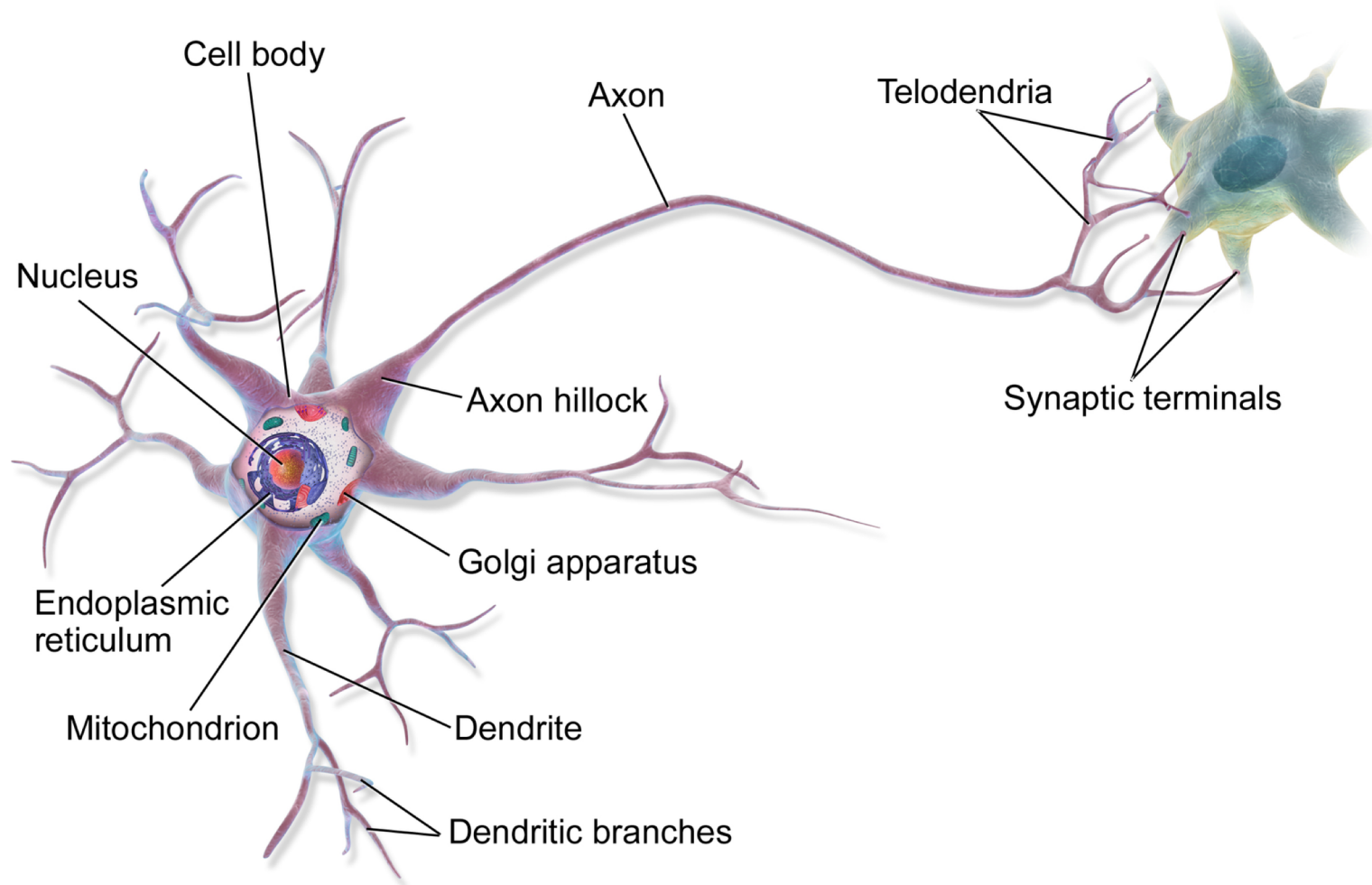


# Introduction to Neural Networks

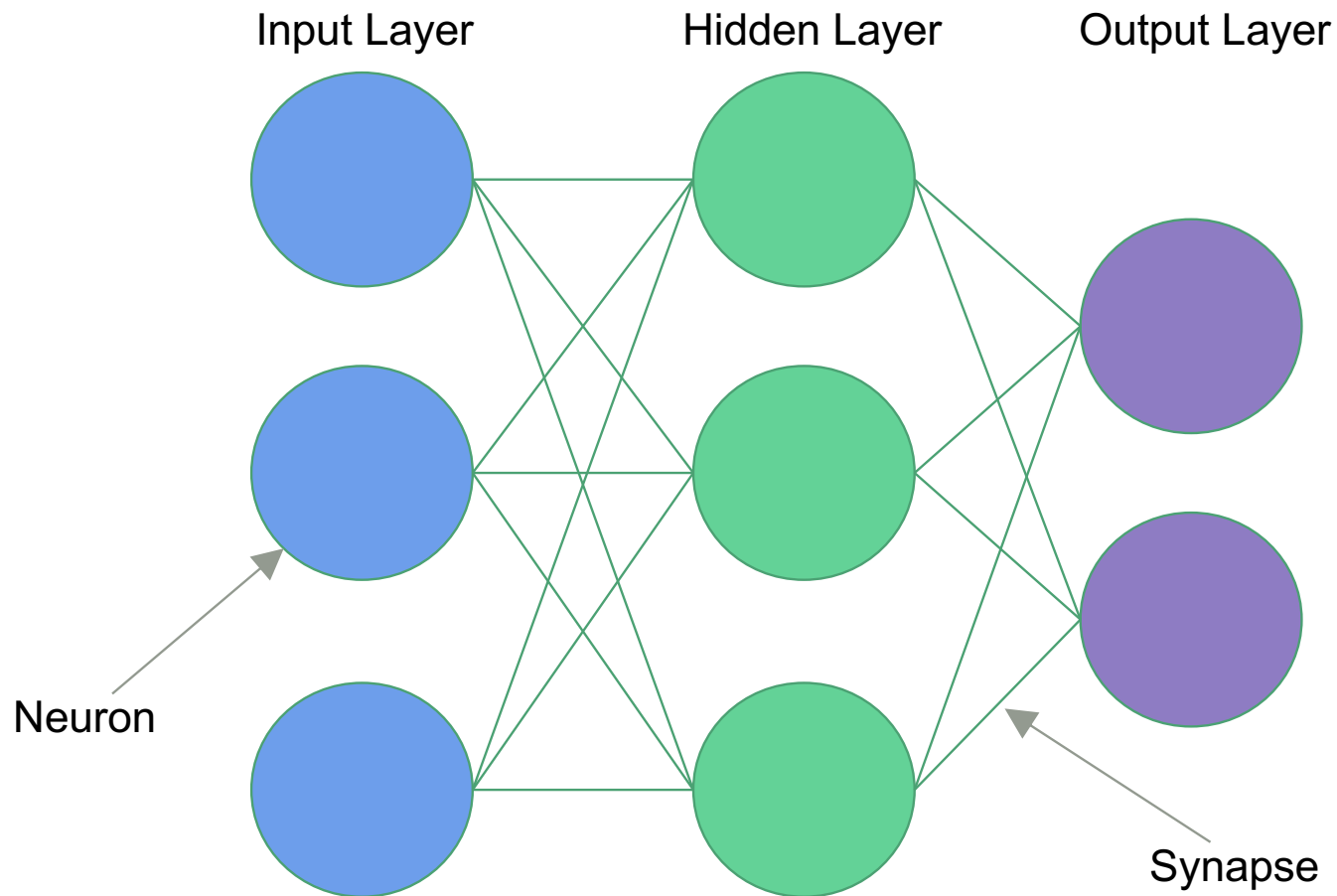
Jay Urbain, PhD

Credits: NYU, nVidia DLI

