

# Identifying and Tracking Solar Magnetic Flux Elements with Deep Learning

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## 1. Introduction

Deep learning has drawn significant interest in recent years due to its effectiveness in processing big and complex observational data gathered from diverse instruments. Here we propose a new deep learning method, called SolarUnet, to identify and track solar magnetic flux elements or features in observed vector magnetograms. SolarUnet is applied to data from the 1.6 meter Goode Solar Telescope at the Big Bear Solar Observatory.

In this notebook, we provide an overview of the SolarUnet tool, detailing how it can be used to identify and track solar magnetic flux elements.

## 2. Workflow of SolarUnet

### 2.1 Data Preparation

Import the `pre_processing()` function from the `solarunet` module.

Convert the SWAMIS 3-class masks to 2-class masks for model training. You may put your data into this directory.

```
In [1]: 1 from solarunet import pre_processing
        2 input_path = 'data/exmaple_data_preprocess/3_class/'
        3 output_path = 'data/exmaple_data_preprocess/2_class/'
        4 pre_processing(input_path, output_path)
```

```
integr_180607_161752.fts
integr_180607_161904.fts
```

### 2.2 Model Training and Testing

You may train the model with your own data (see Section 2.2.1) or directly use the pretrained model (see Section 2.2.2) for prediction and feature tracking.

#### 2.2.1 Training and Predicting

Import the `model_training()` and `model_predicting()` functions from the `solarunet` module.

The model is trained with the data prepared in Section 2.1 and tested on the given magnetograms. Please make sure your input data is in the given directory or you may create your own directory and modify the path. The predicted results will be saved in the given path.

```
In [2]: 1 # from solarunet import model_training, model_predicting
        2 # input_path = 'data/magnetic/'
        3 # output_path = 'results/predicted_mask/'
        4 # model_training(input_path)
        5 # model_predicting(input_path, output_path)
```

#### 2.2.2 Predicting with the Pretrained Model

Import the `model_predicting()` function from the `solarunet` module.

Predict the binary masks of the given magnetograms by using the pretrained model. We set the 3rd argument of `model_predicting()` as `True`. The predicted results will be saved in the given path.

```
In [3]: 1 from solarunet import model_predicting
        2 input_path = 'data/magnetic/'
        3 output_path = 'results/predicted_mask/'
        4 model_predicting(input_path, output_path, pretrain=True)
```

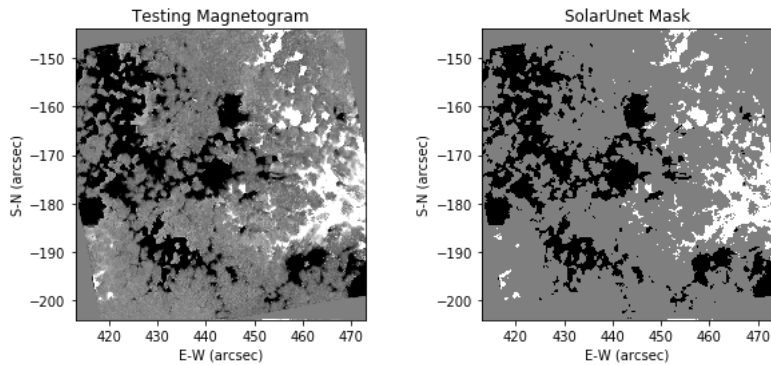
```
3/3 [=====] - 12s 4s/step
Prediction on the given data done
```

## 2.3 Postprocessing Data

Import the `post_processing()` and `plot_mask()` functions from the `solarunet` module.

Convert the predicted binary masks to 3-class masks and use the `plot_mask()` function to draw the SolarUnet masks of the testing magnetograms.

```
In [4]: from solarunet import post_processing
        from solarunet import plot_mask
        %matplotlib inline
        post_processing()
        plot_mask()
```



