

## Mathematical Concepts 1

**Exercise 1: Gradient**

Consider the bivariate function  $f : \mathbb{R}^2 \rightarrow \mathbb{R}, (x_1, x_2) \mapsto x_1^2 + 0.5x_2^2 + x_1x_2$ .

- (a) Show that  $f$  is smooth (as defined in the lecture).
- (b) Find the direction of greatest increase of  $f$  at  $\mathbf{x} = (1, 1)$ .
- (c) Find the direction of greatest decrease of  $f$  at  $\mathbf{x} = (1, 1)$ .
- (d) Find a direction in which  $f$  does not instantly change at  $\mathbf{x} = (1, 1)$ .
- (e) Assume there exists a differentiable parametrization of a curve  $\tilde{\mathbf{x}} : \mathbb{R} \rightarrow \mathbb{R}^2, t \mapsto \tilde{\mathbf{x}}(t)$  such that  $\forall t \in \mathbb{R} : f(\tilde{\mathbf{x}}(t)) = f(1, 1)$ . Show that at each point of the curve  $\tilde{\mathbf{x}}$  the tangent line  $\frac{\partial \tilde{\mathbf{x}}}{\partial t}$  is perpendicular to the gradient  $\nabla f(\tilde{\mathbf{x}})$ .
- (f) Interpret (d), (e) geometrically

**Exercise 2: Convexity**

Consider two convex functions  $f, g : \mathbb{R} \rightarrow \mathbb{R}$ .

- (a) Show that  $f + g : \mathbb{R} \rightarrow \mathbb{R}, x \mapsto f(x) + g(x)$  is convex.
- (b) Now, assume that  $g$  is additionally non-decreasing, i.e.,  $g(y) \geq g(x) \forall x \in \mathbb{R}, \forall y \in \mathbb{R}$  with  $y > x$ . Show that  $g \circ f$  is convex.

**Exercise 3: Taylor polynomials**

Consider the bivariate function  $f : \mathbb{R}^2 \rightarrow \mathbb{R}, (x_1, x_2) \mapsto \exp(\pi \cdot x_1) - \sin(\pi \cdot x_2) + \pi \cdot x_1 \cdot x_2$

- (a) Compute the gradient of  $f$  for an arbitrary  $\mathbf{x}$ .
- (b) Compute the Hessian of  $f$  for an arbitrary  $\mathbf{x}$ .
- (c) State the first order taylor polynomial  $T_{1,\mathbf{a}}(\mathbf{x})$  expanded around the point  $\mathbf{a} = (0, 1)$ .
- (d) State the second order taylor polynomial  $T_{2,\mathbf{a}}(\mathbf{x})$  expanded around the point  $\mathbf{a} = (0, 1)$ .
- (e) Determine if  $T_{2,\mathbf{a}}$  is a convex function.

Mathematical Concepts 1

**Solution 1:**

Gradient

- (a) The gradient  $\nabla f(\mathbf{x}) = (2x_1 + x_2, x_2 + x_1)^\top$  is continuous  $\Rightarrow f \in \mathcal{C}^1$ .
- (b) The direction of greatest increase is given by the gradient, i.e.,  $\nabla f(1, 1) = (3, 2)^\top$ .
- (c) Let  $\mathbf{v} \in \mathbb{R}^2$  be a direction with fixed length  $\|\mathbf{v}\|_2 = r > 0$ .  
The directional derivative  $D_{\mathbf{v}}f(\mathbf{x}) = \nabla f(\mathbf{x})^\top \mathbf{v} = \|\nabla f(\mathbf{x})\|_2 \|\mathbf{v}\|_2 \cos(\theta) = \|\nabla f(\mathbf{x})\|_2 r \cos(\theta)$ . This becomes minimal if  $\theta = \pi$ , i.e., if  $\mathbf{v}$  points in the opposite direction of  $\nabla f \Rightarrow \mathbf{v} = -\nabla f(\mathbf{x})$  if  $r = \|\nabla f(\mathbf{x})\|_2$ . Here, the direction of greatest decrease is given by  $-\nabla f(1, 1) = (-3, -2)^\top$ .
- (d)  $D_{\mathbf{v}}f(\mathbf{x}) = \nabla f(1, 1)^\top \mathbf{v} \stackrel{!}{=} 0 \Rightarrow (3, 2) \cdot \mathbf{v} = 0 \iff \mathbf{v} = \alpha \cdot (-2, 3)^\top$  with  $\alpha \in \mathbb{R}$  and  $\alpha \neq 0$ .
- (e) When we differentiate both sides of the equation  $f(\tilde{\mathbf{x}}(t)) = f(1, 1)$  w.r.t.  $t$  we arrive at  $\frac{\partial f(\tilde{\mathbf{x}}(t))}{\partial t} = 0$ . Via the chain rule it follows that  $\underbrace{\frac{\partial f}{\partial \tilde{\mathbf{x}}}}_{=\nabla f(\tilde{\mathbf{x}})^\top} \frac{\partial \tilde{\mathbf{x}}}{\partial t} = 0$ .
- (f) The gradient is orthogonal to the tangent line of the level curves.

