

# CHAPTER 1

## PROBLEM DOMAIN DESCRIPTION

Surveillance and reconnaissance are essential components of modern warfare, providing valuable information about enemy activities, monitoring sensitive areas, and aiding in search and rescue operations. With the advancement of technology, drones equipped with FPV cameras have become an indispensable tool for the military in gathering real-time information without putting personnel in harm's way.

The Indian Armed Forces have also recognized the potential of drones equipped with FPV cameras in their operations. The integration of drones in the military has significantly improved situational awareness, enhanced the military's ability to monitor remote and inaccessible areas, and enabled them to obtain high-resolution images and videos of the battlefield. The use of drones has also reduced the risk of human casualties and provided a more cost-effective alternative to traditional reconnaissance methods.

In recent years, the integration of machine learning techniques in the surveillance camera with drone system has further enhanced its capabilities. Machine learning allows the system to automatically detect and classify objects, analyze vast amounts of data, and identify patterns and trends that would be difficult to detect manually. The use of machine learning has opened up new possibilities for the Indian Armed Forces, including the ability to conduct more effective reconnaissance and surveillance operations and the ability to process data faster and more accurately.

This project aims to explore the surveillance camera with drone system in the Indian Armed Forces with machine learning in detail. We will discuss the components of the system, including the drone, FPV camera, ground control station, and communication systems. We will also examine the use cases of the system, including border surveillance, search and rescue operations, monitoring of sensitive areas, and maritime reconnaissance.

The project will also cover the technical details of the system, including the machine learning algorithms used, data processing techniques, and the integration of the machine learning models into the system. Additionally, we will discuss the benefits of using machine learning in the surveillance camera with drone system in the Indian Armed Forces, including improved situational awareness, faster and more accurate data processing, and the ability to detect and classify objects automatically.

Furthermore, we will examine the challenges and limitations of using machine learning in the system, including technical limitations, ethical concerns, and regulatory issues. Lastly, the project will discuss the future developments in surveillance camera with drone systems in the Indian Armed Forces with machine learning, including advancements in technology and potential new use cases.

## **1.1 system overview:**

The surveillance camera with drone system used by the Indian Armed Forces is an advanced technology that integrates drones equipped with FPV cameras and ground control stations to monitor and survey military operations. The system allows for real-time data transmission and analysis, providing valuable insights into the battlefield and enhancing situational awareness.

The drone used in the system is a remotely piloted aircraft that can fly autonomously or be controlled by an operator using a ground control station. The drone is equipped with an FPV camera that can capture high-resolution images and videos in real-time. The camera is mounted on a gimbal that allows it to rotate and tilt, providing a 360-degree view of the surroundings.

The ground control station is the command center for the drone and is responsible for controlling and monitoring its operations. The ground control station is equipped with a display screen that displays live video feeds from the drone's camera and provides the operator with real-time information on the drone's position, altitude, speed, and battery life.

The communication system used in the surveillance camera with drone system is a critical component that enables the drone and ground control station to communicate with each other. The communication system consists of two parts: the command link and the video link. The command link is used to send control signals from the ground control station to the drone, while the video link is used to transmit live video feeds from the drone's camera to the ground control station.

The system's architecture is based on a client-server model, where the drone acts as the client and the ground control station as the server. The drone sends commands to the ground control station, and the ground control station responds with data and instructions.

The machine learning component of the surveillance camera with drone system involves using algorithms and statistical models to analyze data from the drone's camera. The machine learning algorithms used in the system can automatically detect and classify objects, recognize patterns and trends, and identify anomalies in the data. Machine learning is a critical component of the system as it enables the drone to process data faster and more accurately than manual methods.

The architecture of the machine learning component of the system involves data preprocessing, model training, and inference. The data preprocessing step involves cleaning and normalizing the data, removing noise and outliers, and converting the data into a suitable format for machine learning models. The model training step involves training the machine learning models on the preprocessed data, which involves selecting appropriate models, optimizing hyperparameters, and evaluating model performance. The inference step involves applying the trained models to new data to make predictions or classifications.

The surveillance camera with drone system in the Indian Armed Forces has several use cases, including border surveillance, search and rescue operations, monitoring of sensitive areas, and maritime reconnaissance. In border surveillance, drones equipped with FPV cameras can fly over the border and transmit real-time data to the ground control station, enabling the military to detect any suspicious activities. In search and rescue operations, drones can be used to locate missing persons or vehicles in remote areas, reducing the risk to human search teams. In monitoring sensitive areas, drones can fly over critical infrastructure or military installations and detect any intruders or suspicious activities. In maritime reconnaissance, drones can be used to monitor shipping lanes, detect piracy or smuggling, and provide real-time information on weather and sea conditions.

In conclusion, the surveillance camera with drone system used by the Indian Armed Forces is an advanced technology that integrates drones equipped with FPV cameras and ground control stations to monitor and survey military operations. The system has several use cases, including border surveillance, search and rescue operations, monitoring of sensitive areas, and maritime reconnaissance. The system's architecture is based on a client-server model, where the drone acts as the client and the ground control station as the server. The communication system used in the system is critical to enabling the drone and ground control station to communicate.

## CHAPTER 2

### LITERATURE SURVEY

Absolutely, diving deeper into each section will provide a more comprehensive understanding of drone-based surveillance cameras for the Indian Armed Forces:

Drone technology has emerged as a transformative asset in modern military operations, revolutionizing the landscape of surveillance and reconnaissance. Within this context, the Indian Armed Forces are increasingly exploring the potential of drones equipped with advanced surveillance cameras to bolster their capabilities in safeguarding national security.

The evolution of drone technology has been marked by significant advancements in both hardware and software. Drones, also known as Unmanned Aerial Vehicles (UAVs), have transitioned from rudimentary reconnaissance tools to sophisticated aerial platforms capable of carrying high-resolution cameras and an array of sensors. These advancements have augmented their role in military applications, offering unparalleled advantages in gathering real-time intelligence, monitoring terrains, and conducting precision strikes.

In the context of the Indian Armed Forces, drone-based surveillance cameras offer a multitude of advantages. They provide a strategic edge by enabling efficient border patrolling, enhancing situational awareness in conflict zones, and supporting counter-terrorism operations. Their ability to navigate diverse terrains, including rugged landscapes and densely populated areas, makes them invaluable assets in scenarios where traditional surveillance methods prove challenging.

#### **2.1. Drone Technology in Surveillance:**

**Evolution of Drone Technology:** Trace the historical development of drones and their integration into military operations worldwide, emphasizing advancements in surveillance capabilities.

**Role in Military Applications:** Detail how drones have revolutionized reconnaissance, intelligence gathering, and battlefield awareness, highlighting their pivotal role in modern warfare.

#### **2.2. Applications and Benefits:**

**Operational Use Cases:** Explore specific instances where drone-based surveillance has been instrumental for the Indian Armed Forces, such as border patrolling, counter-terrorism operations, or disaster management.

**Benefits of Drone Surveillance:** Elaborate on the advantages like increased situational awareness, reduced risk to human personnel, and enhanced response times.

#### **2.3. Challenges and Limitations:**

**Technological Constraints:** Discuss the limitations related to battery life, payload capacity, and range that impact the effectiveness of drone surveillance.

**Regulatory Hurdles:** Examine legal and regulatory barriers hindering the widespread adoption of drone-based surveillance in India, including airspace regulations and privacy laws.

## Technical Aspects

**Camera Specifications:** Detail the technical requirements for surveillance cameras mounted on drones, considering factors like resolution, zoom capabilities, stabilization, and adaptability to various environmental conditions.

