

Goal: Error analysis of solutions under perturbation

Nominal sys.:  $\dot{x} = f(t, x, \alpha)$ ,  $x(0) = x_0$

param.

Perturbed sys.:  $\dot{y} = f(t, y, \beta) + g(t, y)$ ,  $y(0) = y_0$

unmodelled effects.

objective: bound the error  $\|y_{\text{true}} - x(t)\|$

in terms of error in params., init. cond., unmodelled dyn.  
 $\|\beta - \beta^*\|$      $\|x_0 - y_0\|$      $\|g(t, y)\|$

plan:

① Comparison lemma

② Bellman-Gronwall lemma

③ Main result

## Comparison lemma :

$X(t)$  is a number.

- assume  $X(t) \in \mathbb{R}$  satisfies

$$(*) \quad \dot{\alpha}(t) \leq \alpha \alpha(t), \quad X(0) \leq 1$$

and we like to bound  $X(t)$ . How?

- Consider another process  $\beta(t)$  which satisfies  $(*)$  with equality:

$$(\text{**}) \quad \dot{\beta}(t) = \alpha \beta(t), \quad \beta(0) = 1$$

- The solution is given by  $\beta(t) = e^{ta}$

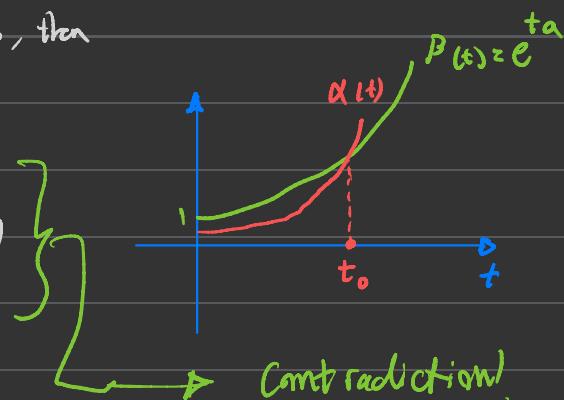
- We can argue that  $\alpha(t)$  never exceeds  $\beta(t) = e^{ta}$

- If  $\alpha(t)$  exceeds  $\beta(t)$  at  $t=t_0$ , then

$$\dot{\alpha}(t_0) > \dot{\beta}(t_0)$$

but

$$\begin{aligned} \dot{\alpha}(t_0) &\stackrel{(*)}{\leq} \alpha \alpha(t_0) = \alpha \beta(t_0) \\ &\stackrel{(\text{**})}{=} \dot{\beta}(t_0) \end{aligned}$$



- Comparison lemma is the generalization of this observation

### Lemma:

- Assume  $\alpha(t) \in \underline{\mathbb{R}}$  satisfies

$$\dot{\alpha}(t) \leq f(t, \alpha(t)) \quad \text{and} \quad \alpha(0) \leq \alpha_0$$

- Then,  $\alpha(t) \leq \beta(t)$  where  $\beta(t)$  solves

$$\dot{\beta}(t) = f(t, \beta(t)), \quad \beta(0) = \alpha_0$$

Example:

① Assume  $\dot{\alpha}(t) \leq \alpha \alpha(t) + u(t)$ ,  $\alpha(0) = \alpha_0$ . Then,

$$\alpha(t) \leq \beta(t) = e^{\int_0^t \alpha(s) ds} \underbrace{\alpha_0 + \int_0^t e^{\int_s^t \alpha(u) du} u(s) ds}_{\text{Solution to } \dot{\beta} = \alpha \beta + u(t), \beta(0) = \alpha_0}$$

② Assume  $\dot{\alpha}(t) \leq \alpha(t) \alpha(t) + u(t)$ ,  $\alpha(0) = \alpha_0$ . Then

$$\alpha(t) \leq \beta(t) = e^{\int_0^t \alpha(\tau) d\tau} \underbrace{\alpha_0 + \int_0^t e^{\int_s^t \alpha(u) du} u(s) ds}_{\text{Solution to } \dot{\beta} = \alpha(t) \beta + u(t), \beta(0) = \alpha_0} \rightarrow \phi(t, s)$$

(BG)

## Bellman-Gronwall Lemma:

- From Comparison lemma, we know that

$$\begin{array}{l} \text{(*)} \\ \left. \begin{array}{l} \dot{\alpha} \leq \alpha(s)\alpha + u(s) \\ \alpha(s) \leq \alpha_0 \end{array} \right\} \Rightarrow \alpha(t) \leq \phi_{(t,0)}\alpha_0 + \int_0^t \phi_{(t,s)} u(s) ds \end{array}$$

- The BG lemma gives the same conclusion, but

under an "integral" version of the assumption:

Lemma:

- if  $\alpha(t) \in \mathbb{R}$  satisfies

this is (\*) integrated  
over 0 to t.

$$(*) \quad \alpha(t) \leq \underbrace{\int_0^t \alpha(s)\alpha(s) ds}_{\Psi(t)} + \alpha_0 + \underbrace{\int_0^t u(s) ds}_{\lambda(t)}$$

and  $\alpha(s) \geq 0$ , then

$$\alpha(t) \leq \phi_{(t,0)}\alpha_0 + \int_0^t \phi_{(t,s)} u(s) ds$$

$e^{\int_s^t \alpha(r) dr}$

Proof:

- Let  $\Psi(t) = \int_0^t \alpha(s) ds$  and  $\lambda(t) = \alpha_0 + \int_0^t u(s) ds$ .

Then,

$$\psi(t) = \alpha(t) \alpha(t) \stackrel{(*)}{\leq} \alpha(t) \Psi(t) + \alpha(t) \lambda(t)$$

Comparison lemma

$$\Rightarrow \Psi(t) \leq \phi(t, 0) \underbrace{\Psi(0)}_0 + \int_0^t \phi(t, s) \alpha(s) \lambda(s) ds$$

$$\alpha(t) \leq \psi(t) + \lambda(t) \Rightarrow \alpha(t) \leq \int_0^t \phi(t, s) \alpha(s) \lambda(s) ds + \lambda(t)$$

Integration by parts

$$\Rightarrow \alpha(t) \leq \int_0^t \phi(t, s) \underbrace{\lambda(s)}_{u(s)} ds + \phi(t, 0) \underbrace{\lambda(0)}_{\alpha_0}$$

$$\frac{d}{dt} \phi(t, s) = -\alpha(t) \phi(t, s)$$

- Special case? assume  $\alpha(t) = \alpha$  and  $u(t) = u$  are constant.

or, equivalently

$$\alpha(t) \leq \int_0^t \alpha(s) ds + \alpha_0 + tu.$$

Then,

$$\alpha(t) \leq \int_0^t e^{(t-s)\alpha} u ds + e^{ta} \alpha_0$$

$$= \frac{e^{ta} - 1}{\alpha} u + e^{ta} \alpha_0$$

Thm:

- Consider the following two systems

(nominal)  $\dot{x} = f(t, x), \quad x_{(0)} = x_0$

(perturbed)  $\dot{y} = f(t, y) + g(t, y), \quad y_{(0)} = y_0$

- Assume  $f$  is globally Lip. unif. in  $t \in [0, T]$

$$\|f(t, x) - f(t, y)\| \leq L \|x - y\|, \quad \forall x, y, \quad \forall t \in [0, T]$$

and  $g$  is unif. bounded

$$\|g(t, y)\| \leq M, \quad \forall y, \quad \forall t \in [0, T]$$

- Then,

$$\|x(t) - y(t)\| \leq e^{Lt} \|x_{(0)} - y_{(0)}\| + \frac{M}{L} (e^{Lt} - 1)$$

Proof:

- Subtracting nominal from perturbed eq. yields :

$$\dot{Y}(t) - \dot{X}(t) = f(t, Y(t)) - f(t, X(t)) + g(t, Y)$$

- Integrating from 0 to t :

$$Y(t) - X(t) = Y_0 - X_0 + \int_0^t f(s, Y(s)) - f(s, X(s)) ds + \int_0^t g(s, Y(s)) ds$$

- Taking the norm of both sides

$$\|Y(t) - X(t)\| \leq \|Y_0 - X_0\| + \int_0^t L \|Y(s) - X(s)\| ds + M t$$

- Applying the special case of BG lemma to

$\alpha(t) = \|Y(t) - X(t)\|$  with  $a=L$  and  $n=M$ , yields

$$\|Y(t) - X(t)\| \leq e^{tL} \|Y_0 - X_0\| + \frac{M}{L} (e^{tL} - 1)$$

## Example:

- Consider the aircraft model

given open-loop control input.

$$\begin{aligned}\ddot{x} &= -\sin(\theta) u_1(t) + \varepsilon \cos(\theta) u_2(t) \\ \ddot{y} &= \cos(\theta) u_1(t) + \varepsilon \sin(\theta) u_2(t) \\ \ddot{\theta} &= u_2(t)\end{aligned}$$

$$\dot{z} = F(t, z, \varepsilon), \quad z_0 = z_0$$

$$\text{with } z = [x, y, \theta, \dot{x}, \dot{y}, \dot{\theta}]^T$$

- We like to bound the simulation error when the parameter  $\varepsilon$  and init. cond. are known up to 1% accuracy.

assumed

$$\frac{|\hat{\varepsilon} - \varepsilon|}{\varepsilon} \leq 0.01, \text{ and}$$

assumed

$$\frac{\|\hat{z}_0 - z_0\|}{\|z_0\|} \leq 0.01$$

- We assume

$$|u_1(t)|, |u_2(t)| \leq V_{\max}, \quad \forall t \quad \text{and} \quad \varepsilon, \hat{\varepsilon} \leq 1$$

- Therefore, we consider the following two systems.

Simulation/  
nominal

$$\dot{\hat{z}} = \underbrace{F(t, \hat{z}, \hat{\varepsilon})}_{f(t, \hat{z})}, \quad \hat{z}_{(0)} = \hat{z}_0.$$

real/  
perturbed

$$\dot{z} = \underbrace{F(t, z, \varepsilon)}_{f(t, z) + g(t, z)}, \quad z_{(0)} = z_0.$$

- Let's write the perturbed sys as

$$\dot{z} = \underbrace{f(t, z, \hat{\varepsilon})}_{f(t, z)} + \underbrace{F(t, z, \varepsilon) - F(t, z, \hat{\varepsilon})}_{g(t, z)}$$

①  $f(t, z)$  is globally Lip. in  $z$  unif int:

$$\left\| \frac{\partial f}{\partial z}(t, z) \right\|_\infty \leq \underbrace{1 + 2U_{\max}}_{L}, \quad \forall z$$

$$\Rightarrow \|f(t, z) - f(t, \hat{z})\|_\infty \leq L \|z - \hat{z}\|_\infty$$

②  $g(t, y)$  is bounded:

$$\|g(t, y)\|_\infty = \|F(t, z, \varepsilon) - F(t, z, \hat{\varepsilon})\| \leq U_{\max} |\varepsilon - \hat{\varepsilon}|$$

- Application of the Thm.:

$$\|z_{0+} - \hat{z}_{0+}\|_\infty \leq e^{tL} \underbrace{\|z_0 - \hat{z}_0\|_\infty}_{\leq 0.01 \|z_0\|} + \frac{U_{\max} |t-0|}{L} (e^{tL} - 1)$$

$$\leq 0.01 \left( e^{tL} \|z_0\| + \frac{U_{\max} \varepsilon}{L} (e^{tL} - 1) \right)$$

$$\text{with } L = 1 + 2U_{\max}$$