High-level concurrency concepts



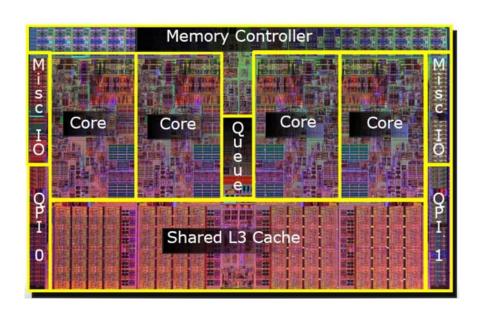
Václav Pech *NPRG014 2022/2023*



http://www.vaclavpech.eu @vaclav_pech

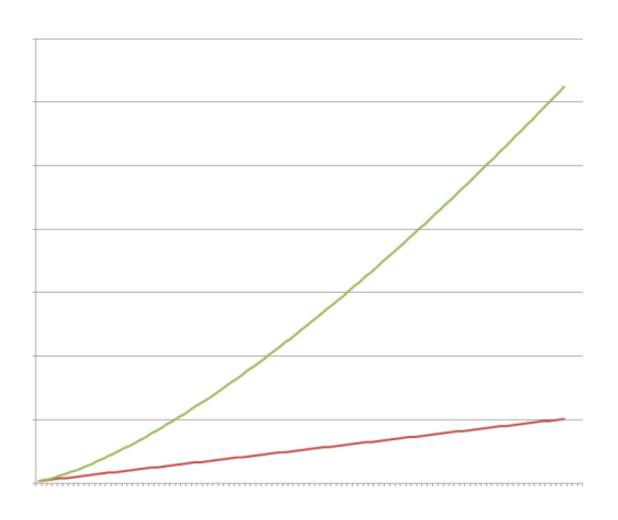
Why concurrency?





We're all in the parallel computing business!

of cores



JVM low-level machinery

Thread, Runnable, Thread Pools, Virtual Threads

- to run things in parallel

JVM low-level machinery

Thread, Runnable, Thread Pools, Virtual Threads

- to run things in parallel

Synchronized blocks

Volatile

Locks

Atomic

- to run things sequentially again

Threads

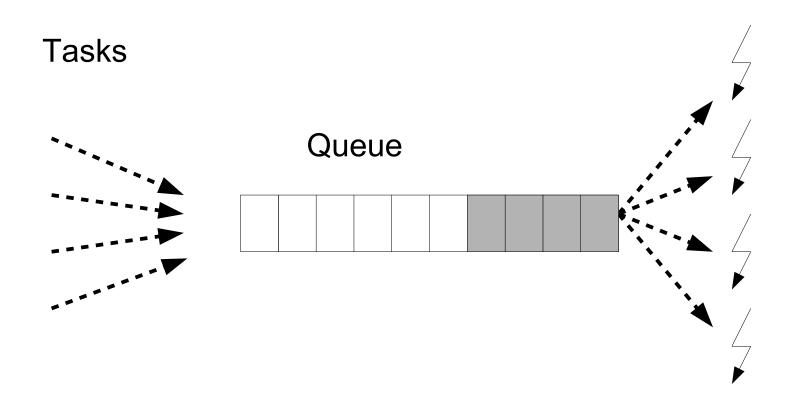
```
def myRunnable = new Runnable {
  public void run() {
new Thread(myRunnable).start()
```

Thread Pool

```
def pool = Executors.newFixedThreadPool(6)
def myCallable = new Callable<T> {
    public T call() {...}
}
```

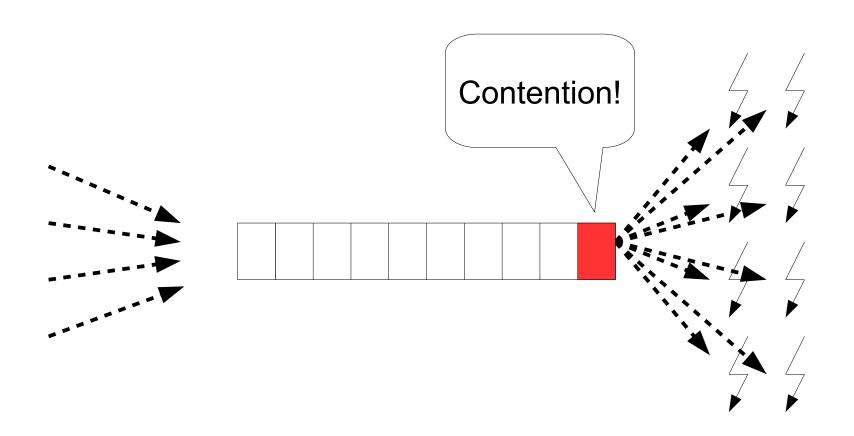
```
Future<T> f = pool.submit(myCallable)
println f.get()
```