**Solution 2:**

Convexity

- (a) Let  $x, y \in \mathbb{R}$  and  $t \in [0, 1]$  then it holds that

$$\begin{aligned} (f + g)(x + t(y - x)) &= f(x + t(y - x)) + g(x + t(y - x)) \\ &\leq f(x) + t(f(y) - f(x)) + g(x) + t(g(y) - g(x)) && (f, g \text{ are convex}) \\ &= f(x) + g(x) + t(f(y) + g(y) - (f(x) + g(x))) \\ &= (f + g)(x) + t((f + g)(y) - (f + g)(x)). \end{aligned}$$

- (b) Let  $x, y \in \mathbb{R}$  and  $t \in [0, 1]$  then it holds that

$$\begin{aligned} (g \circ f)(x + t(y - x)) &= g(f(x + t(y - x))) \\ &\leq g(f(x) + t(f(y) - f(x))) && (g \text{ is non-decreasing, } f \text{ is convex}) \\ &\leq g(f(x)) + t(g(f(y)) - g(f(x))) && (g \text{ is convex}) \\ &= (g \circ f)(x) + t((g \circ f)(y) - (g \circ f)(x)). \end{aligned}$$

**Solution 3:**

Convexity

Consider the bivariate function  $f : \mathbb{R}^2 \rightarrow \mathbb{R}, (x_1, x_2) \mapsto \exp(\pi \cdot x_1) - \sin(\pi \cdot x_2) + \pi \cdot x_1 \cdot x_2$

- (a)  $\nabla f(\mathbf{x}) = \pi \cdot (\exp(\pi x_1) + x_2, -\cos(\pi x_2) + x_1)^\top$
- (b)  $\nabla^2 f(\mathbf{x}) = \pi \cdot \begin{pmatrix} \pi \exp(\pi x_1) & 1 \\ 1 & \pi \sin(\pi x_2) \end{pmatrix}$
- (c)  $T_{1, \mathbf{a}}(\mathbf{x}) = f(\mathbf{a}) + \nabla f(\mathbf{a})^\top (\mathbf{x} - \mathbf{a}) = 1 + \pi \cdot (2, 1) \cdot (x_1, x_2 - 1)^\top = 1 - \pi + 2\pi x_1 + \pi x_2$

## Mathematical Concepts 2

**Solution 1:**

## Matrix Calculus

$$(a) \frac{\partial \|\mathbf{x} - \mathbf{c}\|_2^2}{\partial \mathbf{x}} = \frac{\partial \|\mathbf{u}\|_2^2}{\partial \mathbf{u}} \frac{\partial \mathbf{u}}{\partial \mathbf{x}} = \frac{\partial \mathbf{u}^\top \mathbf{u}}{\partial \mathbf{u}} \frac{\partial \mathbf{x} - \mathbf{c}}{\partial \mathbf{x}} = \frac{\partial \mathbf{u}^\top \mathbf{I} \mathbf{u}}{\partial \mathbf{u}} (\mathbf{I} - \mathbf{0}) = \mathbf{u}^\top (\mathbf{I} + \mathbf{I}^\top) = 2(\mathbf{x} - \mathbf{c})^\top$$

$$(b) \frac{\partial \|\mathbf{x} - \mathbf{c}\|_2}{\partial \mathbf{x}} = \frac{\partial \sqrt{\|\mathbf{x} - \mathbf{c}\|_2^2}}{\partial \mathbf{x}} = \frac{0.5}{\sqrt{\|\mathbf{x} - \mathbf{c}\|_2^2}} \frac{\partial \|\mathbf{x} - \mathbf{c}\|_2^2}{\partial \mathbf{x}} \stackrel{(a)}{=} \frac{(\mathbf{x} - \mathbf{c})^\top}{\|\mathbf{x} - \mathbf{c}\|_2}$$

