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In [3]: from pathlib import Path
from typing import List
import numpy as np
import pandas as pd
import torch
import torch.nn as nn
import matplotlib
import scipy
import matplotlib.pyplot as plt
from sklearn.metrics import (
    confusion_matrix,
    ConfusionMatrixDisplay,
    roc_curve,
    auc,
    RocCurveDisplay,
    precision_recall_curve,
    PrecisionRecallDisplay,
)
from sklearn.preprocessing import StandardScaler
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In [4]: # simple Transformer-based classifier for sequence data
class TransformerClassifier(nn.Module):

    def __init__(
        self,
        input_size: int = 1,      # number of features per time step, 1 as we have
        seq_length: int = 12,     # length of input sequences, covers all the 12 fe
        d_model: int = 64,        # size of embedding vector, kept relatively small
        nhead: int = 4,           # number of attention heads, kept small for speed
        num_layers: int = 2,      # number of Transformer layers, kept small for sp
        dropout: float = 0.3,     # dropout rate for regularisation, set 0.3 to red
    ):
        super().__init__()

        # project input features to model dimension
        self.input_projection = nn.Linear(input_size, d_model)

        # one encoder layer: self-attention + feed-forward
        enc_layer = nn.TransformerEncoderLayer(
            d_model=d_model, nhead=nhead, dropout=dropout, batch_first=True
        )

        # stack the two encoder layers
        self.encoder = nn.TransformerEncoder(enc_layer, num_layers=num_layers)

        # final classification head
        self.classifier = nn.Sequential(
            nn.Linear(d_model, 32),
            nn.ReLU(),
            nn.Dropout(dropout),
            nn.Linear(32, 1)
        )

    def forward(self, x: torch.Tensor) -> torch.Tensor:
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        x = self.input_projection(x)
        x = self.encoder(x)
        pooled = x.mean(dim=1) # mean pooling over the sequence length as suggested
        return torch.sigmoid(self.classifier(pooled)).squeeze()

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In [5]: # wrap the features (X) and labels (y) into a DataLoader for batching
def _to_loader(X, y, batch_size: int, shuffle: bool = False):
    dataset = list(zip(X, y))
    return torch.utils.data.DataLoader(dataset, batch_size=batch_size, shuffle=shuffle)

# train the model for one epoch at a time
def train_one_epoch(model, loader, criterion, optim):
    model.train()
    running = 0.0

    for xb, yb in loader:
        optim.zero_grad()
        loss = criterion(model(xb), yb)
        loss.backward()
        optim.step()
        running += loss.item() * xb.size(0)

    return running / len(loader.dataset)

# Evaluate the model's accuracy
def evaluate(model, loader):
    model.eval()
    correct = 0

    with torch.no_grad():
        for xb, yb in loader:
            preds = (model(xb) >= 0.5).float()
            correct += (preds == yb).sum().item()
    return correct / len(loader.dataset)

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In [6]: device = "cuda" if torch.cuda.is_available() else "cpu"
%matplotlib inline
# manually perform the cross-validation using custom k-folds in the DataFrame
def cross_validate_manual(
    Syn_df: pd.DataFrame,
    feature_columns: List[str],
    epochs: int = 20,
    batch_size: int = 64,
    lr: float = 3e-4,
    weight_decay: float = 1e-3,
):
    results = [] # store best validation accuracy for each fold
    oof_true, oof_score = [], [] # collectors for out-of-fold predictions

    # Loop through each unique fold number
    for fold in sorted(Syn_df["Fold"].unique()):
        print(f"\n— Fold {fold + 1} / {Syn_df['Fold'].nunique()} —————")
        # split into both training and validation sets
        train_df = Syn_df[Syn_df["Fold"] != fold]

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validate_df = Syn_df[Syn_df["Fold"] == fold]

# normalize features here and then reshape for the model input
standard_scaler = StandardScaler()
X_train = standard_scaler.fit_transform(train_df[feature_columns]).reshape(
X_validate = standard_scaler.transform(validate_df[feature_columns]).reshape(

# convert to PyTorch tensors
y_train = train_df["Label"].values.astype(np.float32)
y_validate = validate_df["Label"].values.astype(np.float32)
X_train_ten = torch.tensor(X_train, dtype=torch.float32, device=device)
y_train_ten = torch.tensor(y_train, device=device)
X_val_ten = torch.tensor(X_validate, dtype=torch.float32, device=device)
y_val_ten = torch.tensor(y_validate, device=device)

