## Linear Algebra

Chapter 1: Matrices and Gaussian Elimination

Solution of highlighted problems

2. Solve to find a combination of the columns that equals b:

14. For two linear equations in three unknowns x, y, z, the row picture will show (2 or 3) (lines or planes) in (two or three)-dimensional space. The column picture is in (two or three)-dimensional space. The solutions normally lie on a . .

a strengl+ hime.

22. If (a,b) is a multiple of (c,d) with  $abcd \neq 0$ , show that (a,c) is a multiple of (b,d). This is surprisingly important: call it a challenge question. You could use numbers first to see how a, b, c, and d are related. The question will lead to:

If  $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$  has dependent rows then it has dependent columns.

$$C = C_1 \alpha \quad d = C_1 b$$

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \longrightarrow E_{21} A = \begin{bmatrix} 1 & 0 \\ -C_1 & 1 \end{bmatrix} \begin{bmatrix} a & b \\ c & d \end{bmatrix} = \begin{bmatrix} a & b \\ 0 & 0 \end{bmatrix}$$

$$\chi_1 \begin{bmatrix} a \\ 0 \end{bmatrix} + \chi_2 \begin{bmatrix} b \\ 0 \end{bmatrix} \leq \begin{bmatrix} 0 \\ 0 \end{bmatrix} \longrightarrow \chi_{1=-b}, \chi_{2=-a}$$
Hence the Column are linearly dependent

What multiple ℓ of equation 1 should be subtracted from equation 2?

$$2x + 3y = 1$$
  
 $10x + 9y = 11$ .

After this elimination step, write down the upper triangular system and circle the two pivots. The numbers 1 and 11 have no influence on those pivots.

2. Solve the triangular system of Problem 1 by back-substitution, y before x. Verify that x times (2, 10) plus y times (3,9) equals (1,11). If the right-hand side changes to (4,44), what is the new solution?

$$\begin{bmatrix} 2 & 3 \\ 10 & 9 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 1 \\ 11 \end{bmatrix}$$

Augmented form
$$[A;B] = \begin{bmatrix} 2 & 3 & 1 \\ 10 & 9 & 11 \end{bmatrix} \longrightarrow E_{21}[A;B] = \begin{bmatrix} 1 & 0 \\ -5 & 1 \end{bmatrix}\begin{bmatrix} 2 & 3 & 1 \\ 10 & 9 & 11 \end{bmatrix} = \begin{bmatrix} 2 & 3 & 1 \\ 0 & -6 & 6 \end{bmatrix}$$

Back-Substitution
$$2x + 3y = 1$$

$$-6y = 6$$

$$-7 y = -1, x = 2$$

12. Which number d forces a row exchange, and what is the triangular system (not singular) for that d? Which d makes this system singular (no third pivot)?

$$2x + 5y + z = 0$$
  
 $4x + dy + z = 2$   
 $y - z = 3$ 

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Augmented form 
$$\rightarrow A \begin{bmatrix} 2 & 5 & 1 & 0 \\ 4 & d & 1 & 2 \\ 0 & 1 & -1 & 3 \end{bmatrix} = [A:B]$$

$$E_{2}$$
 [A]B] =  $\begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$   $\begin{bmatrix} 2 & 5 & 1 & 0 \\ 4 & d & 1 & 2 \\ 0 & 1 & 1 & 3 \end{bmatrix}$  =  $\begin{bmatrix} 2 & 5 & 1 & 0 \\ 0 & d & 10 & 1 & 2 \\ 0 & 1 & -1 & 3 \end{bmatrix}$ 

$$-7 ds 10$$
  $P_{23} = \{2, [A(B)] = \begin{bmatrix} 4 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 2 & 5 & 1 & 0 \\ 0 & 1 & -1 & 3 \\ 0 & 0 & -1 \end{bmatrix}$ 

to make the matrix Sigular

$$A = \begin{bmatrix} 2 & 5 & 1 & 0 \\ 0 & d-10 & 1 & 2 \\ 0 & 1 & -1 & 3 \end{bmatrix} \longrightarrow rd=11 \quad E_{32}A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -1 & 1 \end{bmatrix} A = \begin{bmatrix} 2 & 5 & 1 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \end{bmatrix}$$
Signlar mestrix

