

Goal: use Lyapunov method for convergence analysis of optimization algorithms

- Assume, you like to find the minimizer of the function $\mathcal{J}: \mathbb{R}^n \rightarrow \mathbb{R}$

$$\min_{x \in \mathbb{R}^n} \mathcal{J}(x) \quad \rightarrow \text{training NN}$$

- A classical alg. is gradient descent: (we assume \mathcal{J} is differentiable)

$$x_{k+1} = x_k - \eta \nabla \mathcal{J}(x_k)$$

\downarrow step-size

- In the cont. time limit, as $\eta \rightarrow 0$, this update converges to gradient flow:

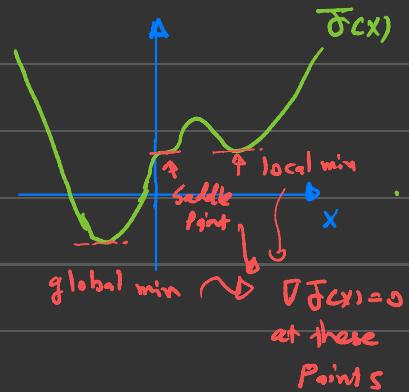
$$\dot{x} = -\nabla \mathcal{J}(x)$$

- We will use Lyapunov method to analyze convergence of gradient flow \rightarrow gives insight about conv. of grad. descent.

- Eq/b. points:

$$E \geq \left\{ x \in \mathbb{R}^n; \nabla f(x) = 0 \right\}$$

→ Critical/extreme points



- Any global minimizer x^* is a critical point

$\nabla f(x^*) = 0 \rightarrow$ 1st-order necessary condition
for optimality.

- Our goal is to analyze the convergence of gradient flow
under different assumptions on the obj. function $f(x)$

Case 1: No assumption

Case 2: radially unbd

Case 3: Convex

Case 4: gradient dominate

Case 5: strongly convex.

Case 1: (No assumption on \bar{f})

- let $V(x) = \bar{f}(x) - \underbrace{\min_x \bar{f}(x)}_{\bar{f}(x^*)}$, then

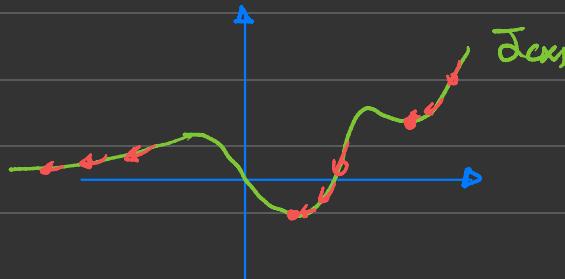
$$\begin{aligned}\frac{d}{dt} V(x_{(t)}) &= \nabla V(x_{(t)}) (-\nabla \bar{f}(x_{(t)})) \\ &= -\|\nabla \bar{f}(x_{(t)})\|_2^2\end{aligned}$$

- Integrating with respect to time:

$$V(x_{(t)}) - V(x_{(0)}) = - \int_0^t \|\nabla \bar{f}(x_{(s)})\|_2^2 ds \leq -t \min_{S \in [0, t]} \|\nabla \bar{f}(x_{(s)})\|_2^2$$

$$\Leftrightarrow \min_{S \in [0, t]} \|\nabla \bar{f}(x_{(s)})\|_2^2 \leq \frac{V(x_{(t)}) - V(x_{(0)})}{t} \leq \frac{\bar{f}(x_{(t)}) - \bar{f}(x^*)}{t}$$

- Easiest conv. result under no assumption $O(\frac{1}{t})$ converge



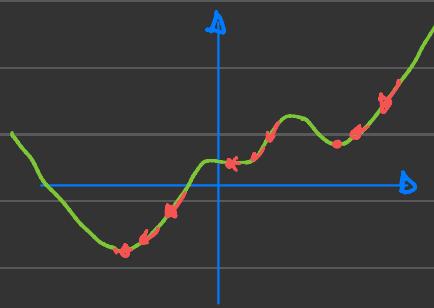
Case 2: (\mathcal{J} is radially unbounded)

- In this case, $V(x) = \mathcal{J}(x) - \mathcal{J}(x^*)$ is a radially unbounded function and $\dot{V}(x) = \|\nabla \mathcal{J}(x)\|_2^2 \leq 0 \quad \forall x$.

\Rightarrow all solutions are bounded

$\xrightarrow{\text{LaSalle}}$ $x(t) \rightarrow E = \{x \in \mathbb{R}^n; \nabla \mathcal{J}(x) = 0\}$ $\xrightarrow{\text{largest invariant set in } E \text{ is } E}$

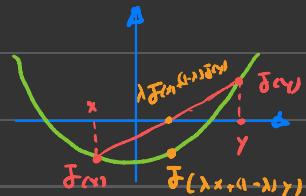
$\xrightarrow{\text{ }} x(t)$ converges to a critical point!



- We can do the linearization procedure to obtain local convergence regions, and local convergence rates.

