



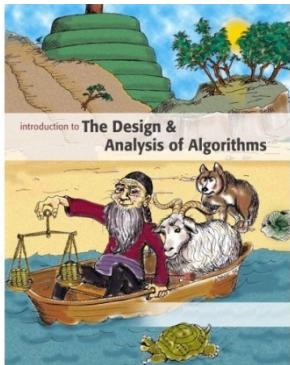
南京大學

NANJING UNIVERSITY

Introduction to

Algorithm Design and Analysis

[12] Directed Acyclic Graph



Yu Huang

<http://cs.nju.edu.cn/yuhuang>

Institute of Computer Software
Nanjing University



In the last class...

- Depth-first and breadth-first search
- Finding connected components
- General DFS/BFS **skeleton**
- Depth-first search **trace**



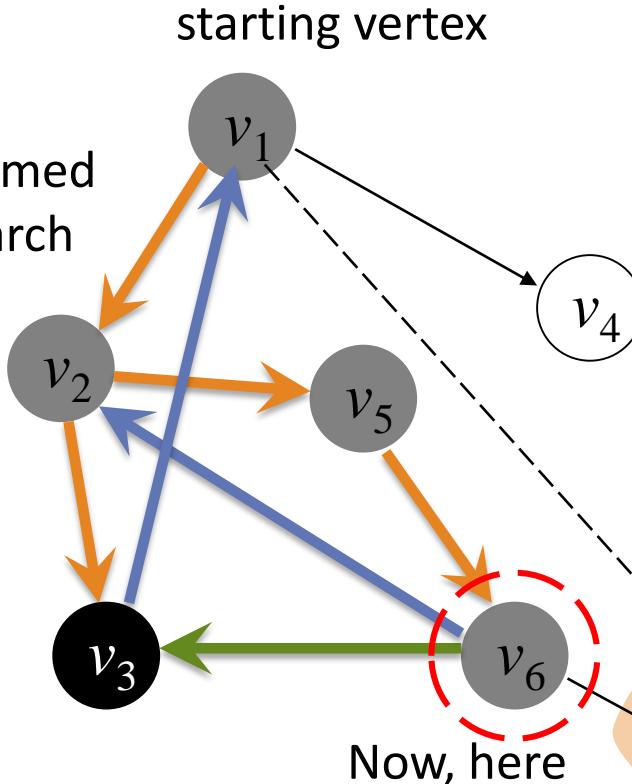
Applications of Graph Decomposition

- **Directed Acyclic Graph**
 - Topological order
 - Critical path analysis
- **Strongly Connected Component (SCC)**
 - Strong connected component and condensation
 - The algorithm
 - Leader of strong connected component



For Your Reference

A DFS tree partially formed at the moment the search checking v_3 from v_6

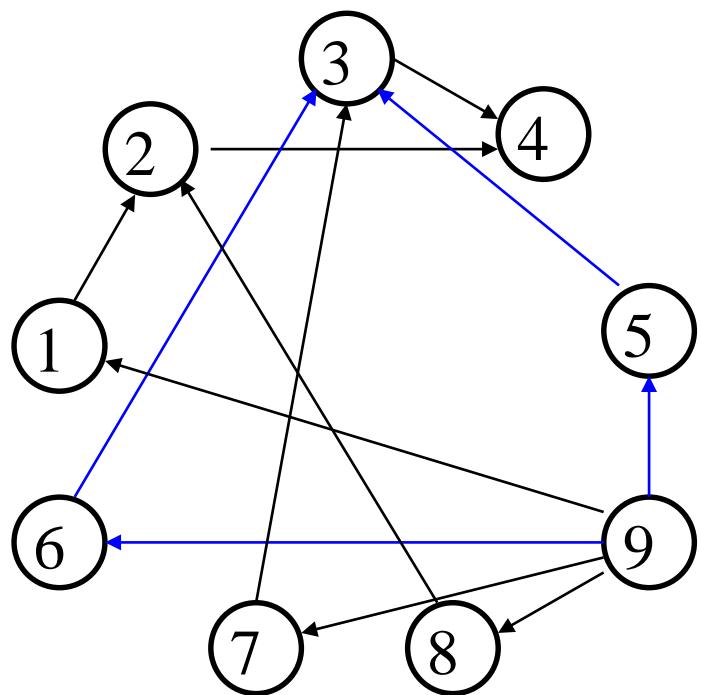


* Note: v_4 is reachable from v_6 , and is white, but it is not a descendant of v_6

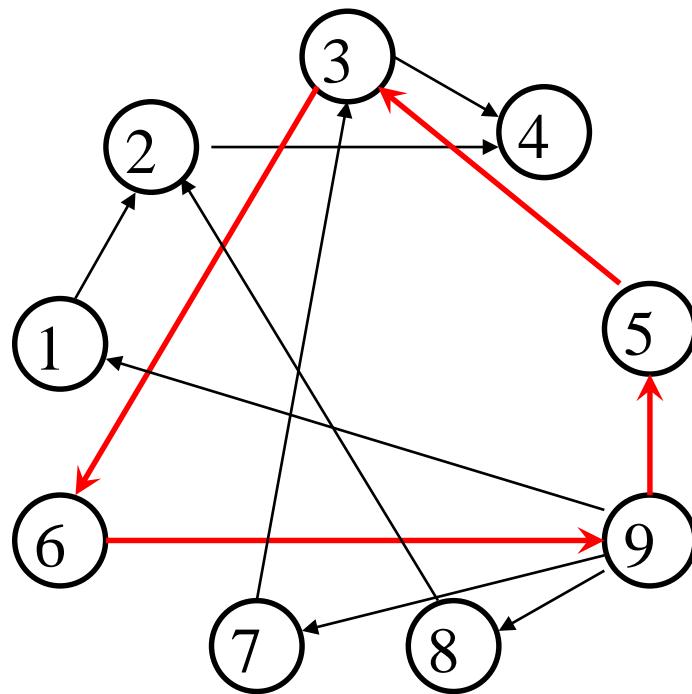
- tree edge
- back edge
- cross edge
- tree edge not accessed yet
- descendant edge not accessed yet



Directed Acyclic Graph (DAG)



A Directed Acyclic Graph

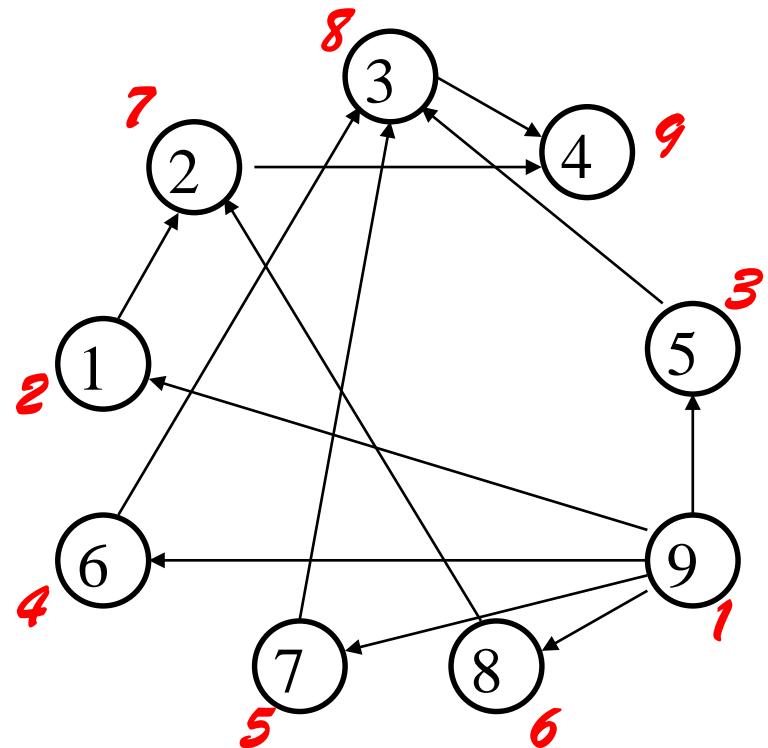


Not a DAG



Topological Order for $G=(V,E)$

- **Topological number**
 - An assignment of distinct integer $1, 2, \dots, n$ to the vertices of V
 - For every $vw \in E$, the topological number of v is less than that of w .
- **Reverse topological order**
 - Defined similarly (“greater than”)