# create the dataLoaders
train_loader = _to_loader(X_train_ten, y_train_ten, batch_size, shuffle=True)
val_loader = _to_loader(X_val_ten, y_val_ten, batch_size)

# initialize model, loss, and optimizer
transformer_model = TransformerClassifier().to(device) # move model to GPU
criterion = nn.BCELoss() # binary classification loss
optim = torch.optim.AdamW(transformer_model.parameters(), lr=lr, weight_dec

best_accuracy = 0.0
inaccurate_epochs = 0
patience = 5 # early stopping if no improvement for 'patience' epochs

# training loop
for epoch in range(1, epochs + 1):
    loss = train_one_epoch(transformer_model, train_loader, criterion, optim)
    val_acc = evaluate(transformer_model, val_loader)
    print(f"Epoch {epoch:02}/{epochs} - loss: {loss:.4f} - val acc: {val_acc:.4f}")

    # save the best model based on validation accuracy
    if val_acc > best_accuracy:
        best_accuracy, inaccurate_epochs = val_acc, 0
        best_state = transformer_model.state_dict()
    else:
        inaccurate_epochs += 1
        if inaccurate_epochs == patience:
            print("Early stopping")
            break

# get the model predictions for the validation set
transformer_model.eval()
with torch.no_grad():
    y_prob = transformer_model(X_val_ten).cpu().numpy().ravel()
oof_true.extend(y_validate.tolist())
oof_score.extend(y_prob.tolist())

# save the best accuracy for the fold
results.append(best_accuracy)

# save the best model checkpoint
Path("checkpoints").mkdir(exist_ok=True)

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torch.save(best_state, f"checkpoints/fold_{fold}.pt")
print(f"Best acc fold {fold + 1}: {best_accuracy:.4f}")

# summary of the final results
print("\n==== Validation Accuracy Summary =====")
for i, acc in enumerate(results, 1):
    print(f"Fold {i}: {acc:.4f}")
print(f"Mean Accuracy: {np.mean(results):.4f}")
print(f"Standard Deviation: {np.std(results):.4f}")
y_bin = (np.array(oof_score) > 0.5).astype(int)

cm = confusion_matrix(oof_true, y_bin)
ConfusionMatrixDisplay(confusion_matrix=cm).plot(cmap='Blues')
plt.title('Transformer Confusion Matrix')
plt.show()

fpr, tpr, _ = roc_curve(oof_true, oof_score)
RocCurveDisplay(fpr=fpr, tpr=tpr, roc_auc=auc(fpr, tpr)).plot()
plt.title('Transformer ROC')
plt.show()

prec, rec, _ = precision_recall_curve(oof_true, oof_score)
PrecisionRecallDisplay(precision=prec, recall=rec).plot()
plt.title('Transformer PR')
plt.show()

return results

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In [ ]: import psutil, os, time, numpy as np, pandas as pd
process = psutil.Process(os.getpid())

# resource monitoring start point
overall_start_time = time.time()
overall_start_ram = process.memory_info().rss / 1024 / 1024 # in MB
overall_start_cpu = psutil.cpu_percent(interval=1)

# Load dataset
Syn_df = pd.read_csv("D:\\Coding Projects\\Detection-of-SYN-Flood-Attacks-Using-Mac")
feature_columns = Syn_df.columns.difference(["Label", "Fold"]).tolist()[:12]

# run cross-validation on Transformer
results = cross_validate_manual(Syn_df, feature_columns)

# end resource monitoring
overall_end_time = time.time()
overall_end_ram = process.memory_info().rss / 1024 / 1024 # in MB
overall_end_cpu = psutil.cpu_percent(interval=1)

# summary of training stats
print("\n Overall Training Stats ")
print(f"Total Training Time: {overall_end_time - overall_start_time:.2f} seconds")
print(f"Total RAM Usage Increase: {overall_end_ram - overall_start_ram:.2f} MB")
print(f"CPU Usage (at final check): {overall_end_cpu}%")

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print("Per-fold accuracies      :", [f"{x:.4f}" for x in results])
print(f"Mean Accuracy          : {np.mean(results):.4f}")
print(f"Std-Dev                 : {np.std(results):.4f}")

# save the notebook as a web PDF
os.getcwd()
!jupyter nbconvert --to webpdf "d:\\Coding Projects\\Detection-of-SYN-Flood-Attacks"
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— Fold 1 / 5 —————