

Accelerating Applications with CUDA C/C++

TOPICS

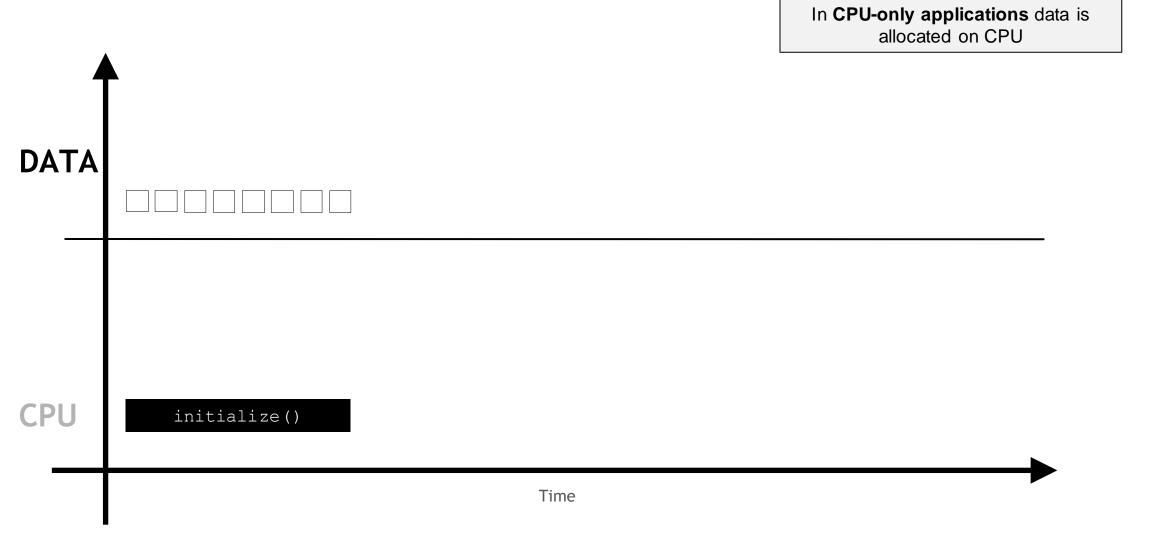
GPU-accelerated vs. CPU-only Applications

CUDA Kernel Execution

Parallel Memory Access

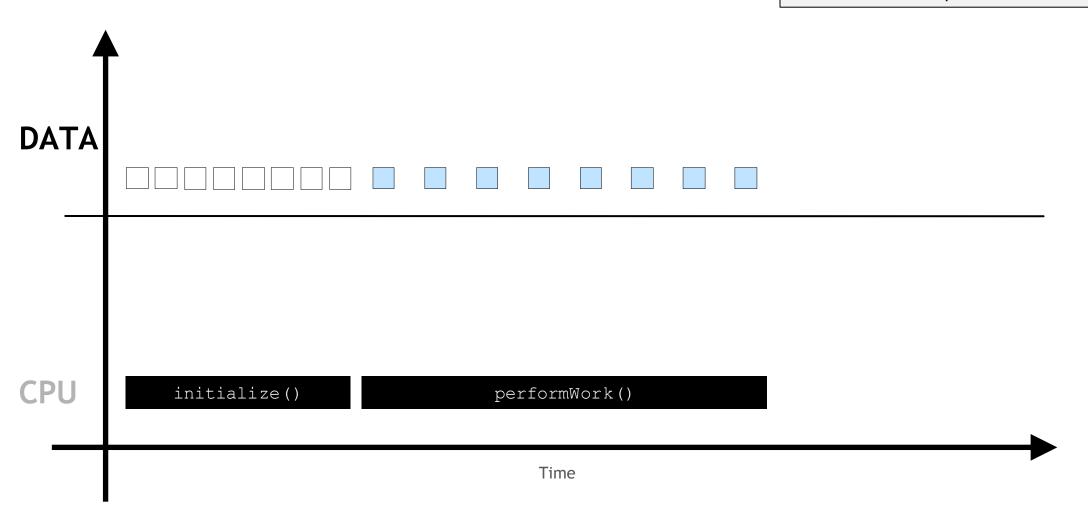
Appendix: Glossary

GPU-accelerated vs. CPU-only Applications





...and all work is performed on CPU



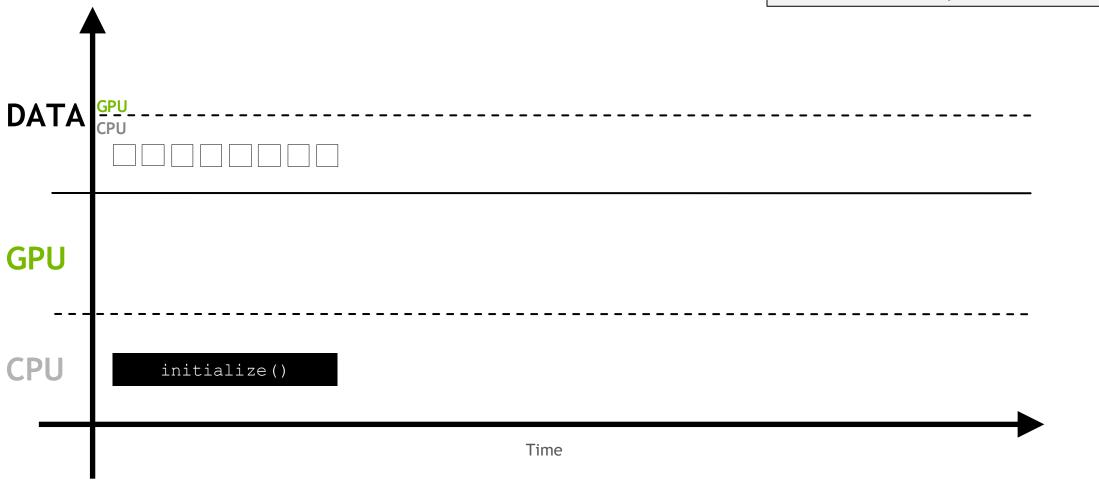
...and all work is performed on CPU

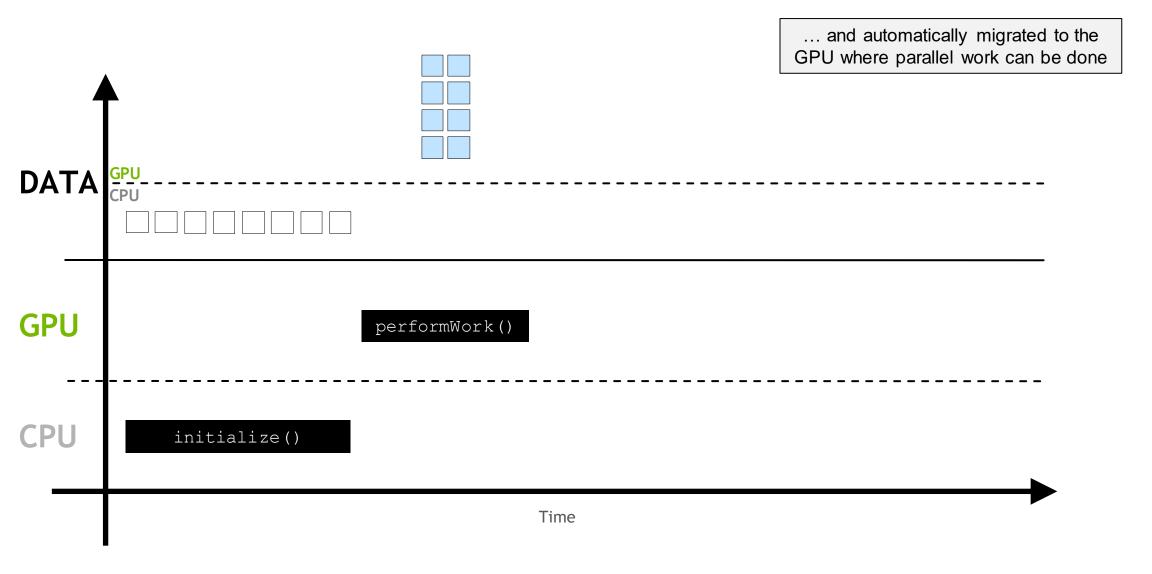


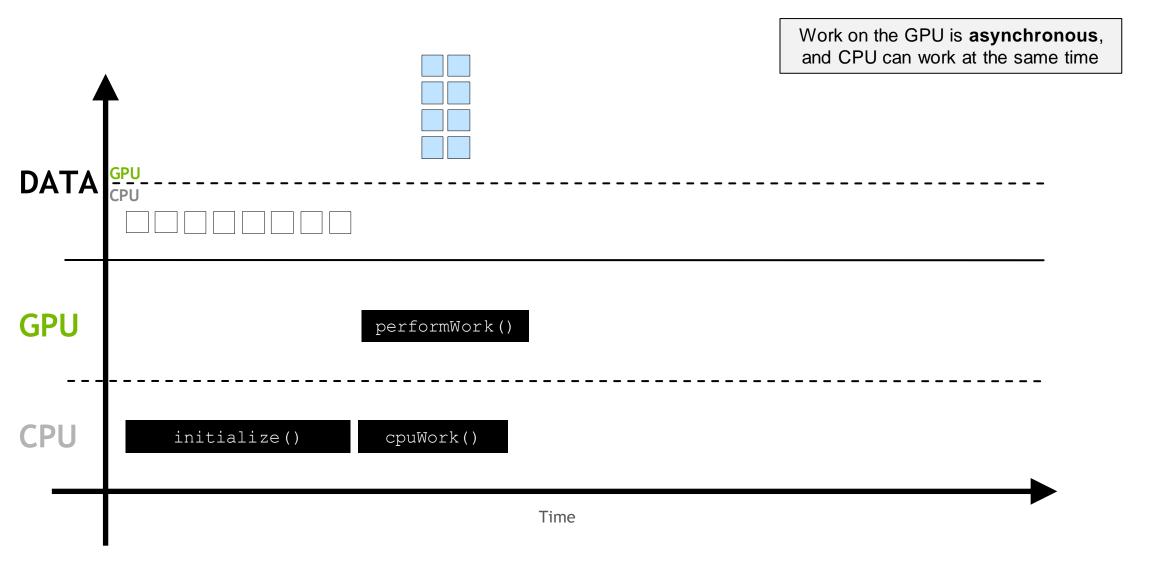
allocated with cudaMallocManaged() **DATA GPU** Time

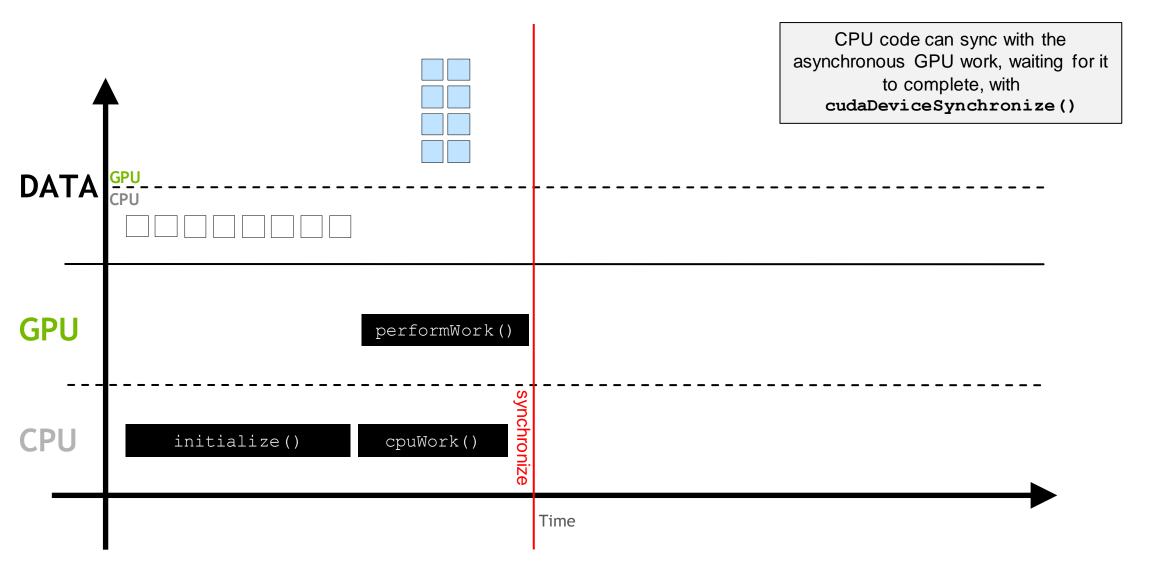
In accelerated applications data is

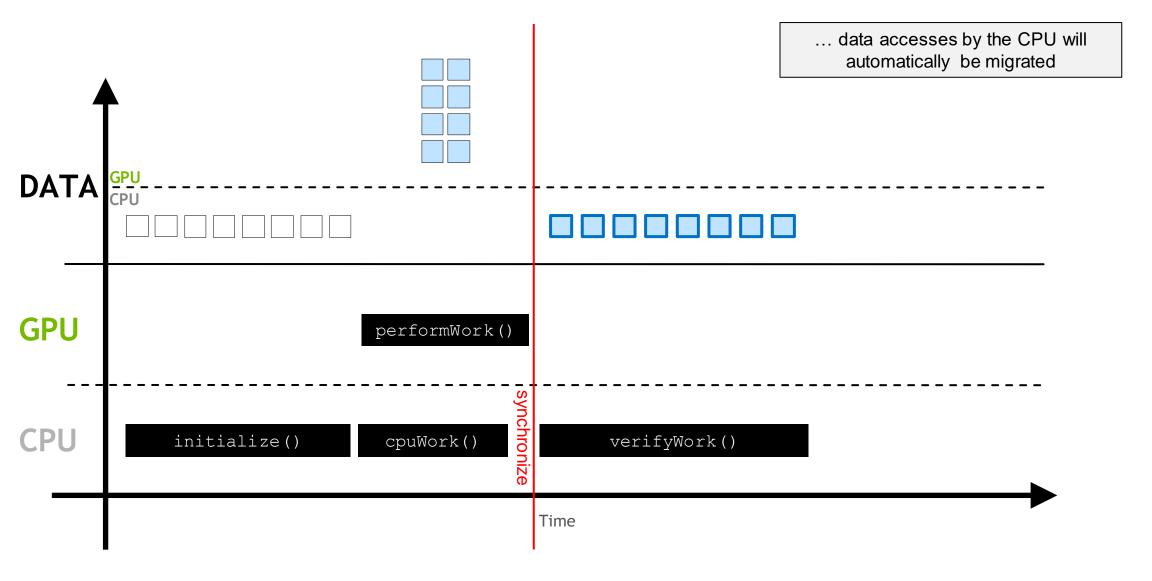
... where it can be accessed and worked on by the CPU



