

$$R = \sqrt{b^2 + l^2}$$

$$x, y = R(\cos(\omega t), \sin(\omega t))$$

$$\vec{u} = \vec{u}_x + \vec{u}_y$$

$$\vec{v} + \vec{w}$$

$$\vec{v}_x = \frac{d}{dt} \vec{w}_x$$

$$\vec{v}_x(t + \Delta t) = \vec{v}_x(t) + \vec{a}_x \Delta t$$

$$T = I \cdot F$$

$$R \cdot f \cdot \sin \alpha$$

$$I \frac{d\omega}{dt} = T$$

$$\boxed{\omega = \frac{d\theta}{dt} \quad \frac{d\omega}{dt} = \frac{T}{I}}$$

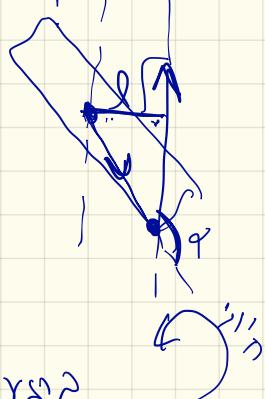
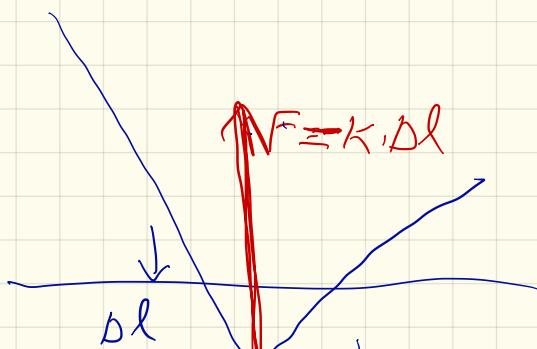
$$\omega_{t+\Delta t} = \omega_t + \frac{T}{I} \cdot \Delta t$$

$$\theta_{t+\Delta t} = \theta_t + \omega_t \cdot \Delta t$$

$$m \frac{dr_y}{dt} = F - mg$$

$$\frac{dy}{dt} = v_y$$

$$F = -k \cdot \Delta l$$



$$r(t) = r_0 + \vec{r}(t)$$

$$\begin{matrix} \text{fpc} \\ ? \end{matrix}$$

$$\Delta t = \frac{1}{f_n}$$