## Problem set 1.3

The first row of AB is a linear combination of all the rows of B. What are the coefficients in this combination, and what is the first row of AB, if

$$A = \begin{bmatrix} 2 & 1 & 4 \\ 0 & -1 & 1 \end{bmatrix} \quad \text{and} \quad B = \begin{bmatrix} 1 & 1 \\ 0 & 1 \\ 1 & 0 \end{bmatrix}?$$

$$A = \begin{bmatrix} 2 & 4 \\ 0 & 1 \end{bmatrix}$$

$$B = \begin{bmatrix} 117 \\ 01 \end{bmatrix}$$

20. The matrix that rotates the x-y plane by an angle  $\theta$  is

$$A(\theta) = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}.$$

Verify that  $A(\theta_1)A(\theta_2) = A(\theta_1 + \theta_2)$  from the identities for  $\cos(\theta_1 + \theta_2)$  and  $\sin(\theta_1 + \theta_2)$ . What is  $A(\theta)$  times  $A(-\theta)$ ?

$$A(\theta) = \begin{bmatrix} G(\theta - \sin\theta) \\ Sin\theta & G(\theta) \end{bmatrix}$$

$$A(\theta_1) A(\theta_2) = \begin{bmatrix} C_1\theta_1 & -Sin\theta_1 \\ Sin\theta_1 & G(\theta_1) \end{bmatrix} \begin{bmatrix} C_1\theta_2 & -Sin\theta_2 \\ Sin\theta_2 & C_1\theta_1 \end{bmatrix}$$

$$= \begin{bmatrix} G(\theta_1, C_1\theta_2 - \sin\theta_1) & -G(\theta_1, \sin\theta_2 - \sin\theta_1, C_1\theta_2) \\ Sin\theta_1, C_1\theta_2 + C_1\theta_1, Sin\theta_2 & -Sin\theta_1, Sin\theta_1 + C_1\theta_1, C_1\theta_1 \end{bmatrix}$$

$$= \begin{bmatrix} G(\theta_1 + \theta_2) & -Sin(\theta_1 + \theta_2) \\ Sin(\theta_1 + \theta_2) & -Sin(\theta_1 + \theta_2) \end{bmatrix} = A(\theta_1 + \theta_2)$$

$$A(\theta) A(-\theta) = \begin{bmatrix} C_1\theta & -Sin\theta \\ Sin\theta & C_1\theta \end{bmatrix} \begin{bmatrix} C_1(\theta_1 + \theta_2) \\ Sin(\theta_1 + \theta_2) \end{bmatrix} = A(\theta_1 + \theta_2)$$

$$= \begin{bmatrix} G^2\theta + Sin^2\theta & Sin\theta G(\theta_1 + G(\theta_1)) \\ Sin\theta C_1\theta_2 + C_1\theta_1 \end{bmatrix} = I$$

$$A(-\theta) = A(\theta)$$

## Problem set 1.4

4. Apply elimination to produce the factors L and U for

$$A = \begin{bmatrix} 2 & 1 \\ 8 & 7 \end{bmatrix} \quad \text{and} \quad A = \begin{bmatrix} 3 & 1 & 1 \\ 1 & 3 & 1 \\ 1 & 1 & 3 \end{bmatrix} \quad \text{and} \quad A = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 4 & 4 \\ 1 & 4 & 8 \end{bmatrix}.$$

$$E_{21} E_{21} E_{21} A_{3} \left(\begin{array}{c} 1 & 1 & 1 \\ 1 & 4 & 8 \end{array}\right) \longrightarrow E_{21} \left(\begin{array}{c} 1 & 1 & 1 \\ 0 & 3 & 3 \\ 1 & 4 & 8 \end{array}\right)$$

$$E_{31} E_{32} E_{31} E_{21} A_{3} \left(\begin{array}{c} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 1 & 1 \end{array}\right) \left(\begin{array}{c} 1 & 1 & 1 \\ 0 & 3 & 3 \\ 0 & 3 & 7 \end{array}\right)$$

$$E_{32} E_{31} E_{21} A_{3} \left(\begin{array}{c} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 1 & 1 \end{array}\right) \left(\begin{array}{c} 1 & 1 & 1 \\ 0 & 3 & 3 \\ 0 & 3 & 7 \end{array}\right) = 0$$

$$F_{21} \left(\begin{array}{c} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 0 & 1 & 1 \end{array}\right) \left(\begin{array}{c} 1 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 1 & 1 \end{array}\right) \left(\begin{array}{c} 1 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 1 & 1 \end{array}\right) = 1$$