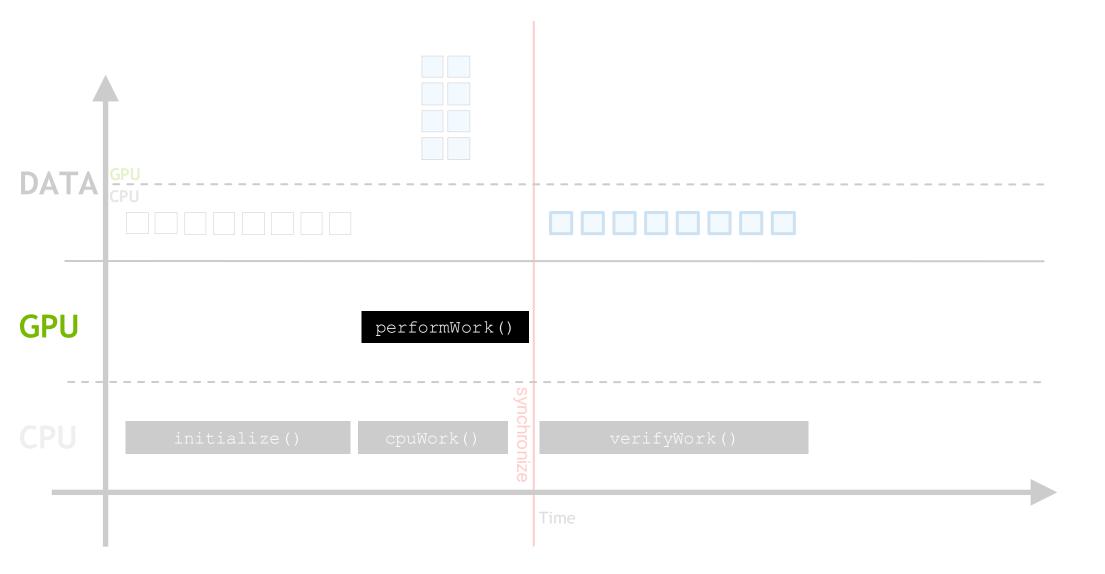




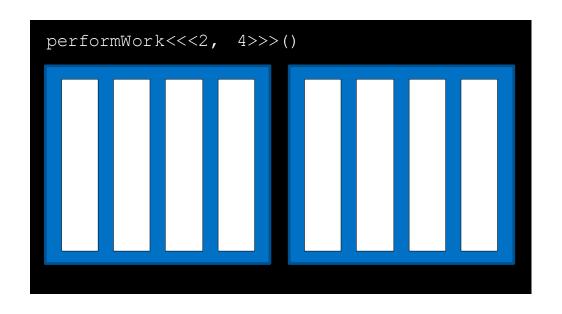


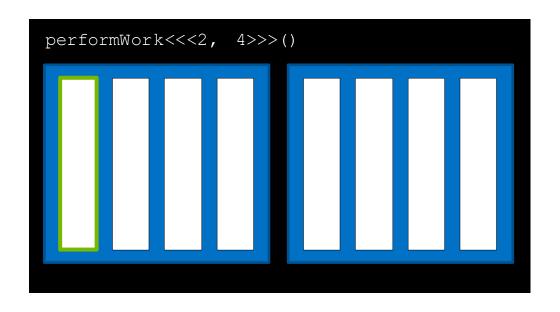


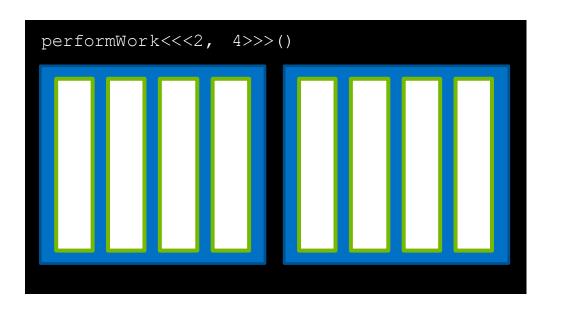
CUDA Kernel Execution

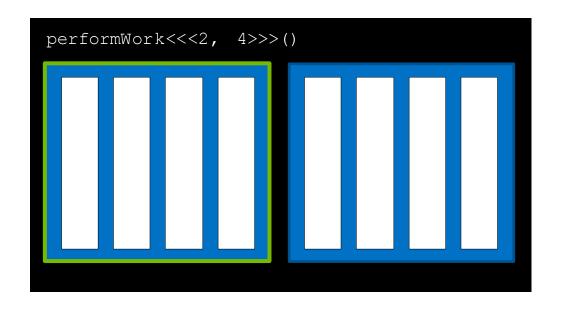


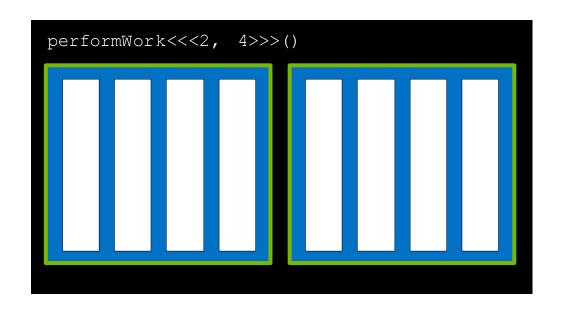




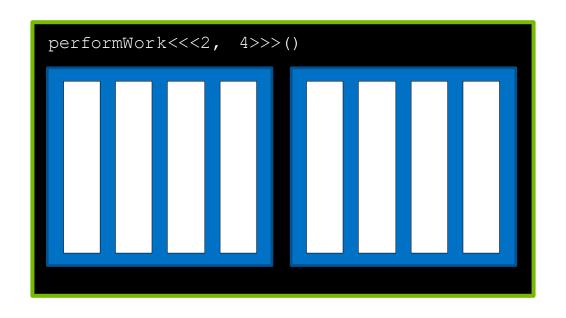


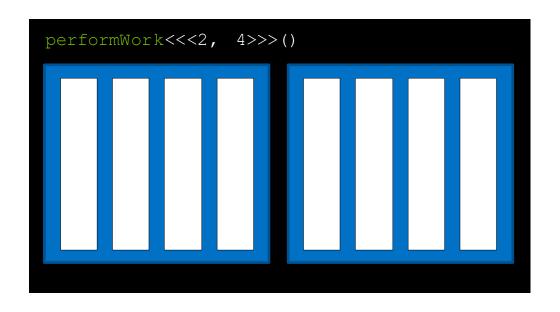




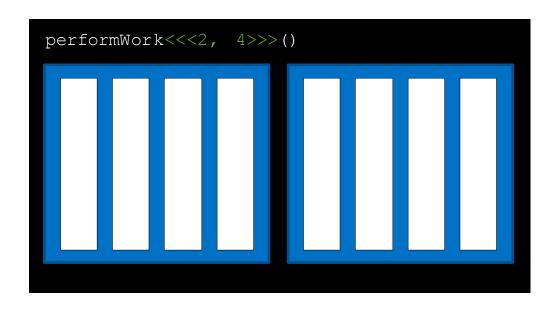




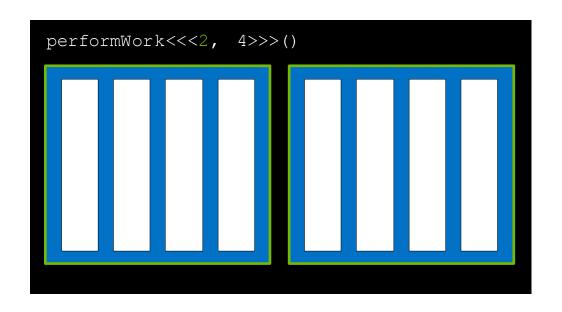




Kernels are launched with an execution configuration

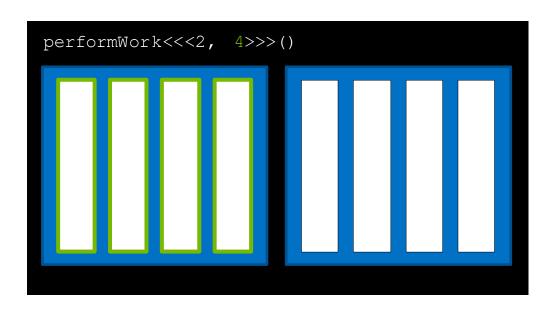




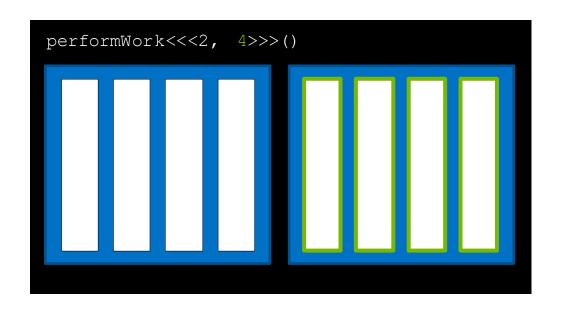




... as well as the number of threads in each block

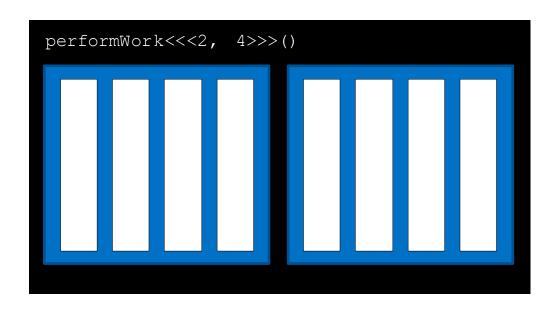






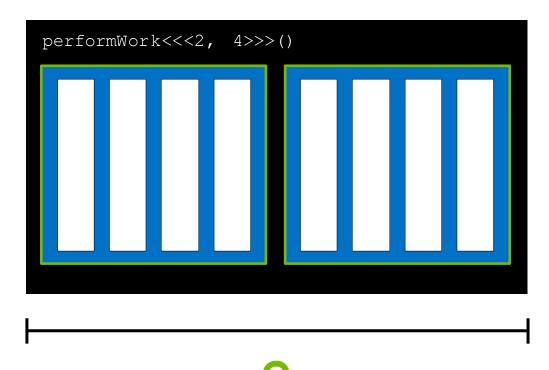
CUDA-Provided Thread Hierarchy Variables

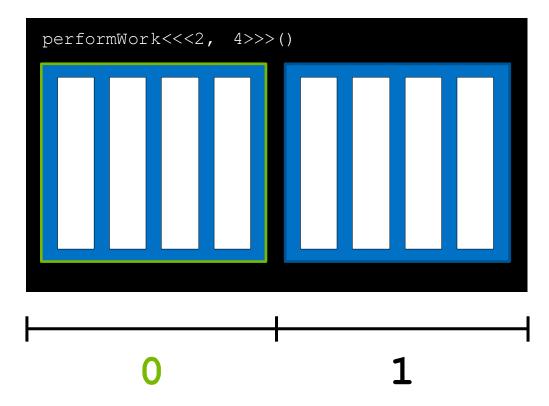
Inside kernels definitions, CUDAprovided variables describe its executing thread, block, and grid



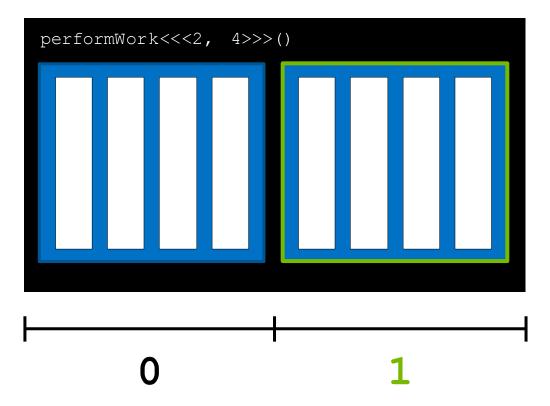


gridDim.x is the number of blocks in
the grid, in this case 2



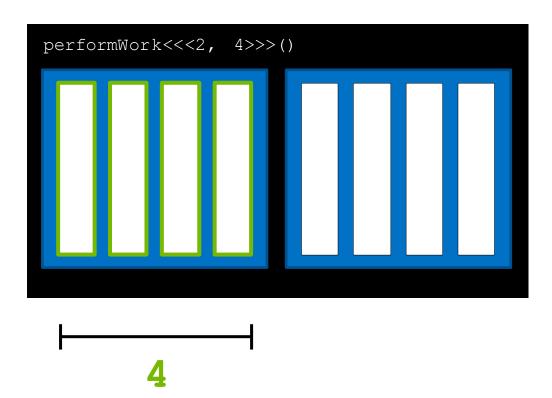


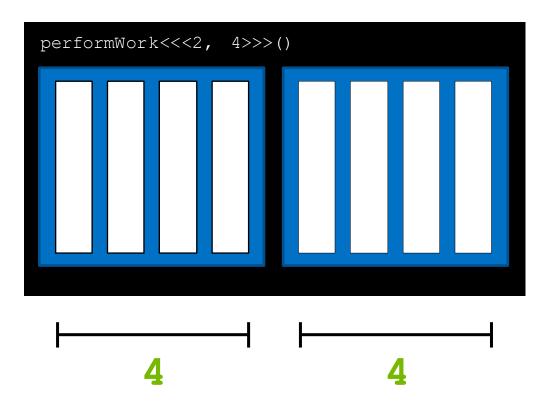


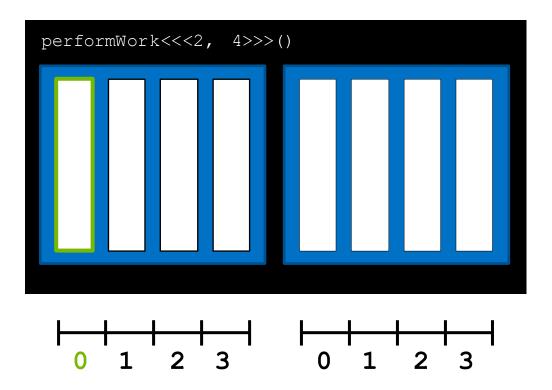


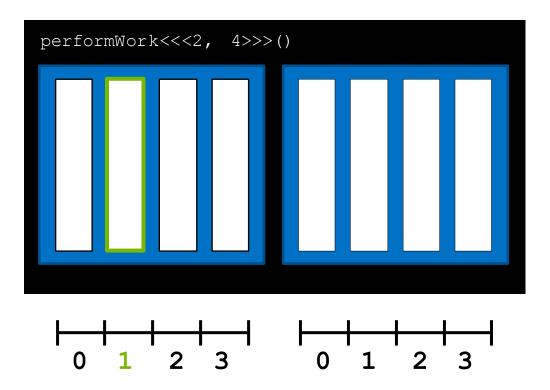


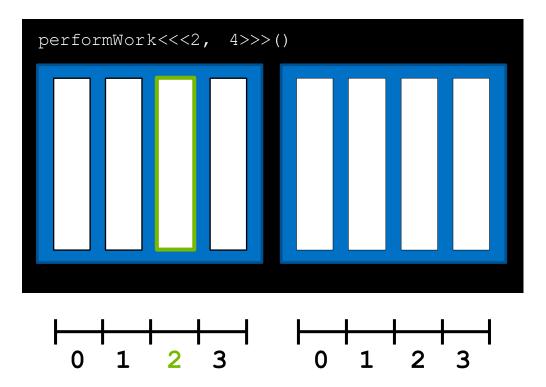
Inside a kernel **blockDim.x** describes the number of threads in a block. In this case **4**