# Biological Inspiration



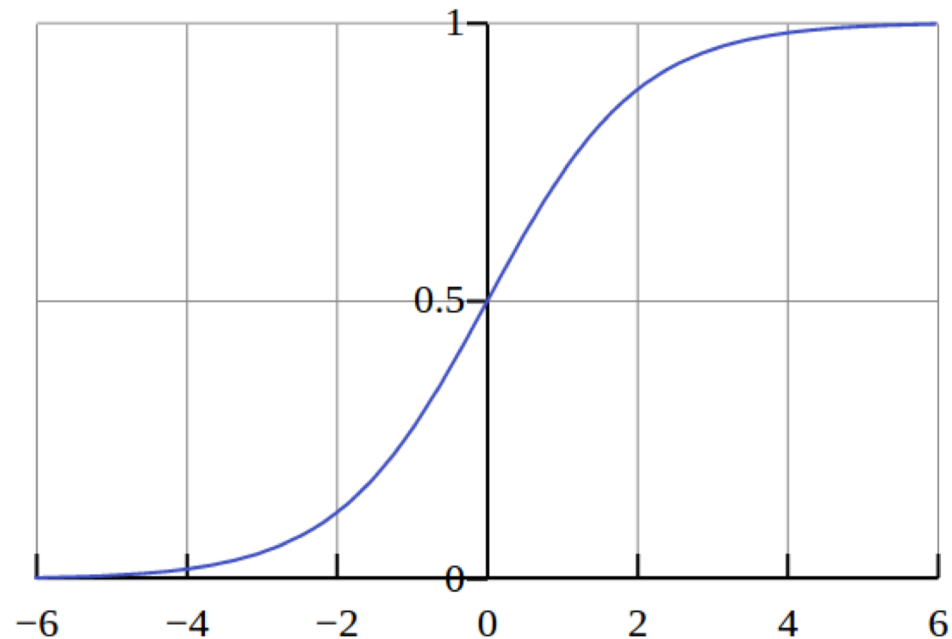
# Neural Network Architecture



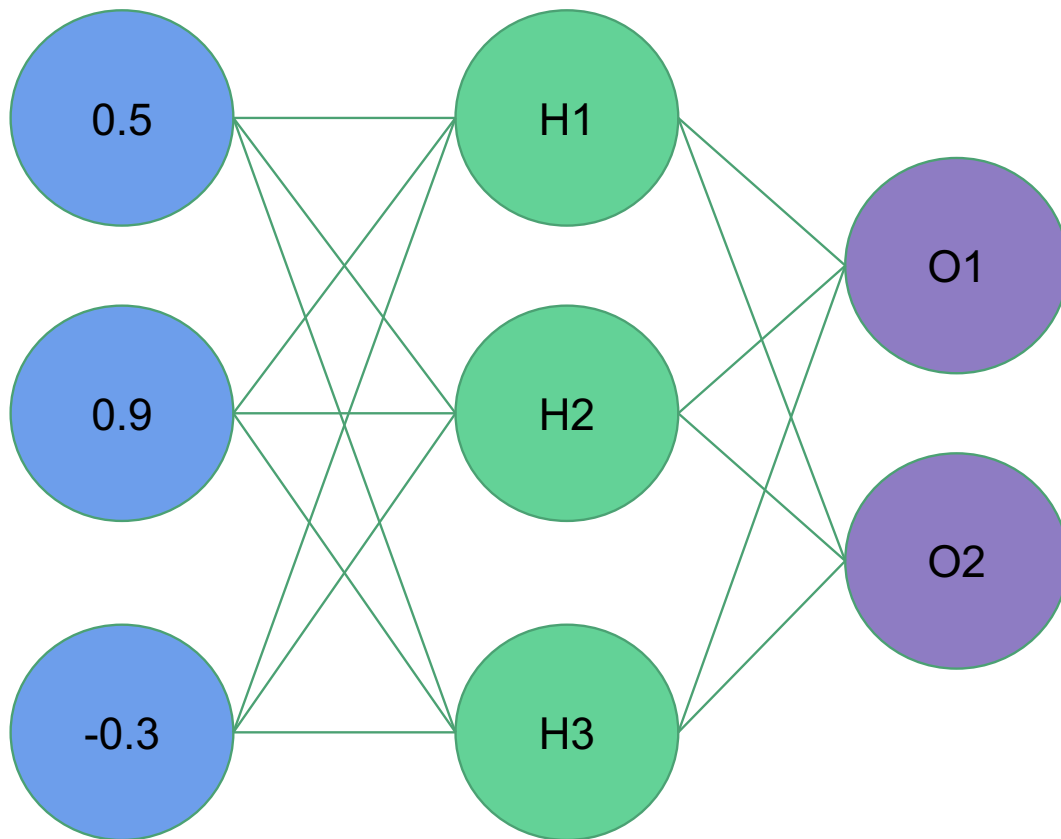
# Activation Functions

- Activation Functions are applied to the inputs at each neuron
  - A common activation function is the Sigmoid

$$S(t) = \frac{1}{1 + e^{-t}}$$



# Inference



H1 Weights = (1.0, -2.0, 2.0)