Thread Pool

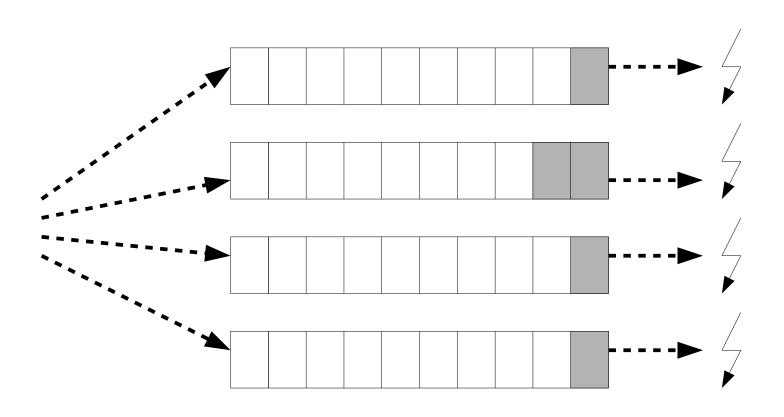


Worker threads

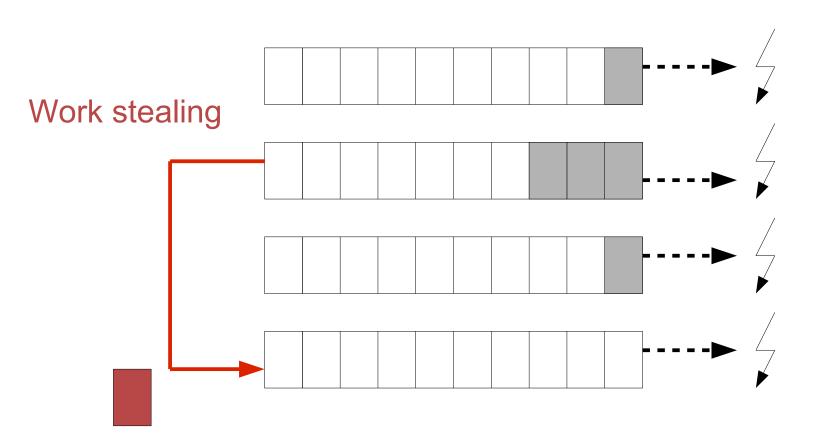
Thread Pool



Fork/Join Thread Pool



Fork/Join Thread Pool



Virtual Threads (Java 19)

def t = Thread.ofVirtual.start(myRunnable)
println f.join()

Virtual Threads (Java 19)

def t = Thread.ofVirtual.start(myRunnable)
println f.join()

def pool = Executors
.newVirtualThreadPerTaskExecutor()

Future<T> f = pool.submit(myCallable) println f.get()

Scopes (Java 19)

```
try (StructuredTaskScope<String> group = new StructuredTaskScope<>()) {
   Future<String> f = group.fork(Demo::calculate);
   group.joinUntil(Instant.now().plusMillis( millisToAdd: 1_000));
   System.out.println(f.resultNow());
}
```

```
Thread vt = Thread.ofVirtual().start(new Runnable() {
```

Scope

Provides virtual threads with:

- a thread pool
- a context
- life-cycle management
- control for sub-groups
- error handling for tasks and sub-groups

Async the Groovy way

```
task {
    calculation.process()
}
```



Async the Groovy way

```
def group = new NonDaemonPGroup(10)
```

```
group.task {
    calculation.process()
}
```



Async the Groovy way

```
group.task {->...}
```

group.task new Runnable() {...}

group.task new Callable<V>() {...}



```
public class Counter {
  private static long count = 0;
  public Counter() {
       count++;
```

```
public class Counter {
  private volatile static long count = 0;
  public Counter() {
       count++;
```

```
public class Counter {
  private volatile static long count = 0;
  public Counter() {
       count = count + 1;
```

```
public class Counter {
  private static long count = 0;
  public Counter() {
    synchronized (this) {
       count++;
```

```
public class Counter {
  private static long count = 0;
  public Counter() {
    synchronized (this.getClass()) {
       count++;
```

```
public class Counter {
  private static Long count = 0;
  public Counter() {
    synchronized (count) {
       count++;
```

```
public class Counter {
  private static Long count = 0;
  public Counter() {
    synchronized (count) {
       count = new Long(count.longValue() + 1);
```

```
public class ClickCounter implements ActionListener {
  private int numberOfClicks;
  public ClickCounter(JButton button, int initValue) {
    button.addActionListener(this);
    numberOfClicks = initValue;
  public void actionPerformed(final ActionEvent e) {
    numberOfClicks++;
```

```
public class ClickCounter implements ActionListener {
  private int numberOfClicks;
  public ClickCounter(JButton button, int initValue) {
    button.addActionListener(this);
    numberOfClicks = initValue;
  public void actionPerformed(final ActionEvent e) {
    numberOfClicks++;
```

Stone age of parallel SW

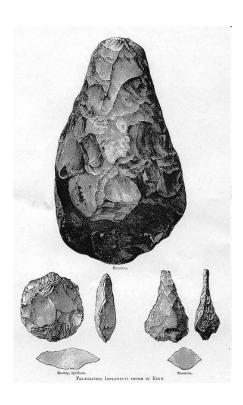
Dead-locks

Live-locks

Race conditions

Starvation

Shared Mutable State



Low-level concurrency

- Monitors
- Locks R/W, ReentrantLock
- Semaphors
- CountDownLatches
- Barriers

Why high-level concurrency?

Multithreaded programs today work mostly by accident!



The root problem

Shared mutable state

Approach 1

Shared mutable state

Use read-only data

Approach 2

Shared mutable state

Use only local encapsulated data

High-level abstractions

- STM
- Hierarchical decomposition
- Geometrical decomposition
- Streams
- Agents, Actors, Active objects
- Communicating Sequential Processes

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Control State Sharing

```
List registrations = □
submissions.each {form →
  group.task {
     if (form.process().valid) {
       registrations << form
```

Control State Sharing

Needs protection

```
List registrations = []
submissions.each {form →
  group.task {
     if (form.process().valid) {
       registrations << form
```

STM (Akka - Scala)