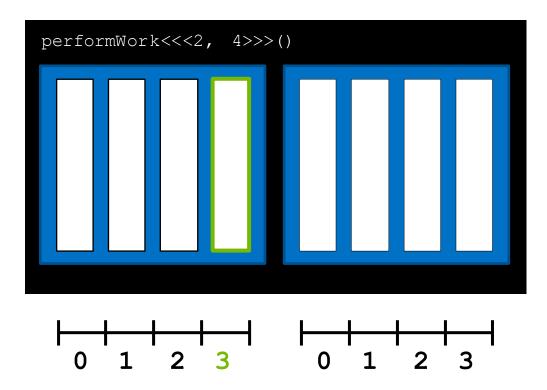


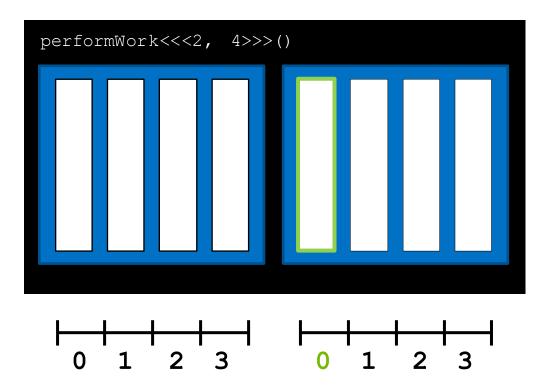


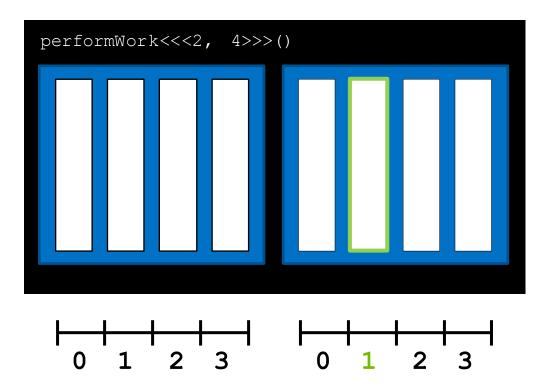


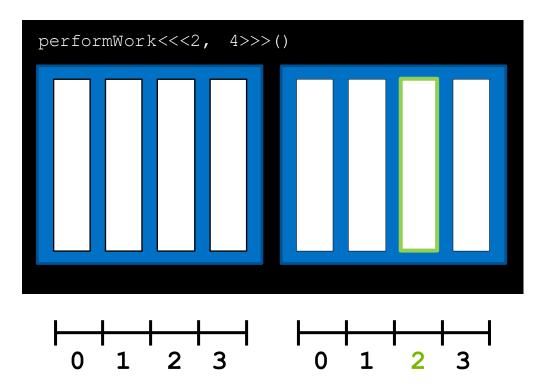


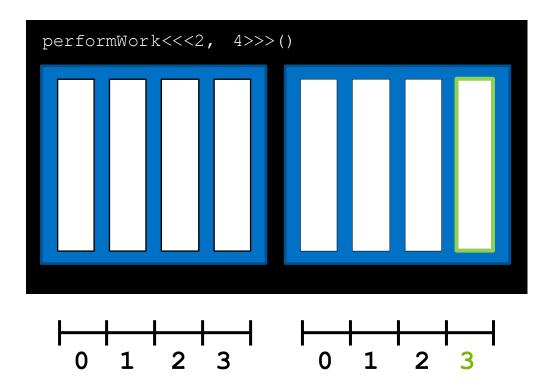




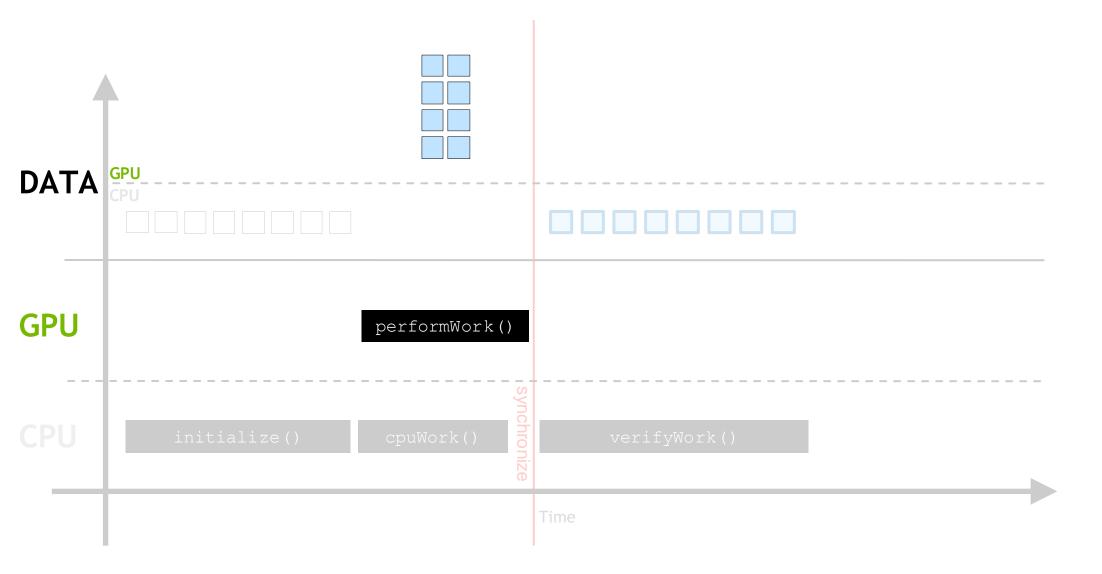






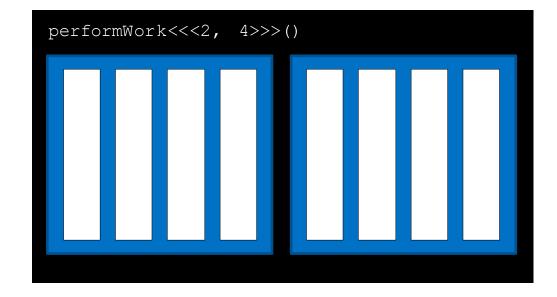


Coordinating Parallel Threads









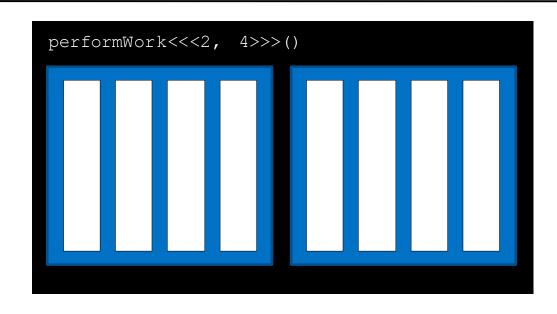


0 4

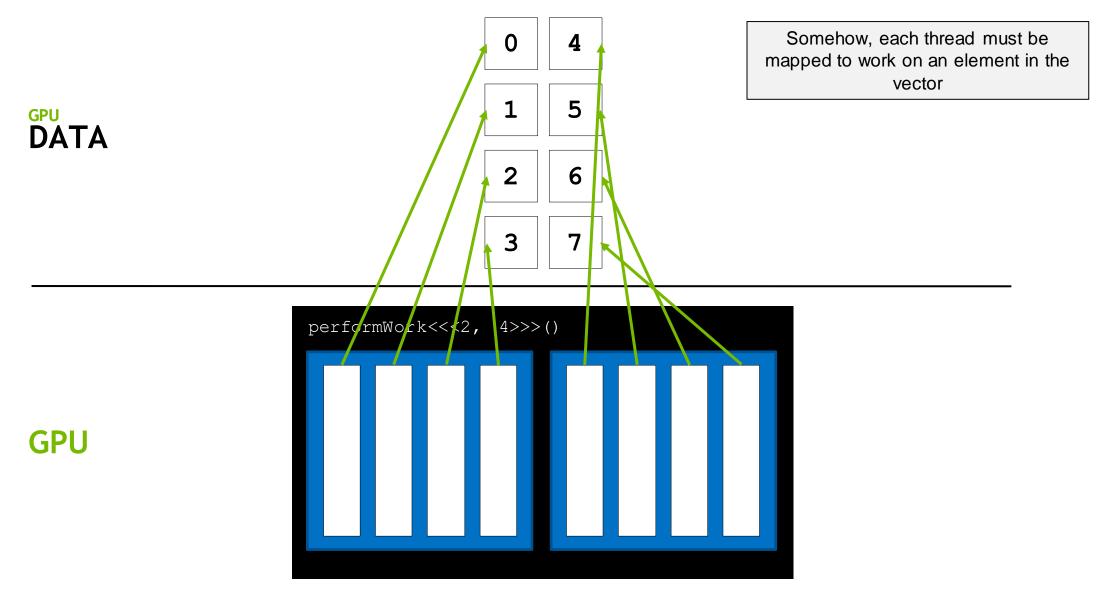
1 5

2 6

3









0 4

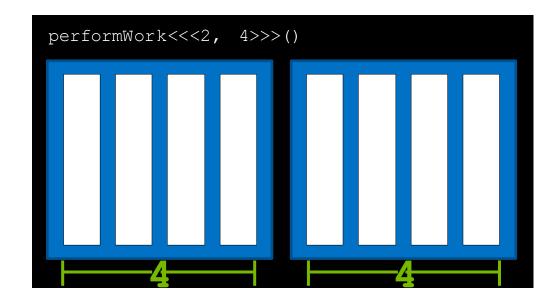
1 5

3

7

6

Recall that each thread has access to the size of its block via blockDim.x





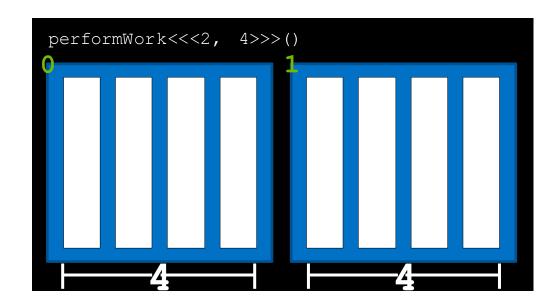
0 4

1 5

2 6

3

...and the index of its block within the grid via blockIdx.x





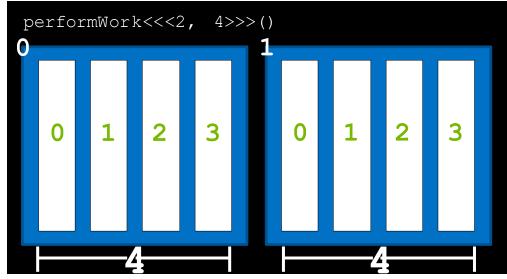
0

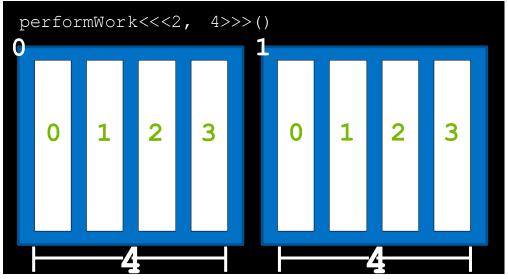
5

6

3

...and its own index within its block via threadIdx.x





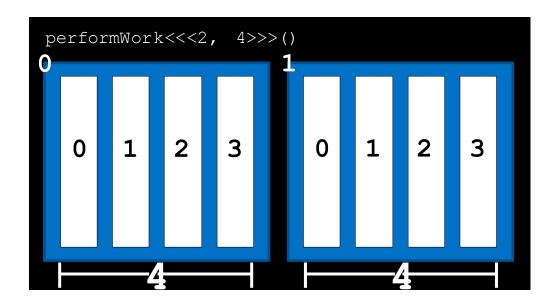
0 4

1 | 5

2 6

3

Using these variables, the formula threadIdx.x + blockIdx.x *
blockDim.x will map each thread to one element in the vector