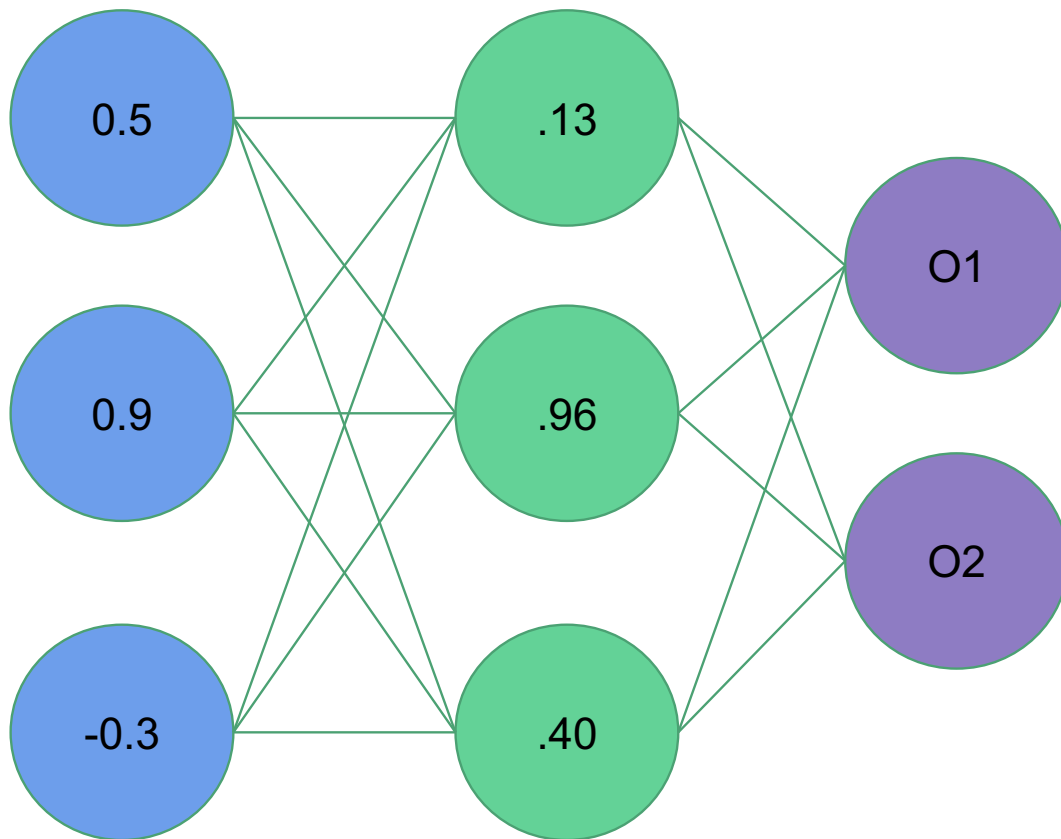
H2 Weights = (2.0, 1.0, -4.0)

H3 Weights = (1.0, -1.0, 0.0)

O1 Weights = (-3.0, 1.0, -3.0)

O2 Weights = (0.0, 1.0, 2.0)

# Inference



H1 Weights = (1.0, -2.0, 2.0)

H2 Weights = (2.0, 1.0, -4.0)

H3 Weights = (1.0, -1.0, 0.0)

O1 Weights = (-3.0, 1.0, -3.0)

