

## Experiment 7: Three Phase Fully Controlled Converter

### Introduction to the Experiment

This experiment is aimed at converting AC (Three phase) to DC using a fully controlled converter. The circuit is implemented in simulation as well as hardware and the performance is studied.

### Learning outcomes:

#### Circuit Diagram:

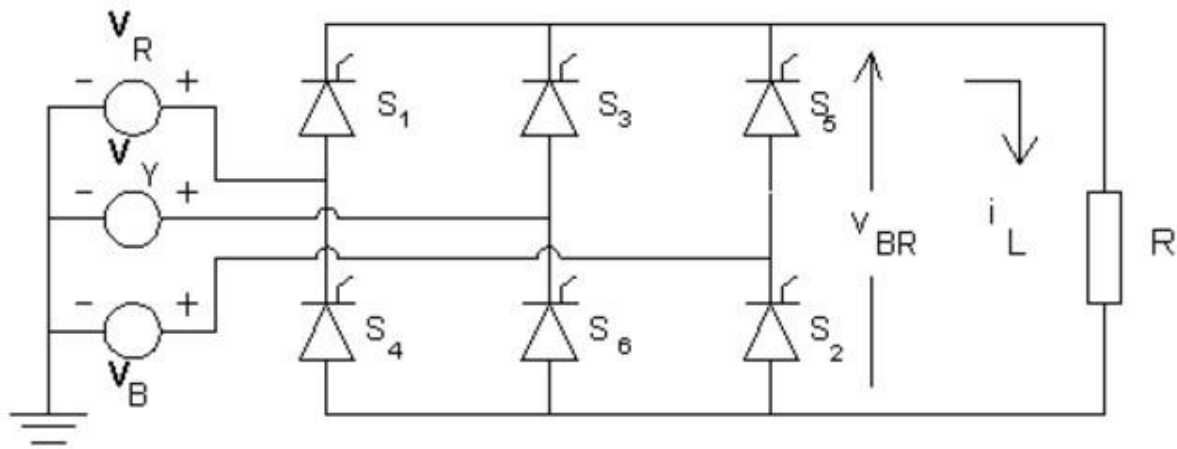


Figure 1 Circuit diagram

#### Theory:

The three-phase bridge rectifier circuit has three-legs, each phase connected to one of the three phase voltages. Alternatively, it can be seen that the bridge circuit has two halves, the positive half consisting of the SCRs  $S_1$ ,  $S_3$  and  $S_5$  and the negative half consisting of the SCRs  $S_2$ ,  $S_4$  and  $S_6$ . At any time when there is current flow, one SCR from each half conducts. If the phase sequence of the source be RYB, the SCRs are triggered in the sequence  $S_1$ ,  $S_2$ ,  $S_3$ ,  $S_4$ ,  $S_5$ ,  $S_6$  and  $S_1$  and so on.

The operation of the circuit is first explained with the assumption that diodes are used in place of the SCRs. The three-phase voltages vary as shown below.

Let the three-phase voltages be defined as shown below.

$$v_R(\theta) = E * \sin(\theta), \quad v_Y(\theta) = E * \sin(\theta - 120^\circ), \quad \text{and} \quad v_B(\theta) = E * \sin(\theta + 120^\circ).$$

It can be seen that the R-phase voltage is the highest of the three-phase voltages when  $\theta$  is in the range from  $30^\circ$  to  $150^\circ$ . It can also be seen that Y-phase voltage is the highest of the three-phase voltages when  $\theta$  is in the range from  $150^\circ$  to  $270^\circ$  and that B-phase voltage is the highest of the three-phase voltages when  $\theta$  is in the range from  $270^\circ$  to  $390^\circ$  or  $30^\circ$  in the next cycle. We also find that R-phase voltage is the lowest of the three-phase voltages when  $\theta$  is in the range from  $210^\circ$  to  $330^\circ$ . It can also be seen that Y-phase voltage is the lowest of the three-phase voltages when  $\theta$  is in the range from  $330^\circ$  to  $450^\circ$  or  $90^\circ$  in the next cycle, and that

