

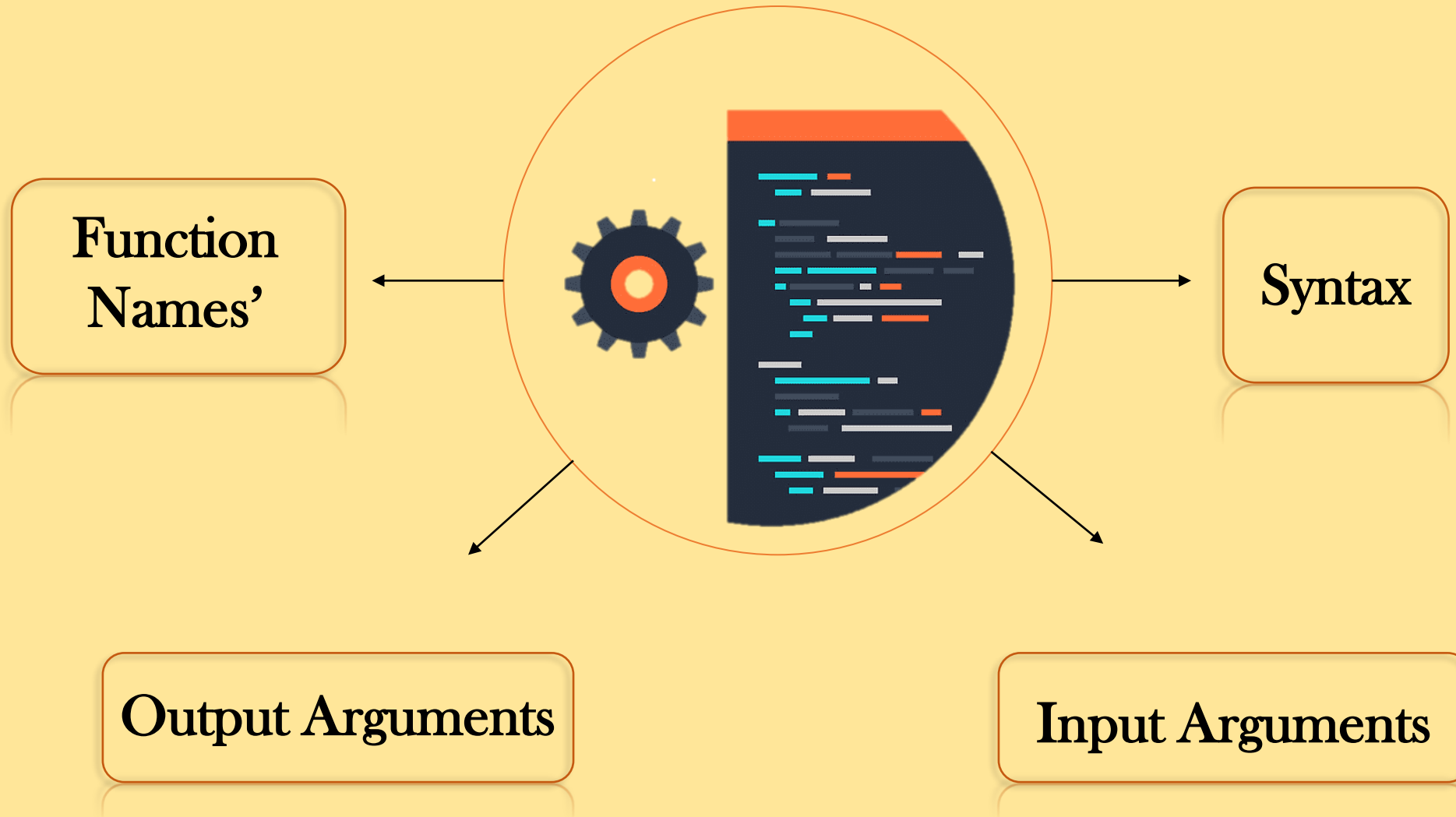
MATLAB

*Linear Programing Problems
(LP)*

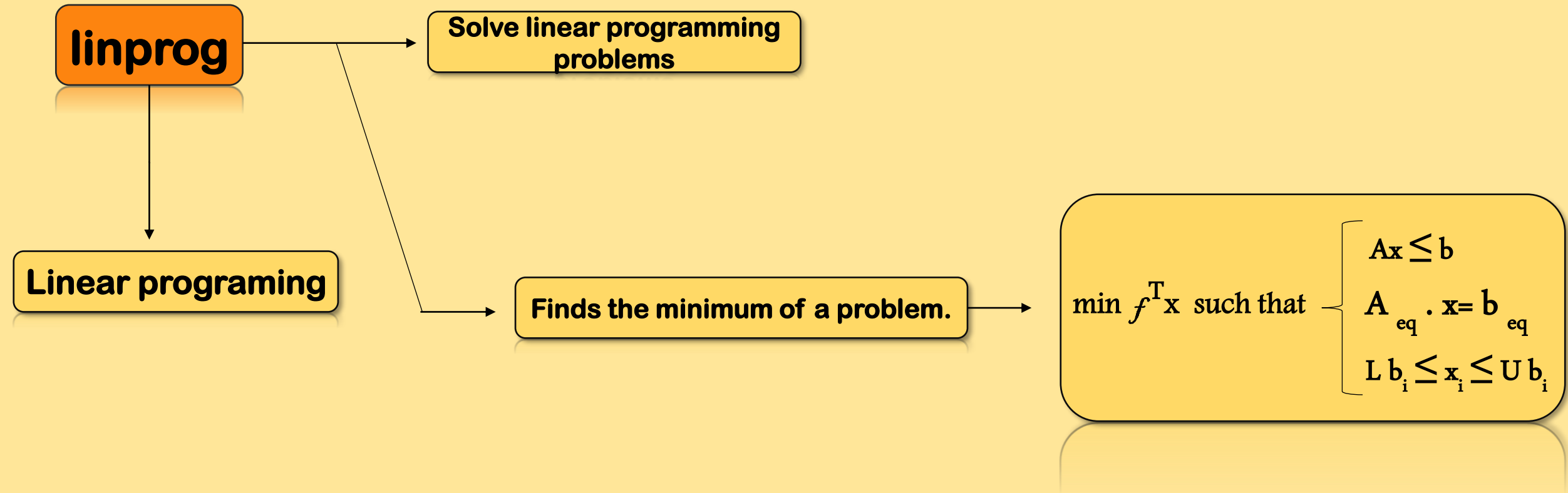


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1 What you'll learn



2 Function Name



$X = \text{linprog}(f, A, b)$

$X = \text{linprog}(f, A, b, A_{\text{eq}}, b_{\text{eq}}, lb, ub)$

$X = \text{linprog}(f, A, b, A_{\text{eq}}, b_{\text{eq}}, lb, ub, \text{options})$

$[X, fval] = \text{linprog}(\text{---})$ **input**

$[X, fval, \text{exitflag}, \text{output}] = \text{linprog}(\text{---})$

$[X, fval, \text{exitflag}, \text{output}, \text{lambda}] = \text{linprog}(\text{---})$

output

Objective Function & Constraints

$$\min Z = \sum_{i=1}^n f_i x_i \xrightarrow{\text{vector notation}} f^T x \quad \text{Objective Function}$$

$$Ax \leq b$$

$$A_{eq} = b_{eq}$$

$$L b_i \leq x_i \leq U b_i$$

Example

$$\min Z = -5x_1 - 4x_2 - 6x_3$$

S . t .

$$x_1 - x_2 + x_3 \leq 20$$

$$3x_1 + 2x_2 + 4x_3 \leq 42$$

$$3x_1 + 2x_2 \leq 30$$

$$x_1, x_2, x_3 \geq 0$$

$$X = \text{linprog}(f, A, b, A_{eq}, b_{eq}, lb, ub)$$

$$\min Z = -5x_1 - 4x_2 - 6x_3$$

$$\underbrace{[-5, -4, -6]}_{f^T} \cdot \underbrace{\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}}_X \longrightarrow f = \begin{bmatrix} -5 \\ -4 \\ -6 \end{bmatrix}$$

S . t .