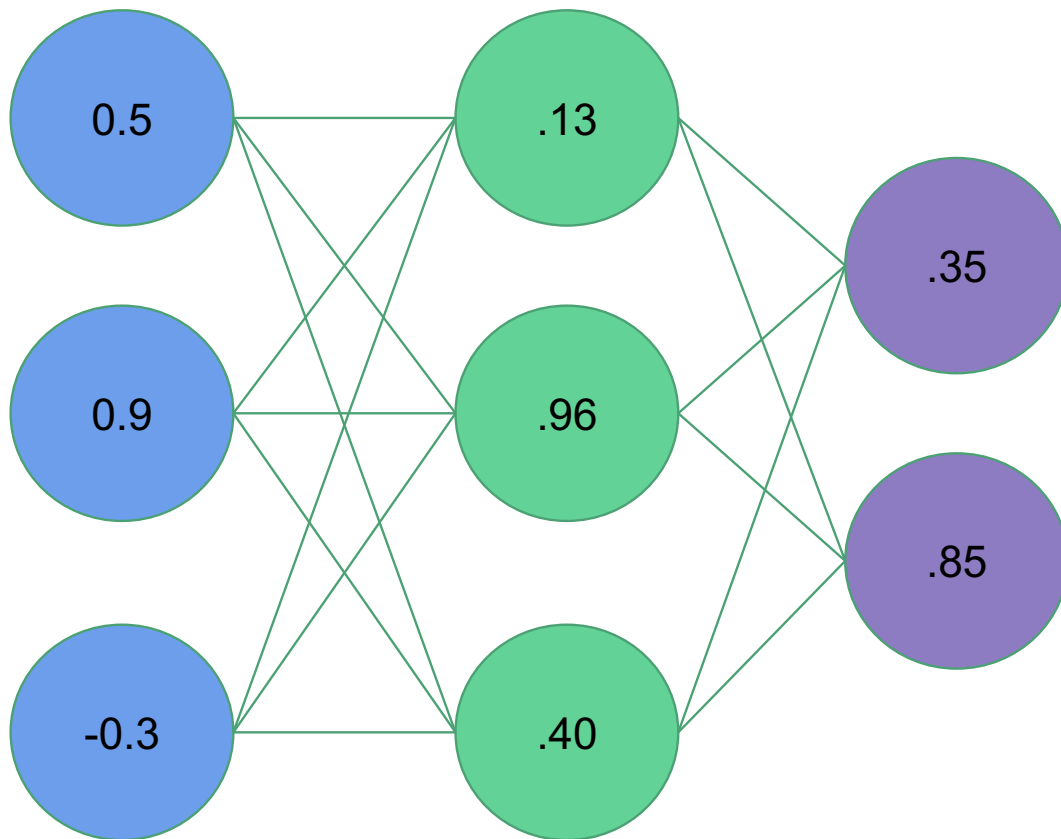
O2 Weights = (0.0, 1.0, 2.0)

$$H1 = S(0.5 * 1.0 + 0.9 * -2.0 + -0.3 * 2.0) = S(-1.9) = .13$$

$$H2 = S(0.5 * 2.0 + 0.9 * 1.0 + -0.3 * -4.0) = S(3.1) = .96$$

$$H3 = S(0.5 * 1.0 + 0.9 * -1.0 + -0.3 * 0.0) = S(-0.4) = .40$$

# Inference



H1 Weights = (1.0, -2.0, 2.0)

H2 Weights = (2.0, 1.0, -4.0)

H3 Weights = (1.0, -1.0, 0.0)

O1 Weights = (-3.0, 1.0, -3.0)

O2 Weights = (0.0, 1.0, 2.0)

$$O1 = S(.13 * -3.0 + .96 * 1.0 + .40 * -3.0) = S(-.63) = .35$$

$$O2 = S(.13 * 0.0 + .96 * 1.0 + .40 * 2.0) = S(1.76) = .85$$

# Matrix Formulation

H1 Weights = (1.0, -2.0, 2.0)

H2 Weights = (2.0, 1.0, -4.0)

H3 Weights = (1.0, -1.0, 0.0)

$$S\left( \begin{array}{|c|c|c|} \hline 1.0 & -2.0 & 2.0 \\ \hline 2.0 & 1.0 & -4.0 \\ \hline 1.0 & -1.0 & 0.0 \\ \hline \end{array} \right) * \begin{array}{|c|} \hline 0.5 \\ \hline 0.9 \\ \hline -0.3 \\ \hline \end{array} \right) = S\left( \begin{array}{|c|c|c|} \hline -1.9 & 3.1 & -0.4 \\ \hline \end{array} \right) = \begin{array}{|c|c|c|} \hline .13 & .96 & 0.4 \\ \hline \end{array}$$