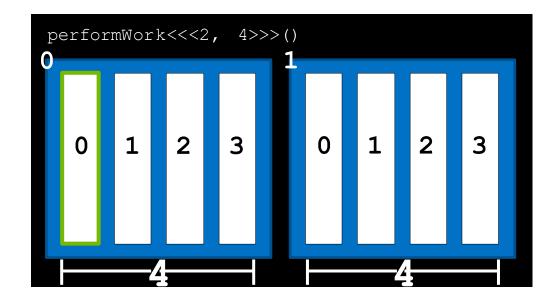
6

3 | 7

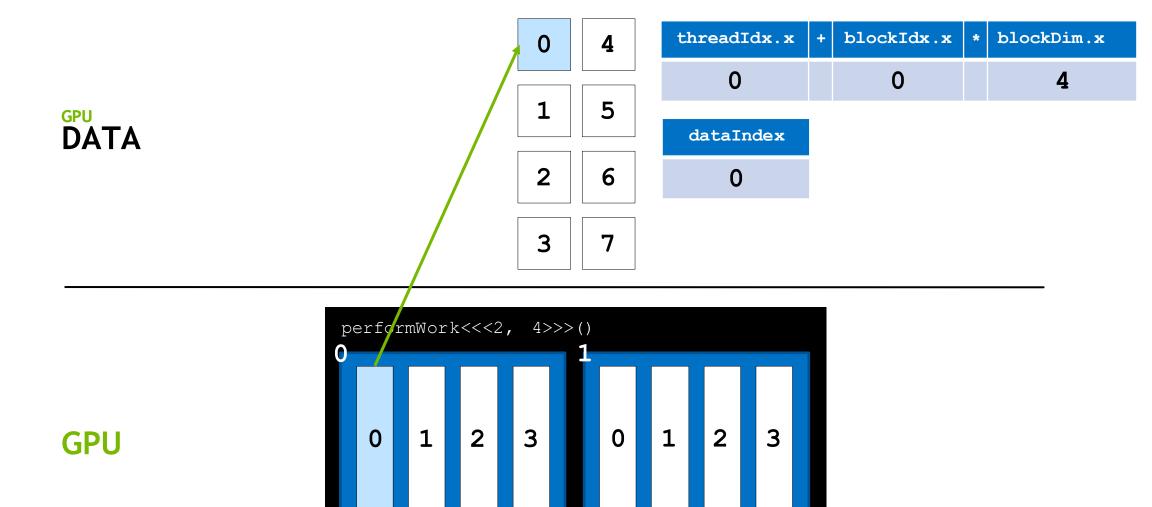
threadIdx.x	+	blockIdx.x	*	blockDim.x
0		0		4

dataIndex

?









123

5

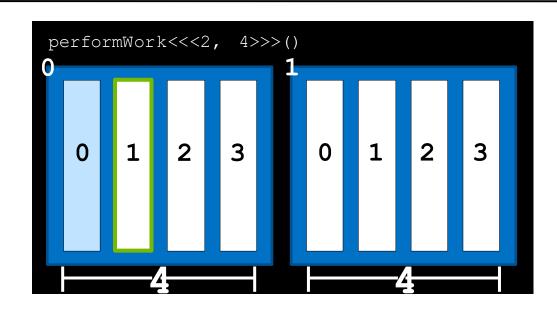
6

7

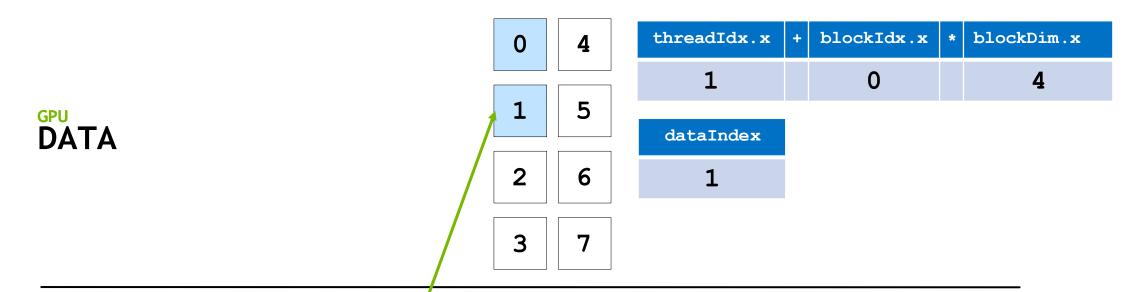
threadIdx.x	+	blockIdx.x	*	blockDim.x
1		0		4

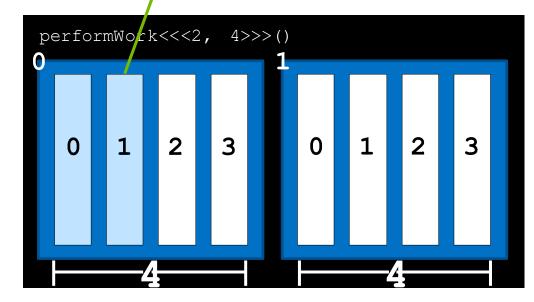
dataIndex

?











0 4

threadIdx.x + blockIdx.x * blockDim.x

2 0 4

1 5

dataIndex

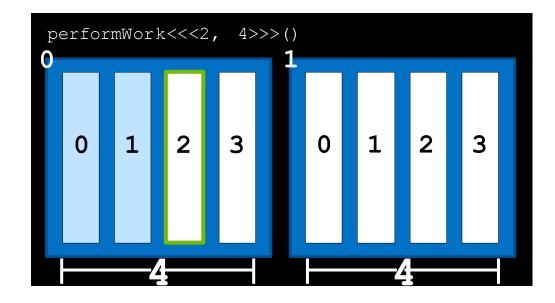
2

6

?

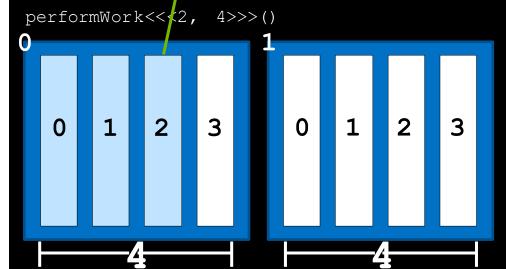
3

7











0 4

threadIdx.x + blockIdx.x * blockDim.x

3 0 4

1 5

dataIndex

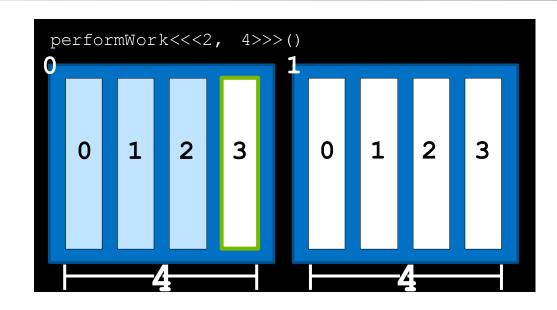
2

6

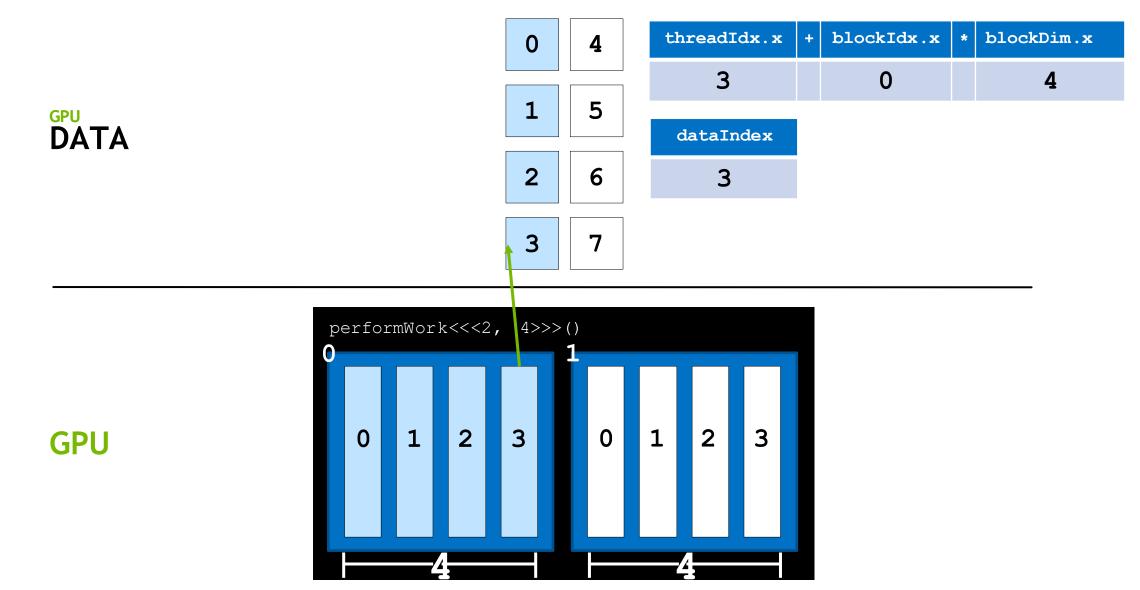
?

3

7

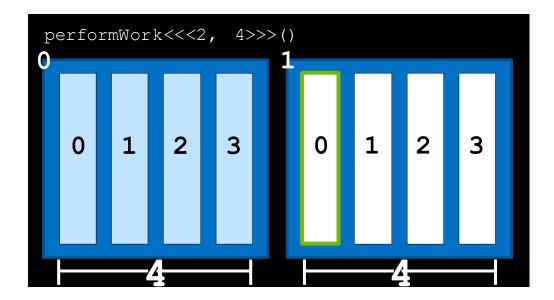




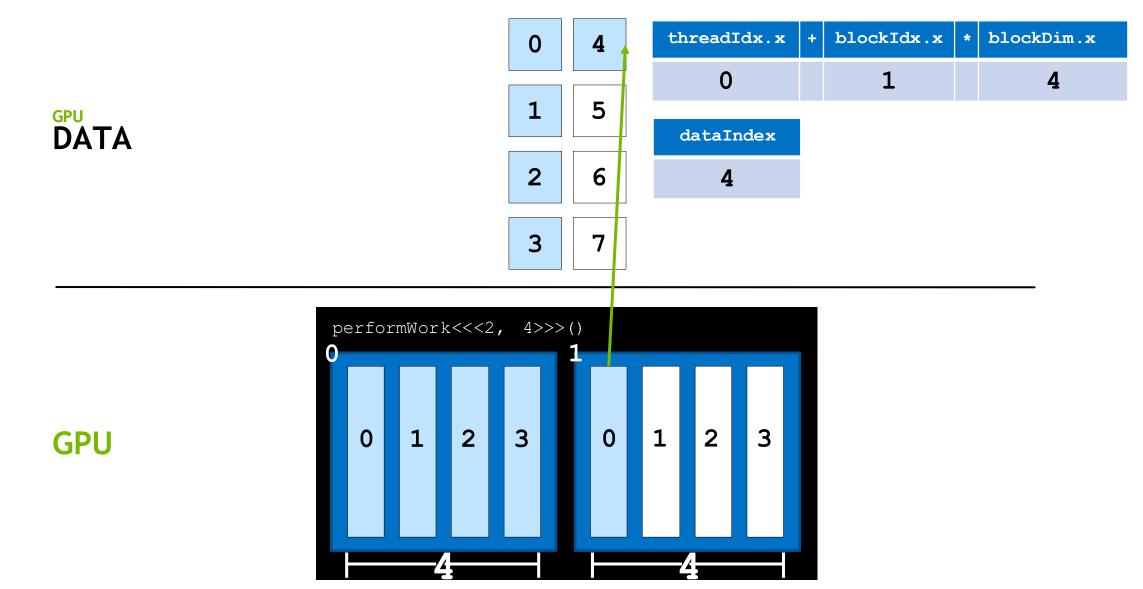




1 5 dataIndex
2 6 ?









0 1 2

4

5

6

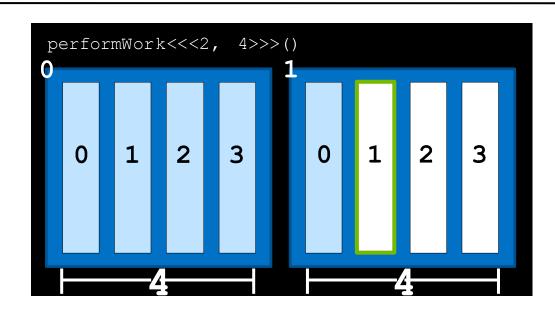
7

threadIdx.x + blockIdx.x * blockDim.x

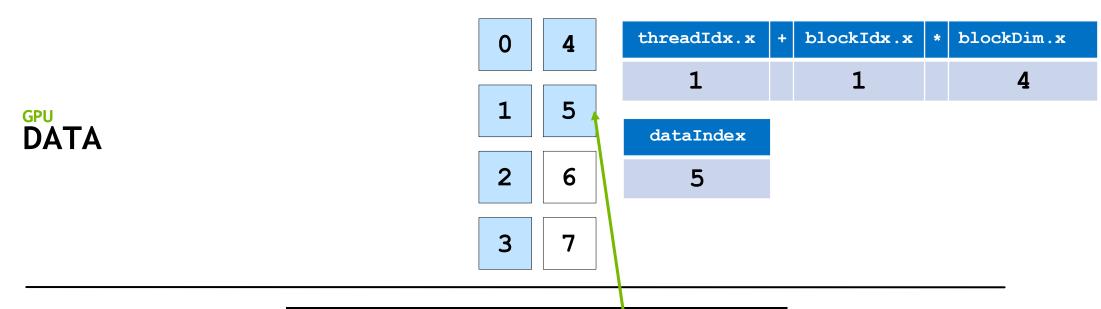
1 1 4

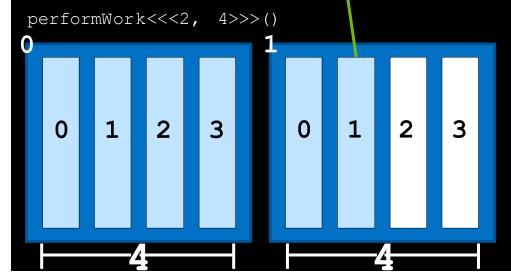
dataIndex

?











