

* *project3.c*
*
* *Created: 05-03-2020 12:54:56*
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*/

```
#include<avr/io.h>
#define F_CPU 1000000UL
#include<util/delay.h>
//#include "lcd_h"
#define lcd PORTD
#define rs 0
#define rw 1
#define en 2

void lcd_init()
{
    lcd_command(0x02);
    lcd_command(0x28);
    lcd_command(0x06);
    lcd_command(0x0c);
}
void lcd_command(unsigned char com)
{
    lcd = com & 0xF0;    //send higher bit

    lcd &= ~(1<<rs);    //rs =0
    lcd &= ~(1<<rw);    //rw =0
    lcd |= (1<<en);      //en =1
    _delay_ms(1);
    lcd &= ~(1<<en);    //en =0
    _delay_ms(1);

    lcd = (com<<4) & 0xF0;    //send lower bit

    lcd &= ~(1<<rs);    //rs =0
    lcd &= ~(1<<rw);    //rw =0
    lcd |= (1<<en);      //en =1
    _delay_ms(1);
    lcd &= ~(1<<en);    //en =0
    _delay_ms(1);
}
void lcd_data(unsigned char value)
{
    lcd =value & 0xF0;    //send higher bit

    lcd |= (1<<rs);      //rs =1
    lcd &= ~(1<<rw);    //rw =0
    lcd |= (1<<en);      //en =1
    _delay_ms(1);
    lcd &= ~(1<<en);    //en =0
    _delay_ms(1);

    lcd =(value<<4) & 0xF0;    //send lower bit

    lcd |= (1<<rs);      //rs =1
    lcd &= ~(1<<rw);    //rw =0
    lcd |= (1<<en);      //en =1
    _delay_ms(1);
    lcd &= ~(1<<en);    //en =0
    _delay_ms(1);
}

void lcd_string(unsigned char *str)
{
    char i=0;
    while(str[i]!='\0')
    {
        lcd_data(str[i]);
        i++;
    }
}

void lcd_number(unsigned int value)
{
    unsigned int d=0;
    lcd_command(0x04);    //auto decrement mode

    if(value==0)
    lcd_data(value+48);

    while(value!=0)
    {
        d=value%10;
        lcd_data(d+48);
        value=value/10;
    }
    lcd_command(0x06);    //auto increment mode
}

void adc_init()
{
    ADMUX|=(1<<REFS0);
    ADCSRA|=(1<<ADEN)|(1<<ADIE)|(1<<ADPS2)|(1<<ADPS1);
}
int acd_read(int ch)
{
    ch &= 0b00001111;
    ADMUX = 0x40|ch;
    ADCSRA|=(1<<ADSC);
    while(!(ADCSRA & (1<<ADIF)));
    return ADC;
}

void main()
{
    DDRB=0xFF;
    DDRD=0xFF;
    DDRC=0x00;

    int x=0,y=0;
    lcd_init();
    adc_init();
    lcd_command(0x01);
    while(1)
    {
        x=acd_read(0);
        y=acd_read(1);
        lcd_command(0x89);
        lcd_number(x);
        _delay_ms(1000);

        if(x>=30 && x<=50 && y>=75 && y<=95)
        {
            lcd_command(0x89);
            lcd_string("forward");
            PORTB=0x05;

        }

        if(x>=30&&x<=50&&y>=20&&y<=45)
        {
            lcd_command(0xc6);
            lcd_string("backward");
            PORTB=0x0A;

        }

        if(x>0&&x<=30&&y>=50&&y<=70)
        {
            lcd_command(0x80);
            lcd_string("left");
            PORTB=0x01;

        }

        if(x>50&&x<=80&&y>=50&&y<=70)
        {
            lcd_command(0x80);
            lcd_string("right");
            PORTB=0x04;

        }

        if(x>30&&x<=50&&y>=50&&y<=70)
        {
            lcd_command(0x80);
            lcd_string("stop");
            PORTB=0x00;

        }

    }
}
```