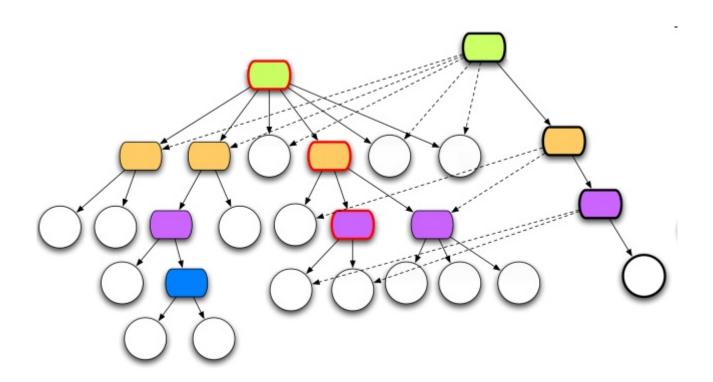
```
atomic {
    .. // do something within a transaction
}

atomic(maxNrOfRetries) { .. }

atomicReadOnly { .. }

atomically {
    .. // try to do something
} orElse {
    .. // if tx clash; try do do something else
}
```

Persistent Data Structures

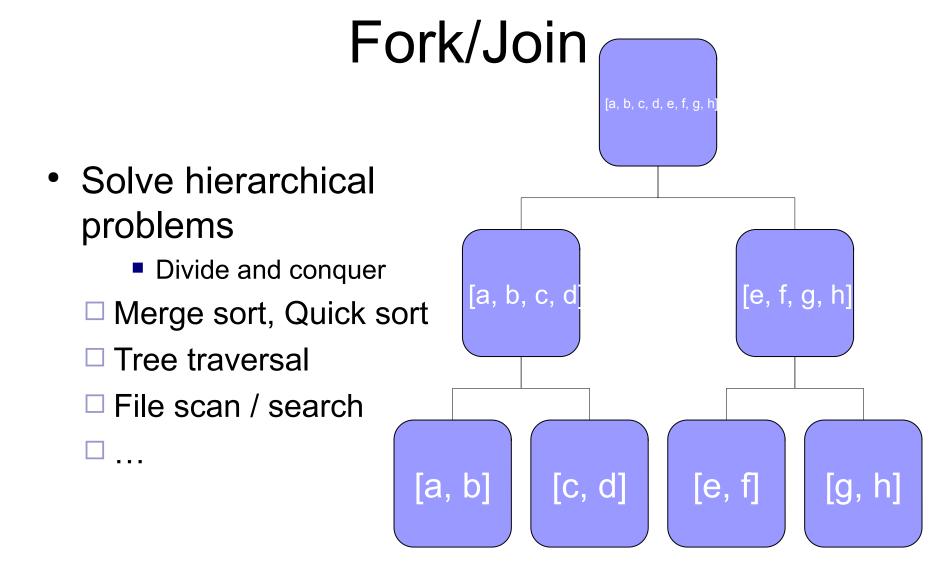


High-level abstractions

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Hierarchical decomposition

[64, 63, 62, 61, 60, 59, 58, 57, 56, 55, 54, 53, 52, 51, 50, 49, 48, 47, 46, 45, 44, 43, 42, 41, 40, 39, 38, 37, 36, 35, 34, 33]							[32, 31, 30, 29, 28, 27, 26, 25, 24, 23, 22, 21, 20, 19, 18
[64, 63, 62, 61, 60, 59, 58, 57, 56, 55, 54, 53, 52, 51, 50, 49]			[48, 47, 46, 45, 44, 43, 42, 41, 40, 39, 38, 37, 36, 35, 34, 33]				[32, 31, 30, 29, 28, 27, 26, 25, 24, 23, 22, 21, 20, 19, 18
64, 63, 62, 61, 60, 59, 58, 57]	[56, 55, 54, 53, 52, 51, 50, 49]		[48, 47, 46, 45, 44, 43, 42, 41]	[40, 39, 38, 37, 36,	35, 34, 33]		
	[56, 55, 54, 53]	[49, 50, 51, 52]		[40, 39, 38, 37]	[33, 34, 35	, 36]	
	[56, 55]	[51, 52] [49, 50]		[40, 39]	[35, 36]	[33, 34]	
					,		



Fork/Join (GPars)

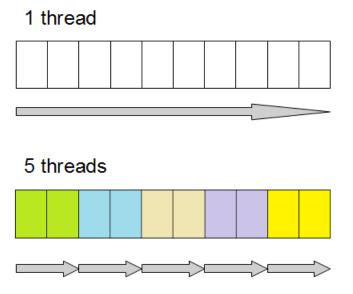
```
{currentDir ->
  long count = 0;
  currentDir.eachFile {
    if (it.isDirectory()) {
       forkOffChild it
    } else {
       count++
    }
  }
  return count + childrenResults.sum(0)
}
Waits for children without blocking the thread!
```

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Geometric decomposition

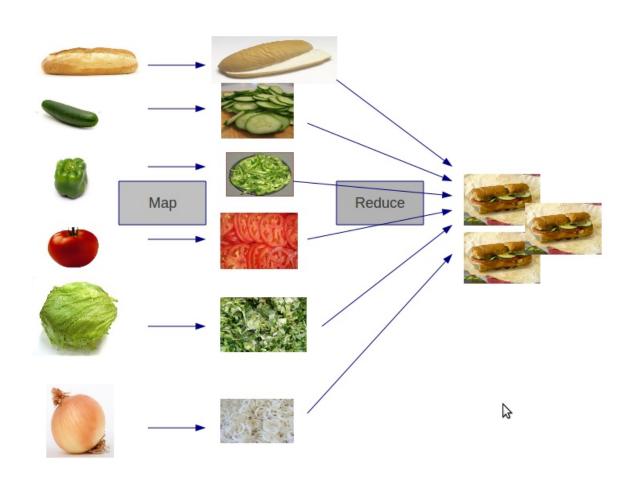
images.eachParallel {it.process()}
documents.sumParallel()
candidates.maxParallel {it.salary}.marry()



Geometric decomposition

```
registrations = submissions
        .collectParallel { form -> form.process()}
        .findAllParallel { it.valid }
registrations = submissions.parallel
        .map { form -> form.process()}
        .filter { it.valid }.collection
```

Map - reduce



Frequent confusion





Tags

Users

Badges

Unanswered

parallel quick sort outdone by single threaded quicksort



I've been reading, here is the example in the book using futures to implement parallel quick sort.