0123

4

5

6

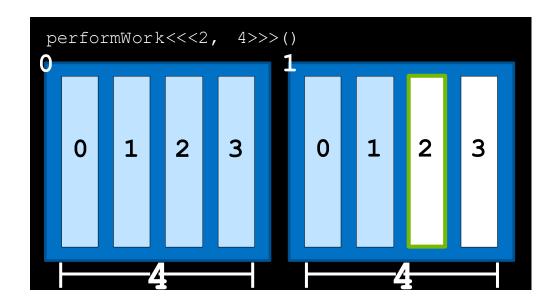
7

dataIndex

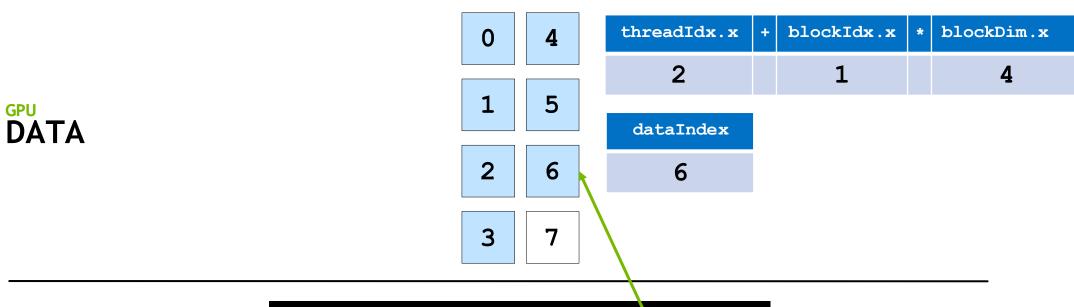
threadIdx.x +

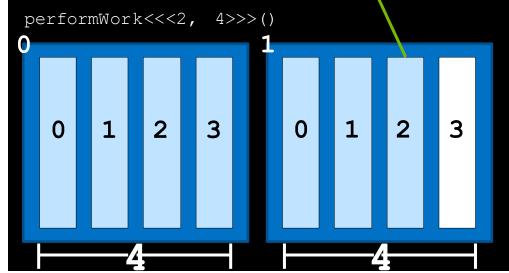
blockIdx.x

blockDim.x











0 1 2

4

5

6

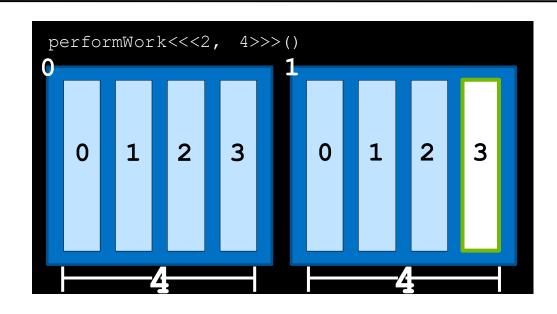
7

threadIdx.x + blockIdx.x * blockDim.x

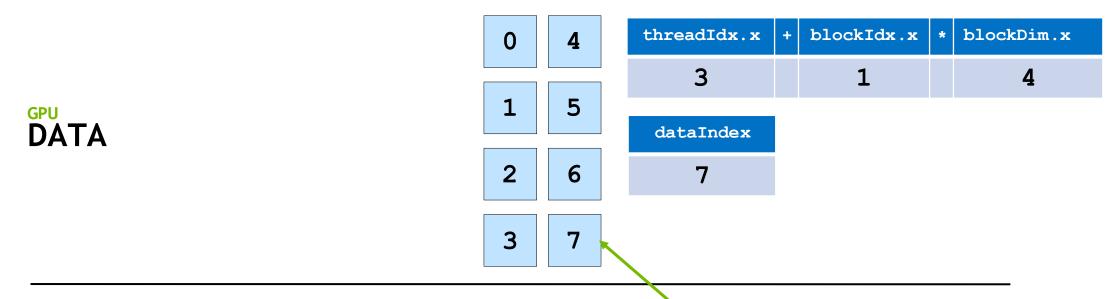
3 1 4

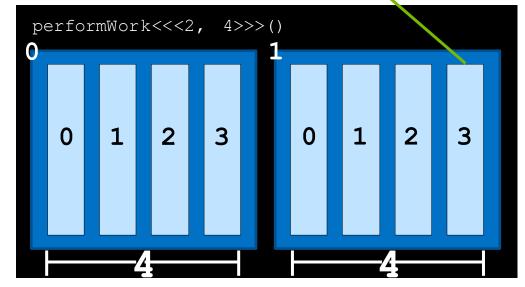
dataIndex

?



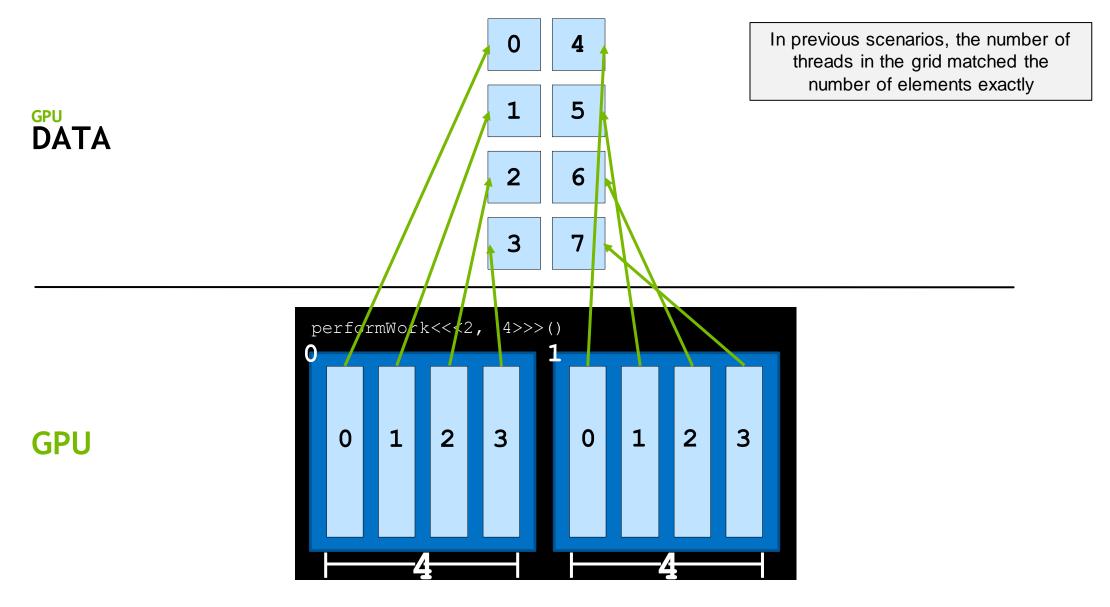








Grid Size Work Amount Mismatch





0

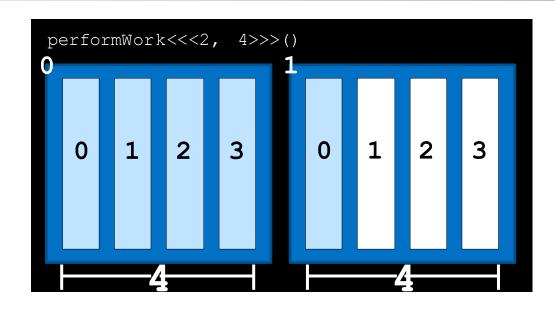
4

What if there are more threads than work to be done?

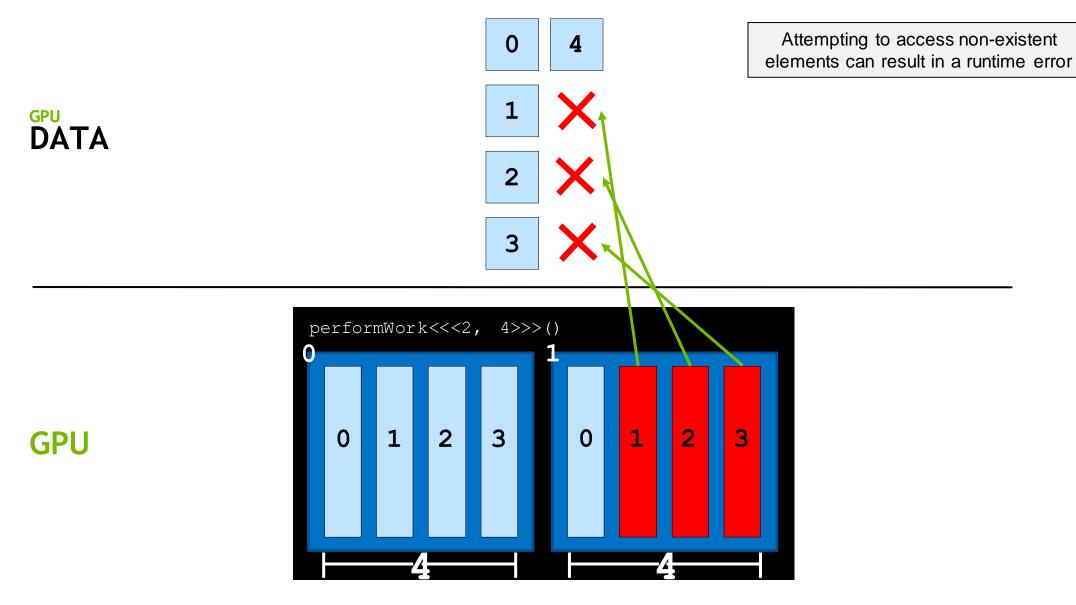
1

2

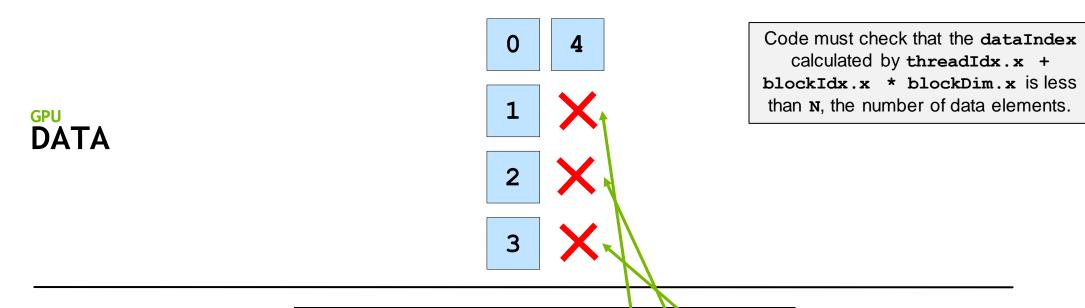
3

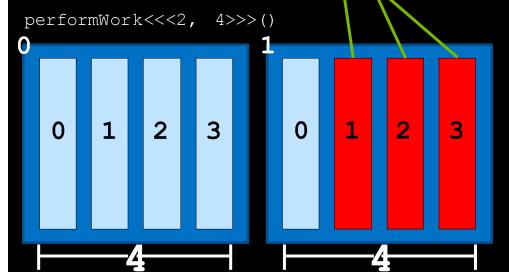














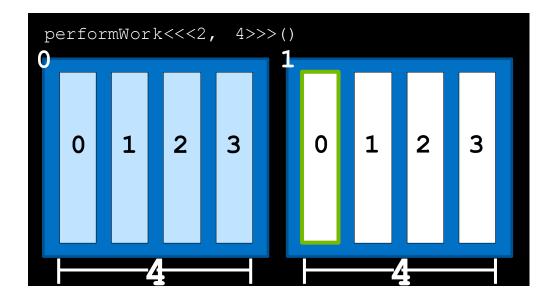
0		1		4
dataIndex	<	N	=	Can work
4		5		?

blockIdx.x

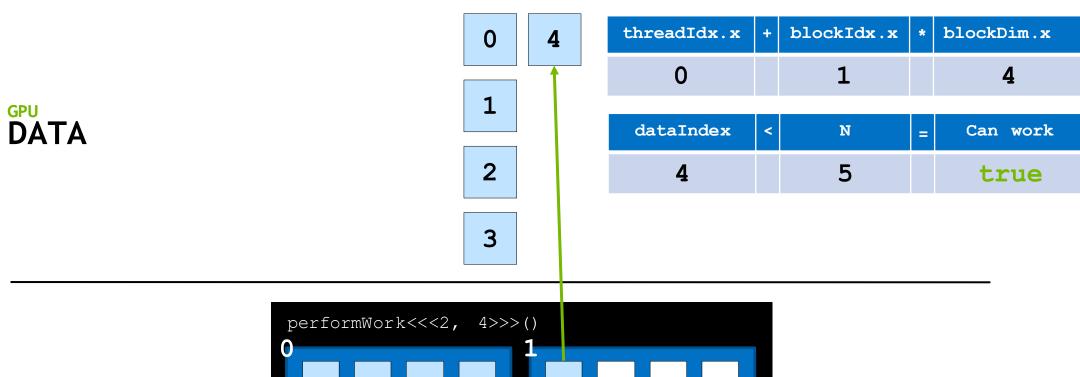
blockDim.x

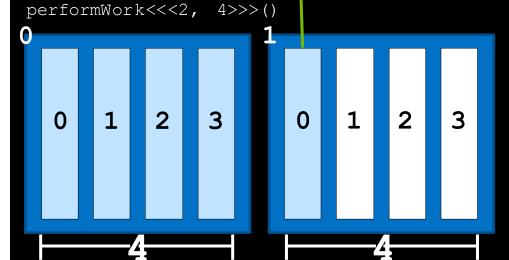
threadIdx.x +

3











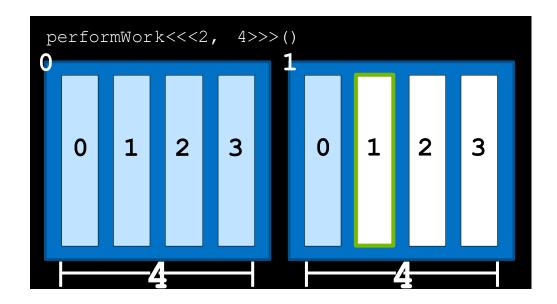
3

1		1		4
dataIndex	<	N	=	Can work
5		5		?