Use the Gauss-Jordan method to invert

$$A_1 = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix},$$

$$A_1 = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix}, \qquad A_2 = \begin{bmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 2 \end{bmatrix}, \qquad A_3 = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}.$$

$$A_3 = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}.$$

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$$\frac{P_{2} \cdot P_{2} \cdot P_{3}}{P_{1} \cdot P_{2} \cdot P_{3}} = \frac{P_{1} \cdot P_{2}}{P_{1} \cdot P_{2}} = \frac{P_{1} \cdot P_{2}}{P_{2} \cdot P_{3}} = \frac{P_{1} \cdot P_{2}}{P_{2} \cdot P_{3}} = \frac{P_{1} \cdot P_{2}}{P_{1} \cdot P_{3}} = \frac{P_{1} \cdot P_{2}}{P_{1} \cdot P_{3}} = \frac{P_{1} \cdot P_{3}}{P_{1} \cdot P_{3}} = \frac{P_{1} \cdot P_{3}}{P_{1}} = \frac{P_{1} \cdot P_{3}}{P_{1} \cdot P_{3}} = \frac{P_{1} \cdot P_{3}}{P_{1} \cdot$$

Compute the symmetric LDL<sup>T</sup> factorization of

$$A = \begin{bmatrix} 1 & 3 & 5 \\ 3 & 12 & 18 \\ 5 & 18 & 30 \end{bmatrix}$$
 and  $A = \begin{bmatrix} a & b \\ b & d \end{bmatrix}$ .

b) 
$$A = \begin{bmatrix} a & b \\ b & d \end{bmatrix} \longrightarrow E_{21} = \begin{bmatrix} 1 & 0 \\ -\frac{b}{a} & 1 \end{bmatrix} \longrightarrow E_{21} A = \begin{bmatrix} a & b \\ 0 & d - \frac{b^2}{a} \end{bmatrix}$$

$$E_{2i} = L = \begin{bmatrix} 1 & 0 \\ \frac{b}{a} & 1 \end{bmatrix}$$
  $\rightarrow A = LOL^{T} \Rightarrow \begin{bmatrix} a & b \\ b & d \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ \frac{b}{a} & 1 \end{bmatrix} \begin{bmatrix} a & 0 \\ 0 & d-b/a \end{bmatrix}$ 

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a) 
$$A = \begin{bmatrix} 1 & 3 & 5 \\ 3 & 12 & 18 \\ 5 & 18 & 30 \end{bmatrix}$$
 —> symmetric

$$E_{21} = \begin{bmatrix} 1 & 8 & 6 \\ -3 & 1 & 0 \end{bmatrix}$$
 —>  $E_{21}A$ :

$$E_{21} = \begin{bmatrix} 1 & 3 & 6 \\ -3 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \longrightarrow E_{21}A_{5} \begin{bmatrix} 1 & 3 & 5 \\ 0 & 3 & 3 \\ \hline 5 & 18 & 36 \end{bmatrix} \qquad E_{31} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ \hline -5 & 0 & 1 \end{bmatrix}$$

$$E_{31}A_{5} \begin{bmatrix} 1 & 3 & 5 \\ 0 & 3 & 3 \\ 0 & 3 & 5 \end{bmatrix} \longrightarrow E_{32} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ \hline 0 & -1 & 1 \end{bmatrix} \longrightarrow E_{32}E_{31}E_{21}A_{5} \begin{bmatrix} 1 & 3 & 5 \\ 0 & 3 & 3 \\ \hline 0 & 0 & 2 \end{bmatrix}$$

$$E_{21} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 3 & 5 \\ \hline 0 & 3 & 5 \end{bmatrix} \longrightarrow \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ \hline 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ \hline 0 & 1 & 0 \end{bmatrix}$$

$$E_{21} = E_{31} = \begin{bmatrix} 1 & 0 & 0 \\ 3 & 1 & 6 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 1 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 & 0 \\ 3 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ \hline \mathbf{S} & 1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 3 & 1 & 0 \\ \hline \mathbf{S} & 1 & 1 \end{bmatrix} = \mathbf{L}$$

$$A = LDL^{T} \longrightarrow \begin{bmatrix} 1 & 3 & 5 \\ 3 & 12 & 18 \\ 5 & 18 & 30 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 3 & 1 & 0 \\ 5 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

41. For which three numbers c is this matrix not invertible, and why not?

$$A = \begin{bmatrix} 2 & c & c \\ c & c & c \\ 8 & 7 & c \end{bmatrix}.$$

## Thanks for your attention