

$$R = \sqrt{\left(\frac{L}{2}\right)^2 + \left(\frac{b}{2}\right)^2}$$

$$x, y = R(\cos(\alpha), \sin(\alpha))$$

$$\vec{u} = \vec{u}_x + \vec{u}_y$$

$$\vec{v} = \vec{v}_x + \vec{v}_y$$

... and ...

$$q_x = q_x + \omega \Delta t$$

$$v_x(t + \Delta t) = v_x(t)$$

$$v_y(t + \Delta t) = v_y(t) + g \Delta t$$

$$T = l \cdot F \left(\frac{\partial \theta}{\partial t} \right)$$

$$R \cdot f \cdot \sin \alpha$$

$$I \frac{d\omega}{dt} = T$$

$$\omega = \frac{d\theta}{dt}$$

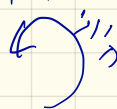
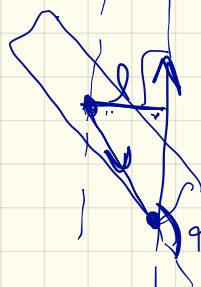
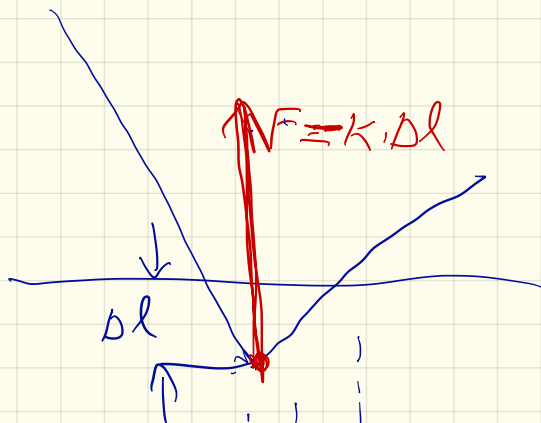
$$\frac{d\omega}{dt} = \frac{T}{I}$$

$$\omega_{t+\Delta t} = \omega_t + \frac{T}{I} \Delta t$$

$$\theta_{t+\Delta t} = \theta_t + \omega_t \Delta t$$

$$m \frac{dr}{dt} = F - mg$$

$$\frac{dy}{dt} = v_y$$



... and ...

$$\Delta t = \frac{1}{\omega}$$

... and ...