$$x_1 - x_2 + x_3 \leq 20$$

$$3x_1 + 2x_2 + 4x_3 \leq 42$$

$$3x_1 + 2x_2 \leq 30$$

$$\begin{matrix} & \underbrace{\hspace{10em}} & & \underbrace{\hspace{10em}} & & \underbrace{\hspace{10em}} \\ & A & & X & & b \\ & \geq & & & & \\ \left(\begin{array}{ccc} 1 & -1 & 1 \\ 3 & 2 & 4 \\ 3 & 2 & 0 \end{array} \right) & & \left(\begin{array}{c} x_1 \\ x_2 \\ x_3 \end{array} \right) & & \left(\begin{array}{c} 20 \\ 42 \\ 30 \end{array} \right) \\ & & \geq & & \end{matrix}$$

$$x_1, x_2, x_3 \geq 0$$

$$x_1 \geq 0$$

$$lb_1 \geq 0$$

$$x_2 \geq 0$$



$$lb_2 \geq 0$$



$$lb =$$

$$\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

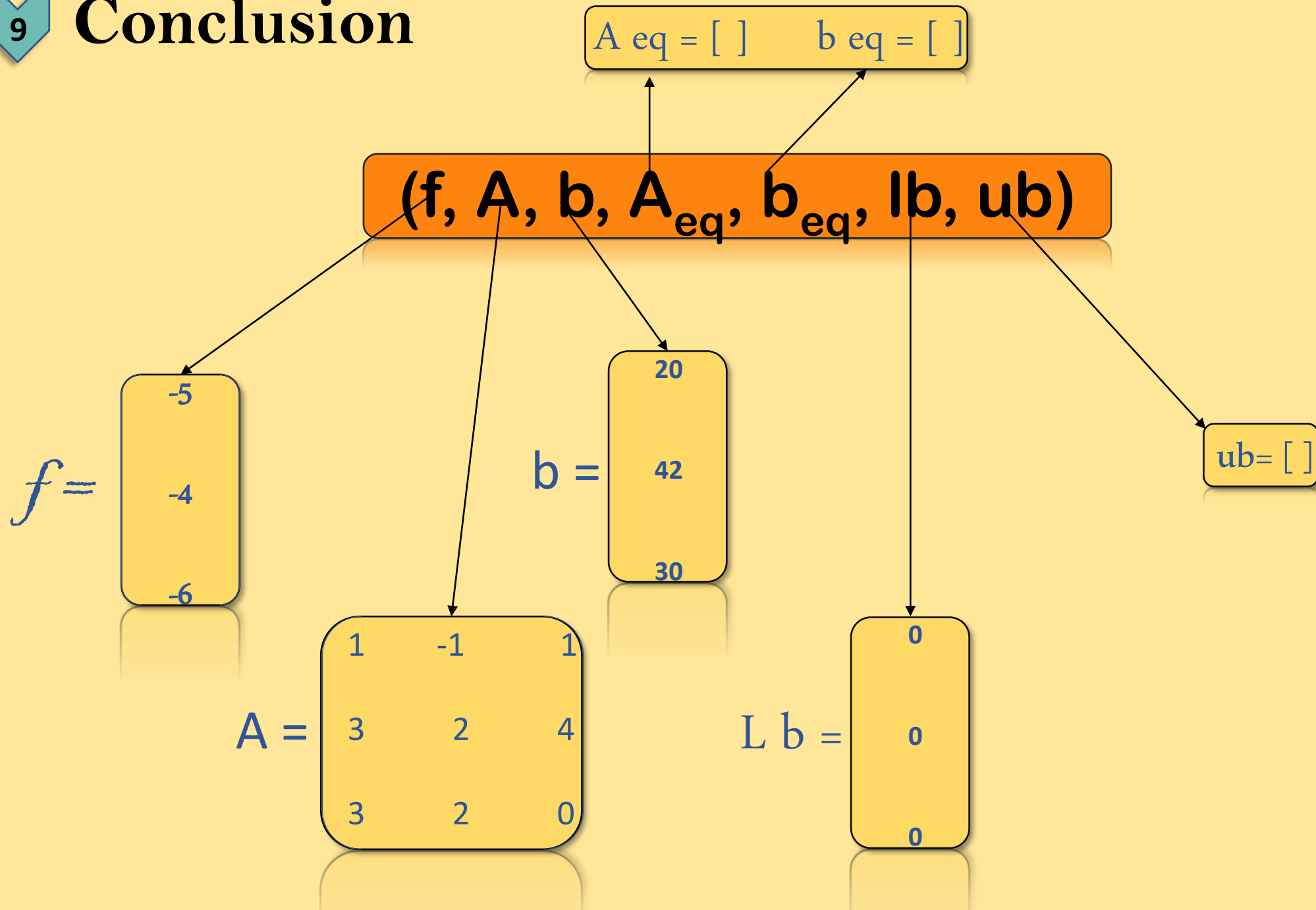


Zeros (n,1)

$$x_3 \geq 0$$

$$lb_3 \geq 0$$










Conclusion



exitflag

exitflag — Reason linprog stopped
integer

Reason linprog stopped, returned as an integer.







