

Department of Computer Science & Engineering

Course Title: Artificial Intelligence & Expert System Lab

Course Code: CSE 404

Assignment No: 02

**Assignment On, Implementation of a small Address Map
(from your home to UAP) using A* Search Algorithm**

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Problem Title: Optimal Path Finding from Home to UAP Using A* Search Algorithm

Problem Description: The objective of this assignment was to implement the A* search algorithm to find the optimal path from a starting location ("Home") to a destination ("UAP") based on a provided graph of locations and their distances.

A* search algorithm formula,

$$f(n) = g(n) + h(n)$$

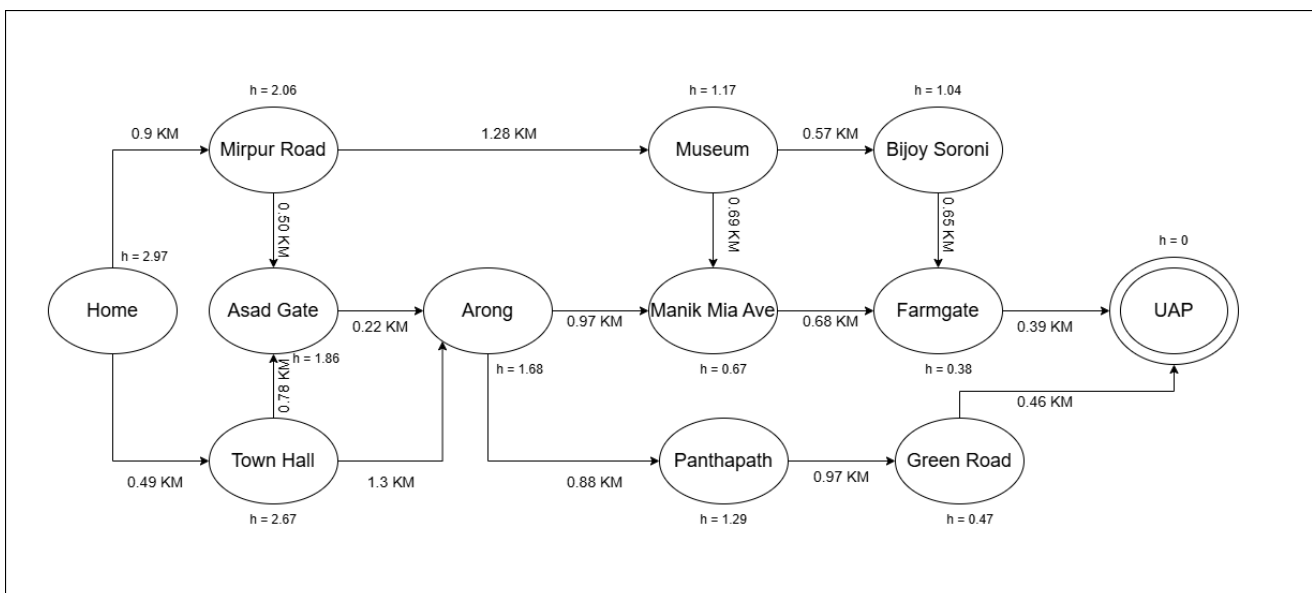
Where,

$f(n)$ = Estimated cost from path n node to goal node

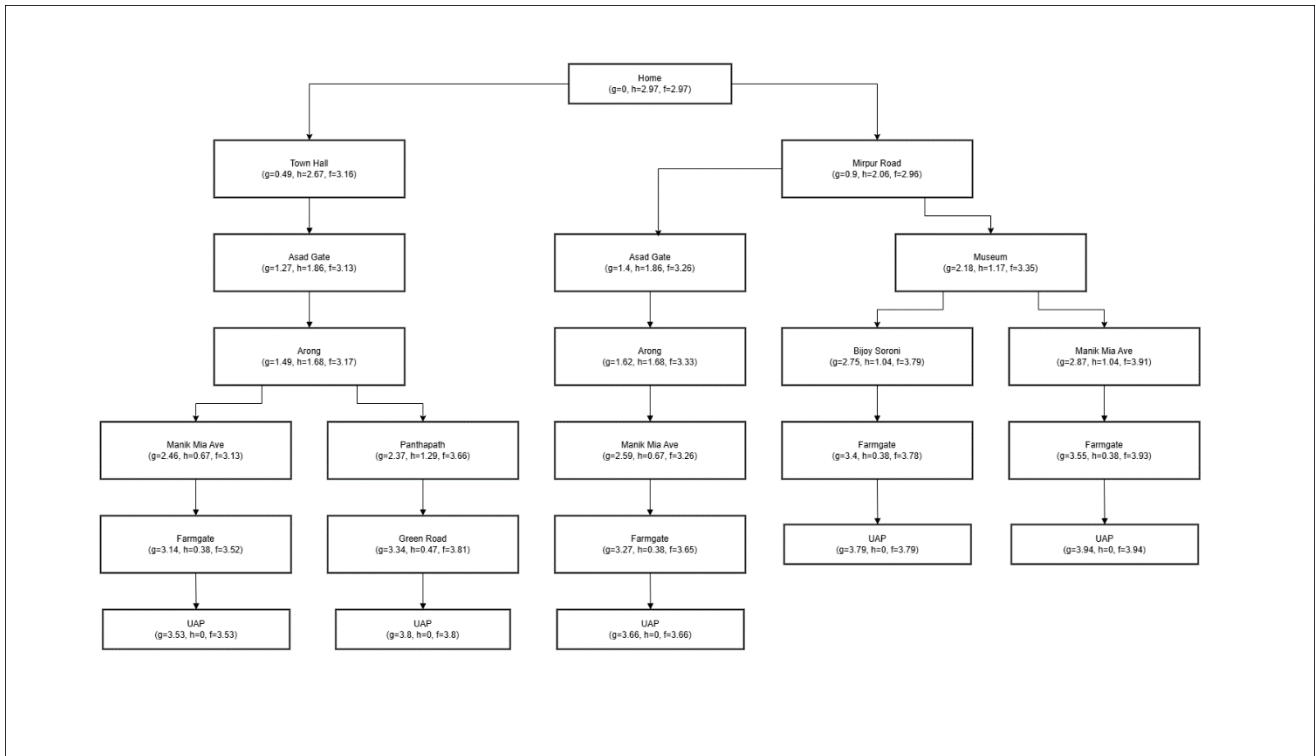
$g(n)$ = Actual Cost from start node to n-node

