial landmarks to extract *specific* regions of the face, apply face alignment, and even build a blink detection system.

Detecting facial landmarks with dlib, OpenCV, and Python

In order to prepare for this series of blog posts on facial landmarks, I've added a few convenience functions to my imutils library, specifically inside face_utils.py.

We'll be reviewing two of these functions inside <code>face_utils.py</code> now and the remaining ones next week.

The first utility function is rect_to_bb , short for "rectangle to bounding box":

```
Facial landmarks with dlib, OpenCV, and Python

18 def rect_to_bb(rect):
19 # take a bounding predicted by dlib and convert it
```

01/07/2019

Lines 2-7 import our required Python packages.

We'll be using the face_utils submodule of imutils to access our helper functions detailed above

We'll then import dlib. If you don't already have dlib installed on your system, please follow the instructions in my previous blog post to get your system properly configured.

Lines 10-15 parse our command line arguments:

- --shape-predictor : This is the path to dlib's pre-trained facial landmark detector. You can download the detector model here or you can use the "Downloads" section of this post to grab the code + example images + pre-trained detector as well.
- --image: The path to the input image that we want to detect facial landmarks on.

Now that our imports and command line arguments are taken care of, let's initialize dlib's face detector and facial landmark predictor:

```
Facial landmarks with dlib, OpenCV, and Python
                                                                                     Python
17 # initialize dlib's face detector (HOG-based) and then create
18 # the facial landmark predictor
19 detector = dlib.get_frontal_face_detector()
20 predictor = dlib.shape_predictor(args["shape_predictor"])
```

Line 19 initializes dlib's pre-trained face detector based on a modification to the standard Histogram of Oriented Gradients + Linear SVM method for object detection.

Line 20 then loads the facial landmark predictor using the path to the supplied --shape-predictor.

But before we can actually detect facial landmarks, we first need to detect the face in our input image:

```
Facial landmarks with dlib, OpenCV, and Python
                                                                                     Pvthon
22 # load the input image, resize it, and convert it to grayscale
23 image = cv2.imread(args["image"])
24 image = imutils.resize(image, width=500)
25 gray = cv2.cvtColor(image, cv2.COLOR_BGR2GRAY)
26
27 # detect faces in the grayscale image
28 rects = detector(gray, 1)
```

Line 23 loads our input image from disk via OpenCV, then pre-processes the image by resizing to have a width of 500 pixels and converting it to grayscale (Lines 24 and 25).

Line 28 handles detecting the bounding box of faces in our image.

The first parameter to the detector is our grayscale image (although this method can work with color images as well).

The second parameter is the number of image pyramid layers to apply when upscaling the image prior to applying the detector (this it the equivalent of computing cv2.pyrUp N number of times on the image).

The benefit of increasing the resolution of the input image prior to face detection is that it may allow us to detect more faces in the image — the downside is that the larger the input image, the more computationally expensive the detection process is.

Given the (x, y)-coordinates of the faces in the image, we can now apply facial landmark detection to each of the face regions:

```
Facial landmarks with dlib, OpenCV, and Python
                                                                                     Pvthon
30 # loop over the face detections
31 for (i, rect) in enumerate(rects):
       # determine the facial landmarks for the face region, then
33
       # convert the facial landmark (x, y)-coordinates to a NumPy
34
35
       shape = predictor(aray, rect)
36
       shape = face_utils.shape_to_np(shape)
37
38
       # convert dlib's rectangle to a OpenCV-style bounding box
39
       # [i.e., (x, y, w, h)], then draw the face bounding box
40
       (x, y, w, h) = face_utils.rect_to_bb(rect)
41
       cv2.rectangle(image, (x, y), (x + w, y + h), (0, 255, 0), 2)
42
43
       # show the face number
44
       cv2.putText(image, "Face \#{}".format(i + 1), (x - 10, y - 10),
45
           cv2.FONT_HERSHEY_SIMPLEX, 0.5, (0, 255, 0), 2)
46
47
       # loop over the (x, y)-coordinates for the facial landmarks
48
      # and draw them on the image
49
       for (x, y) in shape:
50
           cv2.circle(image, (x, y), 1, (0, 0, 255), -1)
52 # show the output image with the face detections + facial landmarks
53 cv2.imshow("Output", image)
54 cv2.waitKey(0)
```

We start looping over each of the face detections on Line 31.

For each of the face detections, we apply facial landmark detection on **Line 35**, giving us the 68 (x. v)-coordinates that map to the specific facial features in the image.

Line 36 then converts the dlib shape object to a NumPy array with shape (68, 2).

Lines 40 and 41 draw the bounding box surrounding the detected face on the image while Lines 44 and 45 draw the index of the face

Finally, Lines 49 and 50 loop over the detected facial landmarks and draw each of them individually.

Lines 53 and 54 simply display the output image to our screen.

