

In The Name of God.  
The Merciful, The Compassionate.

# Orthogonal Vectors and Subspaces, Projecting into subspaces

notes on Gilbert Strang videos, Lecture 14-16

## 1 Orthogonality

- Columnspace  $\perp$  nullspace of  $A^T$
- Orthogonal vectors:  $x^T y = 0$
- Subspace  $\mathcal{S}$  is orthogonal to subspace  $\mathcal{T}$  means: every vector in  $\mathcal{S}$  is perpendicular to every vector in  $\mathcal{T}$

- Row space  $\perp$  nullspace:

$$Ax = 0, \begin{bmatrix} \text{---} & \text{row}_1 & \text{---} \\ \text{---} & \text{row}_2 & \text{---} \\ & \vdots & \\ \text{---} & \text{row}_m & \text{---} \end{bmatrix} x = 0, \text{ so, } x \text{ is orthogonal to each}$$

row. Easy to see row combinations is also orthogonal.

- Row space and nullspace are orthogonal complement: nullspace contains all vectors  $\perp$  to row space.

## 2 Projection

- Projection of a vector  $b$  onto a line  $a$ :

–  $p$  is the projection of  $b$

–  $e$  is error,  $e = b - p$ ,  $p \parallel a$

–  $\Rightarrow p = xa$

–  $a^T(b - xa) = 0 \Rightarrow xa^T a = a^T b \Rightarrow x = \frac{a^T b}{a^T a}, p = a \frac{a^T b}{a^T a}$

– Projection Matrix =  $Pb$ ,  $P = \frac{aa^T}{a^T a}$

–  $C(P)$  : line through  $a$ ,  $\text{rank}(P) = 1$

– Two properties of projection matrices:

1.  $P^T = P$

2.  $P^2 = P$

- Solve  $Ax = b$  when there is no solution (e.g.,  $m > n$ ):

- $A^T A$  is  $n \times n$  and symmetric,
- $A^T A \hat{x} = A^T b$ ,  $\hat{x}$  shows estimation
- $N(A^T A) = N(A)$
- $\text{rank}(A^T A) = \text{rank}(A) \Rightarrow A^T A$  is invertible if  $A$  has independent columns
- solve  $A\hat{x} = p$ ,  $p$  is projection of  $b$  onto columnspace
- again  $e = b - p$
- $b - A\hat{x}$  is  $\perp$  to columnspace  $\Rightarrow A^T(b - A\hat{x}) = 0$ ,  
 (imagine columns of  $A = \begin{bmatrix} | & | & \dots & | \\ a_1 & a_2 & \dots & a_n \\ | & | & \dots & | \end{bmatrix}$  are its bases  $\Rightarrow$  each of its columns must be  $\perp$  to  $e$ . So,  $a_1^T e = 0, \dots, a_n^T e = 0 \Rightarrow A^T e = 0$ )
- $e$  is in nullspace of  $A^T \Rightarrow e \perp C(A)$ , YES!
- So,  $A^T A \hat{x} = A^T b \Rightarrow \hat{x} = (A^T A)^{-1} A^T b$
- $p = A\hat{x} = A(A^T A)^{-1} A^T b$ ,  $P = A(A^T A)^{-1} A^T$
- If  $b$  is in columnspace:  $Pb = b \Leftarrow b$  has the form  $Ax$ , substitute by formulae of  $P$
- If  $b \perp$  columnspace:  $Pb = 0 \Leftarrow b$  is in nullspace of  $A^T$ , substitute by formulae of  $P$
- $p + e = b, p = Pb \Rightarrow e = (I - P)b$ ,
- $I - P$ : proj to perpendicular space

- Least Squares: e.g., 2D:

- $y = C + Dt$ , and we have  $(a_i, b_i)$  for  $i$  in  $[1 - 3]$ .

- Equations are:  $C + Da_i = b_i \Rightarrow Ax = b$ ,  $\begin{bmatrix} \vdots & \vdots \\ 1 & a_i \\ \vdots & \vdots \end{bmatrix} \begin{bmatrix} C \\ D \end{bmatrix} = \begin{bmatrix} \vdots \\ b_i \\ \vdots \end{bmatrix}$

: no solution

- Minimize:  $\|Ax - b\|^2 = \|e\|^2 = \sum_i e_i^2$

- $p_i$  are points on the line:  $p + e = b$  ( if  $p$  was in the place of  $b$ , the equation could be solved. So, it is in the column space of  $A$ .
- to find  $p$ ,  $\hat{x} = \begin{bmatrix} \hat{C} \\ \hat{D} \end{bmatrix}$ :  
 $A^T A \hat{x} = A^T b \rightarrow$  find  $\hat{x} \rightarrow$  best line  $\rightarrow p_i \rightarrow e_i$
- Note:  $e$  is perpendicular to  $p$  and columns of  $A$
- If  $A$  has independent columns, then  $A^T A$  is invertible:
  1. Suppose  $A^T A x = 0$ , So,  $x$  must be zero ( nullspace is only the zero vector)
  2. IDEA:  $x^T A^T A x = 0 \Rightarrow (Ax)^T (Ax) = 0 \Rightarrow Ax = 0$   
columns of  $A$  are independent  $\Rightarrow x = 0$