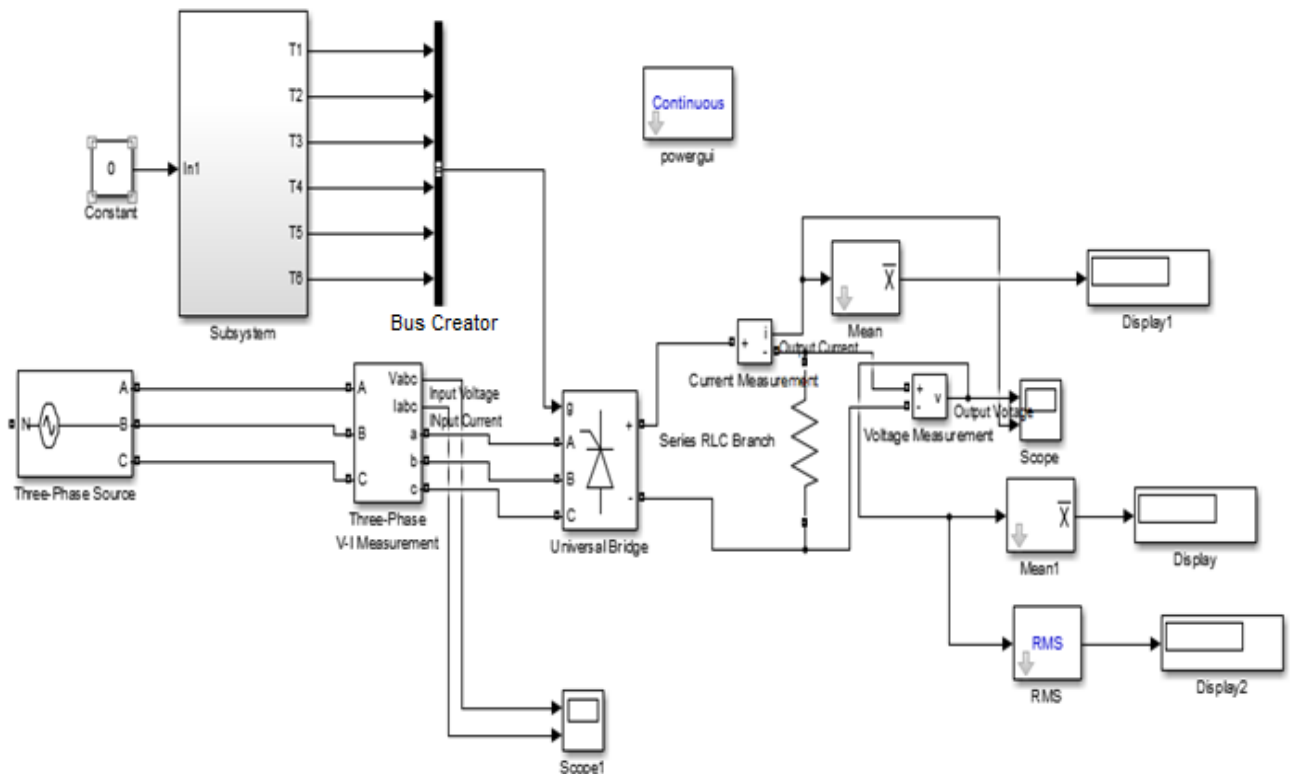
B-phase voltage is the lowest when  $\alpha$  is in the range from  $90^\circ$  to  $210^\circ$ . If diodes are used, diode  $D_1$  in place of  $S_1$  would conduct from  $30^\circ$  to  $150^\circ$ , diode  $D_3$  would conduct from  $150^\circ$  to  $270^\circ$  and diode  $D_5$  from  $270^\circ$  to  $390^\circ$  or  $30^\circ$  in the next cycle. In the same way, diode  $D_4$  would conduct from  $210^\circ$  to  $330^\circ$ , diode  $D_6$  from  $330^\circ$  to  $450^\circ$  or  $90^\circ$  in the next cycle, and diode  $D_2$  would conduct from  $90^\circ$  to  $210^\circ$ . The positive rail of output voltage of the bridge is connected to the topmost segments of the envelope of three-phase voltages and the negative rail of the output voltage to the lowest segments of the envelope.