**Sensor Technologies:** Discuss advanced sensor technologies used for specialized surveillance purposes, such as infrared, LiDAR, or hyperspectral imaging, and their relevance in military applications.

## Indian Armed Forces' Requirements

**Strategic Initiatives:** Review ongoing or completed projects by the Indian Armed Forces focusing on drone-based surveillance, highlighting their objectives, outcomes, and future plans.

**Tailored Solutions:** Address specific needs and preferences of the Indian Armed Forces concerning surveillance cameras on drones, emphasizing customization for operational effectiveness.

## Regulatory and Ethical Considerations

**Legal Framework:** Explore the existing legal framework governing the use of drones in India, including policies related to airspace regulation, licensing, and data privacy.

**Ethical Implications:** Discuss the ethical considerations surrounding surveillance activities by drones, focusing on privacy concerns, data security, and the impact on civilian populations.

Expanding on these aspects will provide a detailed and comprehensive literature survey on drone-based surveillance cameras for the Indian Armed Forces, catering to the technical, operational, regulatory, and ethical dimensions of this technology.

## **CHAPTER 3**

### **MAJOR OBJECT AND SCOPE OF THIS PROJECT**

#### **3.1. Major Objectives:**

**Enhanced Surveillance Capabilities:** The primary objective of this project is to develop and implement a highly efficient and technologically advanced drone-based surveillance system for the Indian Armed Forces. This system aims to significantly enhance their surveillance capabilities in diverse terrains and operational scenarios.

**Tailored Solutions for Military Applications:** The project seeks to design and customize drone-mounted surveillance cameras specifically for military use. These solutions will be engineered to meet the unique requirements of the Indian Armed Forces, ensuring optimal performance in various strategic and tactical operations.

**Addressing Operational Challenges:** One of the key objectives is to overcome the operational challenges associated with traditional surveillance methods by leveraging the agility, versatility, and real-time monitoring capabilities offered by drone-based systems.

**Integration of Advanced Technologies:** The project aims to integrate cutting-edge technologies, including high-resolution cameras, specialized sensors (such as thermal imaging and LiDAR), and robust data transmission systems, to optimize surveillance efficiency and accuracy.

#### **3.2. Scope:**

**Technology Development:** The project encompasses the research, development, and testing of advanced surveillance cameras and sensor systems suitable for integration with drones. This includes focusing on high-resolution imaging, night vision capabilities, and adaptability to various environmental conditions.

**Customization for Military Operations:** The scope involves tailoring the surveillance system to meet the specific needs and challenges faced by the Indian Armed Forces. This includes considerations for border surveillance, counter-terrorism operations, disaster management, and other strategic military applications.

**Compliance with Regulations and Standards:** The project will ensure compliance with existing aviation laws, military protocols, and ethical guidelines governing the use of drones and surveillance technologies in India. This includes addressing data privacy concerns and adherence to airspace regulations.

**Operational Integration and Training:** Beyond technology development, the project scope extends to the integration of the developed surveillance systems into the existing military infrastructure. It also involves providing necessary training and guidance to military personnel for effective utilization of these systems in their operations.

**Continuous Improvement and Adaptation:** The scope encompasses a framework for continuous improvement, adaptation, and upgradation of the surveillance systems based on feedback from field operations and advancements in technology. This iterative approach aims to ensure sustained effectiveness and relevance.

This project's objectives and scope focus on developing a specialized drone-based surveillance system tailored to the Indian Armed Forces' needs, addressing technological advancements, operational challenges, and compliance with regulatory and ethical standards.

### 3.3. Use case :

The surveillance camera with drone system in the Indian Armed Forces has several use cases, including border surveillance, search and rescue operations, monitoring of sensitive areas, and maritime reconnaissance. In this section, we will discuss each of these use cases in detail.

**Border Surveillance:** One of the most significant use cases of the surveillance camera with drone system in the Indian Armed Forces is border surveillance. The system's drones can be used to monitor the borders of the country, providing real-time data on any suspicious activities. This is particularly important in areas where the terrain is difficult to navigate or where traditional surveillance methods are not effective.

The drones can be equipped with thermal imaging cameras, which can detect heat signatures and identify people or vehicles even in low light conditions. This enables the military to detect any illegal crossings and take immediate action to prevent any security breaches.

Furthermore, the drones can fly over the border and transmit real-time data to the ground control station, enabling the military to detect any suspicious activities. The ground control station can use machine learning algorithms to analyze the data and detect any unusual movements, such as groups of people moving towards the border.

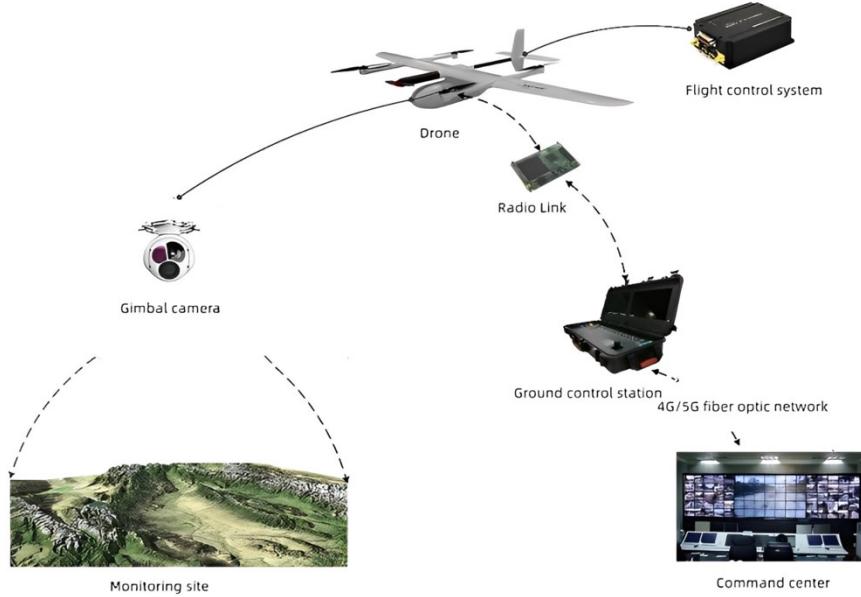
**Search and Rescue Operations:** Another important use case of the surveillance camera with drone system in the Indian Armed Forces is search and rescue operations. The drones can be used to locate missing persons or vehicles in remote areas, reducing the risk to human search teams. The drones can fly over the search area and transmit real-time data to the ground control station, enabling the search teams to locate the missing person or vehicle quickly.

The drones can also be equipped with thermal imaging cameras, which can detect heat signatures and identify people or vehicles even in low light conditions. This can be particularly useful in search and rescue operations at night or in areas with dense foliage.

Furthermore, the drones can provide an aerial view of the search area, enabling the search teams to assess the terrain and plan their search more effectively. The ground control station can use machine learning algorithms to analyse the data and detect any anomalies, such as movements that may indicate the presence of the missing person or vehicle.

**Monitoring of Sensitive Areas:** The surveillance camera with drone system in the Indian Armed Forces can also be used for the monitoring of sensitive areas, such as critical infrastructure or military installations. The drones can fly over the area and transmit real-time data to the ground control station, enabling the military to detect any intruders or suspicious activities.

The drones can be equipped with high-resolution cameras, which can capture detailed images of the area being monitored. The cameras can also be equipped with zoom lenses, enabling the ground control station to get a closer look at any suspicious activities



Furthermore, the drones can provide an aerial view of the area being monitored, enabling the military to assess the terrain and plan their security measures more effectively. The ground control station can use machine learning algorithms to analyse the data and detect any anomalies, such as movements that may indicate the presence of an intruder.

