view_frames Result Recorded at time: 1220.703 map Broadcaster: /ekf_localization_with_gps Average rate: 50.391 Hz Most recent transform: 1220.700 (0.003 sec old) Buffer length: 2.560 sec odom Broadcaster: /ekf_localization Average rate: 50.391 Hz Most recent transform: 1220.700 (0.003 sec old) Buffer length: 2.560 sec base_link Broadcaster: /robot_state_publisher Average rate: 50.394 Hz Most recent transform: 1221.180 (-0.477 sec old) Buffer length: 2.540 sec chassis_link Broadcaster: /robot_state_publisher Average rate: 50.394 Hz Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 50.394 Hz Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 50.394 Hz Most recent transform: 1220.674 (0.029 sec old) Most recent transform: 1220.674 (0.029 sec old) Most recent transform: 1220.674 (0.029 sec old) Most recent transform: 1221.180 (-0.477 sec old) Most recent transform: 1220.674 (0.029 sec old) Buffer length: 2.540 sec rear_left_wheel_link front_left_wheel_link front_right_wheel_link rear_right_wheel_link fenders_link imu_link navsat_link mid_mount Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 50.394 Hz Average rate: 50.394 Hz Most recent transform: 1221.180 (-0.477 sec old) Most recent transform: 1221.180 (-0.477 sec old) Buffer length: 2.540 sec Buffer length: 2.540 sec front_mount rear_mount Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 50.394 Hz Average rate: 50.394 Hz Buffer length: 2.540 sec Buffer length: 2.540 sec front_laser_mount front_camera_mount Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 50.394 Hz Average rate: 50.394 Hz Most recent transform: 1221.180 (-0.477 sec old) Most recent transform: 1221.180 (-0.477 sec old) Buffer length: 2.540 sec Buffer length: 2.540 sec front_camera_beam front_laser Broadcaster: /robot state publisher Average rate: 50.394 Hz Most recent transform: 1221.180 (-0.477 sec old) Buffer length: 2.540 sec front_camera Broadcaster: /robot_state_publisher Average rate: 50.394 Hz Most recent transform: 1221.180 (-0.477 sec old) Buffer length: 2.540 sec front_camera_optical