blockIdx.x

blockDim.x

threadIdx.x +





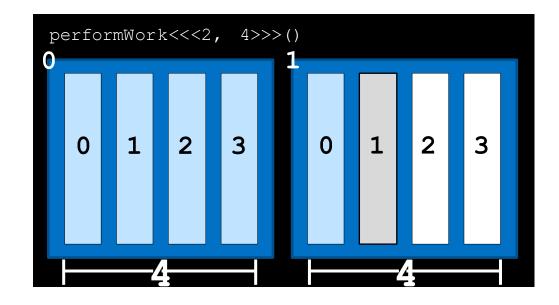
1		1		4
dataIndex	<	N	=	Can work
5		5		false

blockIdx.x

blockDim.x

threadIdx.x +

3





042

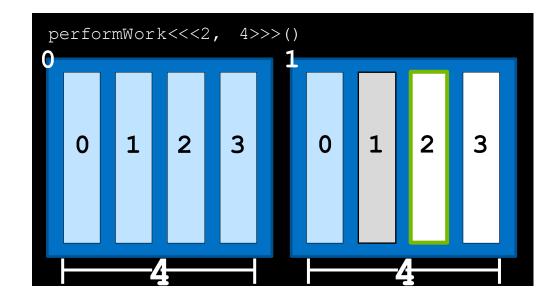
2		1		4
dataIndex	<	N	=	Can work
6		5		?

blockIdx.x

threadIdx.x +

blockDim.x

3





042

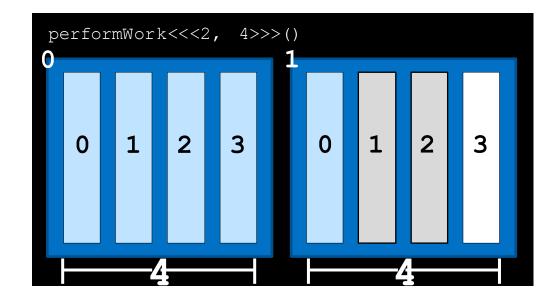
2		1		4
dataIndex	<	N	=	Can work
6		5		false

blockIdx.x

threadIdx.x +

blockDim.x

3





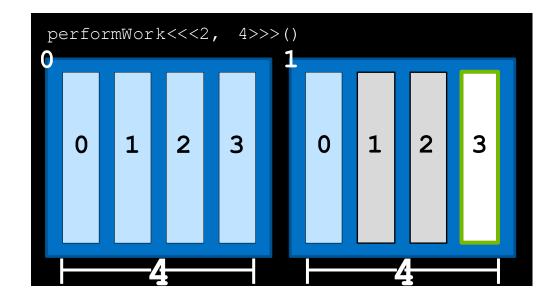
2		1		4
dataIndex	<	N	=	Can work
6		5		?

blockIdx.x

threadIdx.x +

blockDim.x

3





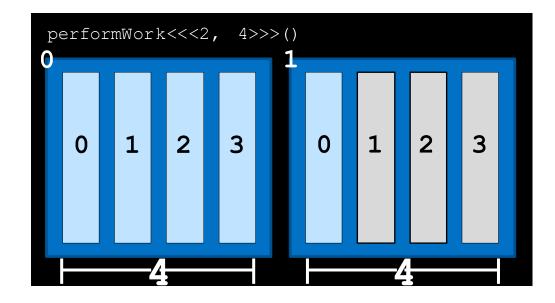
2		1		4
dataIndex	<	N	=	Can work
6		5		false

