

Determinants

- Prove that $\det(B^{-1}AB) = \det(A)$ if B is invertible.
- Suppose Q is a 3×3 real matrix such that $Q^T Q = I$. What values can $\det(Q)$ take?

$\det(B^{-1}AB) = \det(A)$
 $A, B \in M^n$
 $\exists B^{-1}$

$\det(B^{-1}) = \frac{1}{\det(B)}$

$A \in M_{n \times n}$

$|B^{-1}| |A| |B| = |A|$

$|A| = 1.5$
 $|A^{-1}| = \frac{1}{1.5}$

$|A \cdot B| = |A| \cdot |B|$

$$Q \in \mathbb{R}^{n \times n}$$

$$Q^T Q = I \Rightarrow |Q^T Q| = |I| = 1$$

$$|Q^T| = |Q|$$

$$|Q| = 1$$

$$Q^T = Q^{-1}$$

$$|Q^T| = |Q|$$

$| \begin{pmatrix} 1 \\ 0 \end{pmatrix} | = 1$

$$Q^T = Q^{-1}$$

$$\begin{bmatrix} x=7 \\ x=-7 \end{bmatrix}$$

$Q^T Q$ 

Linear dependence, basis, rank

We have the following dataset of cheeses

Cheese	Price in USD	Price in AMD	Year Made	Years Waited	Year Eaten
v_1	300	150,000	2013	5	2018
v_2	450	225,000	2010	9	2019
v_3	350	175,000	2014	3	2017
v_4	400	200,000	2013	5	2018
v_5	280	140,000	2011	6	2017

Tasks

- Determine the maximum possible dimension of the subspace spanned by v_1, \dots, v_5 .

Identify a maximal linearly independent subset (a basis) of these vectors.

Which features would you use in a Machine Learning and why? If not all, why?

$$(w_1, w_2, w_3)$$



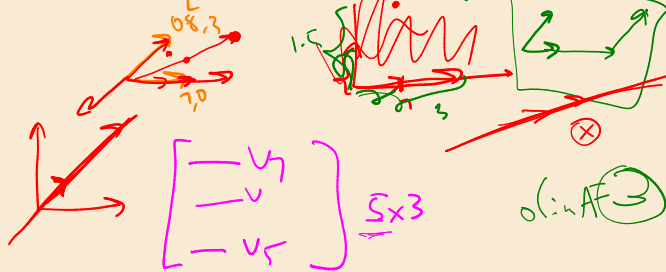
$$w_3 = c_1 w_1 + c_2 w_2$$

$$c_1, c_2 \in \mathbb{R}$$

$$\sum_{i=1}^n c_i^2 \neq 0 \quad (y_1, \dots, y_n \neq 0)$$

$$x_1 = c \cdot x_1$$

$$\langle v_1, v_2, \dots, v_5 \rangle = \{ c_1 v_1 + c_2 v_2 + \dots + c_5 v_5 \mid c_1, c_2, \dots, c_5 \in \mathbb{R} \}$$



$$y = Gx$$

$$\begin{bmatrix} 1 & 1 \\ 1 & 1 \\ 1 & 1 \\ 1 & 1 \\ 1 & 1 \end{bmatrix}$$

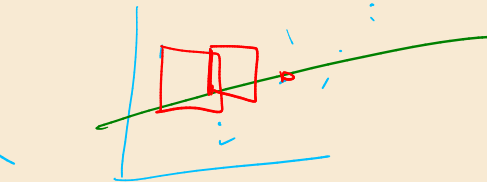
$$\begin{bmatrix} -v_1 \\ -v_2 \\ -v_3 \\ -v_4 \\ -v_5 \end{bmatrix}_{5 \times 3}$$

$$o(\infty)$$

$$X \rightarrow m \times n$$

$$X^T \rightarrow n \times m$$

$$X^T X \rightarrow n \times n$$



$$(X^T X)^{-1} X^T y$$

non-singular

Normal Eqn

$$\frac{1}{2} \text{MSE}$$

Full rank

$$\begin{bmatrix} 3 & 4 \\ 3 & 3 \end{bmatrix}$$

$$\begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}$$



$$\begin{bmatrix} 300 \\ 020 \\ 040 \end{bmatrix}^2$$

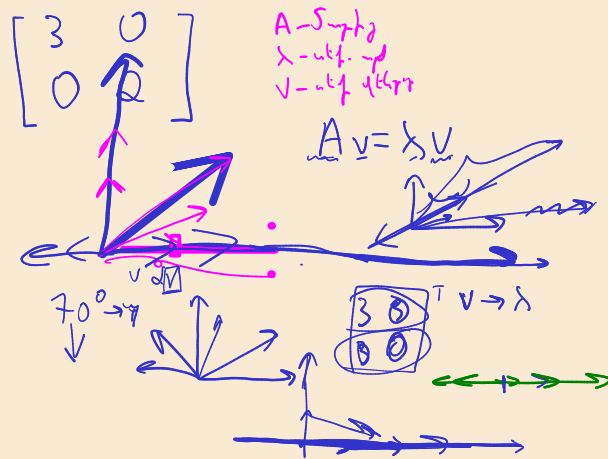
$$|X| = 0$$

$$|X^T| = 0$$

$$|X^T X| = 0 \Rightarrow \exists \text{ linearly dependent}$$

$$\begin{bmatrix} \vdots \\ \vdots \\ \vdots \end{bmatrix} \begin{bmatrix} \vdots \\ \vdots \\ \vdots \end{bmatrix}$$

$$A = \begin{pmatrix} 5 & 8 \\ 2 & 5 \end{pmatrix}$$



$$Av = \lambda_1 v$$

$$Av - \lambda_1 v = 0$$

$$(A - \lambda_1 I)v = 0 \quad \text{where } I = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$|A - \lambda I| = 0$$

$$Av = 3v$$

characteristic polynomial

$A \sim$

λ_1, λ_2
 v_1, v_2

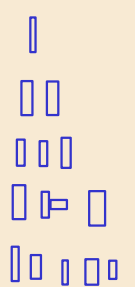
v_1, v_2
 v_1, v_2

$\sim 3 \times 4$

$$\begin{aligned} A \begin{bmatrix} v_{11} \\ v_{12} \end{bmatrix} &= \lambda_1 \begin{bmatrix} v_{11} \\ v_{12} \end{bmatrix} \\ A \begin{bmatrix} v_{21} \\ v_{22} \end{bmatrix} &= \lambda_2 \begin{bmatrix} v_{21} \\ v_{22} \end{bmatrix} \\ A \begin{bmatrix} v_{11} & v_{21} \\ v_{12} & v_{22} \end{bmatrix} &= \begin{bmatrix} \lambda_1 v_{11} & \lambda_2 v_{21} \\ \lambda_1 v_{12} & \lambda_2 v_{22} \end{bmatrix} = \\ &= \begin{bmatrix} v_{11} & v_{21} \\ v_{12} & v_{22} \end{bmatrix} \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix} \end{aligned}$$

$$\begin{bmatrix} \lambda_1^{40} & 0 \\ 0 & \lambda_2^{40} \end{bmatrix}$$

$$\begin{aligned} AP &= P\Lambda \\ AP^{-1} &= P\Lambda P^{-1} \\ A^n &= P\Lambda^n P^{-1} \end{aligned}$$



1. Vector
2. Norm
3. Dot product
4. Cosine similarity
5. Matrix geometrical interpretation
6. Linear dependence/independence
7. Basis
8. Rank
9. Inverse
10. Determinant
11. Eigenvector, eigenvalue
12. Subspace, Linear space