## 2.4 Magnetic Tracking

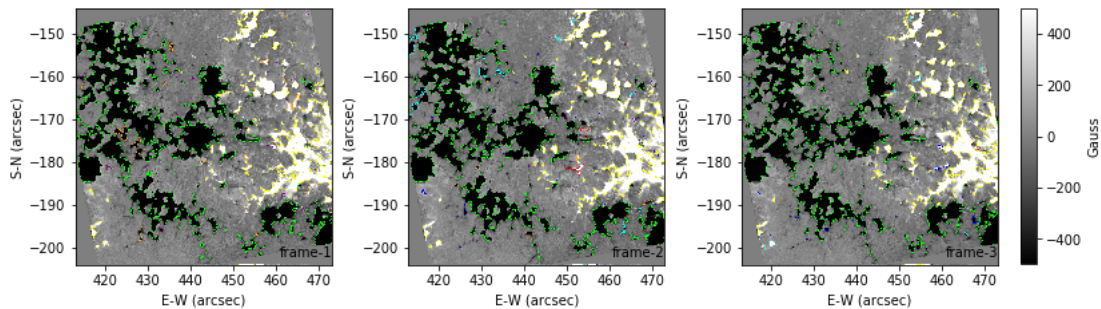
Import the `magnetic_tracking()` function from the `magnetic_tracking` module.

Magnetic tracking algorithms are performed on the three consecutive testing magnetograms. An option of saving feature lifetime is provided through the 3rd argument of the `magnetic_tracking()` function. The tracking results will be saved in the given path.

```
In [5]: from magnetic_tracking import magnetic_tracking
        input_path = 'results/processed_data_for_tracking/'
        output_path = 'results/tracking_results/'
        magnetic_tracking(input_path, output_path)
        # lifetime_path = 'data/statistics_analysis/Lifetime'
        # magnetic_tracking(input_path, output_path, lifetime_path)
```

```
=====magnetic tracking start=====
-----process frame 1-----
-----process frame 2-----
-----process frame 3-----
-----Done-----
```

```
In [6]: from solarunet import plot_tracking_results
        %matplotlib inline
        plot_tracking_results()
```

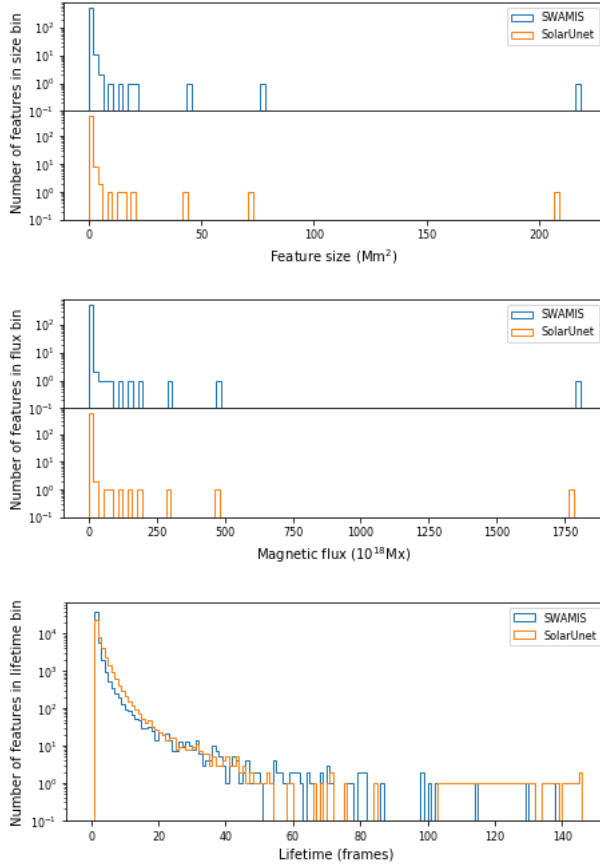


## 2.5 Statistics Analysis

Import the `analysis()` function from the `statistics_analysis` module.

The statistics analysis in this work is demoed as follows:

```
In [7]: from statistics_analysis import analysis
        %matplotlib inline
        analysis()
```



### 3. Conclusion

We develop a deep learning method, SolarUnet, for tracking signed magnetic flux elements (features) and detecting magnetic events in observed vector magnetograms. We apply the SolarUnet tool to data from the 1.6 meter Goode Solar Telescope (GST) at the Big Bear Solar Observatory (BBSO). The tool is able to identify the magnetic features and detect three types of events, namely disappearance, merging and cancellation, in the death category and three types of events, namely appearance, splitting and emergence, in the birth category. We use the BBSO/GST images to illustrate how our tool works on feature identification and event detection, and compares with the widely used SWAMIS tool.

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