view_frames Result Recorded at time: 339.020 world Broadcaster: /robot_state_publisher Average rate: 50.204 Hz Most recent transform: 339.476 (-0.456 sec old) Buffer length: 4.900 sec base_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 50.204 Hz Average rate: 50.204 Hz Most recent transform: 339.476 (-0.456 sec old) Most recent transform: 339.476 (-0.456 sec old) Buffer length: 4.900 sec Buffer length: 4.900 sec cpu_link base_laser Broadcaster: /robot_state_publisher Average rate: 50.204 Hz Most recent transform: 339.476 (-0.456 sec old) Buffer length: 4.900 sec upper_base_link Broadcaster: /robot_state_publisher Average rate: 10.208 Hz Most recent transform: 338.897 (0.123 sec old) Buffer length: 4.800 sec torso_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 50.204 Hz Average rate: 50.204 Hz Average rate: 50.204 Hz Most recent transform: 339.476 (-0.456 sec old) Most recent transform: 339.476 (-0.456 sec old) Most recent transform: 339.476 (-0.456 sec old) Buffer length: 4.900 sec Buffer length: 4.900 sec Buffer length: 4.900 sec head_pan_link left shoulder link right_shoulder_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10.208 Hz Average rate: 10.208 Hz Average rate: 10.208 Hz Most recent transform: 338.897 (0.123 sec old) Most recent transform: 338.897 (0.123 sec old) Most recent transform: 338.897 (0.123 sec old) Buffer length: 4.800 sec Buffer length: 4.800 sec Buffer length: 4.800 sec right_shoulder_forward_link head_tilt_link left_shoulder_forward_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10.208 Hz Average rate: 10.208 Hz Average rate: 10.208 Hz Most recent transform: 338.897 (0.123 sec old) Most recent transform: 338.897 (0.123 sec old) Most recent transform: 338.897 (0.123 sec old) Buffer length: 4.800 sec Buffer length: 4.800 sec Buffer length: 4.800 sec neck_link left_shoulder_up_link right_shoulder_up_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 50.204 Hz Average rate: 50.204 Hz Average rate: 50.204 Hz Most recent transform: 339.476 (-0.456 sec old) Most recent transform: 339.476 (-0.456 sec old) Most recent transform: 339.476 (-0.456 sec old) Buffer length: 4.900 sec Buffer length: 4.900 sec Buffer length: 4.900 sec head link left_upper_arm_link right_upper_arm_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 50.204 Hz Average rate: 10.208 Hz Average rate: 10.208 Hz Most recent transform: 339.476 (-0.456 sec old) Most recent transform: 338.897 (0.123 sec old) Most recent transform: 338.897 (0.123 sec old) Buffer length: 4.900 sec Buffer length: 4.800 sec Buffer length: 4.800 sec right_elbow_link antenna link left elbow link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 50.204 Hz Average rate: 50.204 Hz Most recent transform: 339.476 (-0.456 sec old) Most recent transform: 339.476 (-0.456 sec old) Buffer length: 4.900 sec Buffer length: 4.900 sec left_lower_arm_link right_lower_arm_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10.208 Hz Average rate: 10.208 Hz Most recent transform: 338.897 (0.123 sec old) Most recent transform: 338.897 (0.123 sec old) Buffer length: 4.800 sec Buffer length: 4.800 sec left wrist link right_wrist_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 50.204 Hz Average rate: 50.204 Hz Most recent transform: 339.476 (-0.456 sec old) Most recent transform: 339.476 (-0.456 sec old) Buffer length: 4.900 sec Buffer length: 4.900 sec left_hand_link right_hand_link