blockIdx.x

threadIdx.x +

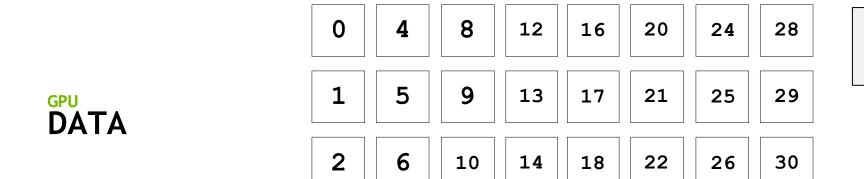
blockDim.x

3



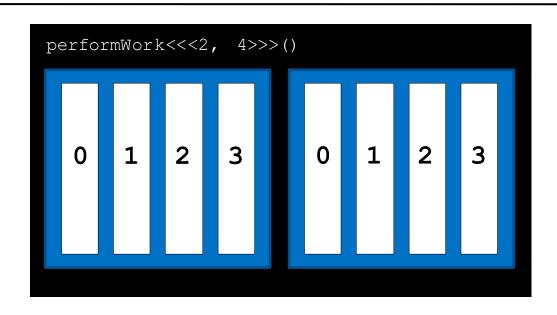


Grid-Stride Loops

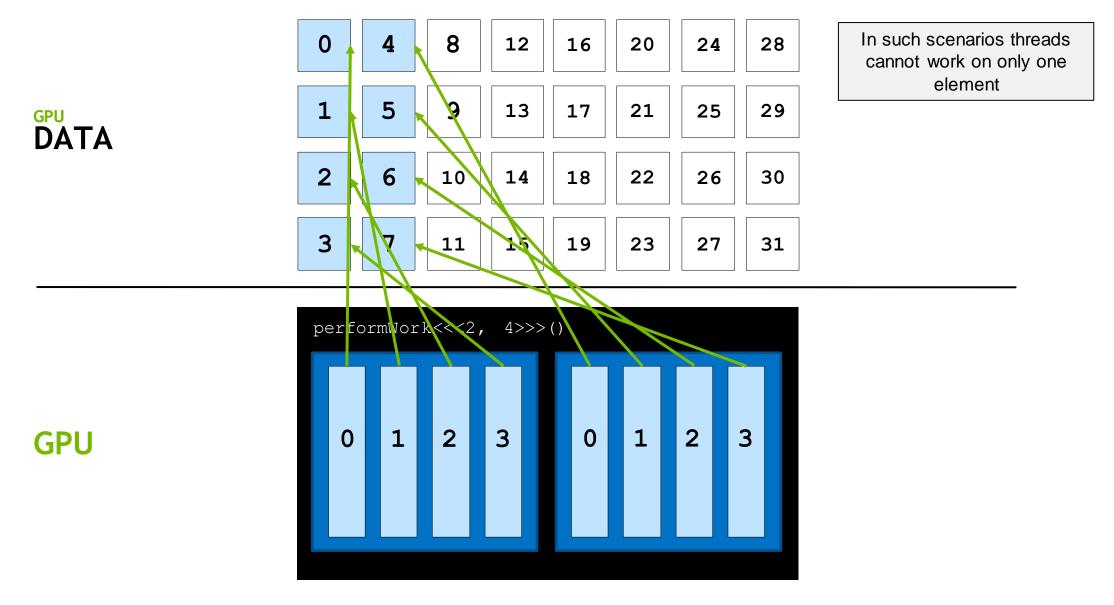


Often there are more data elements than there are threads in the grid

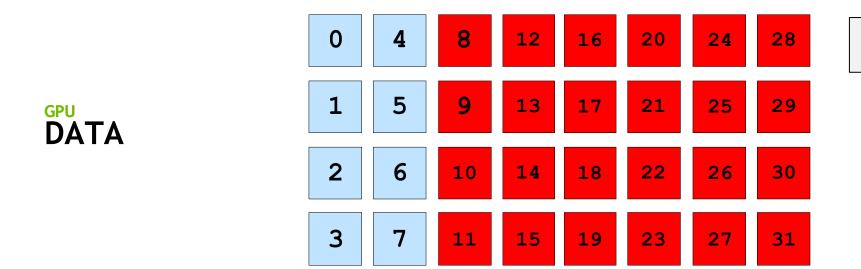






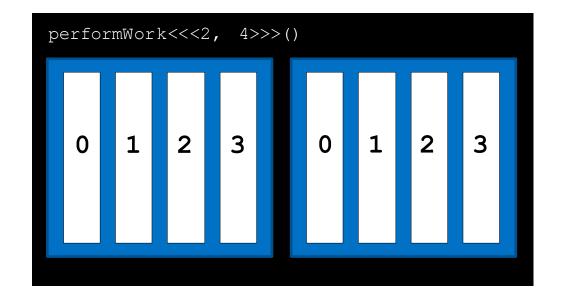




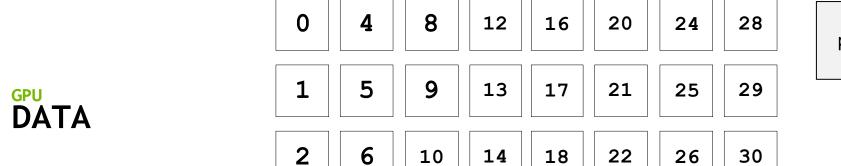


... or else work is left undone



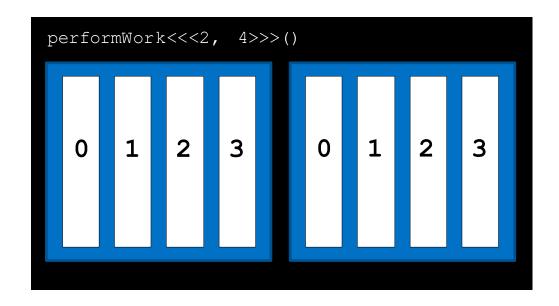




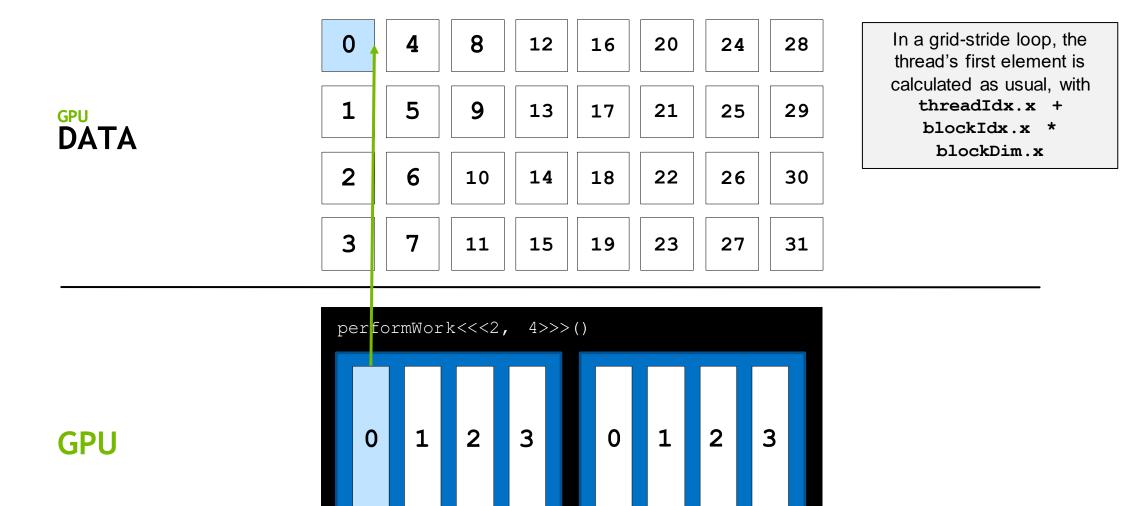


One way to address this programmatically is with a **grid-stride loop**



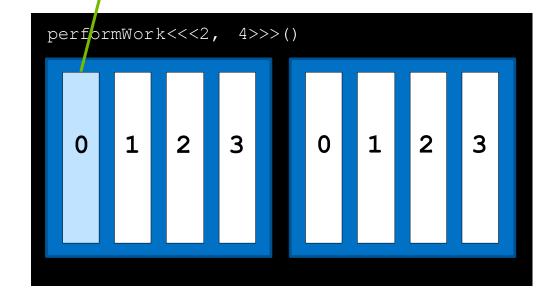




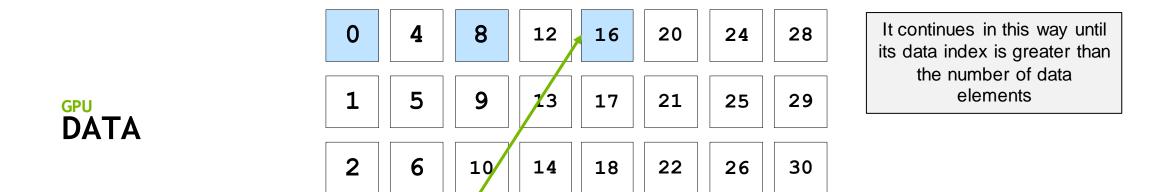


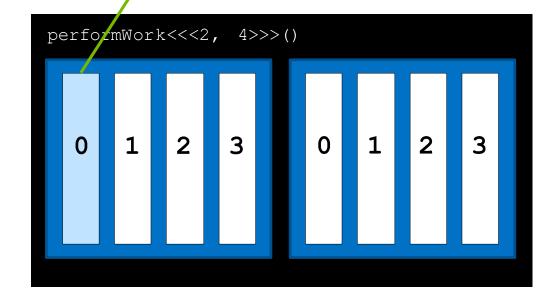




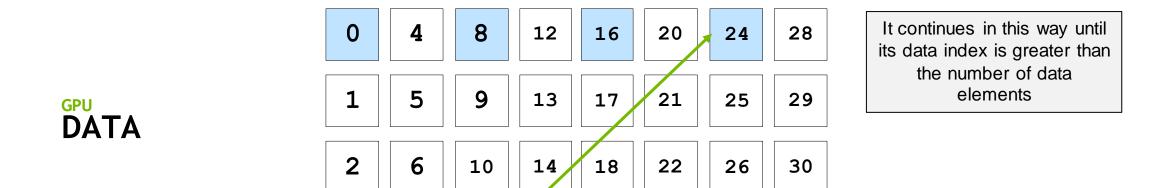




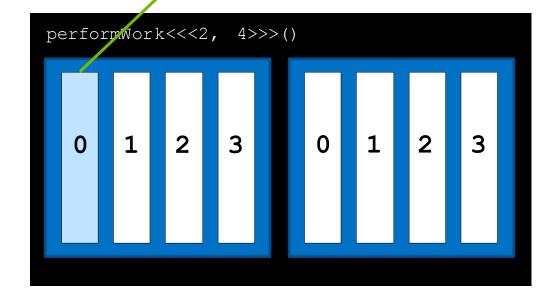




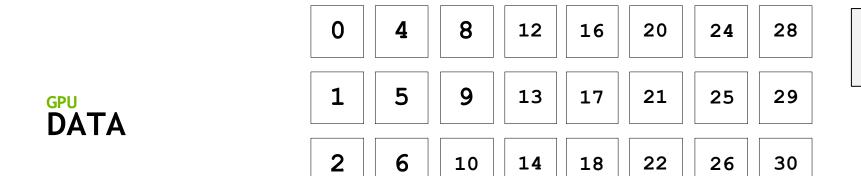






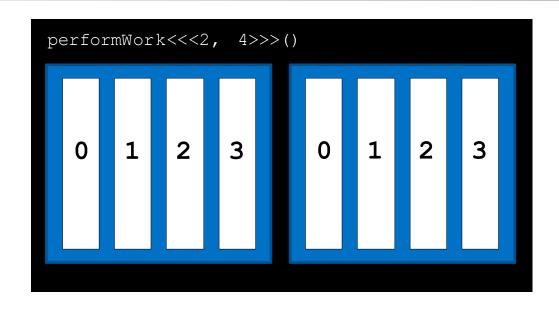




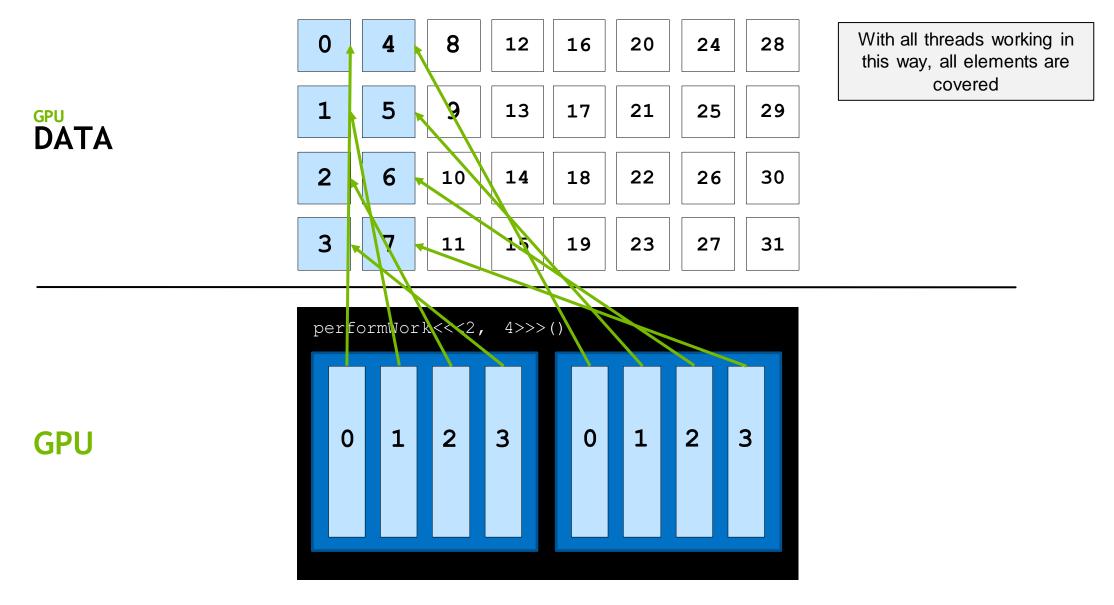


With all threads working in this way, all elements are covered

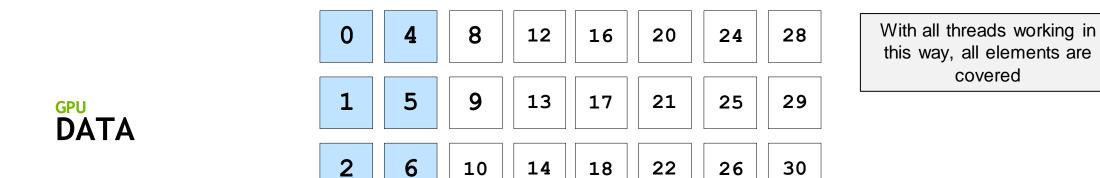






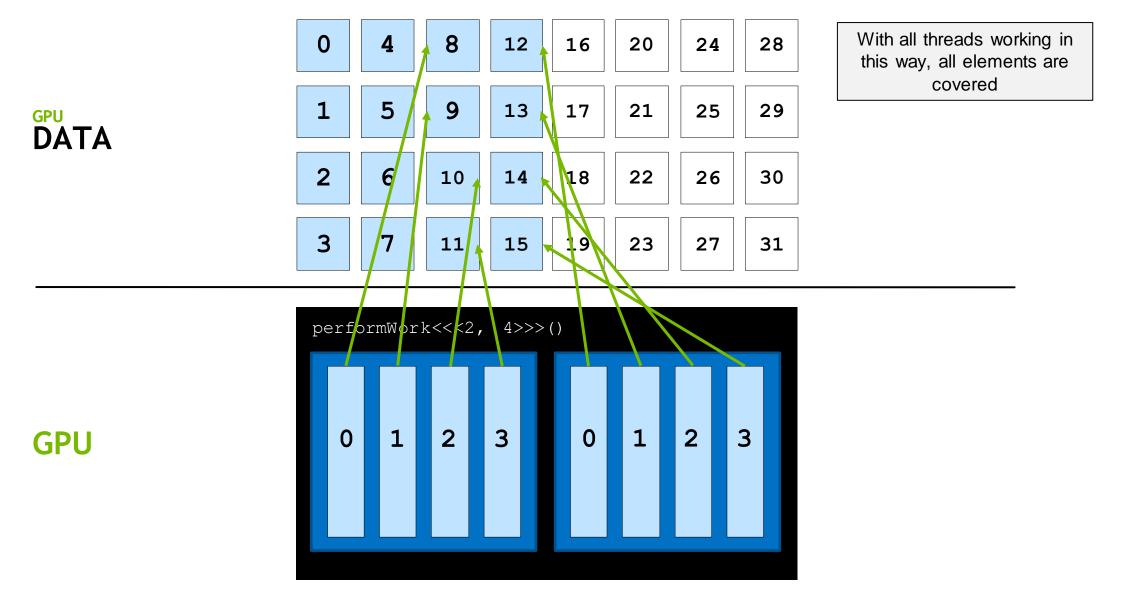


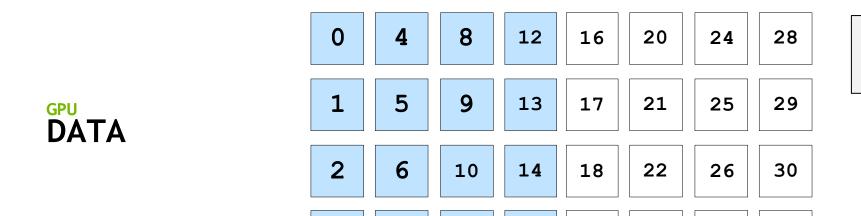




performWork<<<2, 4>>>()

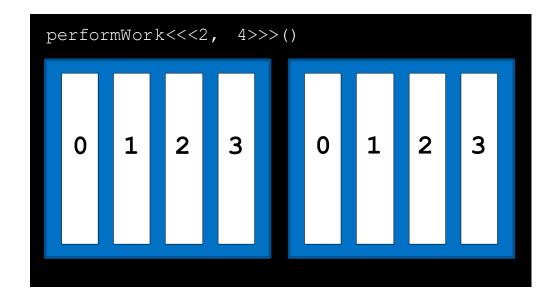




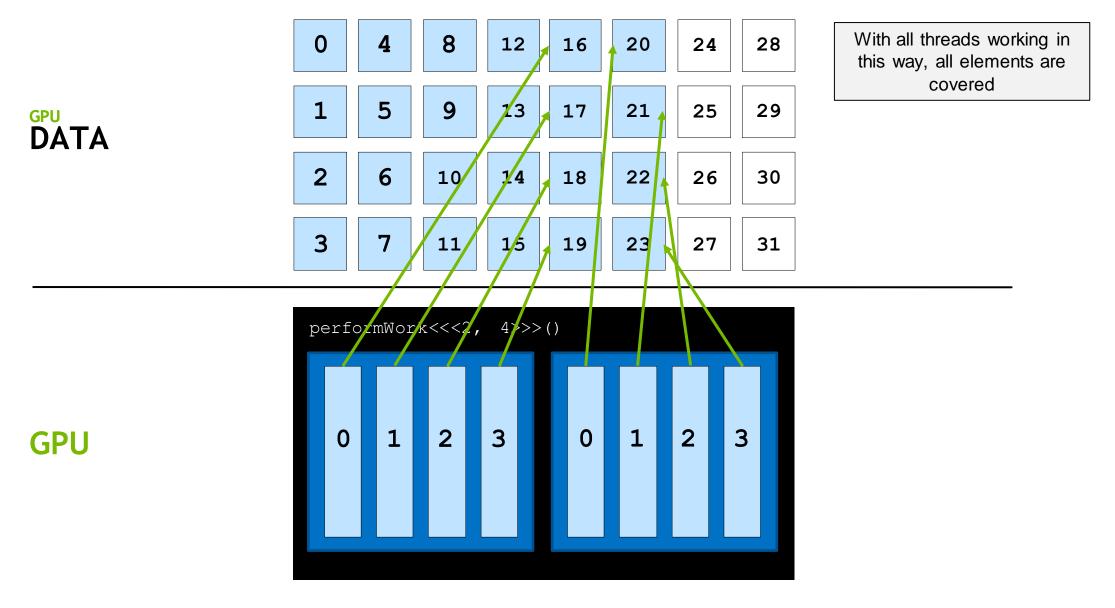


With all threads working in this way, all elements are covered

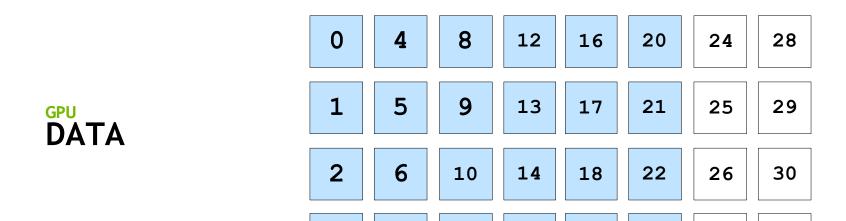






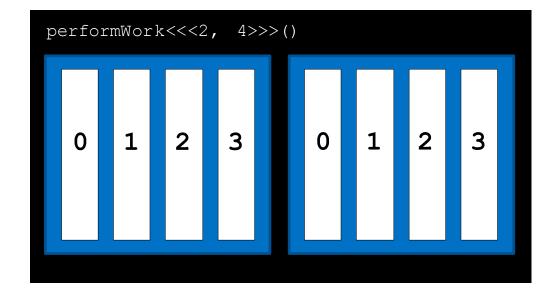




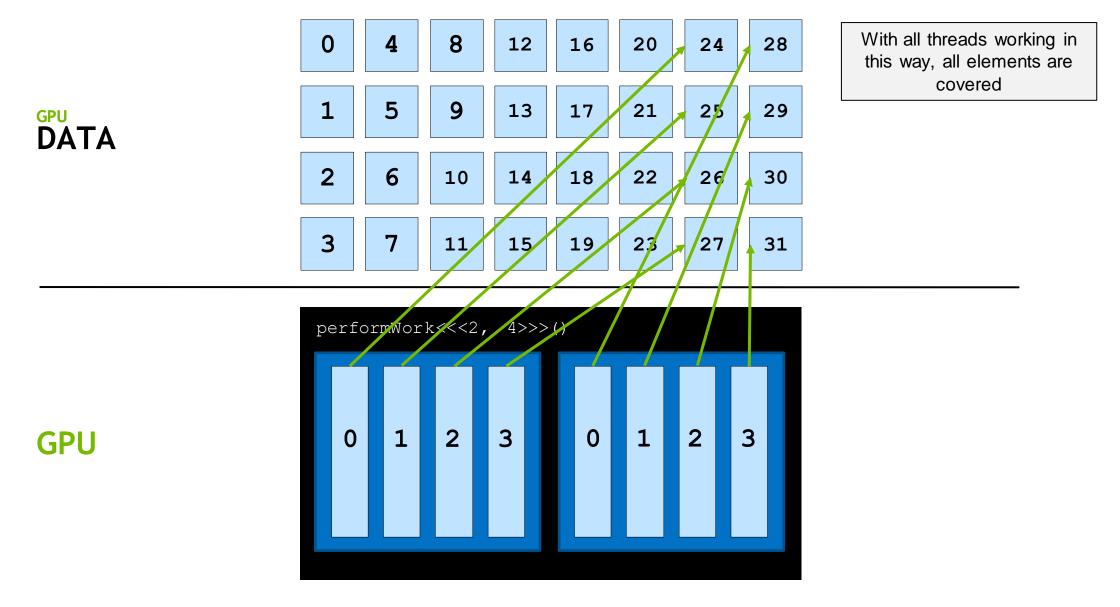


With all threads working in this way, all elements are covered

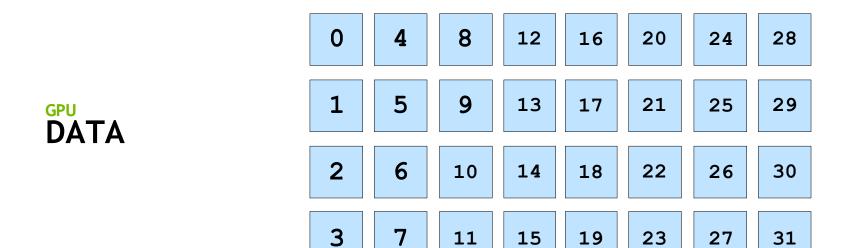
GPU





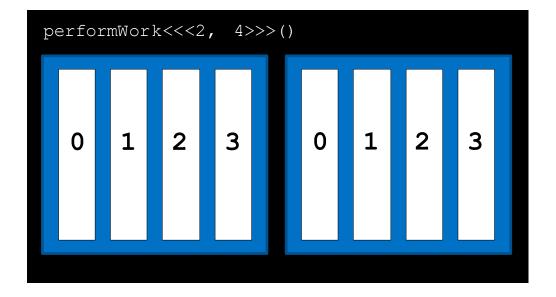




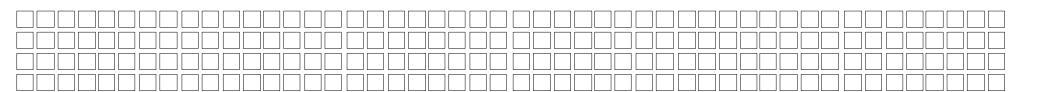


With all threads working in this way, all elements are covered

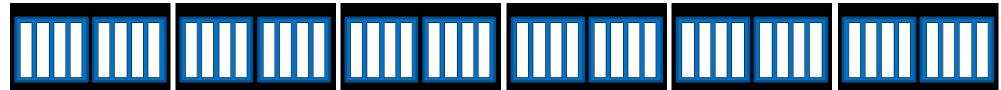








CUDA runs as many blocks in parallel at once as the GPU hardware supports, for massive parallelization