## 1 a). Simulation of full wave Three phase fully controlled converter in MATLAB Simulink

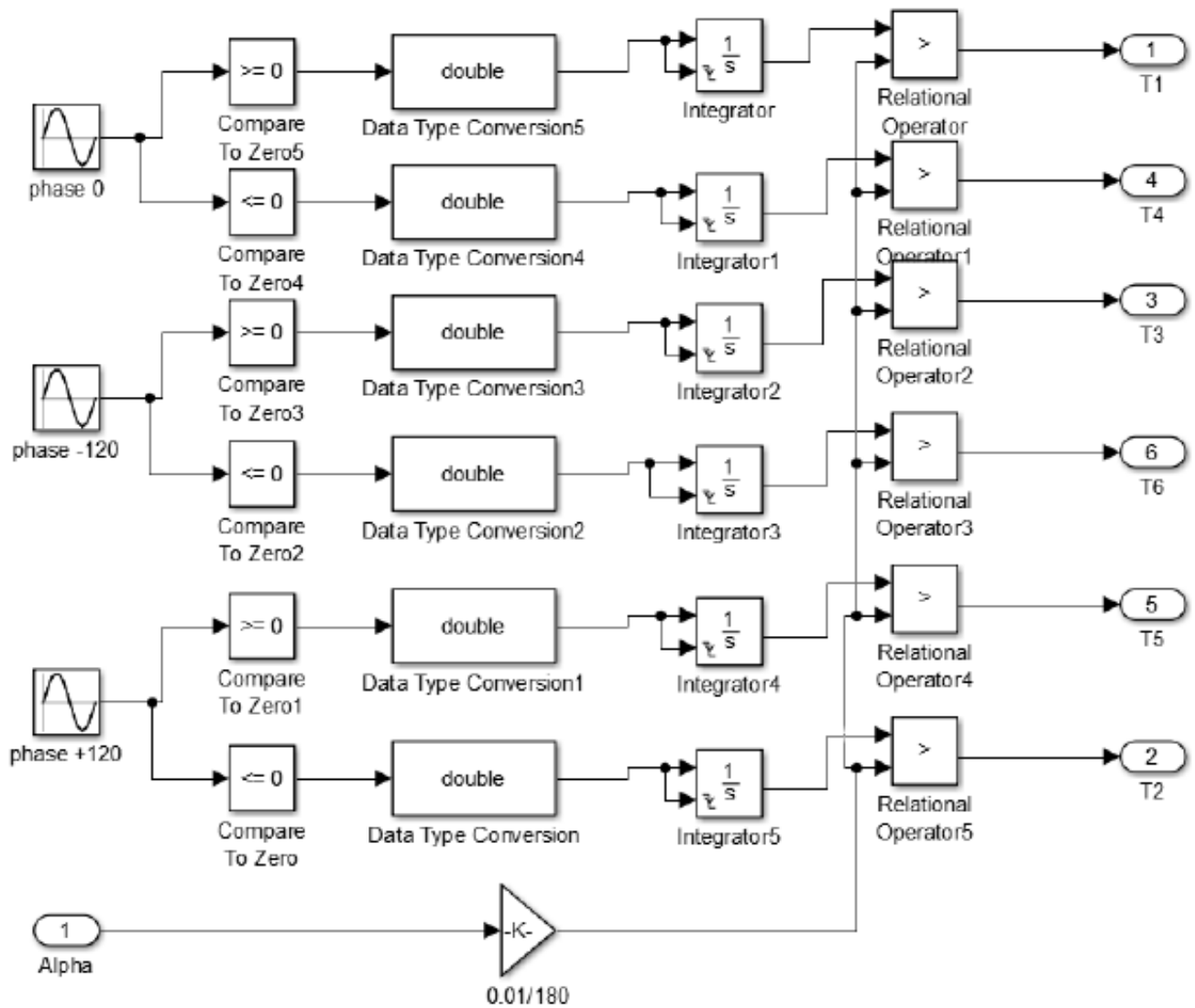
Aim: To simulate the converter in MATLAB Simulink

### PROBLEM 1:

Implement the 3-phase *fully controlled* full wave converter with an R load of **100  $\Omega$** .  
(Input voltage: Phase-to-phase rms voltage (V) = **61.2 V, 50Hz**)



# Gate Triggering circuit





### Source Block Parameters: Phase 0

Samples per period =  $2\pi / (\text{Frequency} * \text{Sample time})$

Number of offset samples =  $\text{Phase} * \text{Samples per period} / (2\pi)$

Use the sample-based sine type if numerical problems due to running for large times (e.g. overflow in absolute time) occur.

#### Parameters

Sine type: Time based

Time (t): Use simulation time

Amplitude:

1

Bias:

0

Frequency (rad/sec):

$100\pi$

Phase (rad):

0

Sample time:

0



OK

Cancel

Help

Apply



Source Block Parameters: Phase - 120

Number of offset samples =  $\text{Phase} * \text{Samples per period} / (2 * \pi)$

Use the sample-based sine type if numerical problems due to running for large times (e.g. overflow in absolute time) occur.

Parameters

Sine type: Time based

Time (t): Use simulation time

Amplitude:

1

Bias:

0

Frequency (rad/sec):

$100 * \pi$

Phase (rad):

$-120 * (\pi / 180)$

Sample time:

0

☒ Interpret vector parameters as 1-D

? OK Cancel Help Apply



Source Block Parameters: Phase + 120

Number of offset samples =  $\text{Phase} * \text{Samples per period} / (2 * \pi)$

Use the sample-based sine type if numerical problems due to running for large times (e.g. overflow in absolute time) occur.

Parameters

Sine type: Time based

Time (t): Use simulation time

Amplitude:  
1

Bias:  
0

Frequency (rad/sec):  
 $100 * \pi$

Phase (rad):  
 $120 * (\pi / 180)$

Sample time:  
0

☒ Interpret vector parameters as 1-D

?

