Class 6: Hierarchical generalised linear models

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From LMs to HGLMs

- ► Reminder: a hierarchical model has prior distributions on the parameters which depend on further parameters
- ▶ A generalised linear model is one in which the probability distribution is not normal, and a link function serves to match the mean of the distribution to the covariates
- ▶ Within this framework, we can borrow the ideas from the previous class to create hierarchical GLMs
- ► We will go through four examples: binomial-logit, Poisson, robust regression, and ordinal regression

Learning outcomes:

- Understand the modelling implications of moving from linear to hierarchical generalised linear models (HGLMs)
- ▶ Know some of the different versions of Hierarchical GLMs
- ▶ Be able to fit HGLMS in JAGS
- ▶ Be able to expand and summarise fitted models

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Example 1: binomial-logit

▶ In class 2, we met the Binomial-logit model for binary data:

$$y_i \sim Bin(1, p_i), logit(p_i) = \alpha + \beta(x_i - \bar{x})$$

Here $logit(p_i)$ is the link function equal to $log\left(\frac{p_i}{1-p_i}\right)$ and transforms the bounded probabilities into an unbounded space

▶ If we have non-binary data we just change the likelihood:

$$y_i \sim Bin(N_i, p_i), logit(p_i) = \alpha + \beta(x_i - \bar{x})$$

▶ In a hierarchical version of this model, we vary the *latent* parameters α and β and give them prior distributions

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The swiss willow tit data

```
swt = read.csv('../data/swt.csv')
head(swt)
##
    rep.1 rep.2 rep.3 c.2 c.3 elev forest dur.1 day.2 day.3 length alt
## 1
       0
            0
                 0 0 0 420
                                 3 240
                                           58
                                                73
                                                     6.2 Low
                 0 0 0 450
## 2
            0
                                 21 160
                                           39
                                                62
                                                     5.1 Low
            0
                 0
                   0 0 1050
                                 32
                                    120
                                           47
                                                     4.3 Med
## 4
            0
                 0 0 0 1110
                                 35
                                    180
                                           44
                                                71
                                                     5.4 Med
## 5
       0
            0
                 0 0 0 510
                                 2 210
                                           56
                                               73
                                                    3.6 Low
                   0 0 630
                                 60
                                    150
                                                    6.1 Low
```

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JAGS code

```
jags_code = '
model{
    # Likelihood
    for(i in 1:N) {
        y[i] - dbin(p[i], N_exp[i])
        logit(p[i]) <- alpha[alt[i]] + beta[alt[i]]* (x[i] - mean(x))
    }
    # Priors
    for(j in 1:N_alt) {
        alpha[j] - dhorm(mu_alpha, sigma_alpha^-2)
        beta[j] - dhorm(mu_beta, sigma_beta^-2)
    }
    mu_alpha - dhorm(0, 5^-2)
    mu_beta - dhorm(0, 0.1^-2)
    sigma_alpha - dt(0,5,1)T(0,)
    sigma_beta - dt(0,5,1)T(0,)
}</pre>
```

A hierarchical model

- Suppose we want to fit a model on the sum $y_i = \text{rep.1} + \text{rep.2} + \text{rep.3}$:

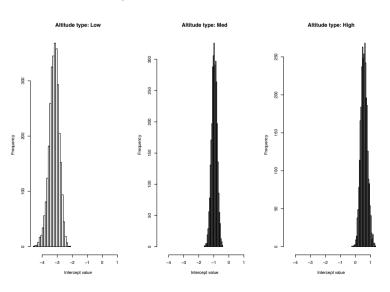
$$y_i \sim Bin(N_i, p_i), logit(p_i) = \alpha_{altitude_i} + \beta_{altitude_i}(x_i - \bar{x})$$

where x_i is the percentage of forest cover

- ▶ What prior distributions should we use for α and β ?
- ▶ Useful side note: A value of 10 on the logit scale leads to a probability of about 1, and a value of -10 leads to a probability of about 0 (you can test this by typing inv.logit(10)) so I wouldn't expect the value of $logit(p_i)$ to ever get much bigger than 10 or smaller than -10
- ▶ I have no idea whether we are more likely to find these birds in high percentage forest or low, so I'm happy to think that β might be around zero, and be positive or negative. Forest cover ranges from 0 to 100 so that suggests that β is every likely to be bigger than 0.1 or smaller than -0.1. Perhaps $\beta \sim N(0,0.1^2)$ is a good prior
- ▶ It looks to me like the intercept is very unlikely to be outside the range (-10, 10) so perhaps $\alpha \sim N(0, 5^2)$ is appropriate