Hidden Layer Weights

Inputs

Hidden Layer Outputs



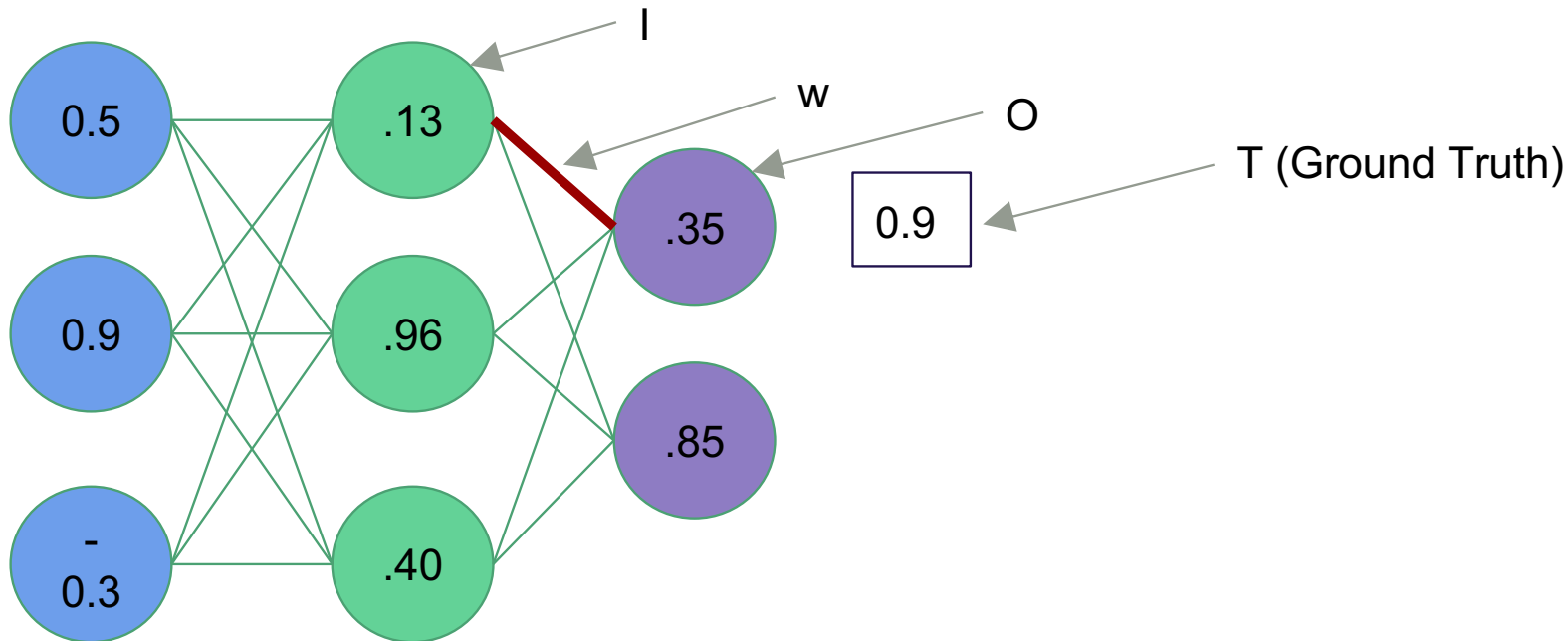
# Training Neural Networks

- Procedure for training Neural Networks
  - Perform inference on the training set
  - Calculate the error between the predictions and actual labels of the training set
  - Determine the contribution of each Neuron to the error
  - Modify the weights of the Neural Network to minimize the error
- Error contributions are calculated using Backpropagation
- Error minimization is achieved with Gradient Descent

# Backpropagation

- Problem: Which weights should be updated and by how much?
  - Insight: Use the derivative of the error with respect to weight to assign “blame”

