view_frames Result Recorded at time: 74.585 map Broadcaster: /amcl Average rate: 45.473 Hz Most recent transform: 75.547 (-0.962 sec old) Buffer length: 2.507 sec odom Broadcaster: /ekf_localization Average rate: 50.394 Hz Most recent transform: 74.580 (0.005 sec old) Buffer length: 2.540 sec base_link Broadcaster: /robot_state_publisher Average rate: 50.394 Hz Most recent transform: 75.080 (-0.495 sec old) Buffer length: 2.540 sec chassis_link Broadcaster: /robot_state_publisher Average rate: 50.394 Hz Broadcaster: /robot_state_publisher Average rate: 50.394 Hz Average rate: 50.394 Hz Average rate: 50.394 Hz Average rate: 50.397 Hz Average rate: 50.397 Hz Average rate: 50.397 Hz Average rate: 50.397 Hz Most recent transform: 75.080 (-0.495 sec old) Most recent transform: 75.080 (-0.495 sec old) Most recent transform: 75.080 (-0.495 sec old) Most recent transform: 75.080 (-0.495 sec old) Most recent transform: 74.566 (0.019 sec old) Most recent transform: 74.566 (0.019 sec old) Most recent transform: 74.566 (0.019 sec old) Most recent transform: 74.566 (0.019 sec old) Buffer length: 2.540 sec Buffer length: 2.540 sec Buffer length: 2.540 sec Buffer length: 2.540 sec Buffer length: 2.520 sec Buffer length: 2.520 sec Buffer length: 2.520 sec Buffer length: 2.520 sec front_left_wheel_link front_right_wheel_link rear_left_wheel_link rear_right_wheel_link fenders_link imu_link navsat_link mid_mount Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 50.394 Hz Average rate: 50.394 Hz Most recent transform: 75.080 (-0.495 sec old) Most recent transform: 75.080 (-0.495 sec old) Buffer length: 2.540 sec Buffer length: 2.540 sec front_mount rear_mount Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 50.394 Hz Average rate: 50.394 Hz Most recent transform: 75.080 (-0.495 sec old) Most recent transform: 75.080 (-0.495 sec old) Buffer length: 2.540 sec Buffer length: 2.540 sec front_laser_mount front_camera_mount Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 50.394 Hz Average rate: 50.394 Hz Most recent transform: 75.080 (-0.495 sec old) Most recent transform: 75.080 (-0.495 sec old) Buffer length: 2.540 sec Buffer length: 2.540 sec front_laser front_camera_beam Broadcaster: /robot_state_publisher Average rate: 50.394 Hz Most recent transform: 75.080 (-0.495 sec old) Buffer length: 2.540 sec front_camera Broadcaster: /robot_state_publisher Average rate: 50.394 Hz Most recent transform: 75.080 (-0.495 sec old) Buffer length: 2.540 sec front_camera_optical