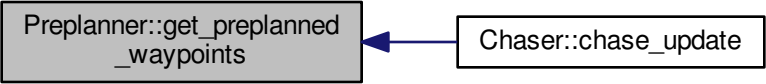


Preplanner::get\_preplanned  
\_waypoints



```
graph LR; A[Chaser::chase_update] --> B[Preplanner::get_preplanned_waypoints]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The box on the left is shaded gray and contains the text 'Preplanner::get\_preplanned\_waypoints'. The box on the right is white with a black border and contains the text 'Chaser::chase\_update'. A dark blue arrow points from the right box to the left box, indicating a function call or data flow.

Chaser::chase\_update