$$(c) \frac{\partial \mathbf{u}^\top \mathbf{v}}{\partial \mathbf{x}} = \frac{\partial \mathbf{u}^\top \mathbf{I} \mathbf{v}}{\partial \mathbf{x}} = \mathbf{u}^\top \mathbf{I} \frac{\partial \mathbf{v}}{\partial \mathbf{x}} + \mathbf{v}^\top \mathbf{I}^\top \frac{\partial \mathbf{u}}{\partial \mathbf{x}} = \mathbf{u}^\top \frac{\partial \mathbf{v}}{\partial \mathbf{x}} + \mathbf{v}^\top \frac{\partial \mathbf{u}}{\partial \mathbf{x}}$$

$$(d) \frac{\partial \mathbf{Y}^\top \mathbf{u}}{\partial \mathbf{x}} = \frac{\partial \begin{pmatrix} \mathbf{y}_1^\top \mathbf{u} \\ \vdots \\ \mathbf{y}_d^\top \mathbf{u} \end{pmatrix}}{\partial \mathbf{x}} \stackrel{(c)}{=} \begin{pmatrix} \mathbf{y}_1^\top \frac{\partial \mathbf{u}}{\partial \mathbf{x}} + \mathbf{u}^\top \frac{\partial \mathbf{y}_1}{\partial \mathbf{x}} \\ \vdots \\ \mathbf{y}_d^\top \frac{\partial \mathbf{u}}{\partial \mathbf{x}} + \mathbf{u}^\top \frac{\partial \mathbf{y}_d}{\partial \mathbf{x}} \end{pmatrix}$$

(e) Note for  $\mathbf{y} : \mathbb{R}^d \rightarrow \mathbb{R}^d, \mathbf{x} \mapsto \mathbf{y}(\mathbf{x})$  the  $i$ -th column of  $\frac{\partial \mathbf{y}}{\partial \mathbf{x}}$  is  $\frac{\partial \mathbf{y}}{\partial x_i}$ . With this it follows that

$$\begin{aligned} \frac{\partial^2 \mathbf{u}^\top \mathbf{v}}{\partial \mathbf{x} \partial \mathbf{x}^\top} &= \frac{\partial}{\partial \mathbf{x}} \left( \frac{\partial \mathbf{u}^\top \mathbf{v}}{\partial \mathbf{x}^\top} \right) \\ &= \frac{\partial}{\partial \mathbf{x}} \left[ \left( \frac{\partial \mathbf{u}^\top \mathbf{v}}{\partial \mathbf{x}} \right)^\top \right] \\ &\stackrel{(c)}{=} \frac{\partial (\mathbf{u}^\top \frac{\partial \mathbf{v}}{\partial \mathbf{x}} + \mathbf{v}^\top \frac{\partial \mathbf{u}}{\partial \mathbf{x}})^\top}{\partial \mathbf{x}} \\ &= \frac{\partial \left( \left( \frac{\partial \mathbf{v}}{\partial \mathbf{x}} \right)^\top \mathbf{u} + \left( \frac{\partial \mathbf{u}}{\partial \mathbf{x}} \right)^\top \mathbf{v} \right)}{\partial \mathbf{x}} \\ &\stackrel{(d)}{=} \begin{pmatrix} \mathbf{u}^\top \frac{\partial^2 \mathbf{v}}{\partial x_1 \partial \mathbf{x}} + \frac{\partial \mathbf{v}}{\partial x_1}^\top \frac{\partial \mathbf{u}}{\partial \mathbf{x}} \\ \vdots \\ \mathbf{u}^\top \frac{\partial^2 \mathbf{v}}{\partial x_d \partial \mathbf{x}} + \frac{\partial \mathbf{v}}{\partial x_d}^\top \frac{\partial \mathbf{u}}{\partial \mathbf{x}} \end{pmatrix}^\top + \begin{pmatrix} \mathbf{v}^\top \frac{\partial^2 \mathbf{u}}{\partial x_1 \partial \mathbf{x}} + \frac{\partial \mathbf{u}}{\partial x_1}^\top \frac{\partial \mathbf{v}}{\partial \mathbf{x}} \\ \vdots \\ \mathbf{v}^\top \frac{\partial^2 \mathbf{u}}{\partial x_d \partial \mathbf{x}} + \frac{\partial \mathbf{u}}{\partial x_d}^\top \frac{\partial \mathbf{v}}{\partial \mathbf{x}} \end{pmatrix}^\top \\ &= \begin{pmatrix} \mathbf{u}^\top \frac{\partial^2 \mathbf{v}}{\partial x_1 \partial \mathbf{x}} \\ \vdots \\ \mathbf{u}^\top \frac{\partial^2 \mathbf{v}}{\partial x_d \partial \mathbf{x}} \end{pmatrix}^\top + \frac{\partial \mathbf{u}}{\partial \mathbf{x}} \left( \frac{\partial \mathbf{v}}{\partial \mathbf{x}} \right)^\top + \frac{\partial \mathbf{v}}{\partial \mathbf{x}} \left( \frac{\partial \mathbf{u}}{\partial \mathbf{x}} \right)^\top + \begin{pmatrix} \mathbf{v}^\top \frac{\partial^2 \mathbf{u}}{\partial x_1 \partial \mathbf{x}} \\ \vdots \\ \mathbf{v}^\top \frac{\partial^2 \mathbf{u}}{\partial x_d \partial \mathbf{x}} \end{pmatrix}^\top \end{aligned}$$