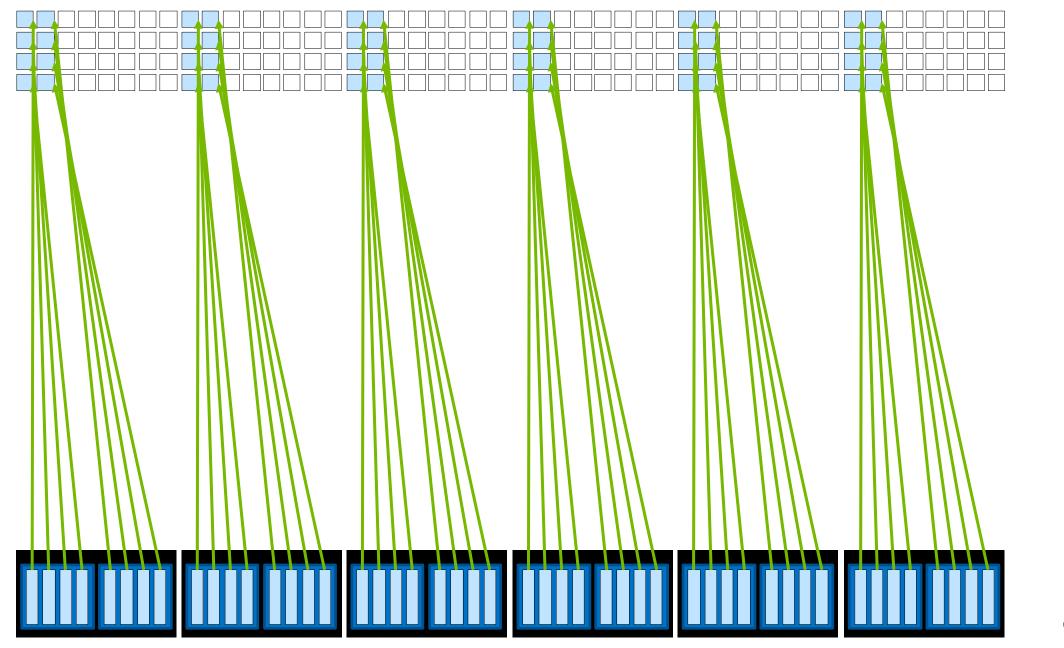




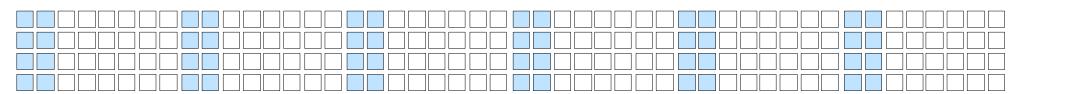


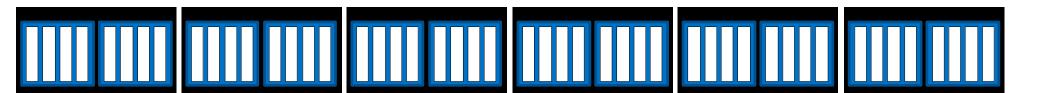




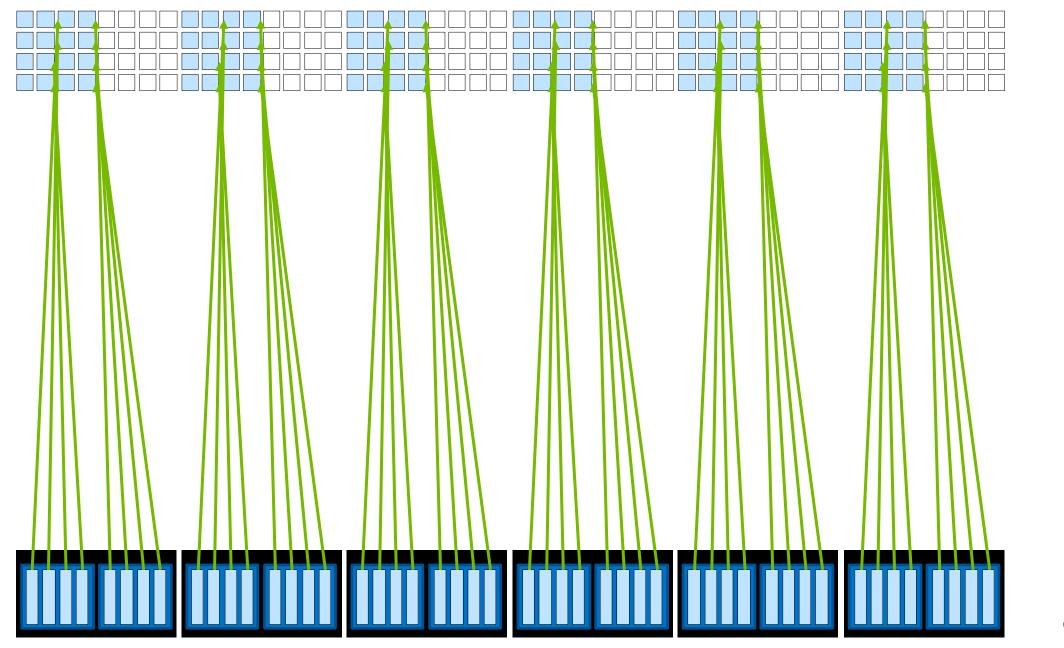




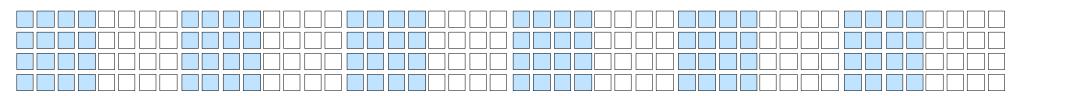


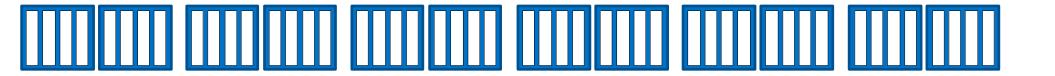




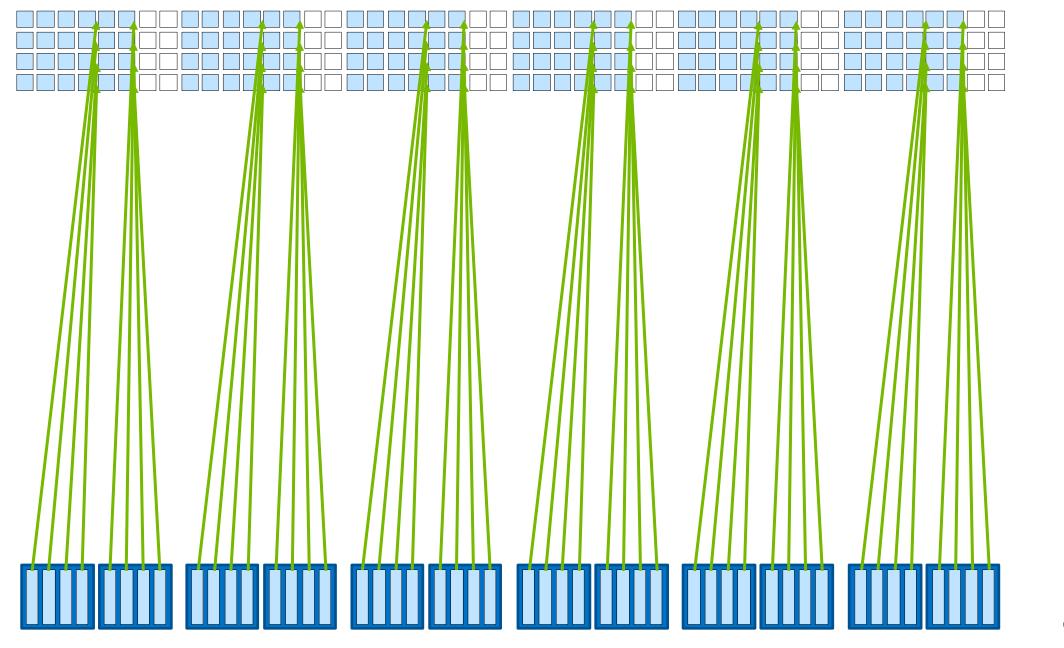




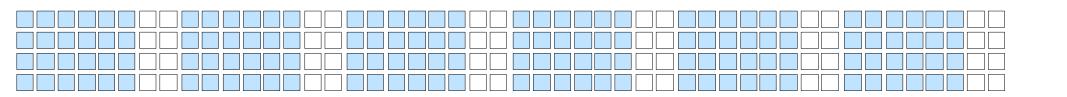


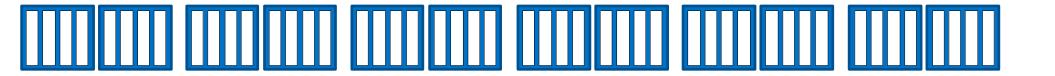




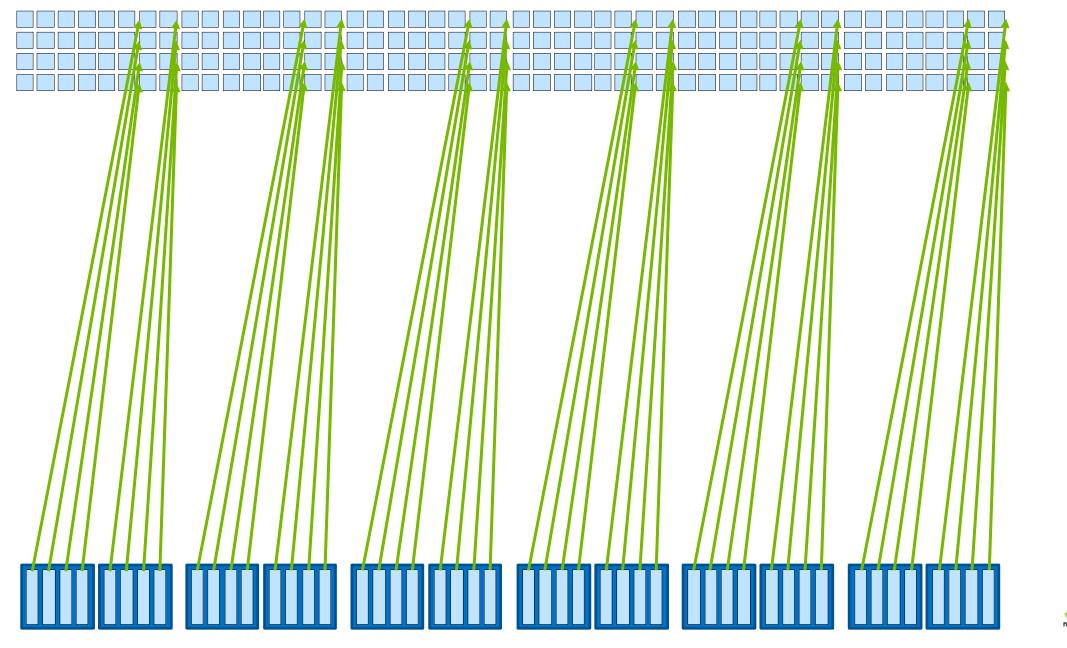




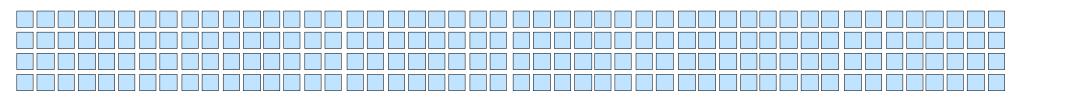


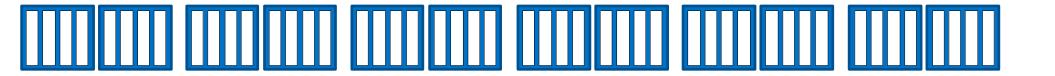
















Glossary

- cudaMallocManaged(): CUDA function to allocate memory accessible by both the CPU and GPUs. Memory allocated this way is called *unified memory* and is automatically migrated between the CPU and GPUs as needed.
- cudaDeviceSynchronize(): CUDA function that will cause the CPU to wait until the GPU is finished working.
- Kernel: A CUDA function executed on a GPU.
- Thread: The unit of execution for CUDA kernels.
- Block: A collection of threads.
- Grid: A collection of blocks.
- **Execution context:** Special arguments given to CUDA kernels when launched using the <<<...>>> syntax. It defines the number of blocks in the grid, as well as the number of threads in each block.
- gridDim.x: CUDA variable available inside executing kernel that gives the number of blocks in the grid
- blockDim.x: CUDA variable available inside executing kernel that gives the number of threads in the thread's block
- blockIdx.x: CUDA variable available inside executing kernel that gives the index the thread's block within the grid
- threadIdx.x: CUDA variable available inside executing kernel that gives the index the thread within the block
- threadIdx.x + blockIdx.x * blockDim.x: Common CUDA technique to map a thread to a data element
- Grid-stride loop: A technique for assigning a thread more than one data element to work on when there are more elements than the number of threads in the grid. The stride is calculated by gridDim.x * blockDim.x, which is the number of threads in the grid.