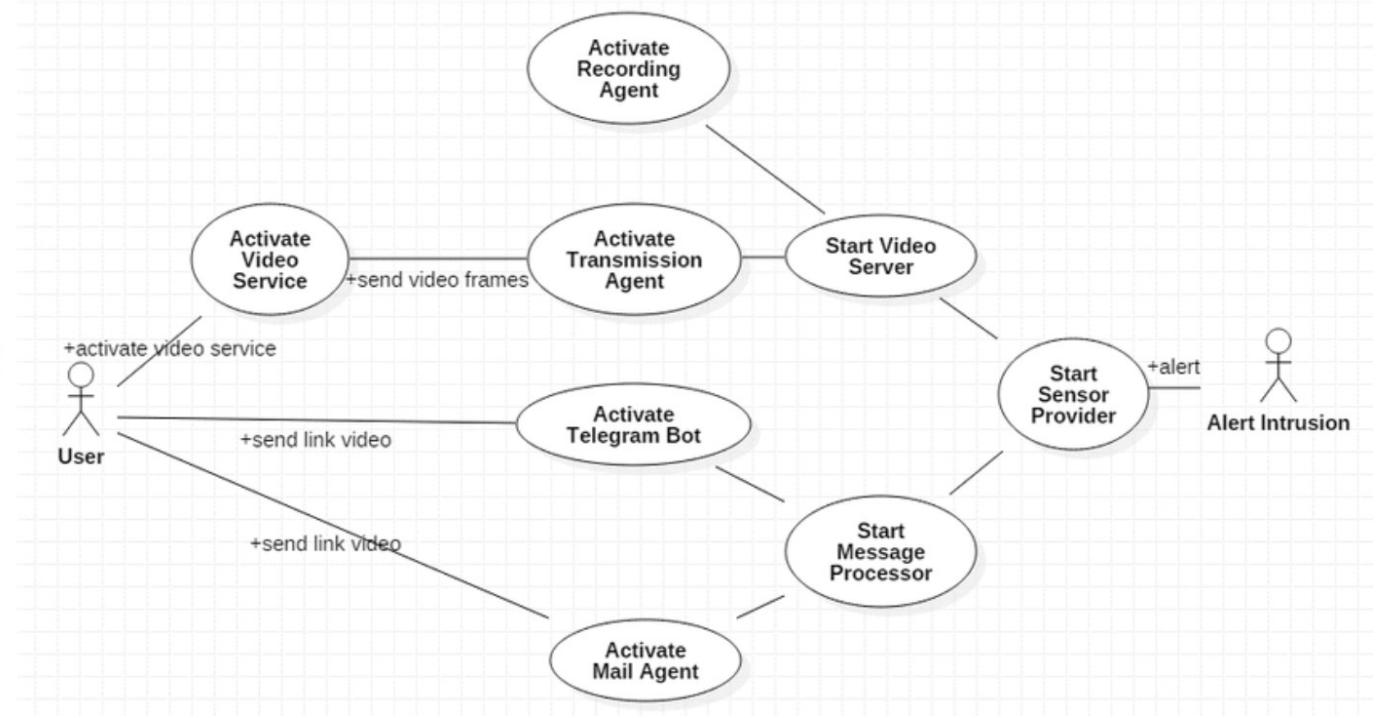
**Maritime Reconnaissance:** The surveillance camera with drone system in the Indian Armed Forces can also be used for maritime reconnaissance. The drones can be used to monitor shipping lanes, detect piracy or smuggling, and provide real-time information on weather and sea conditions.

The drones can be equipped with high-resolution cameras, which can capture detailed images of ships and boats. The cameras can also be equipped with zoom lenses, enabling the ground control station to get a closer look at any suspicious activities.

Furthermore, the drones can provide an aerial view of the sea, enabling the military to assess the terrain and plan their security measures more effectively. The drones can also be equipped with weather sensors, providing real-time information on sea conditions, such as wind speed and wave height.

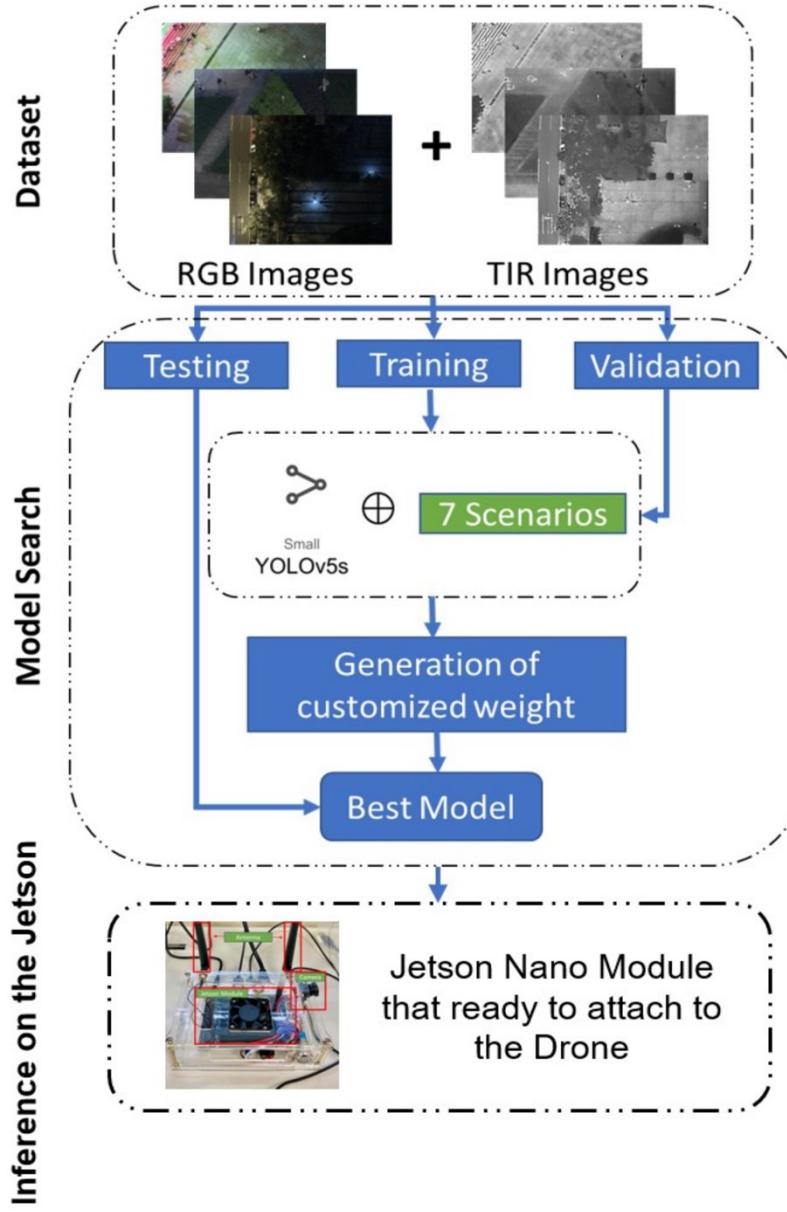
In addition, the drones can be used to monitor fishing activity, enabling the military to detect any illegal fishing practices. The ground control station can use machine

Unmanned aerial vehicles (UAVs, often known as drones) and NVIDIA Jetson modules, a general-purpose GPU, are an affordable and effective solution because they only need a small number of resources. The proposed solution for a surveillance system using drones and Jetson can be seen in Figure 1



**Figure 1.** UAVs with NVIDIA Jetson Nano for surveillance system

The experimental pipeline consists of two main stages: the first one is a model search or training process to find the best model to perform the human-detection task from a UAV perspective. This model search was performed on the computer host machine mentioned earlier. The second stage is the execution or inference in the Jetson Nano module. The flow of this experiment can be seen in Figure 2.



**Figure 2.** Model search and human–object detection on Jetson Nano workflow

## CHAPTER 4

# PROBLEM ANALYSIS AND REQUIREMENT SPECIFICATION

Certainly, here's a narrative-style presentation of the problem analysis and requirement specification for drone-based surveillance cameras for the Indian Armed Forces:

### **Problem Analysis:**

The Indian Armed Forces face critical challenges in their surveillance methodologies. Presently, their surveillance capabilities encounter limitations in effectively monitoring expansive and diverse terrains. Traditional methods, such as manned patrols and stationary cameras, fall short in providing real-time and comprehensive surveillance, particularly in remote or challenging terrains, leading to blind spots and security vulnerabilities. Timely acquisition of accurate intelligence, especially in border security and counter-terrorism operations, remains a significant concern. Furthermore, existing surveillance technologies lack the agility and adaptability required for dynamic military operations, suffering from limitations in camera resolution, range, night vision capabilities, and data transmission.

### **Requirement Specification:**

The imperative for a drone-based surveillance system for the Indian Armed Forces demands specific attributes and functionalities:

Firstly, the system requires high-resolution cameras capable of capturing detailed imagery to facilitate precise identification and analysis of targets or areas of interest. Night vision capabilities and thermal imaging sensors are essential for operations in low-light conditions or during nocturnal activities.

Ensuring a considerable operational range and stability in adverse weather conditions is crucial for drones equipped with surveillance cameras, enabling comprehensive coverage of vast terrains without compromising image quality or stability. Real-time data transmission capabilities are indispensable for timely decision-making in operations.

Adaptability to diverse environments, including mountainous regions, forests, deserts, and urban landscapes, is a fundamental requirement. Moreover, seamless integration with existing military infrastructure for interoperability and actionable intelligence dissemination is imperative.

Compliance with aviation laws, data security protocols, and ethical guidelines regarding civilian privacy are non-negotiable aspects. Provision for training military personnel in operating and maintaining these surveillance systems is essential for their effective utilization.

This requirement specification delineates the vital features and capabilities necessary for the development of a drone-based surveillance system, addressing the identified problems and aligning with the operational requisites of the Indian Armed Forces.

## **CHAPTER 5**

### **DETAILED DESIGN**

#### **5.1. Technical details :**

The surveillance camera with drone system in the Indian Armed Forces is a highly technical system that involves several components, including drones, cameras, ground control stations, and machine learning algorithms. In this section, we will discuss the technical details of each component in detail.

**Drones:** The drones used in the surveillance camera with drone system in the Indian Armed Forces are usually quadcopters or hexacopters, equipped with four or six rotors, respectively. These drones are highly maneuverable and can fly at high speeds, making them ideal for surveillance operations.

The drones are also equipped with GPS technology, which enables them to fly autonomously along pre-programmed flight paths. This ensures that the drones can cover the designated area thoroughly and reduce the risk of human error.

**Cameras:** The cameras used in the surveillance camera with drone system in the Indian Armed Forces are high-resolution cameras that can capture images and videos with exceptional clarity. These cameras are usually equipped with zoom lenses, enabling the ground control station to get a closer look at any suspicious activities.

The cameras can also be equipped with thermal imaging technology, which enables them to detect heat signatures and identify people or vehicles even in low light conditions. This can be particularly useful in border surveillance or search and rescue operations.

**Ground Control Stations:** The ground control station is the hub of the surveillance camera with drone system in the Indian Armed Forces. It is usually a mobile unit that can be transported to the location of the operation. The ground control station is equipped with computers and monitors that receive real-time data from the drones.

The ground control station is also equipped with software that enables the military personnel to control the drones and cameras. This software allows the military personnel to program the flight path of the drones, control the camera settings, and view the images and videos captured by the cameras.

**Machine Learning Algorithms:** The machine learning algorithms used in the surveillance camera with drone system in the Indian Armed Forces are artificial intelligence algorithms that enable the system to analyze the data captured by the cameras and detect any anomalies or suspicious activities.

These algorithms are trained on large datasets of images and videos and can detect patterns and anomalies that may not be immediately apparent to the human eye. For example, the algorithms

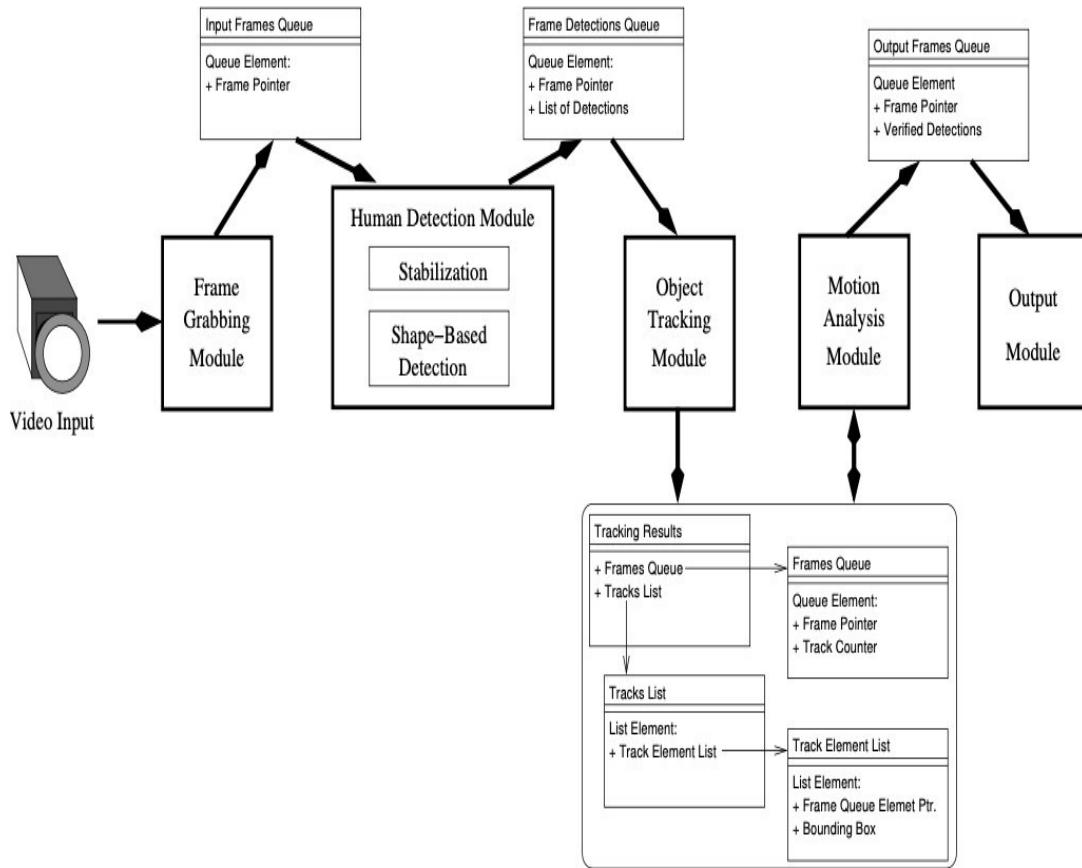
can detect movements that may indicate the presence of a group of people moving towards the border or the presence of an intruder in a sensitive area.

The machine learning algorithms can also be used to detect changes in the environment, such as changes in the sea conditions or changes in the weather. This enables the military to plan their operations more effectively and take appropriate action to prevent any security breaches.

## 5.2 Human detection module :

This module is responsible for invoking the detection algorithm. Ideally, the detection algorithm is to be run on each input frame. However, this will inhibit the system from meeting its real time requirements. Instead, the detection algorithms in our implementation is invoked every two seconds. The location of the human targets in the remaining time is determined by tracking the detected humans using the tracking algorithm.

To further speed up the process, the detection algorithm does not look for humans in the entire frame. Instead, it looks for humans in the regions determined to be fore- ground regions. To determine the foreground regions, a stabilization algorithm is used to align the current frame with a preceding frame and with a succeeding frame. After alignment, the current frame is subtracted from the two other frames. The result of each subtraction is threshold to form a binary image that represents the locations of fore- ground objects in the two subtracted frames. To know the locations of the foreground objects in the current frame, the results of the two subtractions are combined by an AND operation. The subtraction is performed in the hue channel of the HSV colour space.



**Figure 1. System Architecture**

1. Import the libraries:

```

1. import cv2
2. import imutils
3. import numpy as np
4. import argparse

```



2. Create a model which will detect Humans:

As discussed earlier, We will use HOGDescriptor with SVM already implemented in OpenCV. Below code will do this work:

```

1. HOGCV = cv2.HOGDescriptor()
2. HOGCV.setSVMDetector(cv2.HOGDescriptor_getDefaultPeopleDetector())

```

**cv2.HOGDescriptor\_getDefaultPeopleDetector()** calls the pre-trained

model for Human detection of OpenCV and then we will feed our support vector machine with it.

3. Detect() method:

Here, the actual magic will happen.

**Video:** A video combines a sequence of images to form a moving picture. We call these images as Frame. So in general we will detect the person in the frame. And show it one after another that it looks like a video.

That is exactly what our Detect() method will do. It will take a frame to detect a person in it. Make a box around a person and show the frame..and return the frame with person bounded by a green box.

```

1. def detect(frame):
2.     bounding_box_coordinates, weights = HOGCV.detectMultiScale(frame, winStride = (4,
4), padding = (8, 8), scale = 1.03)
3.
4.     person = 1
5.     for x,y,w,h in bounding_box_coordinates:
6.         cv2.rectangle(frame, (x,y), (x+w,y+h), (0,255,0), 2)
7.         cv2.putText(frame, f'person {person}', (x,y), cv2.FONT_HERSHEY_SIMPLEX, 0.5,
(0,0,255), 1)
8.         person += 1
9.
10.    cv2.putText(frame, 'Status : Detecting ', (40,40), cv2.FONT_HERSHEY_DUPLEX, 0.8,
(255,0,0), 2)
11.    cv2.putText(frame, f'Total Persons : {person-1}', (40,70), cv2.FONT_HERSHEY_DUPLEX,
0.8, (255,0,0), 2)
12.    cv2.imshow('output', frame)
13.
14.    return frame

```

#### 4. DetectByPathVideo() method

This method is very similar to the previous method except we will give a path to the Video. First, we check if the video on the provided path is found or not.

*Note – A full path must be given.*

```

1. def detectByPathVideo(path, writer):
2.
3.     video = cv2.VideoCapture(path)
4.     check, frame = video.read()
5.     if check == False:
6.         print('Video Not Found. Please Enter a Valid Path (Full path of Video Should be Provided).')
7.         return
8.
9.     print('Detecting people...')
10.    while video.isOpened():
11.        #check is True if reading was successful
12.        check, frame = video.read()
13.
14.        if check:
15.            frame = imutils.resize(frame , width=min(800,frame.shape[1]))
16.            frame = detect(frame)
17.
18.            if writer is not None:
19.                writer.write(frame)
20.
21.            key = cv2.waitKey(1)
22.            if key== ord('q'):
23.                break
24.            else:
25.                break
26.        video.release()
27.        cv2.destroyAllWindows()
28.
29.    def detectByCamera(writer):
30.        video = cv2.VideoCapture(0)
31.        print('Detecting people...')
32.
33.        while True:
34.            check, frame = video.read()
35.
36.            frame = detect(frame)
37.            if writer is not None:
38.                writer.write(frame)
39.
40.            key = cv2.waitKey(1)
41.            if key == ord('q'):
42.                break
43.
44.        video.release()
45.        cv2.destroyAllWindows()

```

## 5. Main function

We have reached the end of our project.

```
1. if __name__ == "__main__":
2.     HOGCV = cv2.HOGDescriptor()
3.     HOGCV.setSVMDetector(cv2.HOGDescriptor_getDefaultPeopleDetector())
4.
5.     args = argsParser()
6.     humanDetector(args)
```

Instead of declaring our model above, we can declare it in our main function.

# CHAPTER 6

## HARWARE AND SOFTWARE ENVIRONMENT

### 6.1. Drone:

A quadcopter, also called a quadrotor helicopter or quadrotor, is a multirotor helicopter that is lifted and propelled by four rotors. Quadcopters are classified as rotorcraft, as against fixed-wing aircraft, because their lift is generated by a group of rotors (vertically oriented propellers)

Quadcopters generally use two pairs of identical fixed pitched propellers; two clockwise (CW) and two counter clockwise (CCW). These use independent variations of the speed of every rotor to realize control. By changing the speed of every rotor it's possible to specifically generate a desired total thrust; locate for the middle of thrust both laterally and longitudinally, and to create a desired total torque, or turning force.

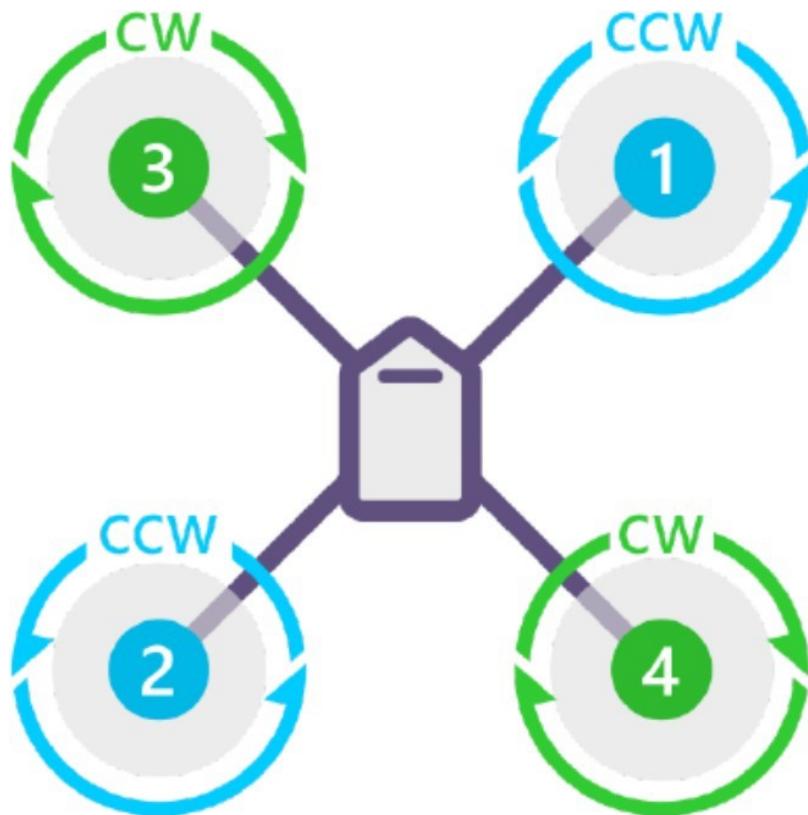


Fig. Quadcopter Rotor Direction

Drones are becoming a major part of society. From hobby drones to military devices to delivery services, more and more drones are getting used today. In fact, between 2014 and 2015, drone sales increased 63% and have only continued to rise. But like all sorts of technology, drones aren't flawless. And if you are a drone owner, it is vital to remember possible issues you'll encounter. So let's explore a couple of common drone problems and the way to repair them.

**Decreased battery life:** Having a functioning battery is one of the foremost important parts of flying a drone. This is why it is vital to properly charge the battery before trying to require flight. When the drone isn't in use, it is best to store the battery during a cool, dry place - the battery shouldn't be left within the drone when it's not in use. This can help maintain the charge and increase the lifespan of the battery. Additionally, it is vital to not overcharge the batter, which may drastically decrease its lifespan. All in all, taking excellent care o the battery will ensure it lasts as long as possible

**Wrong direction during flight:** If the drone's compass isn't calibrated properly, drone users may experience the flight direction being wrong or abnormal during flight. This can also occur if the drone is fitted with a mounted flight controller and therefore the specifications are simply misplaced. This is why it is vital to offer your drone a quick inspection before each flight. Calibrating the compass can usually help solve this issue but sometimes a restart of the remote control can help. If none of those solutions work, then drone repair services could also be needed to detect the basis on those drone problems.

## **CONSTRUCTION:**

### **STEP 1: Making of the Frame**

The primary task is to form a frame. For this purpose, you'll use different materials, like metal, plastic, or wood. These materials will differ supported by how sturdy you plan the drone to be.



The construction of Drone is now complete All we need is to unload the latest firmware available for

### **STEP 2: Propellers, Electronic Speed Controllers and Motors**

The ESCs (Electronic Speed Controllers), the motors, and therefore the propellers are among the foremost important elements of a functional drone.

Put the motor within the appropriate place and fix it to the frame using the screws and a screwdriver.

After mounting the motors, you furthermore may need to mount the speed controllers. How will you be doing this? It's recommended to attach the speed controllers on the bottom side of the wings of the frame.

Now attach the propellers to the motor, and keep the direction of the propeller for the right movement i.e., Clockwise or Counter Clockwise.

The wings of the drone are now ready. Now solder the ESC inputs to the Power Distribution Board.

#### STEP 3: Flight Controller

Every flying drone must have an impact system. This electronic system allows a drone to be stable within the air while flying and processes all the shifts and changes in direction and therefore the wind.

Now, fix the flight controller to the frame at a centre position for good stability.

#### STEP 4: External GPS

Now, Attach the external GPS to the frame and make sure that external GPS is not very near to the flight controller because it causes interference because of magnetometer in flight controller

#### STEP 5: Connection to the Flight Controller

Now connect the ESC to the flight controller output port, GPS to the GPS port and Power module to the PM port of the flight controller.

#### STEP 6: Radio Receiver

Now, connect the channel no. 1-5 to the input of the flight controller. The Channel 1-4 is for Pitch, Roll, Throttle & Yaw. Channel 5 is for flight modes like Stabilize, Position hold etc. the Quadcopter drone by using software Mission Planner.

And, after uploading the firmware, we need to calibrate the GPS and each ESC so that it starts at the

same time with the same frequency

And then, give it a fly and check if it's working fine. If it's stable or not.

## 6.2. Details of every apparatus used in this project:

### 1. Drone Frame:

The stability of the drone is based on frame of the drone and parts aligned at the centre of mass of the drone.

For this project, I've purchased the F450 Quadcopter frame.



## 2. Power Distribution Board:

PDB's essentially distribute the power from the battery to the drone esc. But the technology has improved so much in recent days that PDB's also distribute power to some other peripherals such as FPV Video Transmitters, FPV Cameras and the Quadcopter Flight Controller itself.



**Fig. Basic Power Distibution Board**

## 3. Electronic Speed Controller:

Electronic speed controllers (ESC) are devices that allow drone flight controllers to control and adjust the speed of the aircraft's electric motors. A signal from the flight controller causes the ESC to raise or lower the voltage to the motor as required, thus changing the speed of the propeller.



Fig. Simonk 30Amp. ESC

#### 4. Brush Less DC Motor - BLDC Motor:

A brushless DC motor (also known as a BLDC motor or BL motor) is an electronically commuted DC motor which does not have brushes. The controller provides pulses of current to the motor windings which control the speed and torque of the synchronous motor.

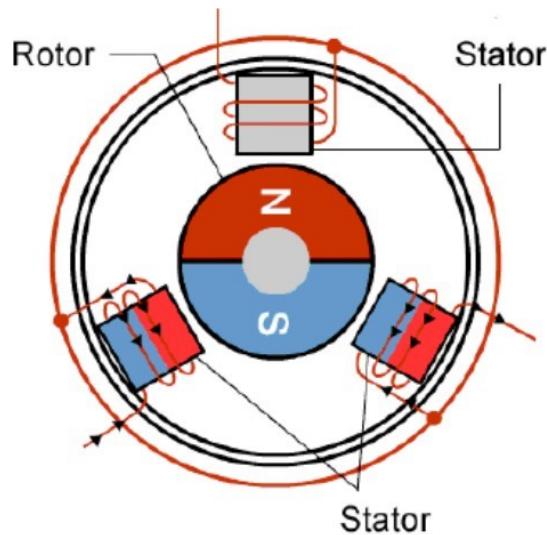


Fig. Working of BLDC Motor



Fig. A2212 - 1400KV BLDC Motor is used in this project.

## 5. Flight Controller:

A flight controller (FC) is a small circuit board of varying complexity. Its function is to direct the RPM of each motor in response to input. A command from the pilot for the multi-rotor to move forward is fed into the flight controller, which determines how to manipulate the motors accordingly.

The majority of flight controllers also employ sensors to supplement their calculations. These range from simple gyroscopes for orientation to barometers for automatically holding altitudes. GPS can also be used for auto-pilot or fail-safe purposes. More on that shortly.

APM 2.8 Flight Controller is used in this project.

Ardu Pilot Mega (APM) is a professional quality IMU autopilot that is based on the Arduino Mega platform. This autopilot can control fixed-wing aircraft, multi-rotor helicopters, as well as traditional helicopters.



Fig. APM 2.8 Flight Controller

## 6. External GPS:

GPS drones are equipped with a GPS module that allows them to know their location relative to a network of orbiting satellites. Connecting to signals from these satellites allows the drone to perform functions such as position hold, autonomous flight, return to home, and waypoint navigation.



Fig. External GPS for Drone

---

## 7. Transmitter & Receiver:

For Transmitting the command for ground to the drone, the Radio Transmission technique is used.

A Radio Transmitter is an electronic device that uses radio signals to transmit commands wirelessly via a set radio frequency over to the Radio Receiver, which is connected to an aircraft or multirotor being remotely controlled.

In other words, it's the device that translates pilot's commands into movement of the Drone. A Radio Transmitter transmits commands via channels. Each channel is an individual action being sent to the aircraft.

