Reinforcement Learning for Addition via Recursion

Mathematical Reasoning Project

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Abstract

This report presents an implementation of a Reinforcement Learning (RL) agent designed to learn and execute the recursive definition of addition. The agent learns to transform expressions like a+b into (a+(b-1))+1 recursively until reaching the base case a+0=a. We demonstrate the agent's capability by solving the addition problem 5+8 and visualizing the solution path as a knowledge graph in Neo4j. This implementation showcases how RL can be applied to mathematical reasoning tasks.

1 Introduction

Addition is typically taught as a basic operation, but it can be formally defined using recursion:

$$a+b = \begin{cases} a & \text{if } b = 0 \text{ (Base Case)} \\ (a+(b-1))+1 & \text{if } b > 0 \text{ (Recursive Case)} \end{cases}$$
 (1)

This recursive definition provides a systematic way to reduce complex addition problems to simpler ones. Our implementation uses Reinforcement Learning to teach an agent to apply this recursive definition correctly.

2 Reinforcement Learning Components

2.1 Key RL Concepts

Reinforcement Learning is a machine learning paradigm where an agent learns to make decisions by interacting with an environment. The key components are:

- Agent: The decision-maker that learns from experience
- Environment: The world with which the agent interacts
- State: The current situation in the environment

- Action: A decision made by the agent
- Reward: Feedback signal indicating the quality of an action
- Policy: The agent's strategy for selecting actions
- Value Function: Estimation of future rewards from a state
- Q-Function: Estimation of future rewards from a state-action pair

2.2 Q-Learning Algorithm

Our implementation uses Q-learning, a model-free RL algorithm that learns the value of an action in a particular state. The Q-function is updated using:

$$Q(s,a) \leftarrow Q(s,a) + \alpha \cdot [r + \gamma \cdot \max_{a'} Q(s',a') - Q(s,a)]$$
 (2)

where:

- Q(s, a) is the value of taking action a in state s
- α is the learning rate
- r is the reward received
- γ is the discount factor for future rewards
- s' is the next state
- $\max_{a'} Q(s', a')$ is the maximum Q-value for the next state

3 Implementation Components

3.1 Environment

The environment (AdditionRecursionEnv) represents the addition problem and tracks:

- Current mathematical expression state
- Target result
- Available actions
- Step count and termination conditions

3.2 State Representation

States are represented by the MathExpressionState class, which contains:

- The current mathematical expression (e.g., "5 + 8", "(5 + 7) + 1")
- Step count for tracking progress

3.3 Actions

The agent can perform the following actions:

- decompose: Transform "a + b" to "(a + (b-1)) + 1"
- further_decompose: Further decompose a nested expression
- apply_base_case: Apply the rule (a + 0) = a
- increment: Perform an increment operation (e.g., (3 + 1) to 4)
- calculate: Calculate the final result
- finish: Conclude the calculation

3.4 Reward Structure

The reward structure guides the agent toward correct solutions:

- \bullet +1.0 for correct decomposition steps
- +1.0 for correctly applying the base case
- \bullet +1.0 for correct increment operations
- +5.0 for reaching the correct final result
- -1.0 for invalid actions
- -5.0 for finishing with an incorrect result

3.5 Agent

The QLearningAgent implements:

- Q-table for storing state-action values
- Epsilon-greedy policy for action selection
- Q-learning update rule
- Exploration rate decay
- Action history tracking

3.6 Knowledge Graph Builder

The KnowledgeGraphBuilder constructs a graph representation of the solution:

- Nodes represent mathematical expressions (states)
- Edges represent transformations (actions) between states
- The graph is exported as triplets for Neo4j storage

4 Training Process

The training process involves:

- 1. Initializing the environment with the problem "5 + 8"
- 2. Training the agent for a specified number of episodes
- 3. For each episode:
 - Reset the environment
 - Agent selects actions using epsilon-greedy policy
 - Environment provides rewards and next states
 - Agent updates Q-values using the Q-learning update rule
- 4. Tracking the best solution found during training
- 5. Building a knowledge graph from the best solution
- 6. Storing the graph in Neo4j

5 Example: Solving 5 + 8

For the addition problem 5 + 8, the ideal solution path is:

6 Knowledge Graph Representation

The solution is represented as a knowledge graph in Neo4j:

- Nodes: Mathematical expressions at each step
- Edges: Actions taken to transform expressions
- Properties: Step information, action types, and rewards

This graph provides a visual representation of the reasoning process, showing how the agent decomposes the problem and builds up to the solution.

7 Conclusion

This implementation demonstrates how Reinforcement Learning can be applied to mathematical reasoning tasks. The agent successfully learns to apply the recursive definition of addition and solve problems like 5+8. The knowledge graph representation provides insight into the reasoning process and can be used for educational purposes.

Future work could include:

- Extending the approach to other mathematical operations (subtraction, multiplication)
- Implementing more complex mathematical reasoning tasks
- Improving the agent's learning efficiency
- Developing a user interface for interactive exploration of the solution paths