But I found this function is more than twice slower than the single threaded quick sort function without using any asynchronous facilities in c++ standard library. Tested with g++ 4.8 and visual c++ 2012.



I used 10M random integers to test, and in visual c++ 2012, this function spawned 6 threads in total to perform the operation in my quad core PC.

I am really confused about the performance. Any body can tell me why?

GPU





Improper use 1

```
def accumulator = 0
myCollection.eachParallel {
   accumulator += calculate(it)
}
```

Do not accumulate, map-reduce!

```
def accumulator = myCollection.parallel .map \ \{calculate(it)\} .reduce \ \{a,\ b \rightarrow a+b\}
```

Improper use 2

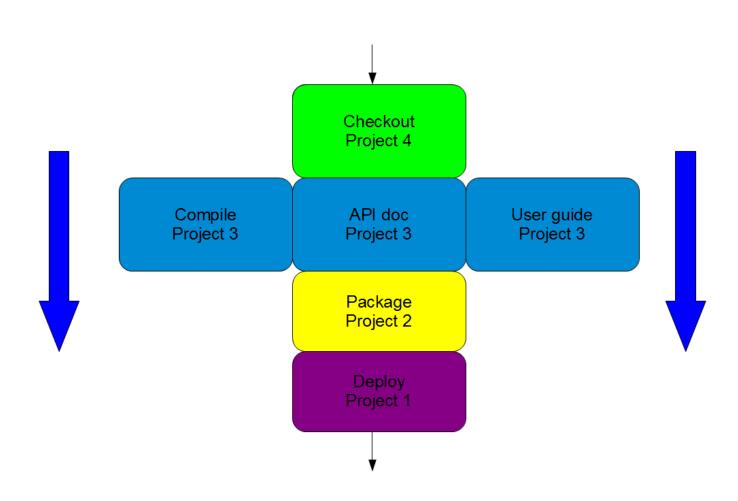
```
new File("/file.txt").withReader{reader ->
  reader.eachParallel {
    def r1 = step1(r)
    def r2 = step2(r1)
    def r3 = step3(r2)
  }
}
```

Unroll iterations into streams

```
def pipeline = data | step1 | step2 | step3

new File("/file.txt").withReader{reader ->
    reader.each {
        data << it
    }
}</pre>
```

Unroll iteration



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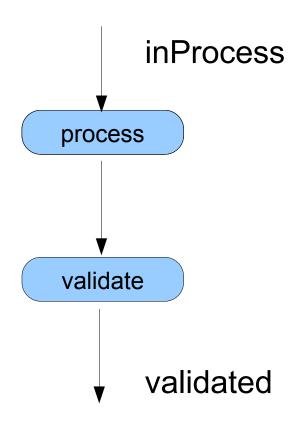
Pipeline DSL

```
def toProcess = new DataflowQueue()

def validated = new DataflowQueue()

toProcess | {form -> process(form)} |
    {processedForm -> validate(processedForm)} | validated
```

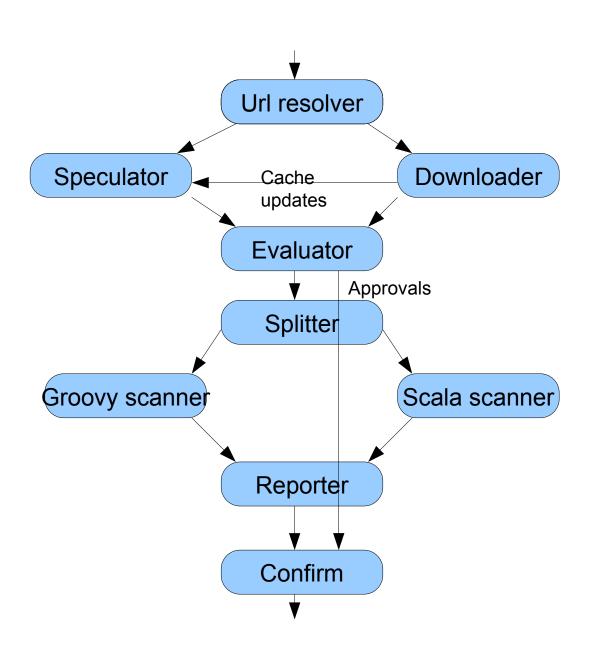
submissions.each {toProcess << it}



Generalization

An operation can take multiple inputs and outputs

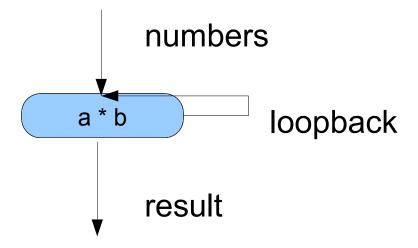
Operations adressed indirectly using channels