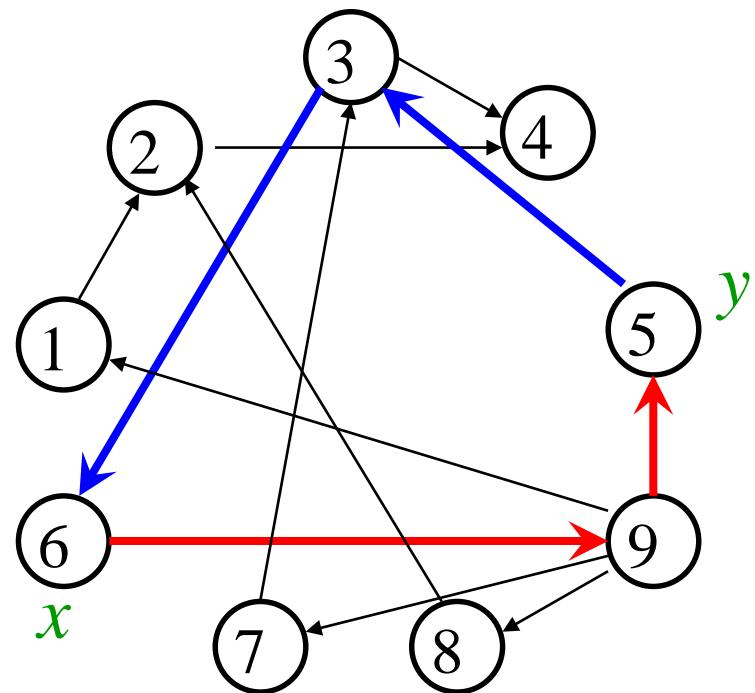


Existence of Topological Order – a Negative Result

- If a directed graph G has a cycle, then G has **no** topological order
- Proof
 - [By contradiction]

----- \rightarrow *yx-path*
----- \rightarrow *xy-path*

For any given topological order, all the vertices on both paths must be in increasing order. Contradiction results for any assignments for x and y .



Reverse Topological Ordering

- **Specialized parameters**
 - Array *topo*, keeps the topological number assigned to each vertex.
 - Counter *topoNum* to provide the integer to be used for topological number assignments
- **Output**
 - Array *topo* as filled.



Reverse Topological Ordering

- `void dfsTopoSweep(IntList[] adjVertices, int n, int[] topo)`
- `int topoNum=0`
- **<Allocate color array and initialize to white>**
- For each vertex v of G , in some order
 - `if (color[v]==white)`
`dfsTopo(adjVertices, color, v, topo, topoNum);`
 - *// Continue loop*
- `return;`

For non-reverse topological ordering,
initialized as $n+1$



Reverse Topological Ordering

```
void dfsTopo(IntList[] adjVertices, int[] color, int v, int[ ] topo, int topoNum)
int w; IntList remAdj; color[v]=gray;
remAdj=adjVertices[v];
while (remAdj!=nil)
    w=first(remAdj);
    if (color[w]==white)
        dfsTopo(adjVertices, color, w, topo, topoNum);
    remAdj=rest(remAdj);
topoNum++; topo[v]=topoNum
color[v]=black;
return;
```

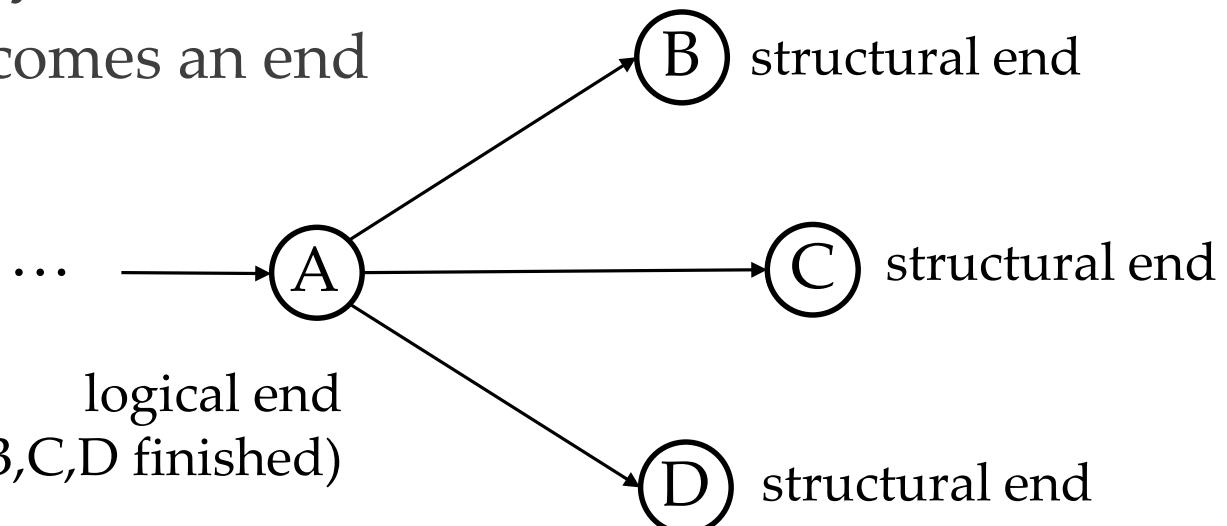
Obviously, in $\Theta(m+n)$

Filling topo is a post-order processing, so, the earlier discovered vertex has relatively greater topo number



Reverse Topological Ordering

- For an “end node”
 - Easy to decide
- Acyclic
 - There is always an end
 - Everyone becomes an end



Correctness of the Algorithm

- If G is a DAG with n vertices, the procedure dfsTopoSweep computes a reverse topological order for G in the array topo .
- Proof
 - The procedure dfsTopo is called exactly once for a vertex, so, the numbers in topo must be distinct in the range $1, 2, \dots, n$.
 - For any edge vw , vw can't be a back edge(otherwise, a cycle is formed). For any other edge types, we have $\text{finishTime}(v) > \text{finishTime}(w)$, so, $\text{topo}(w)$ is assigned earlier than $\text{topo}(v)$. Note that topoNum is incremented monotonically, so, $\text{topo}(v) > \text{topo}(w)$.



Existence of Topological Order

- In fact, the proof of correctness of topological ordering has proved that: DAG always has a topological order.
- So, **G has a topological ordering, iff. G is a directed acyclic graph.**



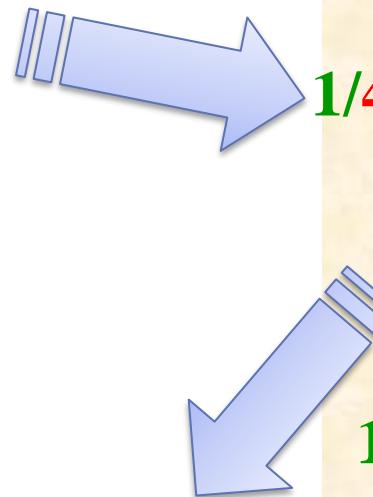
Task Scheduling

- **Problem:**
 - Scheduling a project consisting of a set of **interdependent** tasks to be done by **one** person.
- **Solution:**
 - Establishing a dependency graph, the vertices are tasks, and edge vw is included iff. the execution of v depends on the completion of w ,
 - Making task scheduling according to the topological order of the graph(if existing).

