

Math 201 Mid-term 1 (Fall 2020)_Answer

Model Answer

1- Mark each statement as True or False. **JUSTIFY YOUR ANSWER.**

- If the **reduced** row echelon form of $A_{n \times n}$ can be obtained using only row replacement operations, then $|A|$ must be 1.
- If the matrix A has a pivot for each row, then the equation $A\vec{x} = \vec{b}$ is always consistent.
- If $A_{n \times n}$ is an idempotent matrix (i.e. $A^2 = A$), then $|A|$ must be 1.
- A homogeneous system of three linear equations in two variables has infinitely many solutions.
- If the vectors \vec{u}, \vec{v} belong to the span of S , then so is $\vec{u} + \vec{v}$.
- The columns of a 3×4 matrix are always linearly dependent.

(6 Marks)

- False.** Since the number of pivots might be less than n and hence the determinant is 0.
- True. As no contradiction will occur.
- False.** $|A^2| = |A|^2 = |A| \Rightarrow |A|(|A| - 1) = 0 \Rightarrow |A| = 0$ or $|A| = 1$.
- False.** It might have the trivial solution only (e.g. $x = 0, y = 0, x - y = 0$).
- True. Since \vec{u}, \vec{v} belong to all the possible linear combination of a set of vectors, then any linear combination of \vec{u}, \vec{v} will be too.
- True. Since any 4 vectors in \mathbb{R}^3 will be linearly dependent as the row reduction of the system: $c_1\vec{v}_1 + c_2\vec{v}_2 + c_3\vec{v}_3 + c_4\vec{v}_4 = \vec{0}$ will result in a maximum of 3 pivots, thus there will be at least one free variable and hence the vectors are linearly dependent.

2- Let t be a fixed real number, and let

$$A = \begin{pmatrix} t-1 & t & t \\ t & t-1 & t \\ t & t & t-1 \end{pmatrix}$$

- Find the value(s) of t for which A is invertible.
- For $t = 1$, find, if possible, A^{-1} .
- For $t = 1$, are columns of A linearly independent? **Justify your answer.**
- For $t = 1$, does the set containing the columns of A span \mathbb{R}^3 ? **Justify your answer.**

(8 Marks)

$$\text{a. } |A| = \begin{vmatrix} t-1 & t & t \\ t & t-1 & t \\ t & t & t-1 \end{vmatrix} = (t-1)[(t-1)^2 - t^2] - t[t(t-1) - t^2] + t[t^2 - t(t-1)] = 3t - 1$$

So A is invertible if $t \neq 1/3$.

- For $t = 1$,

$$A = \begin{pmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \end{pmatrix}$$

The inverse can be obtained using the adjugate method,

$$A^{-1} = \frac{1}{|A|} C^T = \frac{1}{2} \begin{pmatrix} -1 & 1 & 1 \\ 1 & -1 & 1 \\ 1 & 1 & -1 \end{pmatrix}^T = \begin{pmatrix} -1/2 & 1/2 & 1/2 \\ 1/2 & -1/2 & 1/2 \\ 1/2 & 1/2 & -1/2 \end{pmatrix}$$

or Gauss-Jordan method,

$$\begin{aligned} & \left[\begin{array}{ccc|ccc} 0 & 1 & 1 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 & 1 & 0 \\ 1 & 1 & 0 & 0 & 0 & 1 \end{array} \right] \sim \left[\begin{array}{ccc|ccc} 1 & 0 & 1 & 0 & 1 & 0 \\ 0 & 1 & 1 & 1 & 0 & 0 \\ 1 & 1 & 0 & 0 & 0 & 1 \end{array} \right] \sim \left[\begin{array}{ccc|ccc} 1 & 0 & 1 & 0 & 1 & 0 \\ 0 & 1 & 1 & 1 & 0 & 0 \\ 0 & 1 & -1 & 0 & -1 & 1 \end{array} \right] \\ & \sim \left[\begin{array}{ccc|ccc} 1 & 0 & 1 & 0 & 1 & 0 \\ 0 & 1 & 1 & 1 & 0 & 0 \\ 0 & 0 & -2 & -1 & -1 & 1 \end{array} \right] \sim \left[\begin{array}{ccc|ccc} 1 & 0 & 1 & 0 & 1 & 0 \\ 0 & 1 & 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1/2 & 1/2 & -1/2 \end{array} \right] \sim \left[\begin{array}{ccc|ccc} 1 & 0 & 0 & -1/2 & 1/2 & 1/2 \\ 0 & 1 & 0 & 1/2 & -1/2 & 1/2 \\ 0 & 0 & 1 & 1/2 & 1/2 & -1/2 \end{array} \right] \end{aligned}$$

- Yes, columns of A are linearly independent, since $A\vec{x} = \vec{0}$ has only the trivial solution or $|A| \neq 0$.
- Yes, the set containing the columns of A spans \mathbb{R}^3 as it contains 3 linearly independent vectors in \mathbb{R}^3 .

3- For

$$A = \begin{pmatrix} 1 & 2 & 0 & 1 \\ 2 & 4 & 1 & 4 \\ 3 & 6 & 3 & 9 \end{pmatrix}, \vec{b} = \begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix}$$

- Find a row echelon form of A .
- Are columns of A linearly independent? **Justify your answer.**
- Find a parametric vector form for the solution set of $A\vec{x} = \vec{0}$?
- Describe, if any, the relation between the solution sets of $A\vec{x} = \vec{b}$ and $A\vec{x} = \vec{0}$?

(8 Marks)

a. $A = \begin{pmatrix} 1 & 2 & 0 & 1 \\ 2 & 4 & 1 & 4 \\ 3 & 6 & 3 & 9 \end{pmatrix} \xrightarrow[\substack{R_2 - 2R_1 \rightarrow R_2 \\ R_3 - 3R_1 \rightarrow R_3}]{\sim} \begin{pmatrix} 1 & 2 & 0 & 1 \\ 0 & 0 & 1 & 2 \\ 0 & 0 & 3 & 6 \end{pmatrix} \xrightarrow{R_3 - 3R_2 \rightarrow R_3} \begin{pmatrix} 1 & 2 & 0 & 1 \\ 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 0 \end{pmatrix}$

- b. No; as the second and fourth columns are not pivot columns, so they are not linearly independent.

c. $x_1 + 2x_2 + x_4 = 0$

$x_3 + 2x_4 = 0$

$$\vec{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} -2x_2 - x_4 \\ x_2 \\ -2x_4 \\ x_4 \end{bmatrix} = x_2 \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} -1 \\ 0 \\ -2 \\ 1 \end{bmatrix}$$

Solution is a hyperplane in \mathbb{R}^4 spanned by the two vectors $\begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ -2 \\ 1 \end{bmatrix}$

d. For $A\vec{x} = \vec{b}$

$$[A \quad \vec{b}] = \begin{pmatrix} 1 & 2 & 0 & 1 & 1 \\ 2 & 4 & 1 & 4 & 2 \\ 3 & 6 & 3 & 9 & 1 \end{pmatrix} \xrightarrow[\substack{R_2 - 2R_1 \rightarrow R_2 \\ R_3 - 3R_1 \rightarrow R_3}]{\sim} \begin{pmatrix} 1 & 2 & 0 & 1 & 1 \\ 0 & 0 & 1 & 2 & 0 \\ 0 & 0 & 3 & 6 & -2 \end{pmatrix} \xrightarrow{R_3 - 3R_2 \rightarrow R_3} \begin{pmatrix} 1 & 2 & 0 & 1 & 1 \\ 0 & 0 & 1 & 2 & 0 \\ 0 & 0 & 0 & 0 & -2 \end{pmatrix}$$

In this case, there is no solution because of a contradiction and hence there is no relation between the solution sets of $A\vec{x} = \vec{b}$ and $A\vec{x} = \vec{0}$.

Hint: you can do the reduction once for the whole problem by reducing $[A \quad \vec{b}]$

- 4- a. Describe all the possible **reduced** row echelon forms of a nonzero 2×2 matrix. Let '*' denotes any value.
- b. Let A and B be two 3×3 matrices such that $\det(A) = 3$ and $\det(B) = 4$. Evaluate $\det(\frac{1}{3}A^T B^{-1}A^2 B^2)$.
- c. Let $\vec{u} = \begin{bmatrix} a \\ b \end{bmatrix}, \vec{v} = \begin{bmatrix} c \\ d \end{bmatrix}$ be vectors in \mathbb{R}^2 . Find, if possible, $(\vec{u}^T \vec{v})^{-1}, (\vec{u} \vec{v}^T)^{-1}$.

(8 Marks)

a. $\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}; \begin{bmatrix} 1 & * \\ 0 & 0 \end{bmatrix}; \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$

b. $\left| \frac{1}{3}A^T B^{-1}A^2 B^2 \right| = \frac{1}{3^3} \frac{|A|^3 |B|^2}{|B|} = \frac{1}{27} |A|^3 |B| = 4.$

c. $\vec{u}^T \vec{v} = ac + bd \rightarrow (\vec{u}^T \vec{v})^{-1} = \frac{1}{ac+bd}, \text{ if } ac + bd \neq 0$

$\vec{u} \vec{v}^T = \begin{bmatrix} ac & ad \\ bc & bd \end{bmatrix} \rightarrow (\vec{u} \vec{v}^T)^{-1} \text{ doesnot exist as } \begin{vmatrix} ac & ad \\ bc & bd \end{vmatrix} = 0$