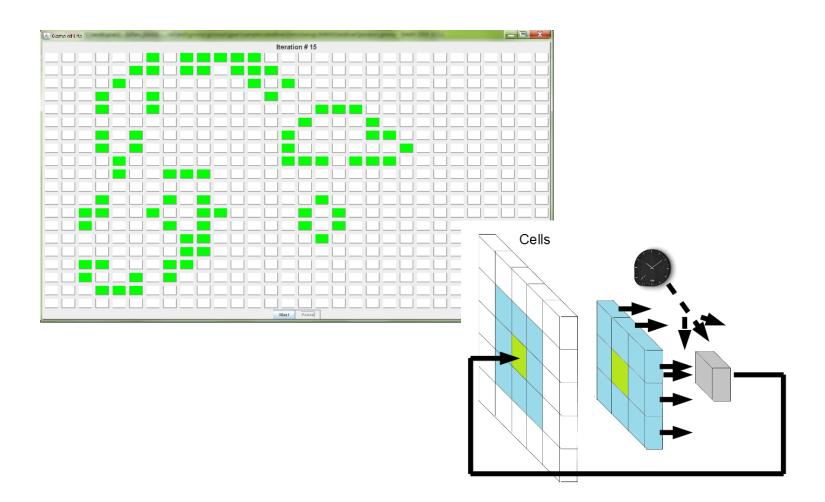


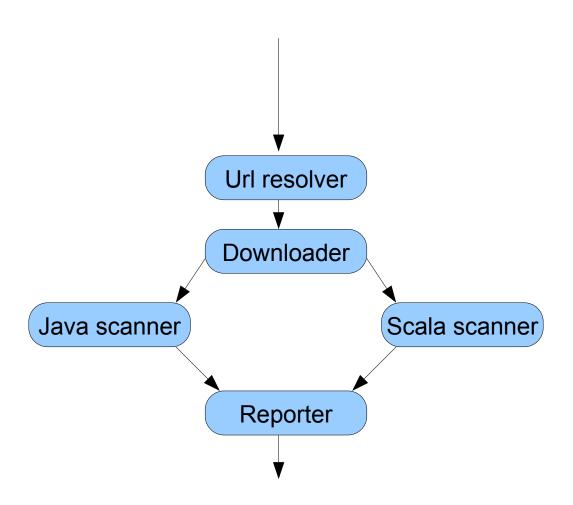
Dataflow Operators

```
operator(inputs: [headers, bodies, footers],
         outputs: [articles, summaries])
  {header, body, footer ->
     def article = buildArticle(header, body, footer)
     bindOutput(0, article)
     bindOutput(1, buildSummary(article))
```

Factorial





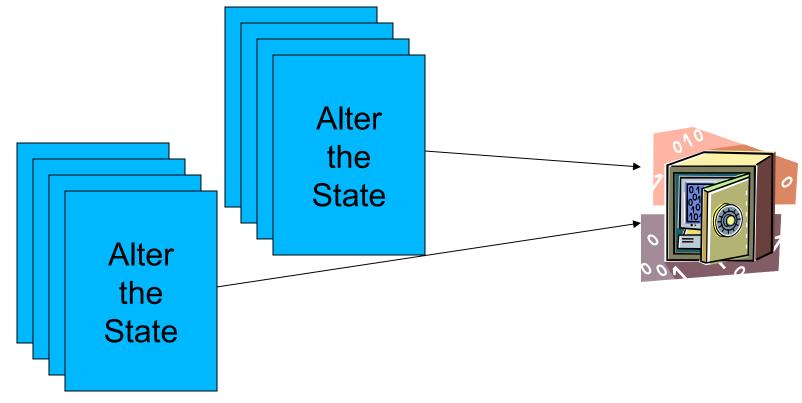


High-level abstractions

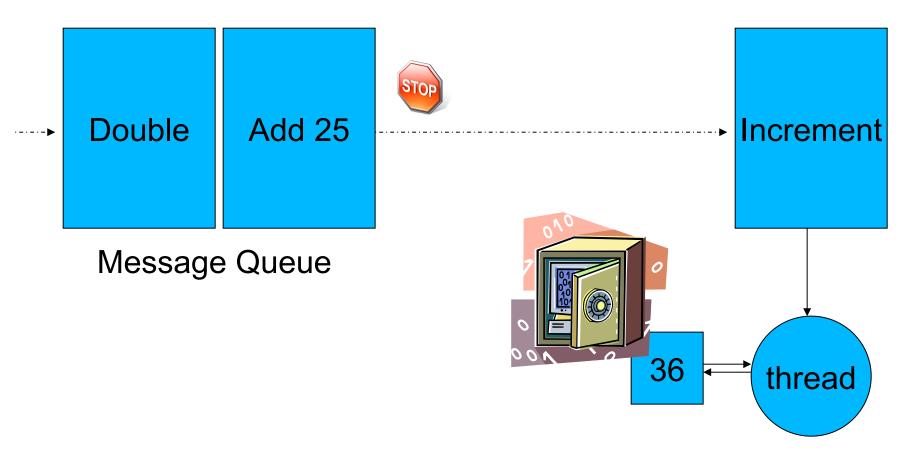
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Agent

Lock Shared Mutable State in a Safe



Agent inside



Sharing through agents

```
Agent registrations = new Agent([])
submissions.each {form →
  task {
     if (form.process().valid) {
       registrations.send {it << form}
```

Actors

Agents send commands

Actors send data

Both use direct addressing (no channels)

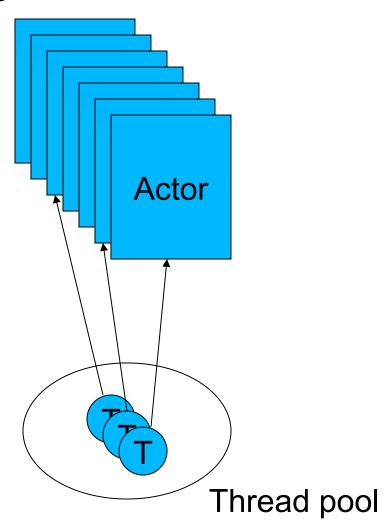
Actors

Isolated state
Active - shared threads
Async Communication

- Direct addressing
- Immutable messages

Activities:

- Create a new actor
- Send a message
- Receive a message

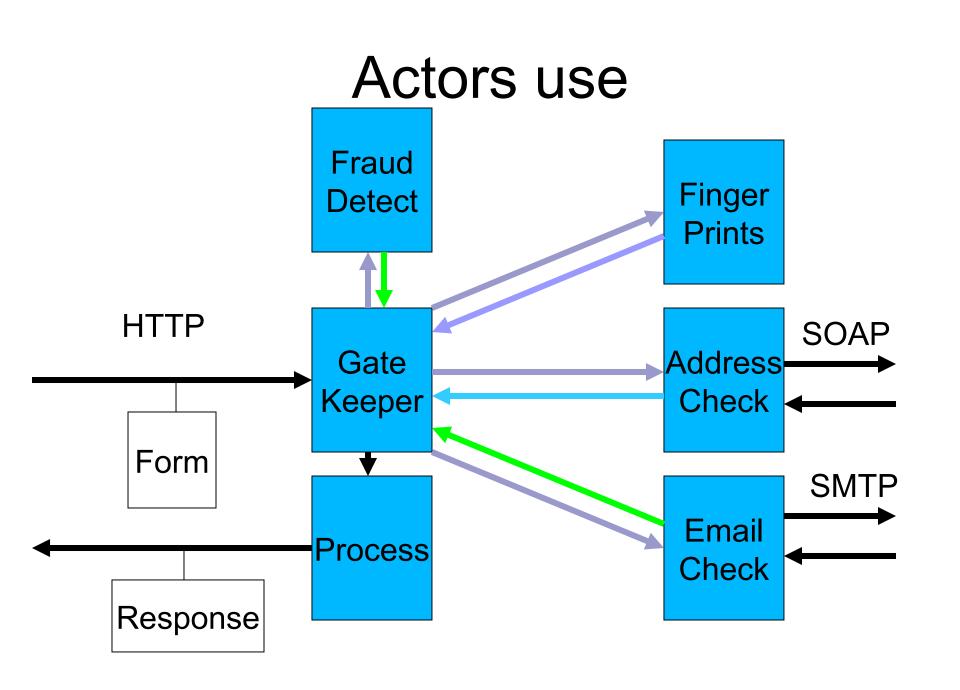


Actor definition

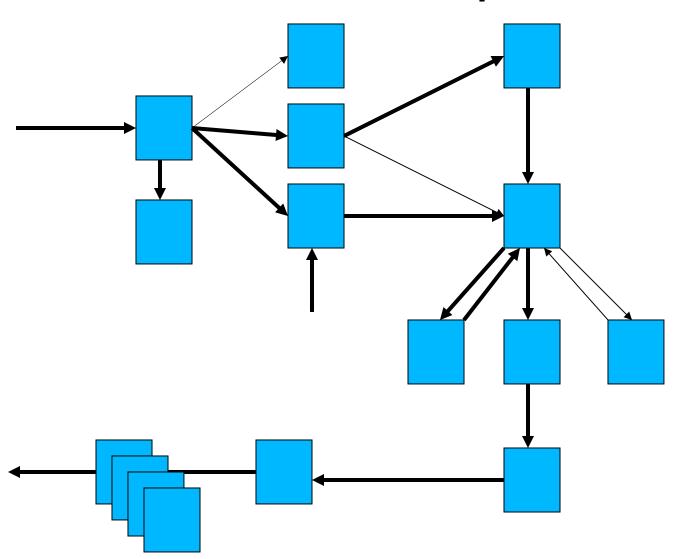
```
class MyActor extends DynamicDispatchActor {
  private int counter = 0
  public void onMessage(String msg) {
    this.counter += msg.size()
  public void onMessage(Integer number) {
    this.counter += number
  public void onMessage(Money cash) {
    this.counter += cash.amount
    reply 'Thank you'
```

Sending messages

```
buddy.send 10.eur
buddy << new Book(title:'Groovy Recipes',
                 author: 'Scott Davis')
def canChat = buddy.sendAndWait 'Got time?'
buddy.sendAndContinue 'Need money!', {cash->
  pocket.add cash
```



Actors patterns



Enricher

Router

Translator

Endpoint

Splitter

Agregator

Filter

Resequencer

Checker

Active objects

```
@ActiveObject
class MyCounter {
  private int counter = 0
@ActiveMethod
  def incrementBy(int value) {
    println "Received an integer: $value"
    this.counter += value
```

High-level abstractions

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CSP

Communicating Sequential Processes

Focus on composable processes more than on data

Abstractions

Tasks (aka coroutines, goroutines)

 Implemented as (pooled) threads or virtual, lighweight threads

Data exchange between tasks

- Tasks' return value
- Dataflow variables
- Dataflow channels

Tasks

```
requests.each {r ->
    task {
       r.handle()
       println "Done processing " + r.id
    }
}
```

Data exchange

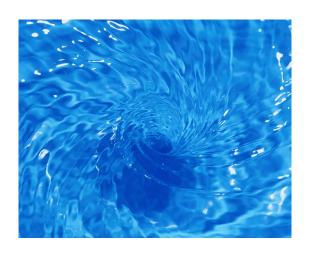
```
task { println "Hello" }
Promise t1 = task {
  def data = loadDataFromDB("Joe")
  data.optimize()
  return data
Promise t2 = task { printData(t1.get()) }
t2.join()
```