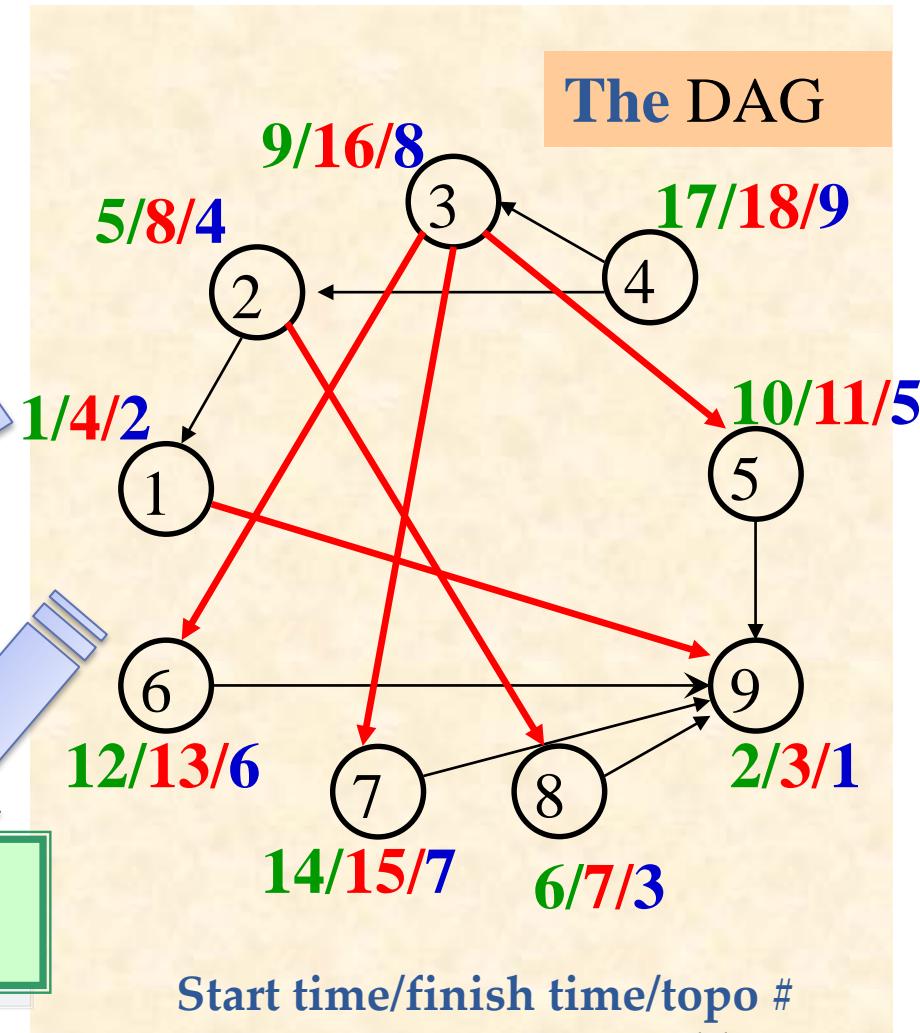


Task Scheduling: an Example

Tasks(No.)	Depends on
choose clothes(1)	9
dress(2)	1,8
eat breakfast(3)	5,6,7
leave(4)	2,3
make coffee(5)	9
make toast(6)	9
pour juice(7)	9
shower(8)	9
wake up(9)	-



A reverse topological order
9, 1, 8, 2, 5, 6, 7, 3, 4



Project Optimization Problem

Assuming that **parallel** executions of tasks (v_i) are possible except for prohibited by interdependency.

- **Observation**
 - In a **critical path**, v_{i-1} , is a critical dependency of v_i , i.e. any delay in v_{i-1} will result in delay in v_i .
 - The time for entire project depends on the time for the critical path.
 - Reducing the time of a off-critical-path task is of no help for reducing the total time for the project.
- **The problems**
 - **Find the critical path in a DAG**
 - (Try to reduce the time for the critical path)

This is a precondition.

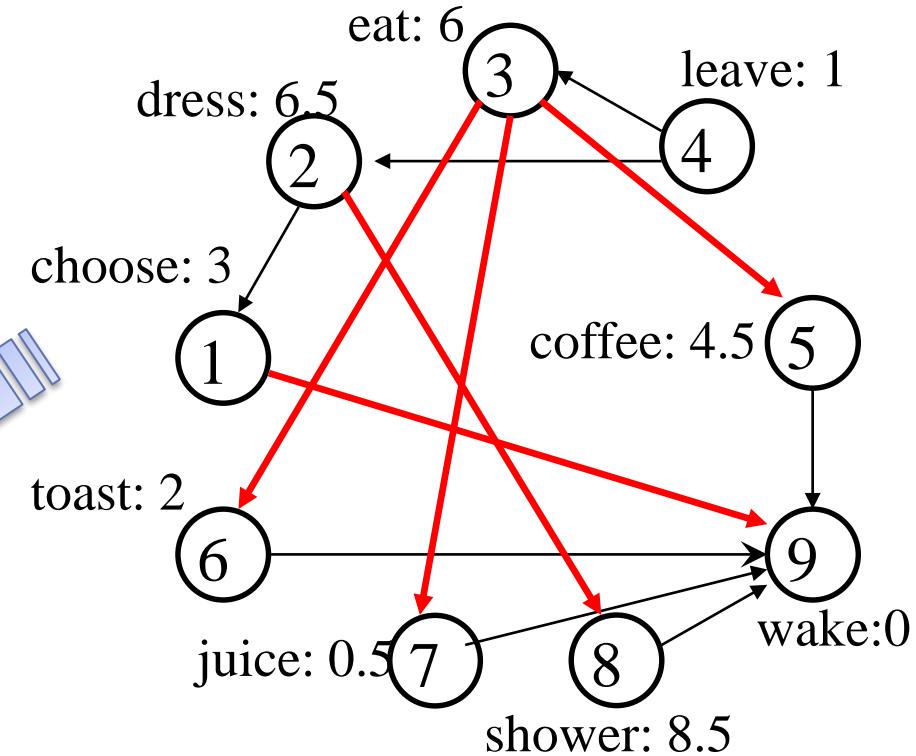
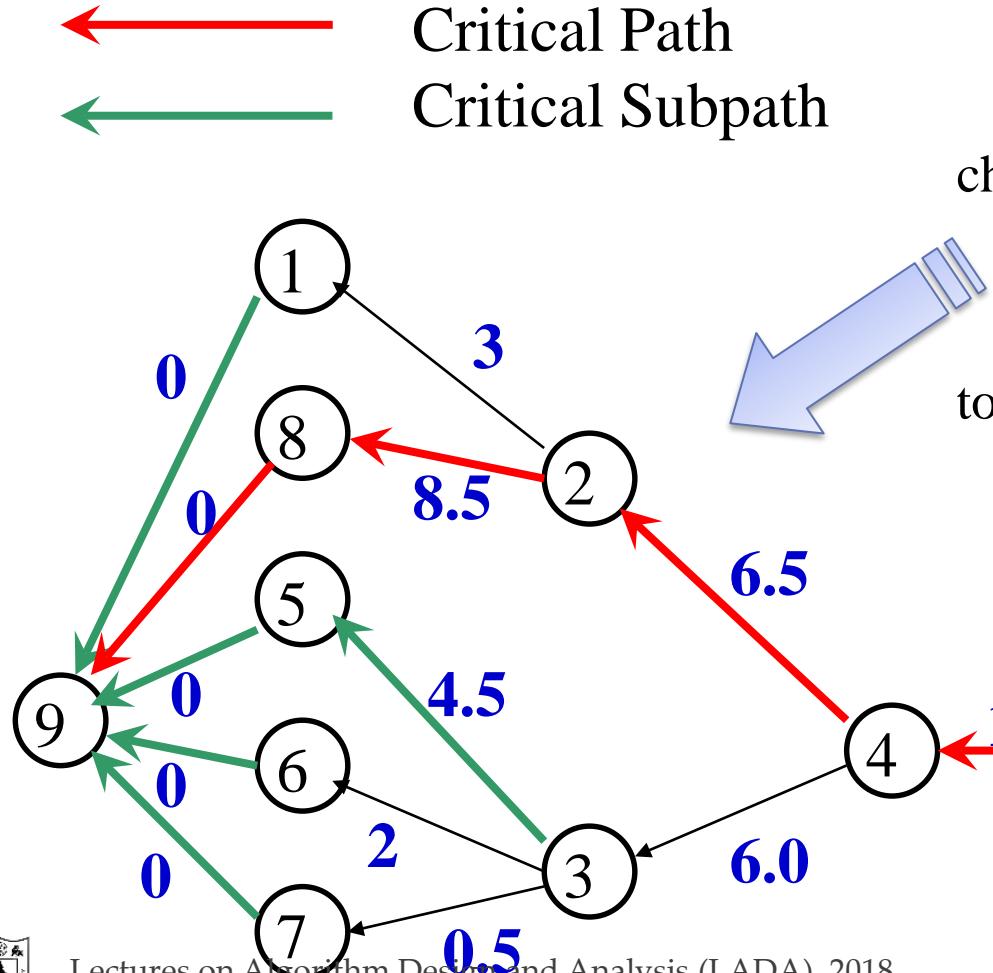


Critical Path in a Task Graph

- **Earliest start time**(est) for a task v
 - If v has no dependencies, the *est* is 0
 - If v has dependencies, the *est* is the maximum of the **earliest finish time** of its dependencies.
- **Earliest finish time**(eft) for a task v
 - For any task: $eft = est + duration$
- **Critical path** in a project is a sequence of tasks: v_0, v_1, \dots, v_k , satisfying:
 - v_0 has no dependencies;
 - For any $v_i (i=1,2,\dots,k)$, v_{i-1} is a dependency of v_i , such that *est* of v_i equals *eft* of v_{i-1} ;
 - *eft* of v_k is maximum for all tasks in the project.



