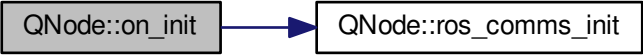


QNode::on\_init



```
graph LR; A[QNode::on_init] --> B[QNode::ros_comms_init]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is shaded gray and contains the text 'QNode::on\_init'. The right box is white and contains the text 'QNode::ros\_comms\_init'. A dark blue arrow points from the right side of the gray box to the left side of the white box.

QNode::ros\_comms\_init