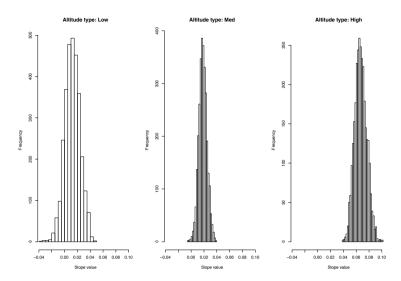
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Model fit - intercepts



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Model fit - Slopes



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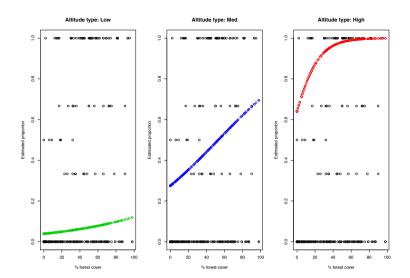
Type 2: Poisson HGLMs

- ► For a Poisson distribution there is no upper bound on the number of counts
- ► We just change the likelihood (to Poisson) and the link function (to log):

$$y_i \sim Po(\lambda_i), \log(\lambda_i) = \alpha + \beta(x_i - \bar{x})$$

- We can now add our hierarchical layers into α and β , or...
- ▶ Another way we can add an extra layer is by giving $log(\lambda_i)$ a probability distribution rather than setting it to a value
- ► This is a way of introducing *over-dispersion*, i.e. saying that the data are more variable than that expected by a standard Poisson distribution with our existing covariates

Model fit - estimated mean proportions



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An over-dispersed model

▶ The over-dispersed model looks like:

$$y_i \sim Po(\lambda_i), \log(\lambda_i) \sim N(\alpha + \beta(x_i - \bar{x}), \sigma^2)$$

where σ is the over-dispersion parameter

- \blacktriangleright We now need to estimate prior distributions for α , β , and σ
- ► We will use the SWT data again, but pretend that we didn't know that they had gone out *N* times looking for the birds

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JAGS code for OD Poisson

```
jags_code =
model{
  # Likelihood
  for(i in 1:N) {
    y[i] ~ dpois(exp(log lambda[i]))
   log_lambda[i] ~ dnorm(alpha + beta * (x[i] - mean(x)),
  alpha ~ dnorm(0, 5^-2)
 beta ~ dnorm(0, 0.1^-2)
  sigma \sim dt(0,5,1)T(0,)
```

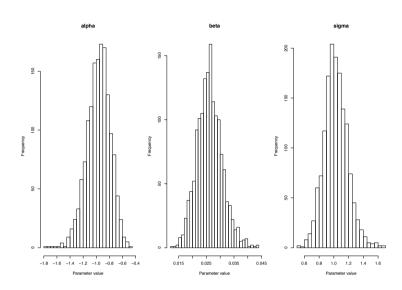
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Notes about OD Poisson model

- ▶ The way to think about OD models is via the data generating process. Draw a DAG and think about how these processes might arise
- ▶ We could compare this model to one without over dispersion via DIC (or if time, cross validation). We should also compute a posterior predictive distribution for full comparison
- ▶ In general, the parameter values (i.e. alpha and beta) tend to be more uncertain when you add in over dispersion
- ▶ Also in the data set is a variable called dur which represents how long they spent looking for the birds. This could be added in as an offset via the likelihood:

```
y[i] ~ dpois(dur[i] * exp(log_lambda[i]))
```

Model run



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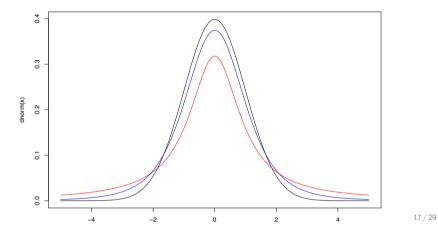
Type 3: *t*-distributed HGLMs

- ▶ How do Bayesians deal with outliers?
- ▶ A common view is that we should delete these observations before we run the model, but what if we can't find a reason for doing so
- ▶ A good Bayesian will include outliers as part of the model.
- ▶ One way of doing this is by switching from a normal distribution to a t-distribution