DAG with Weights



Critical Path Finding - DFS

- **Specialized parameters**
 - Array *duration*, keeps the execution time of each vertex.
 - Array *critDep*, keeps the critical dependency of each vertex.
 - Array *eft*, keeps the earliest finished time of each vertex.
- **Output**
 - Array *topo*, *critDep*, *eft* as filled.
- **Critical path is built by tracing the output.**

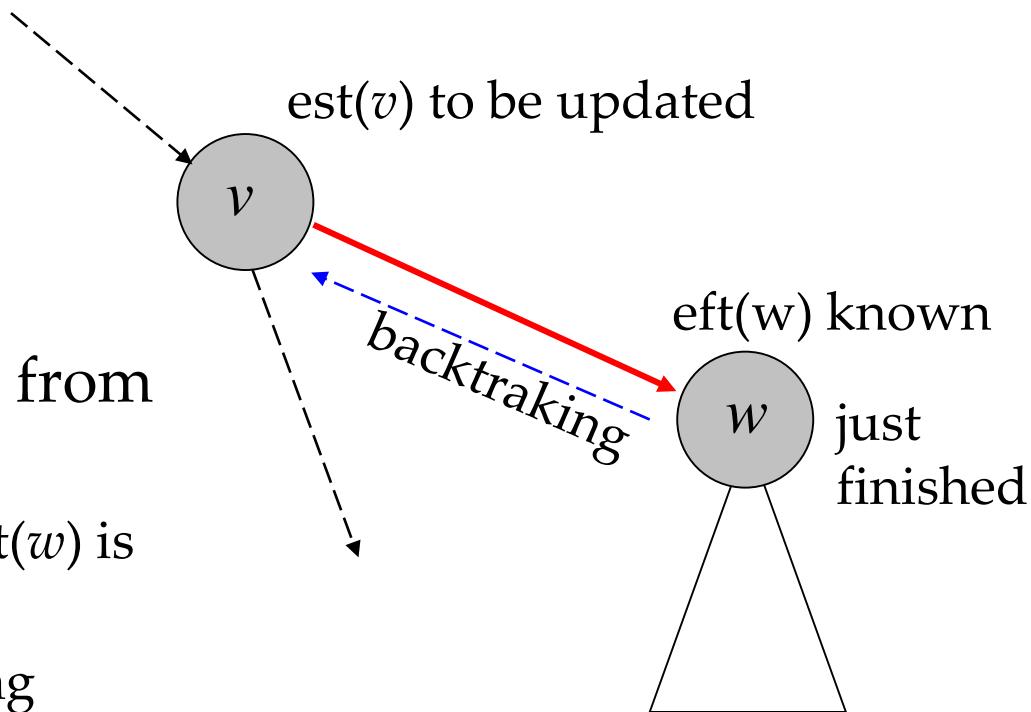


Critical Path – Case 1

Upon backtracking from

w :

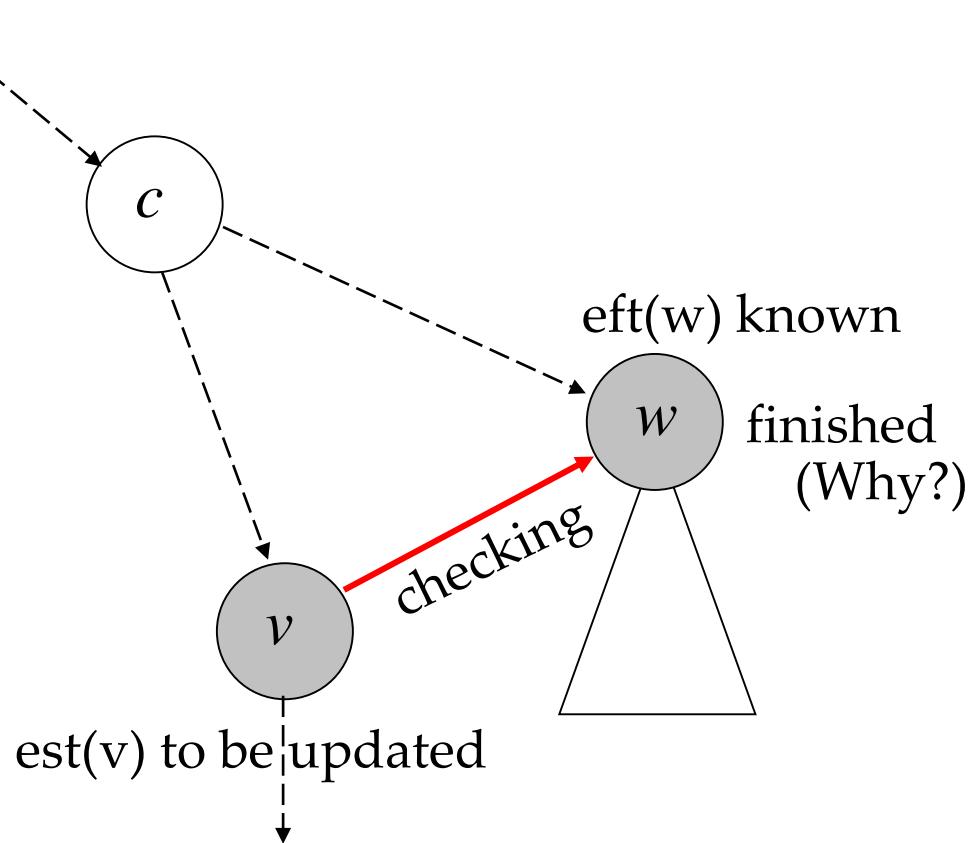
- $\text{est}(v)$ is updated if $\text{eft}(w)$ is larger than $\text{est}(v)$
- and the path including edge vw is recognized as the critical path for task v
- and the $\text{eft}(v)$ is updated accordingly



Critical Path – Case 2

Checking w :

- $\text{est}(v)$ is updated if $\text{eft}(w)$ is larger than $\text{est}(v)$
- and the path including edge vw is recognized as the critical path for task v
- and the $\text{eft}(v)$ is updated accordingly



Critical Path by DFS

- `void dfsCritSweep(IntList[] adjVertices,int n, int[] duration, int[] critDep, int[] eft)`
- **<Allocate color array and initialize to white>**
- For each vertex v of G , in some order
 - if (color[v]==white)
 - `dfsCrit(adjVertices, color, v, duration, critDep, eft);`
 - *// Continue loop*
 - `return;`



Critical Path by DFS

- void **dfsCrit**(.. *adjVertices*, .. *color*, .. *v*, int[] *duration*, int[] *critDep*, int[] *eft*)
 - int *w*; IntList *remAdj*; int *est*=0;
 - *color*[*v*]=gray; *critDep*[*v*]=-1; *remAdj*=*adjVertices*[*v*];
 - while (*remAdj*≠nil) *w*=first(*remAdj*);
 - if (*color*[*w*]==white)
 - **dfsCrit**(*adjVertices*, *color*, *w*, *duration*, *critDep*, *efs*);
 - if (*eft*[*w*]≥*est*) *est*=*eft*[*w*]; *critDep*[*v*]=*w*
 - else//~~checking for nontree edge~~
 - if (*eft*[*w*]≥*est*) *est*=*eft*[*w*]; *critDep*[*v*]=*w*
 - *remAdj*=rest(*remAdj*);
 - *eft*[*v*]=*est*+*duration*[*v*]; *color*[*v*]=black;
 - return;

When is the eft[w] initialized?

Only black vertex

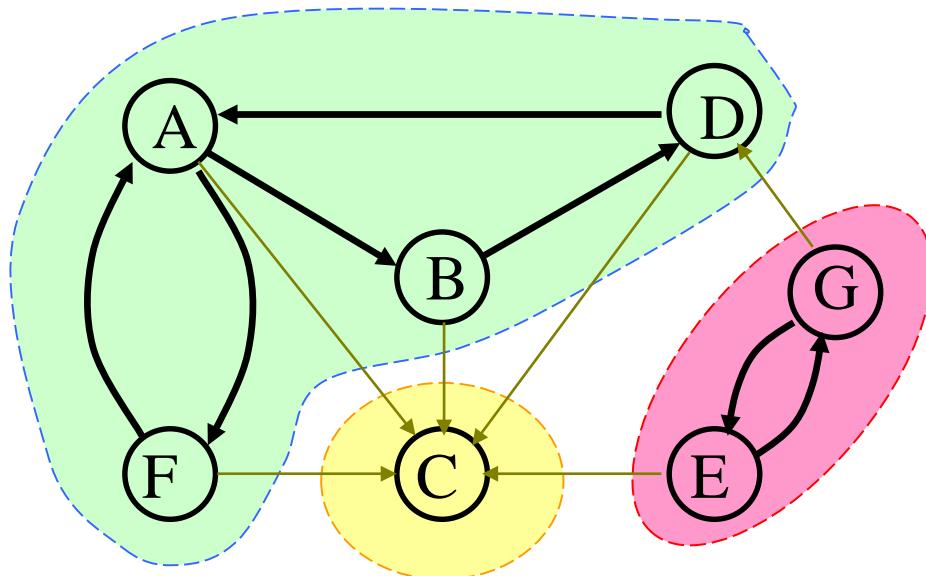


Analysis of Critical Path Algorithm

- **Correctness:**
 - When $eft[w]$ is accessed in the while-loop, the w must not be gray(otherwise, there is a cycle), so, it must be black, with eft initialized.
 - According to DFS, each entry in the eft array is assigned a value **exactly once**. The value satisfies the definition of eft .
- **Complexity**
 - Simply same as DFS, that is **$\Theta(n+m)$** .