3		The solution is feasible with respect to the relative ConstraintTolerance tolerance, but is not feasible with respect to the absolute tolerance.
1		Function converged to a solution x.
0		Number of iterations exceeded options.MaxIterations or solution time in seconds exceeded options.MaxTime.
-2		No feasible point was found.
-3		Problem is unbounded.
-4		NaN value was encountered during execution of the algorithm.
-5		Both primal and dual problems are infeasible.
-7		Search direction became too small. No further progress could be made
-9		Solver lost feasibility.

Exitflags 3 and -9 relate to solutions that have large infeasibilities. These usually arise from linear constraint matrices that have large condition number, or problems that have large solution components. To correct these issues, try to scale the coefficient matrices, eliminate redundant linear constraints, or give tighter bounds on the variables.

11 output

✓ output — Information about the optimization process
structure

Information about the optimization process, returned as a structure with these fields.

iterations		Number of iterations
algorithm		Optimization algorithm used
cgiterations		0 (interior-point algorithm only, included for backward compatibility)
message		Exit message
constrviolation		Maximum of constraint functions
firstorderopt		First-order optimality measure

12 lambda

✓ lambda — Lagrange multipliers at the solution structure

Lagrange multipliers at the solution, returned as a structure with these fields.

lower	Lower bounds corresponding to <code>lb</code>
upper	Upper bounds corresponding to <code>ub</code>
ineqlin	Linear inequalities corresponding to <code>A</code> and <code>b</code>
eqlin	Linear equalities corresponding to <code>Aeq</code> and <code>beq</code>

Options



options — Optimization options

output of `optimoptions` | structure as `optimset` returns

Optimization options, specified as the output of `optimoptions` or a structure as `optimset` returns.

Some options apply to all algorithms, and others are relevant for particular algorithms. See [Optimization Options Reference](#) for detailed information.

Some options are absent from the `optimoptions` display. These options appear in *italics* in the following table. For details, see [View Options](#).

All Algorithms

Algorithm	<p>Choose the optimization algorithm:</p> <ul style="list-style-type: none"> 'dual-simplex' (default) 'interior-point-legacy' 'interior-point' <p>For information on choosing the algorithm, see Linear Programming Algorithms.</p>
Diagnostics	Display diagnostic information about the function to be minimized or solved. Choose 'off' (default) or 'on'.
Display	<p>Level of display (see Iterative Display):</p> <ul style="list-style-type: none"> 'final' (default) displays just the final output. 'off' or 'none' displays no output. 'iter' displays output at each iteration.
MaxIterations	<p>Maximum number of iterations allowed, a positive integer. The default is:</p> <ul style="list-style-type: none"> 85 for the 'interior-point-legacy' algorithm 200 for the 'interior-point' algorithm $10 \times (\text{numberOfEqualities} + \text{numberOfInequalities} + \text{numberOfVariables})$ for the 'dual-simplex' algorithm <p>See Tolerances and Stopping Criteria and Iterations and Function Counts.</p> <p>For <code>optimset</code>, the name is <code>MaxIter</code>. See Current and Legacy Option Name Tables.</p>

Example of the feasible region

$$\max Z = 143x + 60y$$

S . t .

$$x + y \leq 75$$

$$110x + 30y \leq 4000$$

$$120x + 210y \leq 15000$$

$$x, y \geq 0$$

$$f = \begin{pmatrix} 143 \\ 60 \end{pmatrix}$$

$$A = \begin{pmatrix} 1 & 1 \\ 110 & 30 \\ 120 & 210 \end{pmatrix}$$

$$b = \begin{pmatrix} 75 \\ 4000 \\ 15000 \end{pmatrix}$$

$$Lb = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

**OPTIMIZATION
PROCESS**