$h(n)$ = Estimated Cost from n-node to goal node

Designed Map:



Search Tree:



Source Code:

```
A_star_search.py > a_star_search
1 import heapq
2 from itertools import count
3
4 def a_star_search(graph, heuristics, start, goal):
5     pq = []
6     heapq.heappush(pq, (0 + heuristics[start], start, [start], 0))
7     visited = set()
8
9     while pq:
10         f, current, path, g = heapq.heappop(pq)
11
12         if current in visited:
13             continue
14         visited.add(current)
15
16         if current == goal:
17             return path, g
18
19         for neighbor, cost in graph[current].items():
20             if neighbor not in visited:
21                 new_g = g + cost
22                 new_f = new_g + heuristics[neighbor]
23                 heapq.heappush(pq, (new_f, neighbor, path + [neighbor], new_g))
24
25     return None, float('inf')
```

```

28 graph = {
29     'Home': {'Mirpur Road': 0.9, 'Town Hall': 0.49},
30     'Mirpur Road': {'Home': 0.9, 'Museum': 1.28, 'Asad Gate': 0.5},
31     'Asad Gate': {'Mirpur Road': 0.5, 'Arong': 0.22, 'Town Hall': 0.78},
32     'Town Hall': {'Home': 0.49, 'Arong': 1.3, 'Asad Gate': 0.78},
33     'Arong': {'Asad Gate': 0.22, 'Manik Mia Ave': 0.97, 'Town Hall': 1.3, 'Panthapath': 0.88},
34     'Museum': {'Mirpur Road': 1.28, 'Manik Mia Ave': 0.69, 'Bijoy Soroni': 0.57},
35     'Manik Mia Ave': {'Arong': 0.97, 'Museum': 0.69, 'Farmgate': 0.68},
36     'Panthapath': {'Arong': 0.88, 'Green Road': 0.97},
37     'Green Road': {'Panthapath': 0.97, 'UAP': 0.46},
38     'Bijoy Soroni': {'Museum': 0.57, 'Farmgate': 0.65},
39     'Farmgate': {'Bijoy Soroni': 0.65, 'Manik Mia Ave': 0.68, 'UAP': 0.39},
40     'UAP': {'Farmgate': 0.39, 'Green Road': 0.46}
41 }
42
43 heuristics = {
44     'Home': 2.97, 'Town Hall': 2.67, 'Mirpur Road': 2.06, 'Asad Gate': 1.86,
45     'Arong': 1.68, 'Museum': 1.17, 'Bijoy Soroni': 1.04, 'Manik Mia Ave': 0.67,
46     'Farmgate': 0.38, 'Panthapath': 1.29, 'Green Road': 0.47, 'UAP': 0.0
47 }
48
49 start, goal = 'Home', 'UAP'
50 path, cost = a_star_search(graph, heuristics, start, goal)
51 if path:
52     print("Optimal Path:", " -> ".join(path))
53     print(f"Total Cost: {cost:.2f} km")
54 else:
55     print(f"No path found from {start} to {goal}.")
56

```

Output:

```

[Running] python -u "d:\-Artificial-Intelligence-and-Expert-System-\A_star_search.py"
Optimal Path: Home -> Town Hall -> Asad Gate -> Arong -> Manik Mia Ave -> Farmgate -> UAP
Optimal Cost: 3.53 km

[Done] exited with code=0 in 0.052 seconds

```

Results:

The A* search algorithm successfully found the optimal path from "Home" to "UAP," with the following results:

- **Optimal Path:** "Home" → "Town Hall" → "Asad Gate" → "Arong" → "Manik Mia Ave" → "Farmgate" → "UAP"
- **Total Cost:** 3.53 km

This path and cost were derived by summing the individual edge distances along the route:

- Home to Town Hall: 0.49 km
- Town Hall to Asad Gate: 0.78 km
- Asad Gate to Arong: 0.22 km
- Arong to Manik Mia Ave: 0.97 km
- Manik Mia Ave to Farmgate: 0.68 km
- Farmgate to UAP: 0.39 km
- Total: $0.49 + 0.78 + 0.22 + 0.97 + 0.68 + 0.39 = 3.53$ km

Conclusion:

The assignment successfully demonstrated the application of the A* search algorithm to solve a pathfinding problem in a road network. The implementation found the optimal path from "Home" to "UAP" with a total cost of 3.53 km, which matched the expected distance based on the provided graph data.