Convex analysis : [Rockafellar]

- $f: \mathbb{R}^n \rightarrow \mathbb{R}$ is convex if



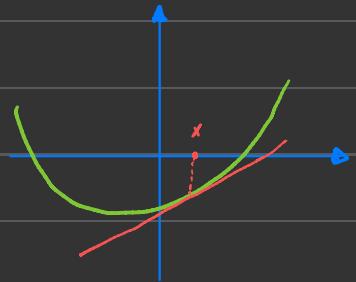
$$f(\lambda x + (1-\lambda)y) \leq \lambda f(x) + (1-\lambda)f(y), \quad \forall x, y \in \mathbb{R}^n$$

$$\text{And } \lambda \in [0, 1]$$

- A convex func is always locally Lip. on its domain (diff almost everywhere)
- If f is diff. everywhere, then

$$f(y) \geq f(x) + \nabla f(x)(y-x), \quad \forall x, y \in \mathbb{R}^n$$

graph lies above
its tangents



- For convex functions :

all critical points are global minimizers

why?

$$\nabla f(x) = 0 \Rightarrow f(y) \geq f(x) \quad \forall y \Rightarrow x \text{ is global minimizer}$$

Case 3: (\mathcal{J} is convex)

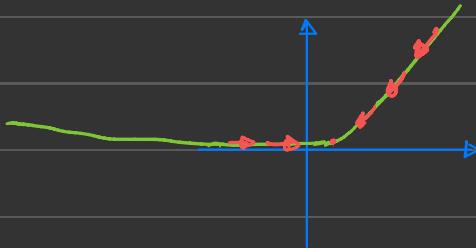
- Take $V(t, x) = \frac{1}{2} \|x - x^*\|^2 + t(\mathcal{J}(x) - \mathcal{J}(x^*))$

- Then, $\frac{d}{dt} V(t, x_{(t)}) = (x_{(t)} - x^*)^\top (-\nabla \mathcal{J}(x_{(t)})) + \mathcal{J}(x_{(t)}) - \mathcal{J}(x^*)$
 $- t \|\nabla \mathcal{J}(x_{(t)})\|^2 \leq 0$

- Integrating: $V(t, x_{(t)}) \leq V(0, x_{(0)}) = \frac{1}{2} \|x_{(0)} - x^*\|^2$

$$\Rightarrow \mathcal{J}(x_{(t)}) - \mathcal{J}(x^*) \leq \frac{1}{2t} \|x_{(0)} - x^*\|^2$$

$\mathcal{O}(\frac{1}{t})$ convergence of
value of obj. func.



→ Polyak - L ojasiewicz

Gradient dominance or PL condition:

$$\bar{f}(x) - \bar{f}(x^*) \leq \frac{1}{2\mu} \|\nabla \bar{f}(x)\|_2^2, \quad \forall x$$

Case 4: (\bar{f} is not convex, but satisfies PL condition)

- Take $V(x) = \bar{f}(x) - \bar{f}(x^*)$, then

$$\frac{d}{dt} V(x_{(t)}) = - \|\nabla \bar{f}(x)\|_2^2 \leq -2\mu V(x_{(t)})$$

Comparison lemma $\Rightarrow V(x_{(t)}) \leq e^{-2\mu t} V(x_{(0)})$

$$\Rightarrow \bar{f}(x_{(t)}) - \bar{f}(x^*) \leq e^{-2\mu t} (\bar{f}(x_{(0)}) - \bar{f}(x^*))$$



exp. convergence

Strongly convex functions:

- $\mathcal{F}: \mathbb{R}^n \rightarrow \mathbb{R}$ is μ -strongly convex if

$$\mathcal{F}(y) \geq \mathcal{F}(x) + \nabla \mathcal{F}(x)^T (y - x) + \frac{\mu}{2} \|y - x\|^2$$

Case 5: (\mathcal{F} is strongly convex)

$$- \text{let } V(x_0) = \frac{1}{2} \|x - x^*\|^2 \Rightarrow$$

$$\frac{d}{dt} V(x_{(t)}) = \nabla \mathcal{F}(x_{(t)})^T (x^* - x_{(t)})$$

- Strong Convexity condition for $y = x^*$ and $x = x_{(t)}$ implies

$$\nabla \mathcal{F}(x_{(t)})^T (x^* - x_{(t)}) \leq \underbrace{\mathcal{F}(x^*) - \mathcal{F}(x_{(t)})}_{\leq 0} - \underbrace{\frac{\mu}{2} \|x_{(t)} - x^*\|^2}_{V(x_{(t)})}$$

$$\leq -\mu V(x_{(t)})$$

$$\Rightarrow \frac{d}{dt} V(x_{(t)}) \leq -\mu V(x_{(t)}) \Rightarrow V(x_{(t)}) \leq e^{-t\mu} V(x_0)$$

$$\Rightarrow \|x_{(t)} - x^*\|^2 \leq \underbrace{e^{-\mu t} \|x_0 - x^*\|^2}_{\text{exp. convergence!}}$$

Remark:

- Strong Convexity \Rightarrow PL

- Some PL functions are not convex, and convex function
not PL

Summary:

