

# Analysis of CVAE Implementation

## Coulomb Explosion Atomic Reconstruction

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November 11, 2024

- **Input Features** (Position Coordinates):

- Carbon (cx, cy, cz)
- Oxygen (ox, oy, oz)
- Sulfur (sx, sy, sz)

- **Target Features** (Momenta):

- Carbon (pcx, pcy, pcz)
- Oxygen (pox, poy, poz)
- Sulfur (psx, psy, psz)

- **Goal:** Solving inverse problem

## Data Split

- Training: 70% (Primary training)
- Validation: 15% (Checking overfitting)
- Test: 15% (Final evaluation)

## Normalization

- Position: StandardScaler
- It has inverse function
- Momenta: None!

- **Encoder Network:**

- Input dimension: 9
- Hidden layers: [256, 512, 1024]
- Output:  $\mu$  and  $\log \sigma$  vectors (1024 each)

- **Latent Space:**

- Dimension: 1024
- Reparameterization trick
- Gaussian prior ( $N(0,1)$ )

- **Decoder Network:**

- Input: Concatenated [z, condition]
- Hidden layers: [512, 256]
- Output dimension: 9

# Detailed Layer Configuration

- **Layer Sizes:**

Input  $\rightarrow 9$

Encoder<sub>1</sub>  $\rightarrow 256$

Encoder<sub>2</sub>  $\rightarrow 512$

Encoder<sub>3</sub>  $\rightarrow 1024$

Latent  $\rightarrow 1024$

Decoder<sub>1</sub>  $\rightarrow 512$

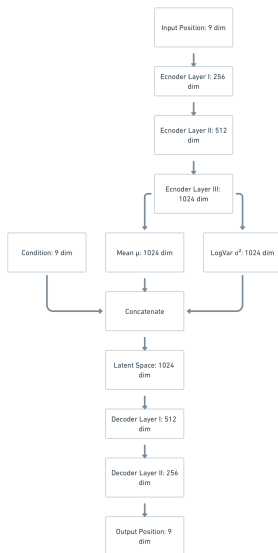
Decoder<sub>2</sub>  $\rightarrow 256$

Output  $\rightarrow 9$

- **Activation:** Sigmoid

- **Parameter Sharing:** None between encoder and decoder

# Model Architecture



## Basic Parameters

- Epochs: 200
- Batch Size: 256
- Learning Rate:  $1 \cdot 10^{-4}$
- Encoders Layer Size: [256, 512, 1024]
- Decoders Layer Size: [512, 256]
- Number of Hidden Layers: 3

## Advanced Parameters

- Latent Dimension: 1024
- Early Stopping Patience: 100
- Minimum Delta:  $1 \cdot 10^{-5}$
- L1 Lambda: *False*
- L2 Lambda:  $1 \cdot 10^{-2}$
- Gradient Clip: 5.0

# Loss Function Components

$$\mathcal{L}_{\text{total}} = \mathcal{L}_{\text{recon}} + \mathcal{L}_{\text{KL}} + \lambda \mathcal{L}_{\text{L1}}$$

$$\mathcal{L}_{\text{recon}} = \text{MSE}(x_{\text{recon}}, x)$$

$$\mathcal{L}_{\text{KL}} = -\frac{1}{2N} \sum (1 + \log \sigma^2 - \mu^2 - \sigma^2)$$

$$\mathcal{L}_{\text{L1}} = \sum |\theta|$$

where:

- $x_{\text{recon}}$  is the reconstructed output
- $\mu, \sigma$  are latent space parameters
- $\theta$  represents model parameters
- $\lambda = 1.41 \cdot 10^{-4}$  (L1 regularization strength)



# L2 Regularization Deep Dive

**Mathematical Formulation:**  $L_{\text{reg}}(\theta) = L(\theta) + \lambda \sum_{i=1}^n \theta_i^2$

- **Properties:**

- Creates circular/spherical constraint region
- Assumes Gaussian prior on weights
- Differentiable everywhere

- **Mathematical Characteristics:**

- Gradient proportional to parameter value
- Strictly convex optimization
- Handles multicollinearity effectively

- **Effects:**

- Shrinks weights proportionally
- Distributes importance across correlated features
- Produces unique solutions

# Additional Regularization Techniques

- **Early Stopping:**

- Monitors validation loss
- Patience: 100 epochs
- Minimum improvement:  $1 \cdot 10^{-5}$

- **Gradient Clipping:**

- Maximum norm: 5.0
- Prevents exploding gradients
- Stabilizes training

- **Data Normalization:**

- StandardScaler for Positions
- No Normalization for Momanta
- Prevents scaling issues
- Consider inverting to original scale for Evaluation

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## Algorithm CVAE Training Process

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```
1: for epoch in range(EPOCHS) do
2:   for batch in train_loader do
3:      $x, \text{condition} \leftarrow \text{batch}$ 
4:      $\mu, \log \sigma \leftarrow \text{encoder}(x)$ 
5:      $z \leftarrow \mu + \epsilon * \exp(0.5 * \log \sigma)$ 
6:      $x_{\text{recon}} \leftarrow \text{decoder}(z, \text{condition})$ 
7:     Compute loss  $\mathcal{L}_{\text{total}}$ 
8:     Backward pass and update weights
9:     Clip gradients at 5.0
10:  end for
11:  Validate and check early stopping
12: end for
```

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- **Loss Tracking:**

- Training loss per epoch
- Validation loss per epoch
- Individual loss components

- **Model Checkpointing:**

- Save best model state
- Based on validation loss
- Restore for testing

- **Early Stopping Logic:**

- Monitor validation loss
- Reset counter on improvement
- Stop when patience exceeded

- **Mean Relative Error (MRE):**

$$\text{MRE} = \frac{1}{n} \sum_{i=1}^n \frac{|y_{\text{pred},i} - y_{\text{true},i}|}{|y_{\text{true},i}| + \epsilon}$$

- **Latent Space Statistics:**

- Best Test MRE: 48%

Dataset	MRE	MSE
Training	0.553	5.128
Validation	0.489	5.152
Test	0.486	5.263

**Table:** Model Performance Metrics

MRE: Mean Relative Error, MSE: Mean Squared Error

# Learning Curve Plot