**Solution 2:**

## Optimality in 1d

Let  $f : [-1, 2] \rightarrow \mathbb{R}, x \mapsto \exp(x^3 - 2x^2)$

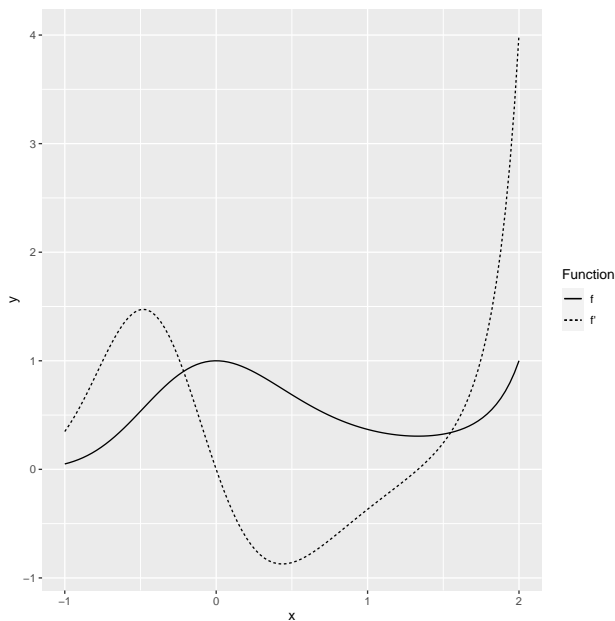
$$(a) f'(x) = \exp(x^3 - 2x^2) \cdot (3x^2 - 4x)$$

(b) `library(ggplot2)`

```
f <- function(x) exp(x^3 - 2*x^2)
df <- function(x) f(x) * (3*x^2 - 4*x)
```

```
ggplot(data.frame(x = seq(-1, 2, by=0.005)), aes(x)) +
```

```
geom_function(fun = f, aes(linetype = "f")) +  
geom_function(fun = df, aes(linetype = "f'")) +  
scale_linetype_discrete(name = "Function")
```



(c)  $f$  is continuously differentiable  $\Rightarrow$  candidates can only be stationary points and boundary points.

Find stationary points, i.e., points where

$$f'(x) = 0 \iff \underbrace{\exp(x^3 - 2x^2)}_{>0} \cdot (3x^2 - 4x) = 0 \iff 3x^2 - 4x = 0 \iff x(3x - 4) = 0.$$

$\Rightarrow x_1 = 0, x_2 = 4/3$ . The other candidates are boundary points, i.e.,  $x_3 = -1, x_4 = 2$ .

(d)  $f''(x) = \exp(x^3 - 2x^2) \cdot (3x^2 - 4x)^2 + \exp(x^3 - 2x^2) \cdot (6x - 4)$

(e)  $f''(x_1) = \exp(0) \cdot (-4) < 0$

$\Rightarrow x_1$  is a local maximum

$$f''(x_2) = \exp((4/3)^3 - 2(4/3)^2) \cdot (4) > 0$$

$\Rightarrow x_2$  is a local minimum.

The boundary points  $x_3$  and  $x_4$  are not considered as *local* optima.

(f)  $f(x_1) = \exp(0) = 1$

$$f(x_2) = \exp((4/3)^3 - 2(4/3)^2) \approx 0.3057$$

$$f(x_3) = \exp(-3) \approx 0.05$$

$$f(x_4) = \exp(0) = 1$$

$\Rightarrow x_1, x_4$  are global maxima.  $x_3$  is global minimum.