

# COMPUTER CONTROLLED PAN-TILT UNIT

## Models PTU-46-17.5 & PTU-46-70

- Simple control from host computer via RS-232/485
- Speeds to 300°/second
- Resolution to 0.012857°
- Load capacity to 6 lbs (2.72kg)
- Precise control of position, speed & acceleration
- On-the-fly position and speed changes
- Small form factor
- Low cost
- Applications:
  - Robotics & computer vision
  - Webcams
  - Security & surveillance
  - Industrial automation
  - Tracking
  - Laser ranging
  - Teleconferencing/distance learning
  - Photography, video & special effects



Actual size. Camera not included.

 *Directed Perception, Inc.*

1485 Rollins Road, Burlingame, California 94010

(650) 342-9399 • FAX: (650) 342-9199

Email: [info@DPerception.com](mailto:info@DPerception.com) • URL: <http://www.DPerception.com>

# COMPUTER CONTROLLED PAN-TILT UNIT

## Models PTU-46-17.5 & PTU-46-70

### Technical Specifications

#### General Features

- Simple to use from any RS-232 terminal or computer
- Fast and accurate camera positioning at low cost
- Precise control of position, speed & acceleration
- Small form factor
- Allows on-the-fly position and speed changes
- Self calibration upon reset
- Power consumption can be controlled from host
- ASCII command mode for simplicity, binary commands available for efficient program control
- DC power input from an unregulated source
- Radiation hardened
- CE Mark certified for Europe

#### Pan-Tilt Performance

	PTU-46-17.5	PTU-46-70
<b>Rated payload</b>	4 lbs (1.81kg)	6 lbs (2.72kg)
<b>Max. unloaded speed (@36VDC)</b>	300°/second	60°/second
<b>Resolution</b>	3.086 arc minutes (0.051428°)	0.771 arc minutes (0.012857°)

**Acceleration/Deceleration:** Trapezoidal. On-the-fly speed and position changes.

**Tilt Range (approx):** minimum 31° up and 47° down (78° range) with option of 80° down (111° range)

**Pan Range (approx):** ±159° (318° range) with option of ±180° (360° range)

#### Power Requirements

**Input Voltage:** 11-37VDC unregulated

##### Power Consumption:

- 16W continuous peak (full-power mode)
- 7.5W continuous peak (low-power mode)
- 1W continuous peak (holding power off mode)

#### Mechanical

##### Pan-Tilt Unit:

- **Weight:** 3 lb.
- **Dimensions:** 3" wide x 5.13" high x 4.25" deep
- **Camera mounting:** Hole for 1/4-20 screw standard. Camera mounting plate removes for easy customizing.
- **Pan-tilt unit mounting:** Bottom or front 1/4-20 mounting

##### Controller:

- **Weight:** 12 oz.
- **Dimensions:** 3.4" wide x 5.5" long x 2.5" high

Specifications subject to change without notice.

#### Built-In Connectivity Capabilities

**Basic Mode:** Host RS-232 port controls single pan-tilt unit

**Extended Mode:** Control of multiple pan-tilt units from one or more host computers. Multidrop RS-485 network using RJ-11.

#### Host Control

**Host:** RS-232 (default is 9600 baud, 1 start bit, 8 data bits, 1 stop bit, no parity, no handshaking). DB-9 female connector.

**Host modes:** Interactive Mode (ASCII command set) and Encoded Mode (binary format for higher bandwidth computer control)

#### Commands include:

<axis> is **T** for the tilt axis or **P** for the pan axis.

##### Axis Control Commands:

**General form:** <axis><command><value><delim> [<status>]

**Go to position:** <axis>**P**<position><delim> [<status>]

**Go to offset position:** <axis>**O**<relative position><delim> [<status>]

**Set target speed:** <axis>**S**<positions/sec><delim> [<status>]

**Set acceleration:** <axis>**A**<positions/sec<sup>2</sup>><delim> [<status>]

**Set speed bounds:** <axis>**[U | L]**<positions/sec><delim> [<status>]

##### Move power mode:

<axis>**M**[<hi power> | <reg power> | <lo power>]<delim> [<status>]

##### Hold (stationary) power mode:

<axis>**H**[<reg power> | <lo power> | <power off>]<delim> [<status>]

##### Axis Queries:

**General form:** <axis><command><delim> <query answer>

(Axis Control Commands become queries when the <value> argument is omitted.)

**Resolution:** <axis>**R**<delim> <arc seconds per position>

**Position bounds:** <axis>**[N | X]**<delim> <boundary position>

##### Unit Commands:

**Command menu:** ?<delim> <menu>

**Await completion:** A<delim> <status>

**Reset unit:** R<delim> [<status>]

**Immediate mode:** I<delim> [<status>]

(immediate position command execution)

**Slaved mode:** S<delim> [<status>]

(position commands execute upon Await Completion command)

**Defaults:** D[<save> | <restore> | <factory settings>]<delim> [<status>]

(Saves and restores unit defaults at power up)

#### Available Options

- International AC/DC Power Supply (model PT-PS-IHPS)
- Weatherized option provides outdoor use (add "W" to PTU model)
- Nodal (gimbal) pan-tilt adaptor
  - Payload can mount at the intersection of the pan and tilt axes
  - Uses include rotating camera at focal point & mirror positioning
- C Programmer's Interface (model PTU-CPI)
- PTU network cabling kits (PTU-NET-SK and PTU-NET-AU)
- Analog joystick interface

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