SCC: Strongly Connected Component

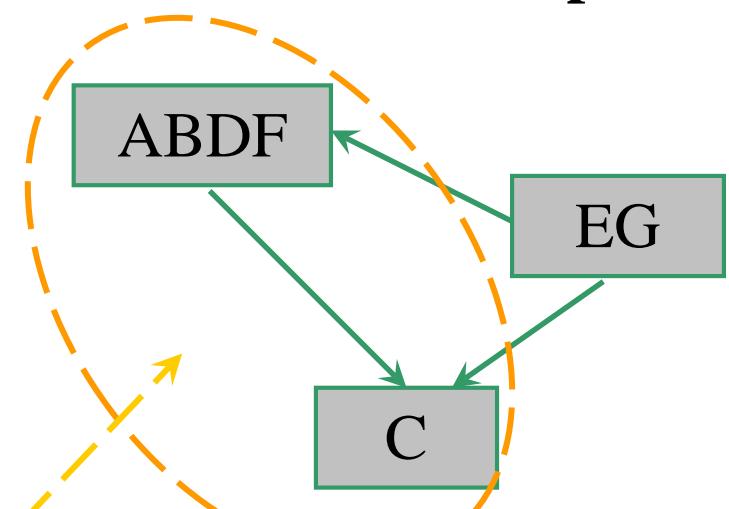


Graph G

3 Strongly Connected Components

Note: two SCC in one DFS tree

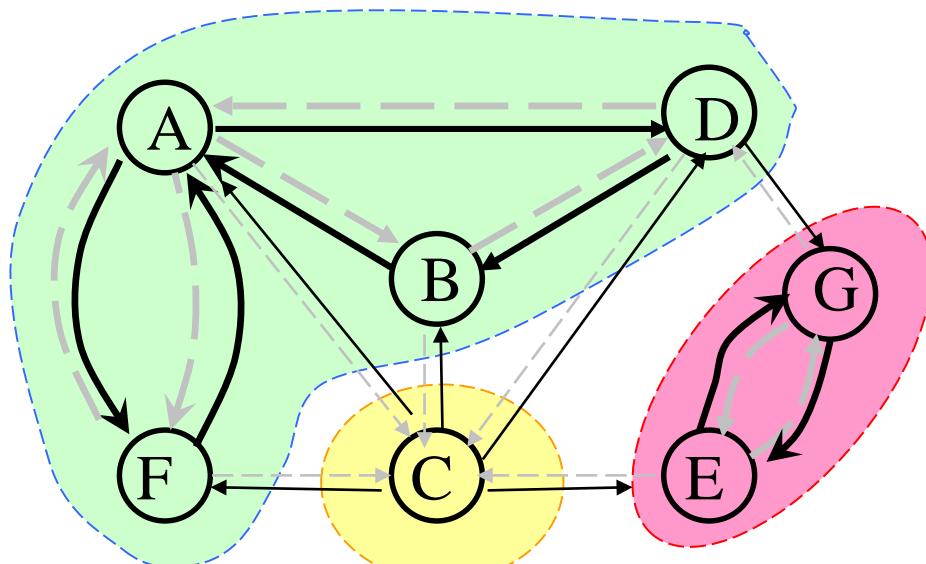
Condensation Graph $G \downarrow$



It's acyclic, **Why?**



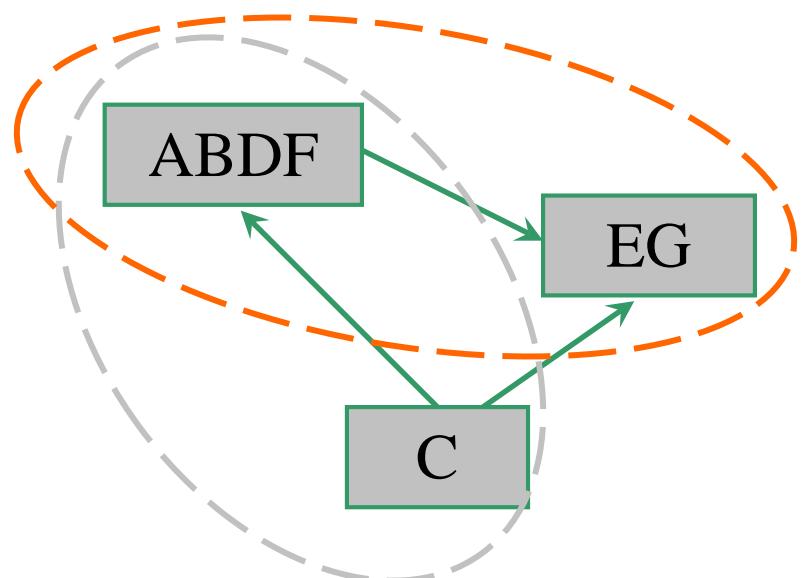
Transpose Graph



