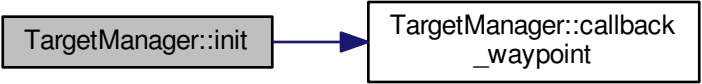


TargetManager::init



```
graph LR; A[TargetManager::init] --> B[TargetManager::callback_waypoint]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is shaded gray and contains the text 'TargetManager::init'. A dark blue arrow points from the right side of this box to the left side of the right box. The right box is white with a black border and contains the text 'TargetManager::callback\_waypoint'.

TargetManager::callback  
\_waypoint