# Backpropagation Example



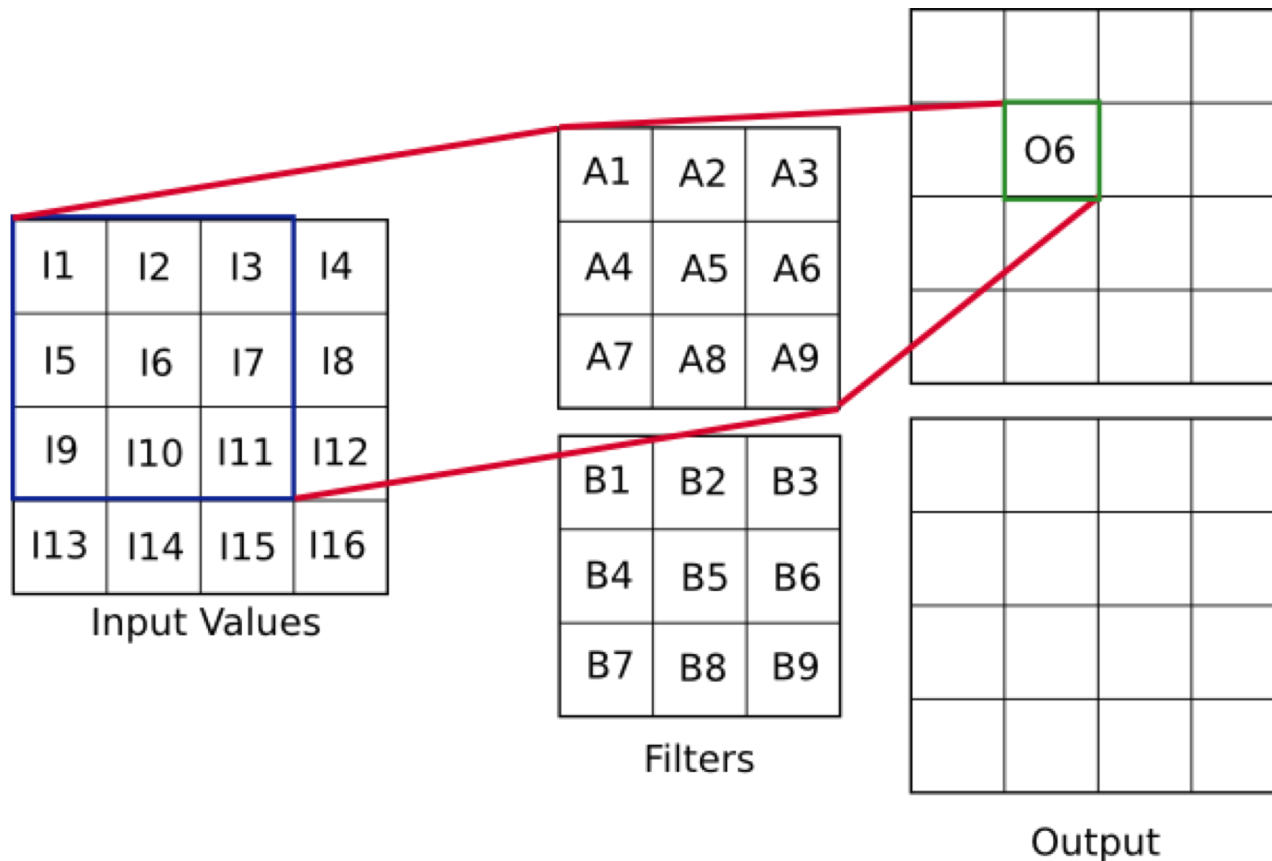
$$\frac{\partial E}{\partial w} = I \cdot (O - T) \cdot O \cdot (1 - O)$$

$$\frac{\partial E}{\partial w} = .13 \cdot (.35 - .9) \cdot .35 \cdot (1 - .35)$$