Dataflow Variables

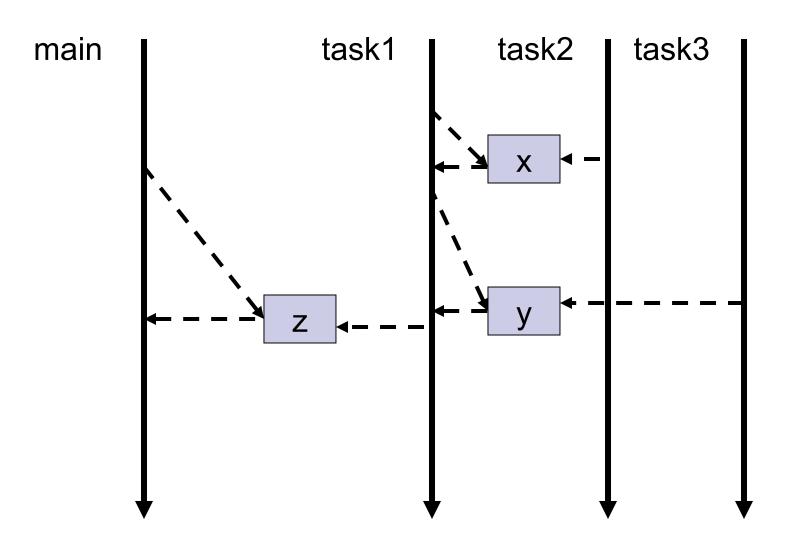
No race-conditions

No live-locks

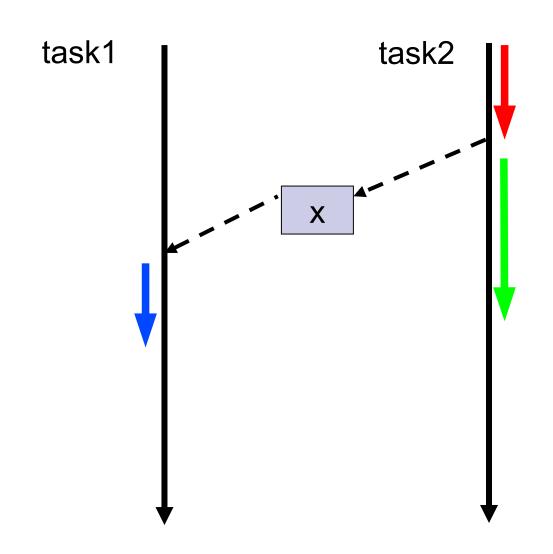
Deterministic deadlocks



Dataflow Variables / Promises



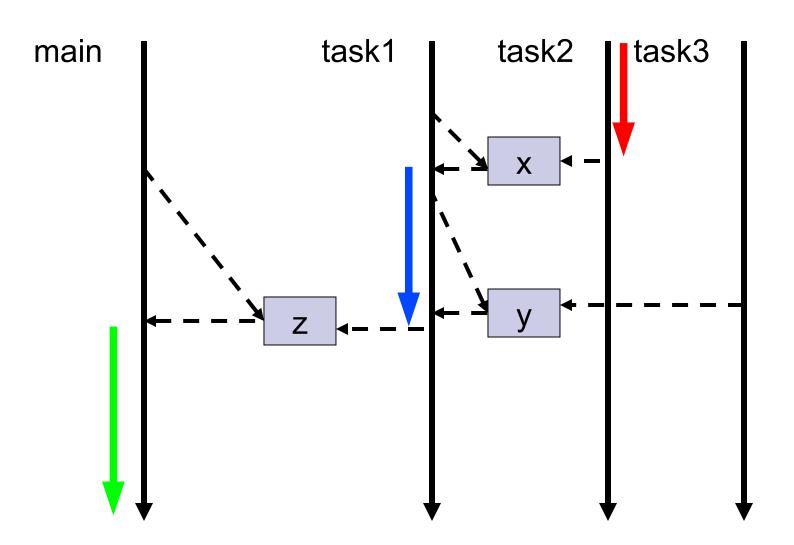
Dataflow Variables / Promises



DataflowVariables/Promises

```
def x = new DataflowVariable()
task { println x.get() }
task {
  storeInDB(x.get())
task { x << 10 }
x.join()
```

Dataflow Variables / Promises



Promises to exchange data

```
def x,y,z = new DataflowVariable()
task { z << x.get() + y.get() }
task { x << 10 }
task {
  println "I am task 3"
  y << 5
assert 15 == z.get()
```

Promises as return values

```
Promise x = task { return 10 }
Promise y = task {
  println "I am task 3"
  return 5
Promise z = task {x.get() + y.get() }
assert 15 == z.get()
```

Kotlin coroutines

```
val time = measureTimeMillis {
   val one = async { doSomethingUsefulOne() }
   val two = async { doSomethingUsefulTwo() }
   println("The answer is ${one.await() + two.await()}")
}
println("Completed in $time ms")
```

Reactive approach

- Needed when tasks are implemented on top of system threads (unlike virtual/lightweight threads)
- Blocking in Promise.get() is too expensive

Reactive allows for callbacks to be registered on Promises

Callbacks

```
def x = new DataflowVariable()
x.then { println it }
task {
  x.then { storeInDB(it) }
    .then {dbStatus → println dbStatus}
task { x << 10 }
x.join()
```

Chaining promises

def h1 = download('url') then {text → text.trim()} then hash

Chaining promises

def h1 = download('url') then {text → text.trim()} then hash

def h1 = download('url') | {text → text.trim()} | hash

Error handling

```
url.then(download)
   .then(calculateHash)
   .then(formatResult)
   .then(printResult, printError)
   .then(sendNotificationEmail);
```