Transpose Graph G^T

Connected Components **unchanged**
according to vertices

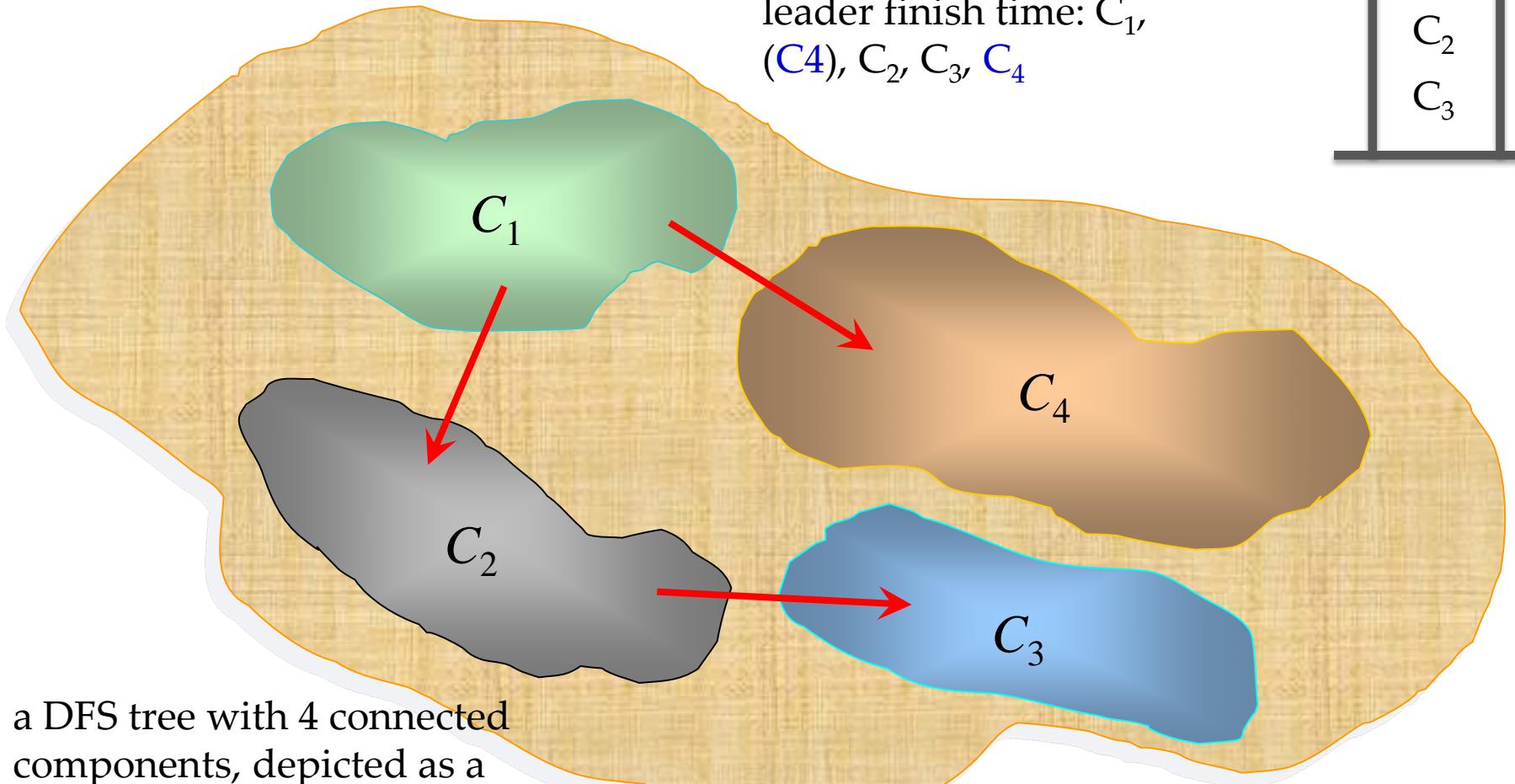
Condensation Graph $G \downarrow$



But, DFS tree **changed**



Basic Idea - G



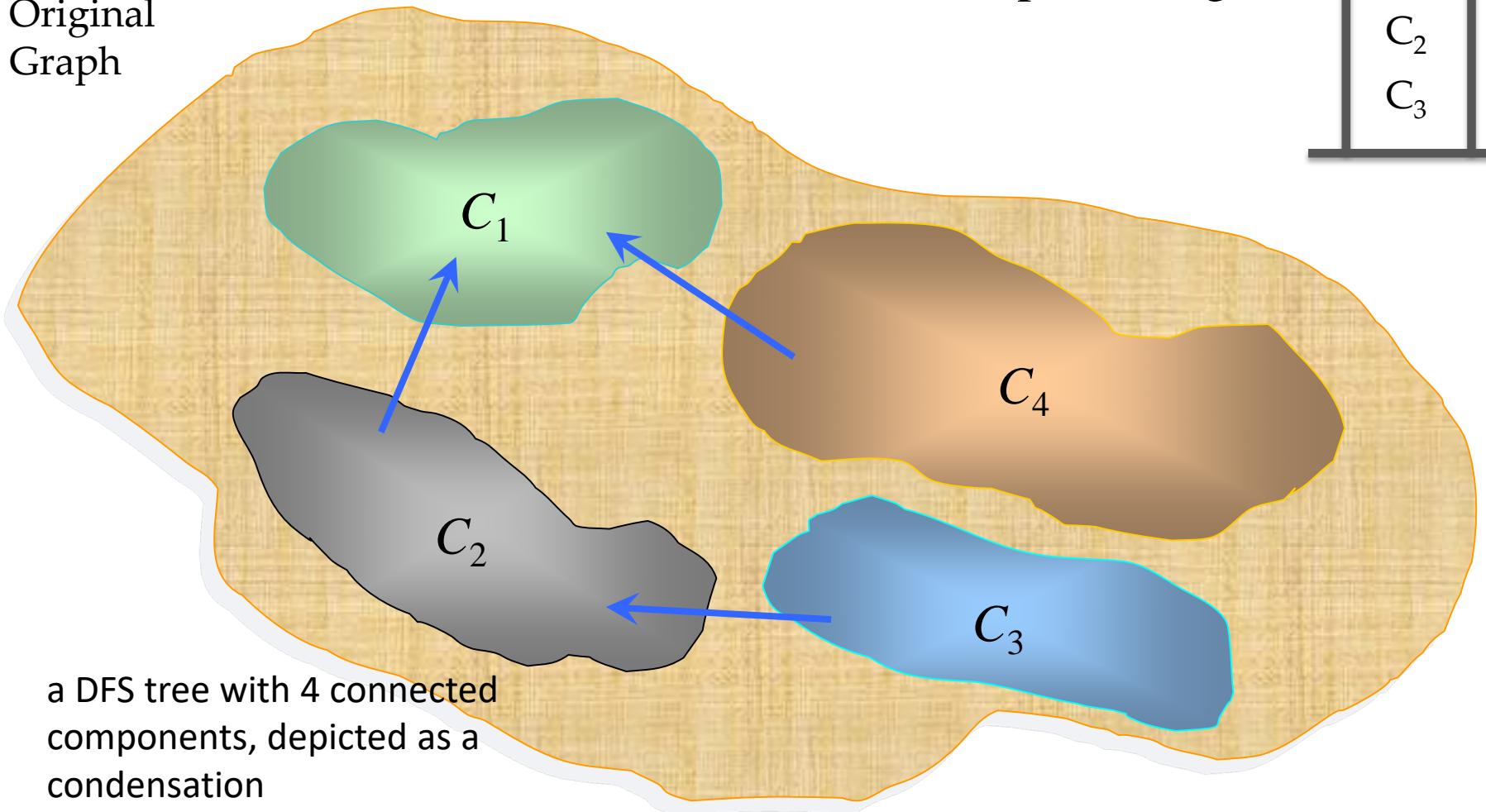
a DFS tree with 4 connected components, depicted as a condensation