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Normal vs t

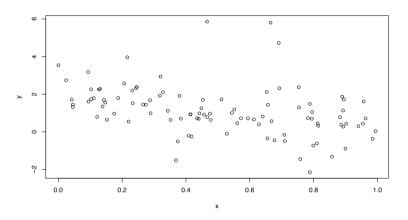
```
curve(dnorm, from = -5, to = 5)
curve(dt(x, df = 1), add = TRUE, col = 'red')
curve(dt(x, df = 4), add = TRUE, col = 'blue')
```



JAGS code for a t-model

Polluted data

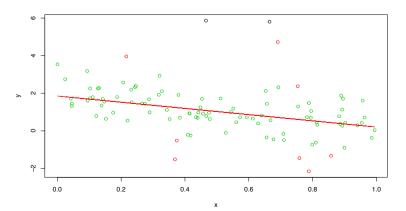
▶ Suppose we had some data which looked like this:



There are a few observations here which look a bit odd

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Output from the model



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Prior distributions on the degrees of freedom

- ▶ Here I've set a prior distribution on the degrees of freedom parameter to be Binomial with the maximum value to be 10+1 = 11
- ► The probability of each observation being an outlier is *p*, set to be uniform between 0 and 1
- ► We thus also create a posterior distribution for the probability that each observation is an outlier
- ► The Binomial distribution we use has a peak at the degrees of freedom being 6 or 7, we might instead use a discrete uniform prior though this is harder to code in JAGS/Stan

Type 4: Ordinal data HGLMs

- ► Often we have a response variable which is ordinal, e.g. disagree, neutral, agree, etc
- ► There are lots of different (and complicated) ways to model such data
- ► Perhaps the easiest is to think of it as a hierarchical model with 'cut-points' on a latent linear regression

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An ordinal model example

▶ Suppose $y_i = \{\text{disagree, neutral, agree}\}$ and we make it dependent on a latent continuous variable z_i , so that :

$$y_i = \left\{ egin{array}{ll} \mathsf{agree} & \mathsf{if} \ z_i > 0.5 \\ \mathsf{neutral} & \mathsf{if} \ -0.5 < z_i \leq 0.5 \\ \mathsf{disagree} & \mathsf{if} \ z_i \leq -0.5 \end{array}
ight.$$

• We then give z_i a prior distribution, e.g. $N(\beta_0 + \beta_1 x_i, \sigma^2)$

Fitting ordinal models in JAGS

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Simulating some example data

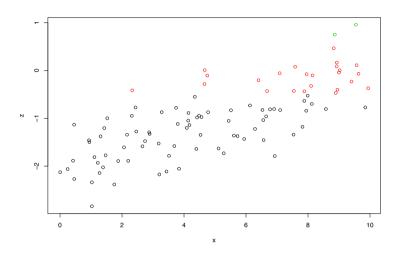
```
N = 100
alpha = -1
beta = 0.2
sigma = 0.51
set.seed(123)
x = runif(N, 0, 10)
cuts = c(-0.5, 0.5)
z = rnorm(N, alpha + beta * (x - mean(x)), sigma)
y = findInterval(z, cuts)
```

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Fitting in JAGS - needs initial values

Simulated data - plot

```
plot(x, z, col = y + 1)
```



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Output

```
print(jags_run)
```

```
## Inference for Bugs model at "5", fit using jags,
## 3 chains, each with 2000 iterations (first 1000 discarded)
   n.sims = 3000 iterations saved
            mu.vect sd.vect
                            2.5%
                                     25%
                                            50%
                                                   75% 97.5%
                    0.200 -1.619 -1.172 -1.038 -0.945 -0.814 1
## alpha
             -1.082
## beta
             0.220
                     0.059 0.134 0.179 0.210 0.249 0.367 1
             0.537
                     0.123  0.363  0.449  0.515  0.597  0.842  1
## sigma
## deviance
             0.000
                     0.000 0.000 0.000 0.000 0.000 0.000 1
## For each parameter, n.eff is a crude measure of effective sam
## and Rhat is the potential scale reduction factor (at converge
## DIC info (using the rule, pD = var(deviance)/2)
## pD = 0.0 and DIC = 0.0
## DIC is an estimate of expected predictive error (lower devian
```

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Summary

- ► We have now seen a number of different types of hierarchical GLM
- ► Many of the ideas of hierarchical linear models transfer over, but we can explore richer behaviour with hierarchical GLMs
- ► These have all used the normal, binomial or Poisson distribution at the top level, and have allowed for over-dispersion, robustness, and ordinal data, to name just three