TEAM 11

Computer Vision Section:

Features:

- Beautiful and clear GUI implementation
- Clear and easy to use home layout that shows video, open door, lock door, add, delete and reset password buttons
- Dropdown menu for deleting persons from database instead of text field which is more convenient
- Confirmation dislogs for: open door, lock door, delete and reset password which gives homeowner a chance to think desicion through
- Notifications for carried out/cancelled activities which is convenient and less confusing for homeowner
- Most activities carried out using keys in the terminal, this allows running to be a lot smoother

Design considerations:

- Adding a person is a very simple process of snapping a picture of unknown person and creating a file with the persons image under the name of the person provided by the homeowner. This makes deleting a person exceptionally easy as all that needs to be done is delete the file's path obtained by joing the database path and the person's name.
- GUI is implemented using Flet which makes it easier to turn the program into a mobile app

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Micro-controllers Section:

Features:

- Home Protection: When the house is **locked**, the PIR Sensor scans for motion and if detected, the ATmega sends a warning message to the Control Interface.
- Dynamic Lighting: When the light level of the surrounding is low, the Photoresistor detects the low light and the ATmega lights up an LED and vice versa.
- Dynamic Fan Speed/RGB Indicator: According to the following ranges of temperature picked up by the NTC Thermo Sensor, the RGB – Fan Speed are as follow:

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*T > 30°C : Red – 3500 RPM

* 30°C => T => 20°C: Green – [3000, 2000] RPM

* T < 20°C: Blue – Fan Off
```

- Entering/Exiting House: A person can enter the house by:
 - 1- Entering the correct password on a 4*4 keypad
 - 2- By scanning their face (if a person is in the database, the Control Interface sends an **open** command to the ATmega)
 - 3- Pressing **open** on the Control Interface.

A person can also **lock** the house via the Control Interface, turning off all the lighting and fan, and enabling the PIR Sensor to sends warning upon motion detection. The house/system is unlocked if the door is opened by any means of the 3.

 Door Password: A person can enter the house using a password and can change the password via the Control Interface. The password can have a length up to 31 characters. If a wrong password is entered, a Buzz is played and a warning message is sent to the Control Interface.

Libraries used:

• <Keypad.h>: For the keypad

Design considerations:

- If the door is opened, that means: the servo motor rotates up to a certain degree, waits for about 7 seconds and then closes.
- Added a "lock" feature, explained in the previous section.
- The fans always spin in 1 direction, therefore, the direction (in1 and in2) pins of the driver are connected directly to 5V and GND instead of the ATmega.

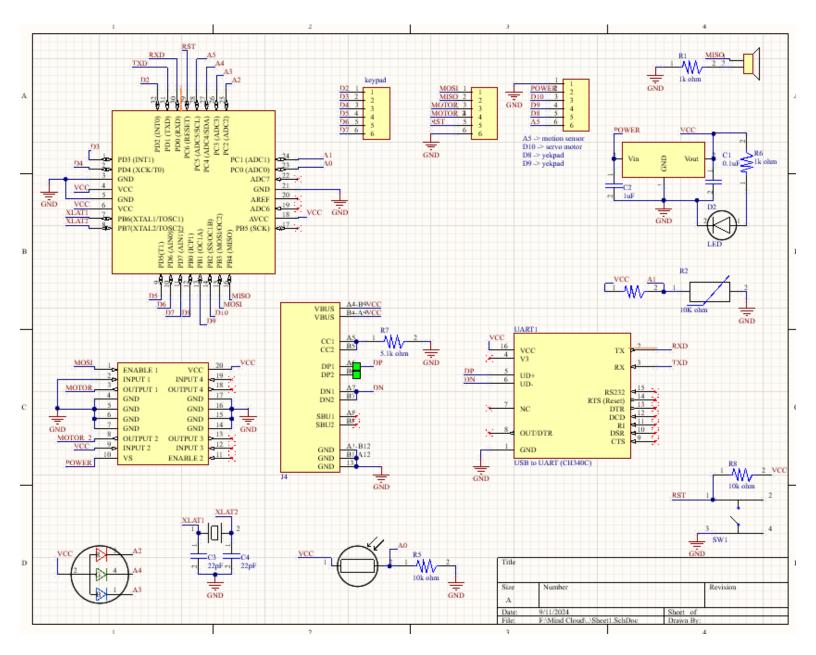
Other relevant information:

- The ATmega chip is programmed for the first time using an Arduino as ISP Programmer to burn the bootloader and/or upload the code.
- A USB to TTL (Serial) was used for the communication between the ATmega and the Control Interface (Computer), can also be used for uploading code after burning a bootloader first.

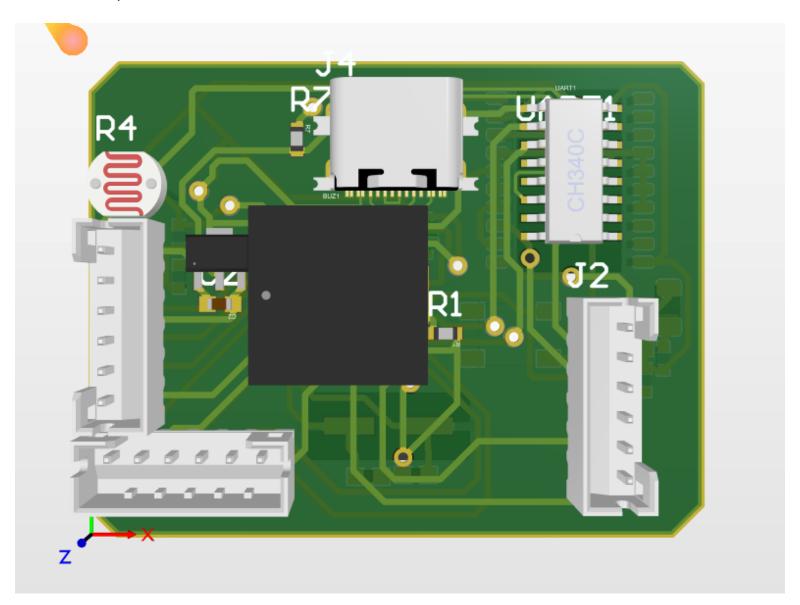
Hardware Section:

Altium:

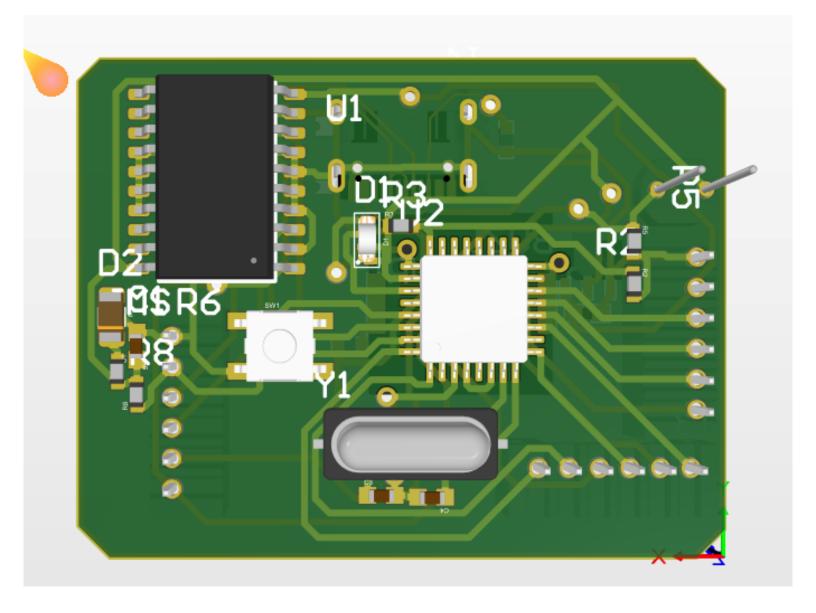
Schematic:



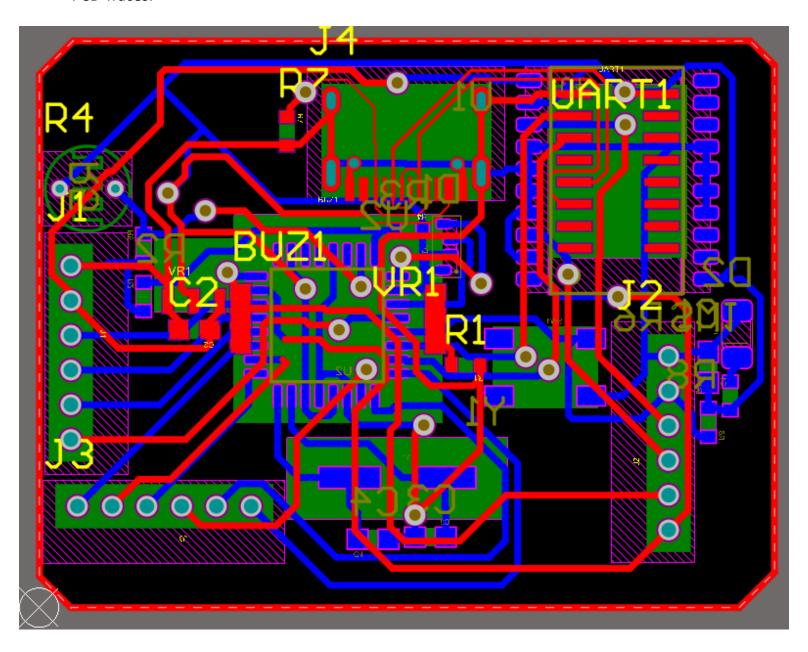
PCB-Top:



PCB-Bottom:



PCB-Traces:



Design considerations:

- The servo motor, the fans motor and the keypad are not included in the Altium design, instead, they have pin-headers to connect them to the board externally.
- There are 6 Pins needed to exist as pin-headers to be able to program the ATmega chip (Burn the bootloader). The 6 pins are (MOSI – MISO – SCK – VCC – GND – Reset).
- We're using a USB-to-UART chip and USB-C port for the communication of the ATmega and Computer.

Links:

<u>AmirKaseb/Mini-Smart-Home-System: This Repo demonstrates our journey (Team 11) for Mind Cloud Final Project (github.com)</u>

https://www.tinkercad.com/things/emIDLEaHkLq-mindcloud-megaproject-microcontroller-team-11