CompletableFuture (Java)

```
Promise c1 = task {compile(module1)}
```

Promise c2 = task {compile(module2)}

```
Promise c1 = task {compile(module1)}
Promise c2 = task {compile(module2)}
```

```
Promise j1 = c1.then {jar it}
Promise j2 = c2.then {jar it}
```

```
Promise c1 = task {compile(module1)}
Promise c2 = task {compile(module2)}
Promise i1 = c1.then {jar it}
Promise j2 = c2.then {jar it}
when All Bound (j1, j2) \{m1, m2 \rightarrow deploy(m1, m2)\}
i1.then {pushToRepo it}
```

```
Promise c1 = task { compile(module1) }
Promise c2 = task { compile(module2) }
Promise i1 = c1.then {iar it}
Promise j2 = c2.then {jar it}
when All Bound (j1, j2) \{m1, m2 \rightarrow deploy(m1, m2)\}
i1.then {pushToRepo it}
iWillSendEmailWhenJarred(j1)
```

Glue tasks without callbacks

```
Promise c1 = task { compile(module1) }
Promise c2 = task { compile(module2) }
Promise i1 = task { jar c1.get() }
Promise j2 = task { jar c2.get() }
task { deploy(j1.get(), j2.get()) }
task {pushToRepo j1.get()}
iWillSendEmailWhenJarred(j1.get())
```

Dataflow variables wrap-up

- Promise is the reading side
- Blocking read val, get(), await()
- Callbacks then, |, whenAllBound
- Callback handlers can be chained
- Promises are typically returned from async calls – task, async

Abstractions

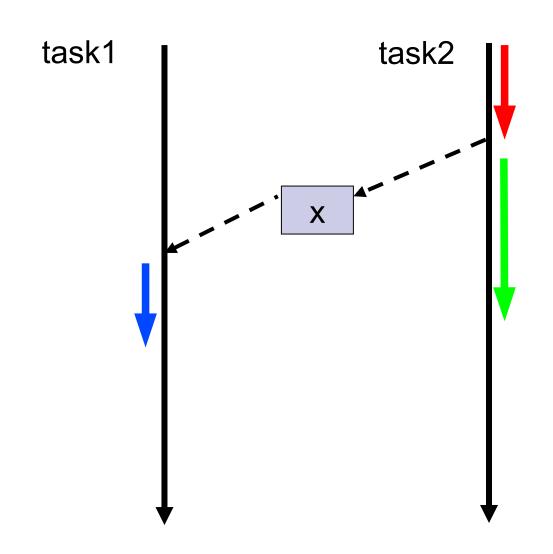
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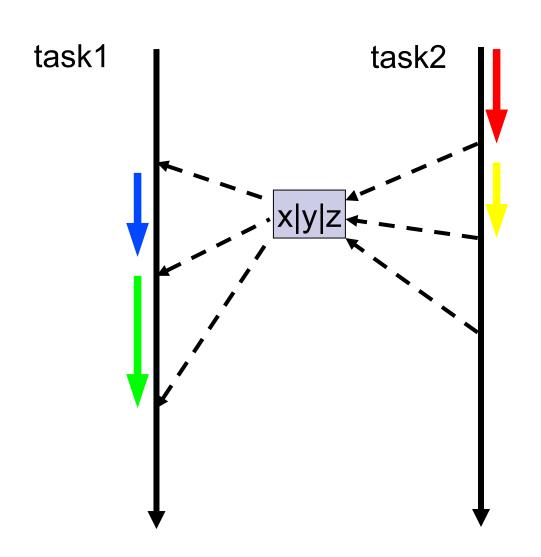
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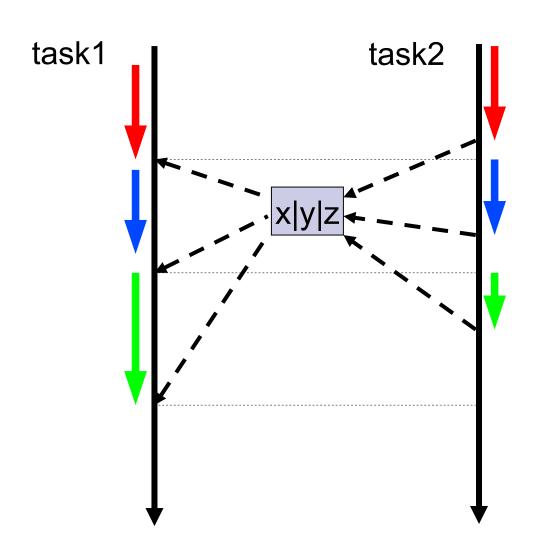
Dataflow Variables / Promises



Dataflow Channels



Synchronous Channels



Async progress indication

```
List<Promise> forms=submissions.collect {form →
  group.task {
     def result = form.process()
     progressQueue << 1
     if (result.valid) {
       return form
```

Async result reporting

```
submissions.each {form →
    group.task {
      if (form.process().valid) queue << form
    }
}</pre>
```

Channel Selection

```
Select alt = group.select(validForms, invalidForms)
SelectResult selectResult = alt.select() //alt.prioritySelect()
switch (selectResult.index) {
     case 0: registrations << selectResult.value; break</pre>
     case 1: ...
```

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Summary

Parallelism is not hard, multi-threading is

Jon Kerridge, Napier University

References

http://groovy-lang.org

http://grails.org

http://groovyconsole.appspot.com/

http://www.manning.com/koenig2/