Original edge
5/7/2018 27

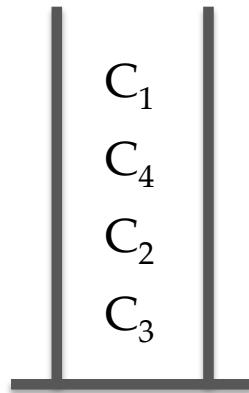


Basic Idea - G^T

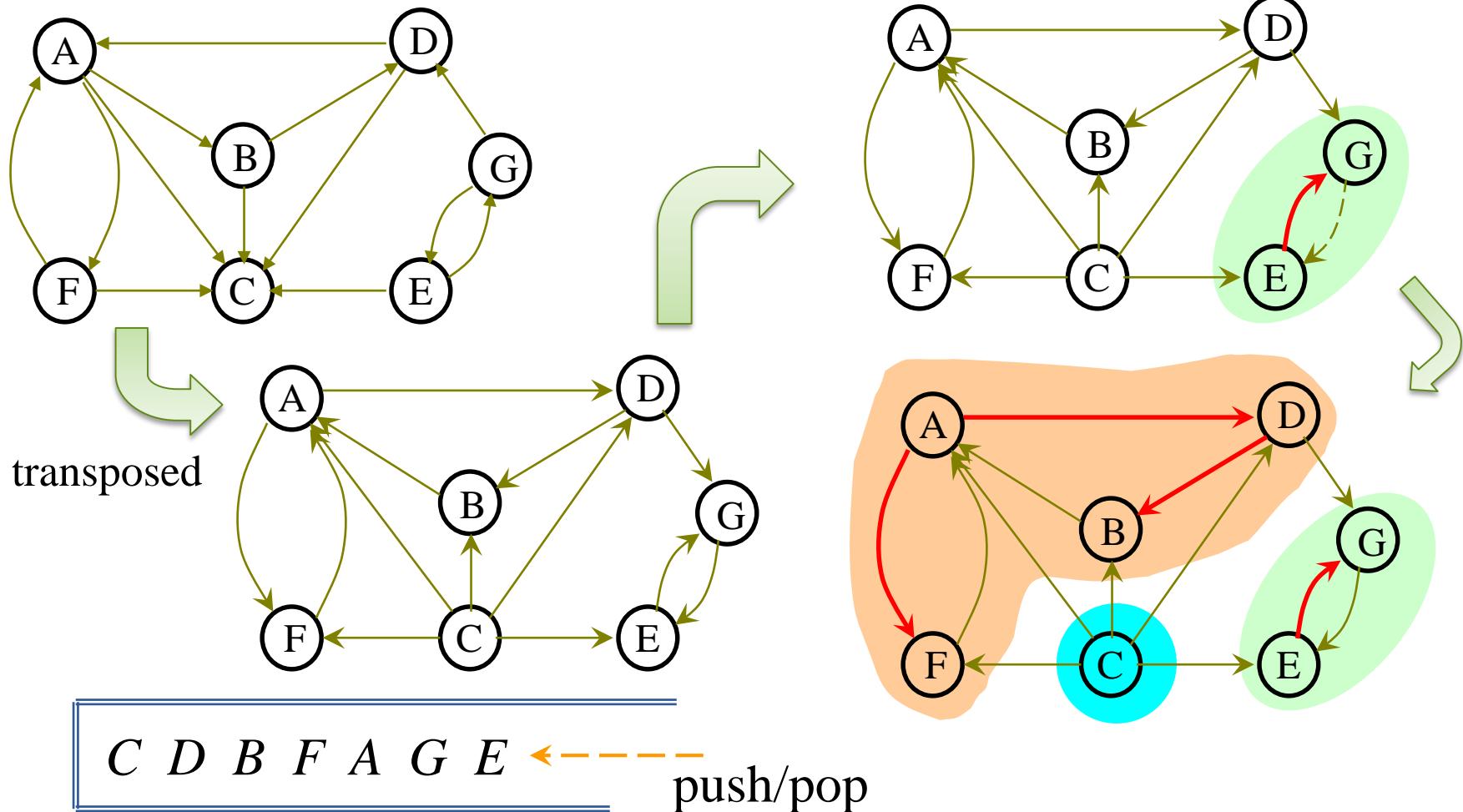
Original
Graph



Transposed edge



SCC - An Example



Strong Component Algorithm: Outline

- `void strongComponents(IntList[] adjVertices, int n, int[] scc)`
- *//Phase 1*
 - 1. `IntStack finishStack=create(n);`
 - 2. Perform a depth-first search on G , using the DFS skeleton. At postorder processing for vertex v , insert the statement: `push(finishStack, v)`
- *//Phase 2*
 - 3. Compute G^T , the transpose graph, represented as array `adjTrans` of adjacency list.
 - 4. `dfsTsweep(adjTrans, n, finishStack, scc);`
 - `return`

Note: G and G^T have the same SCC sets



Strong Component Algorithm: Core

- `void dfsTsweep(IntList[] adjTrans, int n, IntStack finishStack, int[] scc)`
- `<Allocate color array and initialize to white>`
- `while (finishStack is not empty)`
 - `int v=top(finishStack);`
 - `pop(finishStack);`
 - `if (color[v]==white)`
 - `dfsT(adjTrans, color, v, v, scc);`
 - `return;`
- `void dfsT(IntList[] adjTrans, int[] color, int v, int leader, int[] scc)`
- `Use the standard depth-first search skeleton. At postorder processing for vertex v insert the statement:`
 - `scc[v]=leader;`
 - `Pass leader and scc into recursive calls.`



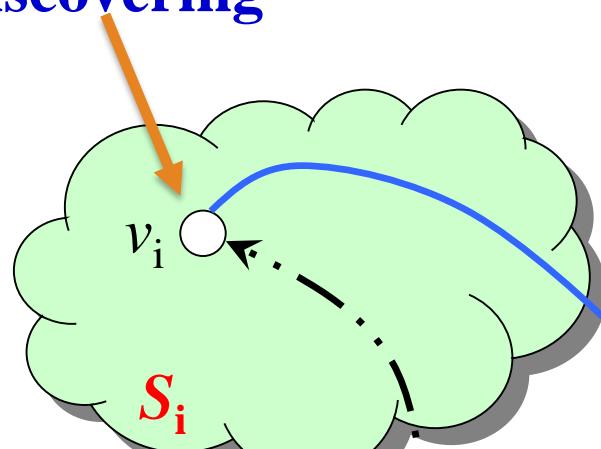
Leader of a Strong Component

- For a DFS, the first vertex discovered in a strong component S_i is called the **leader** of S_i .
- Each DFS tree of a digraph G contains **only complete** strong components of G, one or more.
 - Proof: Applying White Path Theorem whenever the leader of S_i ($i=1,2,\dots,p$) is discovered, starting with all vertices being white.
- The leader of S_i is the last vertex to finish among all vertices of S_i . (**since all of them in the same DFS tree**)



Path between SCCs

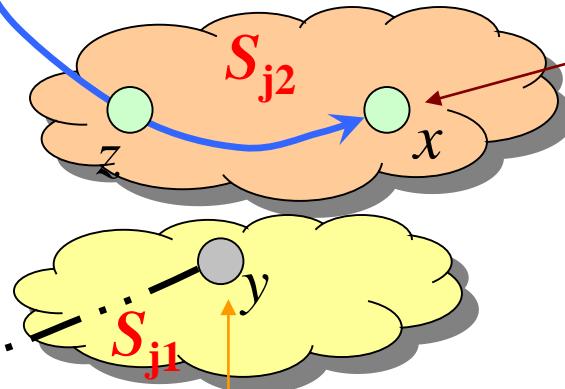
The leader of S_i
At discovering



Existing a yv_i -path, so x must be in
a different strong component.
No v_iy -path can exist.

x can't be gray.

- White case: $v_i x$ -path is a White Path, or
- Black case: x is black (consider the [possible] last non-white vertex z on the $v_i x$ -path)



*What's the
color?*

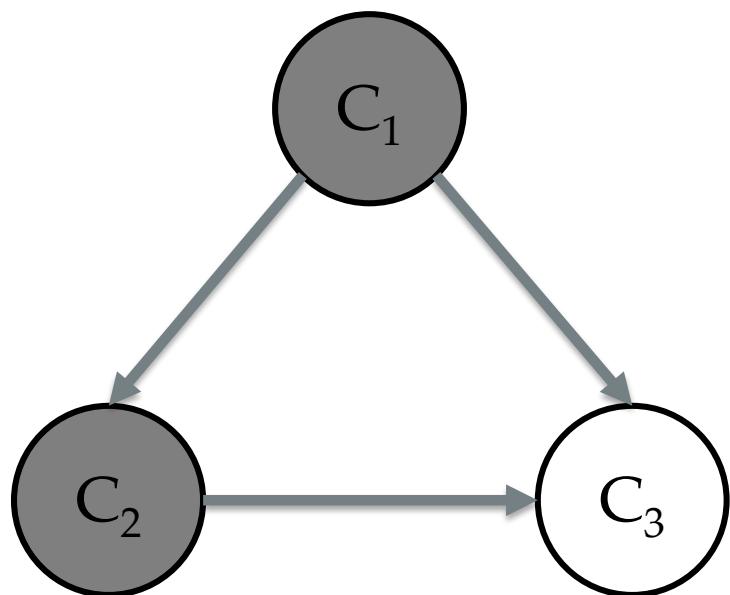
See Lemma 7.8 & 7.9
p. 360 of [Baase01]