OK

Cancel

Help

Apply



Function Block Parameters: Data Type Conversion

**Data Type Conversion**

Convert the input to the data type and scaling of the output.

The conversion has two possible goals. One goal is to have the Real World Values of the input and the output be equal. The other goal is to have the Stored Integer Values of the input and the output be equal. Overflows and quantization errors can prevent the goal from being fully achieved.

**Parameters**

Output minimum:  Output maximum:

Output data type: double >>

☐ Lock output data type

Input and output to

Integer rounding mode:

☐ Saturate on integer overflow

**Output data type dropdown menu:**

- Inherit: Inherit via back propagation
- double
- single
- int8
- uint8
- int16
- uint16
- int32
- uint32
- boolean
- fixdt(1,16)
- fixdt(1,16,0)
- fixdt(1,16,2^0,0)
- Enum: <class name>
- <data type expression>
- Refresh data types ---

? Apply



Function Block Parameters: Integrator6

**Integrator**  
Continuous-time integration of the input signal.

**Parameters**

External reset: falling

Initial condition: none

Initial condition: rising

Initial condition: falling

Initial condition: either

Initial condition: level

Initial condition: level hold

☐ Limit output

Upper saturation limit: inf

Lower saturation limit: -inf

☐ Show saturation port

☐ Show state port

Absolute tolerance: auto

☐ Ignore limit and reset when linearizing

☒ Enable zero crossing detection

? OK Cancel Help Apply



## b) Hardware Implementation of 3-Phase (R Load)

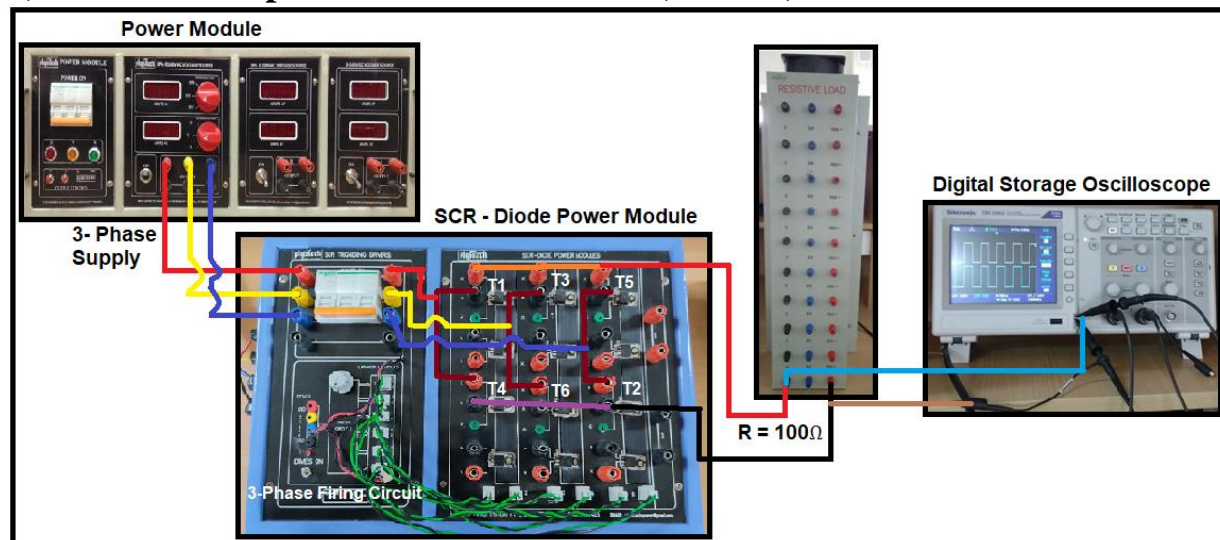


Fig. 3 Hardware implementation of 3-phase fully controlled converter

### Procedure:

1. Connect the circuit as shown in Fig. 3 (with R load ( **$R=100$  ohms**)), Connect CRO probes across the R load to measure the output voltage.
2. Switch ON the MCB of 3 $\emptyset$  supply on the Left hand side of your Experimental Table.
3. Switch ON the MCB on the POWER MODULE kit.
4. Switch ON the MCB on the SCR-Diode Power module and slowly increase the Voltage to reach up to **61.2 V in RMS** using + symbol Push Button in the Power Module kit.

*Note: The Voltage Adjustment Controls are a pair of push buttons to finely adjust the voltage to required value.*

5. Switch on the driver power switch
6. Connect DSO probes across the **R** Load to measure the output voltage.
7. Vary the firing angle as mentioned in the “Exp7\_Part B.doc” file.
8. Observe the Output voltage waveforms in the DSO.

**Conclusion:** Obtain the results as per “Exp7\_Part B.doc” file.