# Gradient Descent

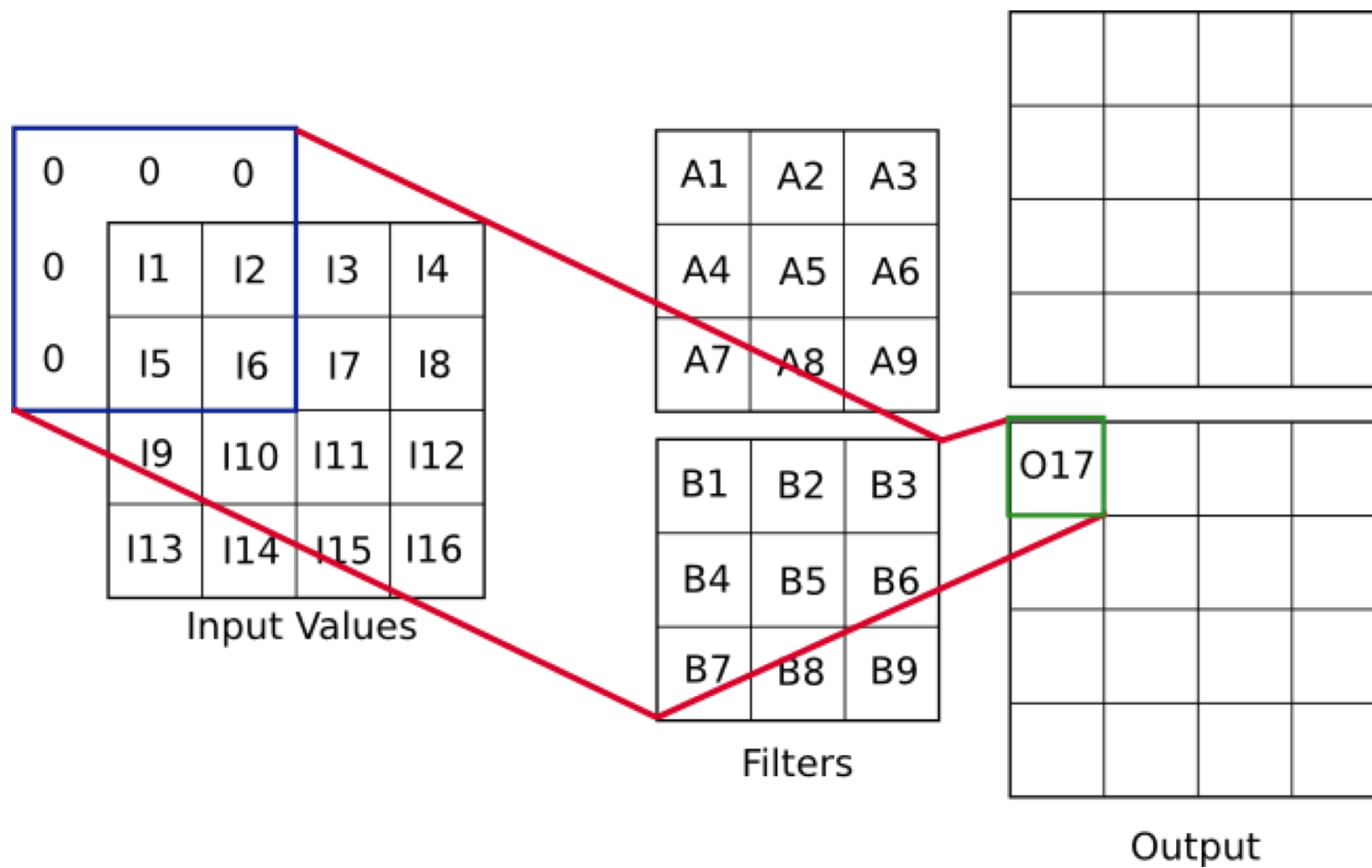
- Gradient Descent minimizes the neural network's error
  - At each time step the error of the network is calculated on the training data
  - Then the weights are modified to reduce the error
- Gradient Descent terminates when
  - The error is sufficiently small
  - The max number of time steps has been exceeded

# Convolutional Neural Networks



$$\begin{aligned} O_6 = & A_1 \cdot I_1 + A_2 \cdot I_2 + A_3 \cdot I_3 \\ & + A_4 \cdot I_5 + A_5 \cdot I_6 + A_6 \cdot I_7 \\ & + A_7 \cdot I_9 + A_8 \cdot I_{10} + A_9 \cdot I_{11} \end{aligned}$$

# Convolutional Neural Networks



$$O_{17} = B_5 \cdot I_1 + B_6 \cdot I_2 + B_8 \cdot I_5 + B_9 \cdot I_6$$

# Max-Pooling

1	0	2	2
1	3	0	1
3	1	4	1
2	0	2	1

2x2 Max Pooling

3	2
3	4