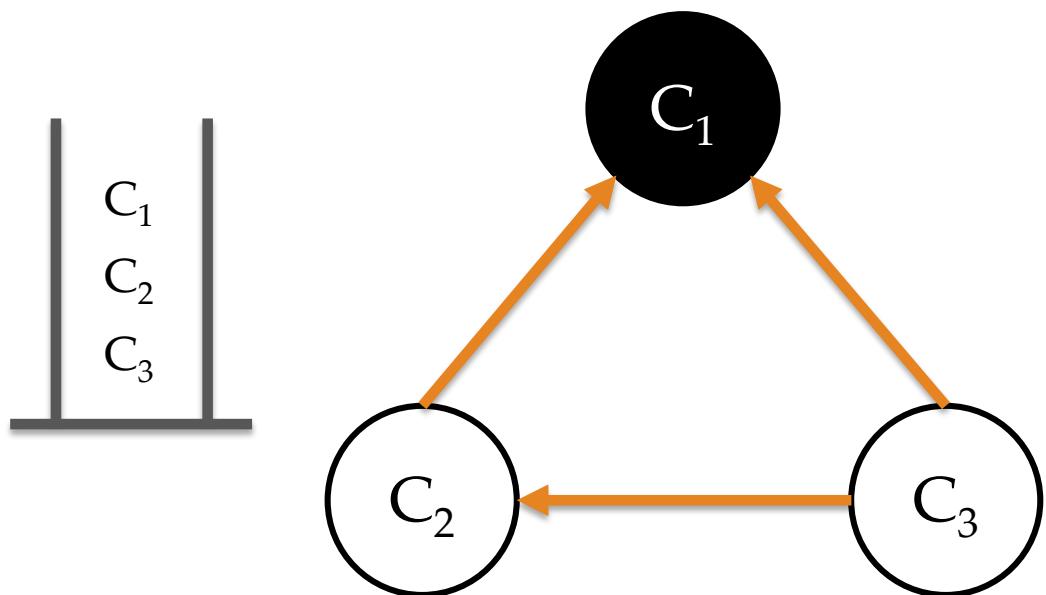
C_1 : The End Case

Looking at C_2, C_3 from C_1

G



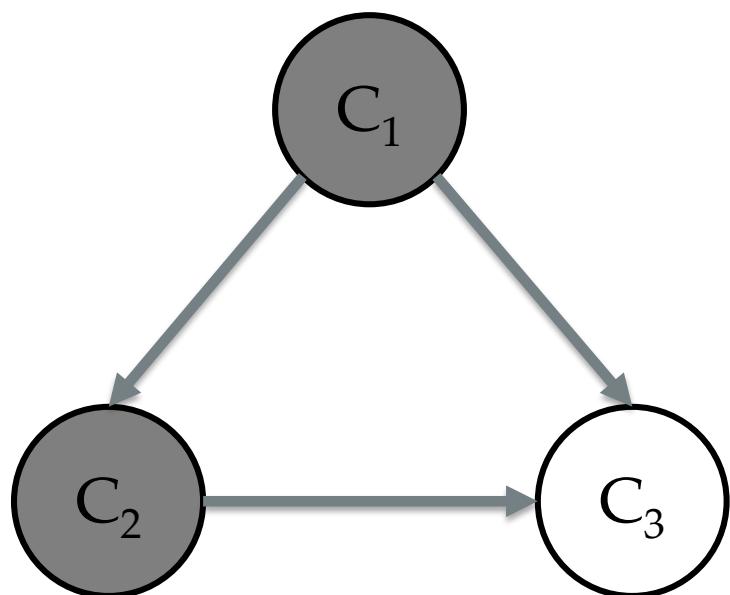
G^T



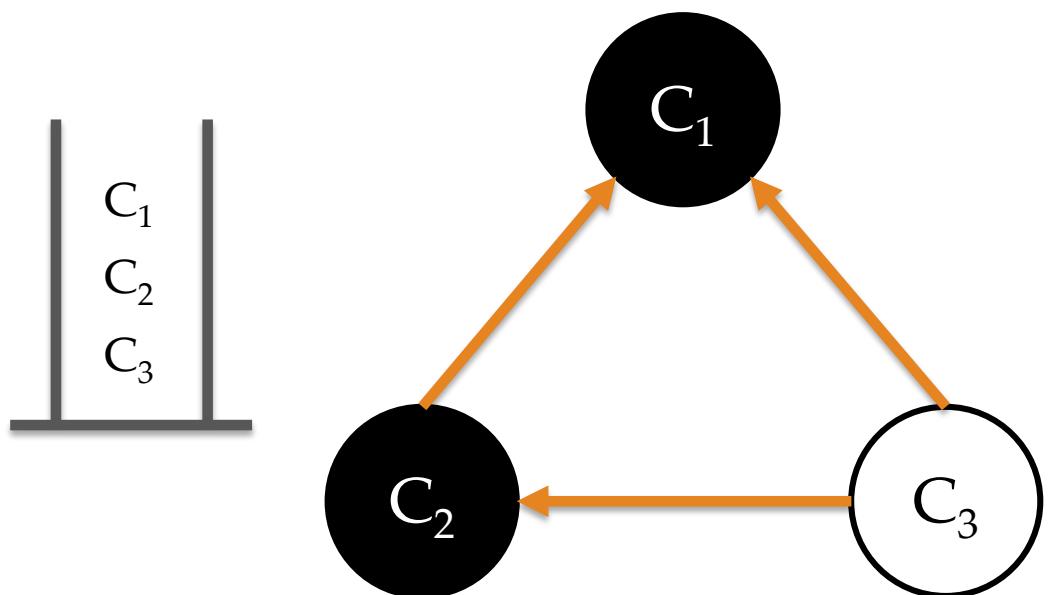
C_2 : The White Case

Looking at C_3 from C_2

G



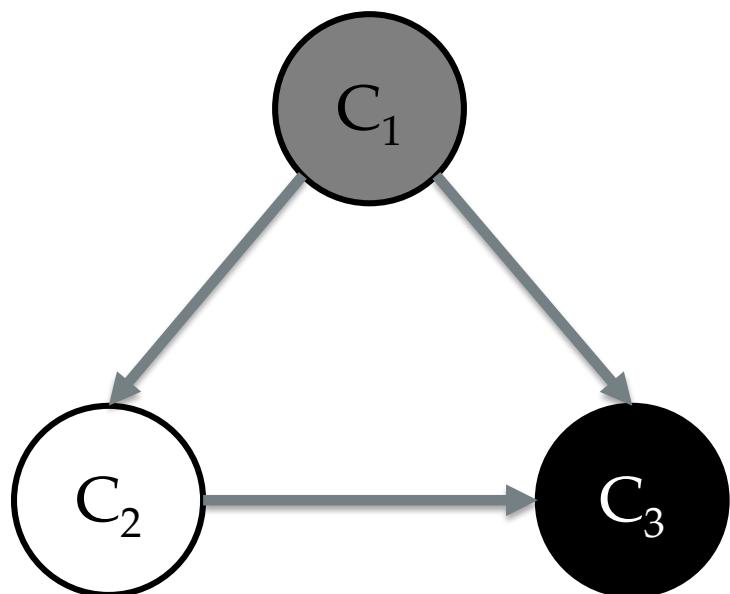
G^T



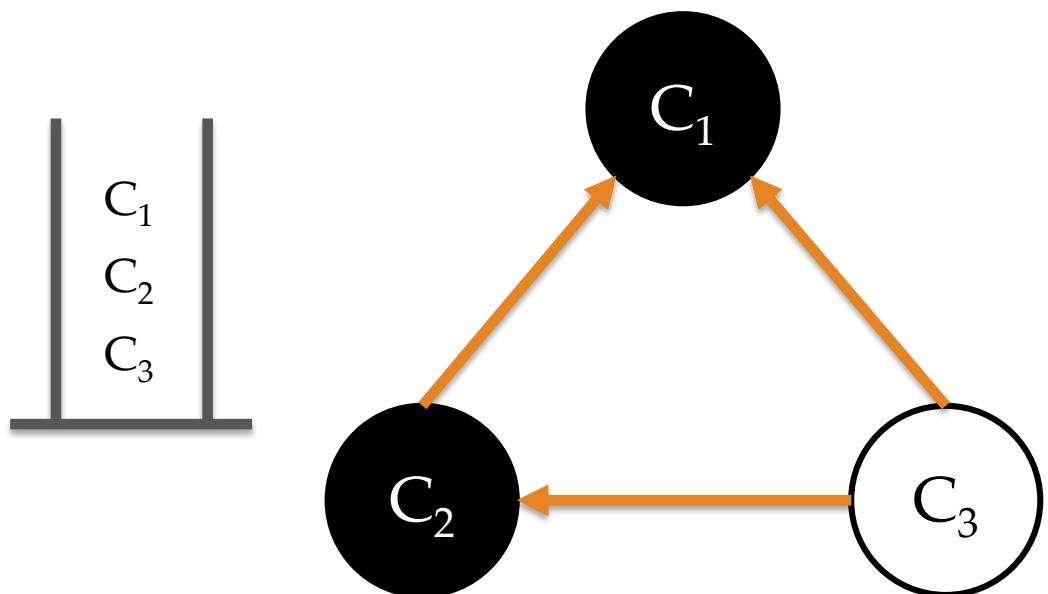
C_2 : The Black Case

Looking at C_3 from C_2

G



G^T



Active Intervals

- If there is an edge from S_i to S_j , then it is **impossible** that the active interval of v_j is **entirely after** that of v_i . (Note: for leader v_i only)
 - There is no path from a leader of a strong component to any gray vertex.
 - If there is a path from the leader v of a strong component to any x in a different strong component, v finishes later than x .



Correctness of Strong Component Algorithm (1)

- In phase 2, each time a white vertex is popped from *finishStack*, that vertex is the Phase 1 leader of a strong component.
 - The later finished, the earlier popped
 - The leader is the first to get popped in the strong component it belongs to
 - If x popped is not a leader, then some other vertex in the strong component has been visited previously. But not a partial strong component can be in a DFS tree, so, x must be in a completed DFS tree, and is not white.



Correctness of Strong Component Algorithm (2)

- In phase 2, each depth-first search tree contains exactly one strong component of vertices
 - Only “exactly one” need to be proved
 - Assume that v_i , a phase 1 leader is popped. If another component S_j is reachable from v_i in G^T , there is a path in G from v_j to v_i . So, in phase 1, v_j finished later than v_i , and popped earlier than v_i in phase 2. So, when v_i popped, all vertices in S_j are black. So, S_j are not contained in DFS tree containing $v_i(S_i)$.



Thank you!

Q & A

yuhuang

<http://cs.nju.edu.cn/yuhuang>