Facial landmark visualizations

Before we test our facial landmark detector, make sure you have upgraded to the latest version of imutils which includes the face_utils.py file:

```
Facial landmarks with dlib, OpenCV, and Python
                                                                                      Shell
1 $ pip install --upgrade imutils
```

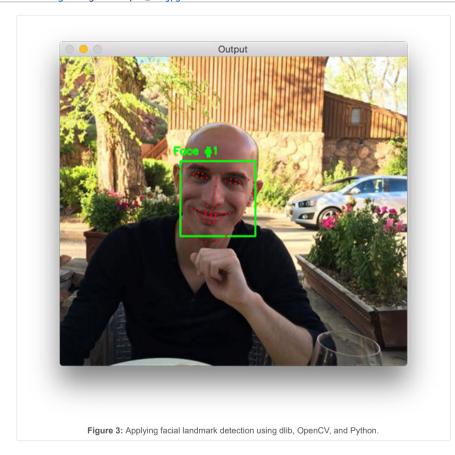
Note: If you are using Python virtual environments, make sure you upgrade the *imutils* inside the virtual environment.

Facial landmarks with dlib, OpenCV, and Python - PylmageSearch

From there, use the "Downloads" section of this guide to download the source code, example images, and pre-trained dlib facial landmark detector.

Once you've downloaded the .zip archive, unzip it, change directory to facial-landmarks , and execute the following command:

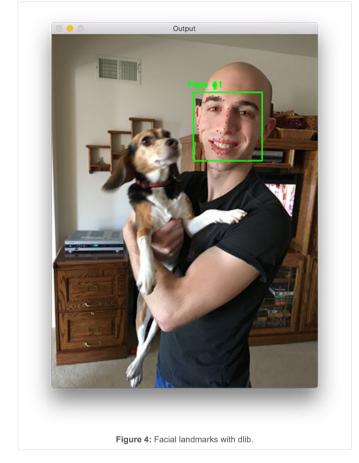
Facial landmarks with dlib, OpenCV, and Python Shell 1 \$ python facial_landmarks.py --shape-predictor shape_predictor_68_face_landmarks.dat \ --image images/example_01.jpg



Notice how the bounding box of my face is drawn in green while each of the individual facial landmarks are drawn in red.

The same is true for this second example image:

Facial landmarks with dlib, OpenCV, and Python Shell 1 \$ python facial_landmarks.py --shape-predictor shape_predictor_68_face_landmarks.dat \ --image images/example_02.jpg



Here we can clearly see that the red circles map to specific facial features, including my jawline, mouth, nose, eyes, and eyebrows.

Let's take a look at one final example, this time with multiple people in the image:

Facial landmarks with dlib, OpenCV, and Python Shell 1 \$ python facial_landmarks.py --shape-predictor shape_predictor_68_face_landmarks.dat \ --image images/example_03.jpg

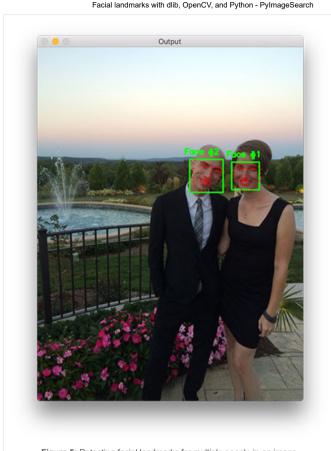


Figure 5: Detecting facial landmarks for multiple people in an image

For both people in the image (myself and Trisha, my fiancée), our faces are not only *detected* but also *annotated* via facial landmarks as well.

Summary

In today's blog post we learned what facial landmarks are and how to detect them using dlib, OpenCV, and Python.

Detecting facial landmarks in an image is a two step process:

- 1. First we must localize a face(s) in an image. This can be accomplished using a number of different techniques, but normally involve either Haar cascades or HOG + Linear SVM detectors (but any approach that produces a bounding box around the face will suffice).
- 2. Apply the shape predictor, specifically a facial landmark detector, to obtain the (x, y)-coordinates of the face regions in the face ROI.

Given these facial landmarks we can apply a number of computer vision techniques, including:

- Face part extraction (i.e., nose, eyes, mouth, jawline, etc.)
- Facial alignment
- Head pose estimation
- Face swapping
- Blink detection
- ...and much more!

In next week's blog post I'll be demonstrating how to access each of the face parts *individually* and extract the eyes, eyebrows, nose, mouth, and jawline features simply by using a bit of NumPy array slicing magic.

To be notified when this next blog post goes live, be sure to enter your email address in the form below!

Downloads:



If you would like to download the code and images used in this post, please enter your email address in the form below. Not only will you get a .zip of the code, I'll also send you a FREE 17-page Resource Guide on Computer Vision,

OpenCV, and Deep Learning. Inside you'll find my hand-picked tutorials, books, courses, and libraries to help you master CV and DL! Sound good? If so, enter your email address and I'll send you the code immediately!

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• dlib, face detection, face regions, facial landmarks