Throttle, Yaw, Pitch and Roll are the four main inputs required to control the quad. Each of them uses one channel, so there is minimum of four channels required. Every switch, slider or knob on the transmitter uses one channel to send the information through to the receiver.

## **CHAPTER 7**

### **SNAPSHOT OF INPUT AND OUTPUT**

#### **Input:**

Technical Expertise and Research: Input from experts in drone technology, surveillance systems, and military operations is crucial. Research on cutting-edge camera technologies, sensor systems, and data transmission methods is fundamental for system development.

Operational Requirements Analysis: Detailed analysis and understanding of the specific needs of the Indian Armed Forces, including their operational scenarios, terrain complexities, and strategic objectives, serve as critical inputs for designing tailored surveillance solutions.

Regulatory and Compliance Guidelines: Inputs regarding aviation laws, military protocols, data security standards, and ethical guidelines governing the use of surveillance technologies in India are essential for ensuring compliance during system development.

Prototype Development Tools and Resources: Resources for prototyping and testing the surveillance system components, including software and hardware tools, computing resources, and simulation environments, are necessary inputs for the development phase.

#### **Output:**

Developed Drone-based Surveillance System: The primary output is a fully functional drone-based surveillance system designed specifically for the Indian Armed Forces. This system integrates high-resolution cameras, advanced sensor technologies, and robust data transmission capabilities suitable for diverse operational environments.

Technical Documentation and Specifications: Comprehensive technical documentation outlining the system architecture, specifications of surveillance cameras and sensors, operational procedures, and maintenance guidelines serves as a reference for system deployment and operation.

Integration with Military Infrastructure: The output includes successful integration of the surveillance system with existing military infrastructure, ensuring interoperability with other systems and seamless data exchange for actionable intelligence.



**Training Modules and Manuals:** Development of training modules and manuals for military personnel, covering operation, maintenance, and troubleshooting of the surveillance system, ensures efficient utilization and optimal performance in real-world operations.

**Compliance Reports and Certifications:** Reports validating compliance with regulatory frameworks, including adherence to aviation laws, data security standards, and ethical guidelines, serve as critical output for the system's lawful and ethical use.

**Operational Deployment and Evaluation:** Deployment of the surveillance system in actual operational scenarios and subsequent evaluation reports detailing its performance, effectiveness, and areas for improvement serve as crucial outputs for iterative enhancement.

These outputs collectively represent the culmination of the project, delivering a tailored drone-based surveillance system equipped to meet the specific needs of the Indian Armed Forces while adhering to legal, operational, and ethical standards.

# CHAPTER 8

## CODING

### • Coding Part

This is the GitHub link of my project - <https://github.com/Heyamit24/Human-Ditection>

1. First of all we need to run the `human_action_classification.ipynb` file so that it will install all the required modules and files in your pc.

The screenshot shows the Jupyter Notebook interface with the file `human_action_classification.ipynb` open. The code cell contains the following commands:

```
git clone https://github.com/spmallick/learnopencv.git
cd learnopencv/Human-Action-Recognition-Using-Detectron2-And-Lstm
pip install torch==1.4.0 torchvision==0.5.0 -f https://download.pytorch.org/whl/torch_stable.html
pip install -r requirements.txt
```

Below the code cell, there are sections for "Install dependencies" and "Install Detectron2".

Install dependencies:

```
pip install torch==1.4.0 torchvision==0.5.0 -f https://download.pytorch.org/whl/torch_stable.html
pip install -r requirements.txt
```

Install Detectron2:

```
import torch
assert torch.__version__.startswith("1.8") # need to manually install torch 1.8 if Colab changes its default version
pip install detectron2 -f https://dl.fbaipublicfiles.com/detectron2/wheels/cu101/torch1.8/index.html
```

Install ngrok for tunneling to the web application we are about to run on colab:

```
# Download ngrok for tunneling.
!if [ ! -f ./ngrok ]; then \
wget https://bin.equinox.io/c/4VmDzA7iaHb/ngrok-stable-linux-amd64.zip; \
unzip -o ngrok-stable-linux-amd64.zip; \
fi
```

The screenshot continues from the previous one, showing the execution of the code. The code cell now includes the following additional steps:

```
# Then start a mini web server.
port = 5000
!kill ngrok
!kill $!ps x | grep -v grep | grep http.server | awk '{print $1}' 2>/dev/null
get_ipython().system_raw(
    'python app.py && python3 -m http.server {} &'.format(port)
)

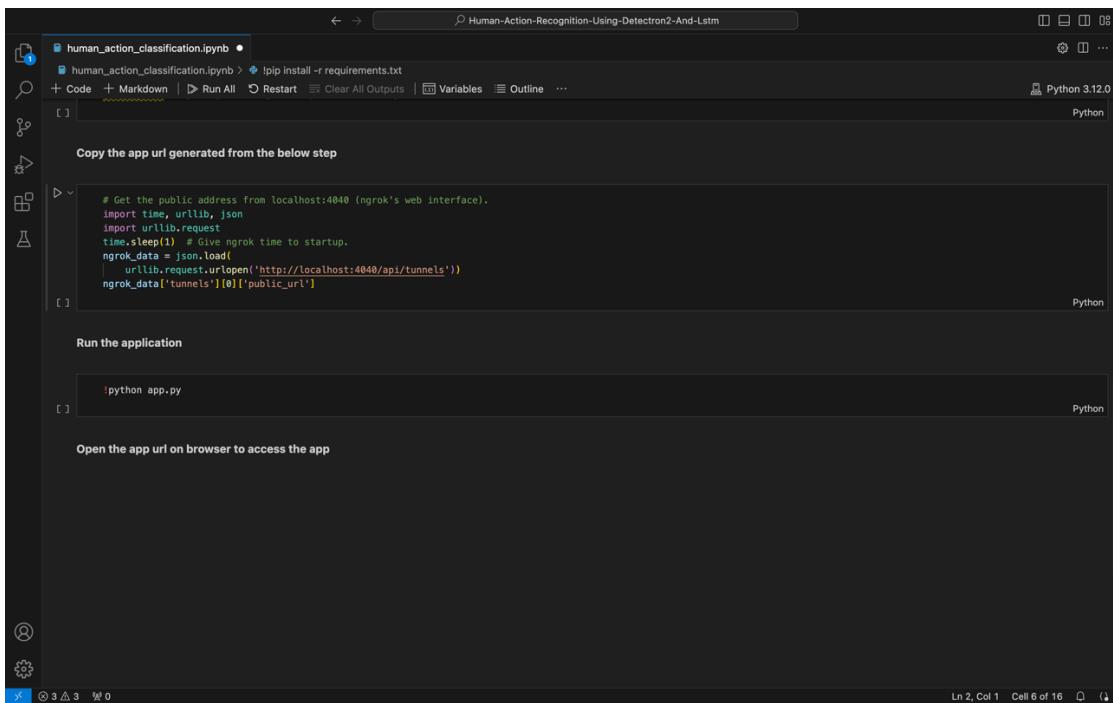
# And, forward the port using ngrok.
get_ipython().system_raw('./ngrok http {}&.format(port))
```

Copy the app url generated from the below step:

```
# Get the public address from localhost:4040 (ngrok's web interface).
import time, urllib, json
import urllib.request
time.sleep(1) # Give ngrok time to startup.
ngrok_data = json.load(urllib.request.urlopen('http://localhost:4040/api/tunnels'))
ngrok_data['tunnels'][0]['public_url']
```

Run the application:

- After installing all the required Modules, we need to run the app.py file in which project source code is written



The screenshot shows a Jupyter Notebook interface with the following details:

- Title Bar:** Human-Action-Recognition-Using-Detectron2-And-Lstm
- File List:** human\_action\_classification.ipynb (marked with a blue dot)
- Cell List:** human\_action\_classification.ipynb > !pip install -r requirements.txt
- Toolbar:** Code, Markdown, Run All, Restart, Clear All Outputs, Variables, Outline, Python 3.12.0
- Code Cell:** Contains Python code to get a public address from ngrok. It includes imports for time, urllib, json, and urllib.request, and uses the requests module to make a GET request to 'http://localhost:4040/api/tunnels'.
- Text Cell:** Copy the app url generated from the below step
- Text Cell:** Run the application
- Text Cell:** !python app.py
- Text Cell:** Open the app url on browser to access the app
- Bottom Status Bar:** Ln 2, Col 1 Cell 6 of 16

## The code written in app.py is:

```
import os
import time

from flask import Flask
from flask import render_template, Response, request, send_from_directory, flash,
url_for
from flask import current_app as app
from werkzeug.utils import secure_filename

from src.lstm import ActionClassificationLSTM
from src.video_analyzer import analyse_video, stream_video

# import some common Detectron2 utilities
from detectron2 import model_zoo
from detectron2.engine import DefaultPredictor
from detectron2.config import get_cfg

app = Flask(__name__)
UPLOAD_FOLDER = './'
app.config['UPLOAD_FOLDER'] = UPLOAD_FOLDER
app.secret_key = "secret key"

start = time.time()

# obtain detectron2's default config
cfg = get_cfg()

# load the pre trained model from Detectron2 model zoo
cfg.merge_from_file(model_zoo.get_config_file("COCO-
Keypoints/keypoint_rcnn_R_50_FPN_3x.yaml"))

# set confidence threshold for this model
cfg.MODEL.ROI_HEADS.SCORE_THRESH_TEST = 0.5

# load model weights
cfg.MODEL.WEIGHTS = model_zoo.get_checkpoint_url("COCO-
Keypoints/keypoint_rcnn_R_50_FPN_3x.yaml")

# create the predictor for pose estimation using the config
```

```

pose_detector = DefaultPredictor(cfg)
model_load_done = time.time()
print("Detectron model loaded in ", model_load_done - start)

# Load pretrained LSTM model from checkpoint file
lstm_classifier =
ActionClassificationLSTM.load_from_checkpoint("models/saved_model.ckpt")
lstm_classifier.eval()

class DataObject():
    pass

def checkFileType(f: str):
    return f.split('.')[ -1] in ['mp4']

def cleanString(v: str):
    out_str = v
    delm = ['_', '-', '.']
    for d in delm:
        out_str = out_str.split(d)
        out_str = " ".join(out_str)
    return out_str

@app.route('/', methods=['GET'])
def index():
    obj = DataObject
    obj.video = "sample_video.mp4"
    return render_template('/index.html', obj=obj)

@app.route('/upload', methods=['POST'])
def upload():
    obj = DataObject
    obj.is_video_display = False

```

```

obj.video = ""
print("files", request.files)
if request.method == 'POST' and 'video' in

request.files:
    video_file = request.files['video']
    if checkFileType(video_file.filename):
        filename =
            secure_filename(video_file.filename)
            print("filename", filename)
            # save file to /static/uploads
            filepath =
                os.path.join(app.config['UPLOAD_FOLDER'], filename)
                print("filepath", filepath)
                video_file.save(filepath)
                obj.video = filename
                obj.is_video_display = True
                return render_template('/index.html',
                    obj=obj)
            else:
                if video_file.filename:
                    msg = f'{video_file.filename} is not a video file'
                else:
                    msg = "Please select a video file"
                    flash(msg)
                    return render_template('/index.html', obj=obj)
                return render_template('/index.html', obj=obj)

@app.route('/sample', methods=['POST'])
def sample():
    obj = DataObject
    obj.is_video_display = True
    obj.video = "sample_video.mp4"
    return render_template('/index.html', obj=obj)

@app.route('/files/<filename>')
def get_file(filename):

```

```

    return send_from_directory(app.config['UPLOAD_FOLDER'], filename)

@app.route('/analyzed_files/<filename>')
def get_analyzed_file(filename):
    return send_from_directory(app.config['UPLOAD_FOLDER'],
"res_{}".format(filename), as_attachment=True)

@app.route('/result_video/<filename>')
def get_result_video(filename):
    stream = stream_video("{}res_{}".format(
        app.config['UPLOAD_FOLDER'], filename))
    return Response(stream, mimetype='multipart/x-mixed-
replace; boundary=frame')

# route definition for video upload for analysis

@app.route('/analyze/<filename>')
def analyze(filename):
    # invokes method analyse_video
    return Response(analyse_video(pose_detector, lstm_classifier, filename),
        mimetype='text/event-stream')

if __name__ == '__main__':
    app.run(debug=True, use_reloader=True)

```

# CHAPTER 9

## PROJECT LIMITATIONS AND FUTURE SCOPES

### **9.1. Benefits:**

The surveillance camera with drone system in the Indian Armed Forces offers several benefits that make it a valuable tool for military operations. In this section, we will discuss the benefits of the system in detail.

8. Increased situational awareness: The surveillance camera with drone system enables military personnel to monitor a large area of land or sea in real-time. This provides them with a comprehensive view of the situation and enables them to identify any suspicious activities quickly. This increased situational awareness is especially useful in border surveillance, where a slight delay in detecting an intrusion can have serious consequences.
9. Improved response time: The real-time data captured by the drones and cameras enables military personnel to respond quickly to any security breaches. This can be crucial in situations where every second counts, such as during a terrorist attack or a border intrusion. The improved response time enabled by the system can help prevent any security breaches and ensure the safety of military personnel and civilians.
10. Cost-effective: The surveillance camera with drone system is a cost-effective alternative to traditional methods of surveillance. The system can cover a large area of land or sea, which would otherwise require a significant number of personnel to monitor. The use of drones also reduces the need for expensive helicopters or fixed-wing aircraft for surveillance, making the system more cost-effective.
11. Safe and efficient: The use of drones in the surveillance camera with drone system eliminates the need for military personnel to physically patrol the area. This reduces the risk of injury or death to military personnel and enables them to focus on other critical tasks. The use of drones also makes the surveillance more efficient, as the drones can cover large areas quickly and effectively.
12. Machine learning capabilities: The machine learning algorithms used in the surveillance camera with drone system enable the system to analyze the data captured by the cameras and detect any anomalies or suspicious activities. This provides military personnel with an additional layer of intelligence, enabling them to identify potential security breaches more accurately.
13. Flexibility: The surveillance camera with drone system is highly flexible and can be used for a variety of military operations. The system can be used for border surveillance, search and rescue operations, disaster relief operations, and even for monitoring the movements of hostile forces. The flexibility of the system makes it a valuable tool for military operations.

14. Scalability: The surveillance camera with drone system can be scaled up or down depending on the requirements of the operation. This makes it suitable for both large-scale and small-scale operations. The system can be deployed in remote locations and can operate for extended periods, providing military personnel with a reliable surveillance tool.

## **1. INCREASED SITUATIONAL AWARENESS:**

Increased situational awareness is one of the key benefits of the surveillance camera with drone system in the Indian Armed Forces. The system provides military personnel with real-time data and a comprehensive view of the situation, enabling them to identify any suspicious activities quickly. This is particularly useful in border surveillance, where even a small delay in detecting an intrusion can have serious consequences.

The drones and cameras used in the system can cover a large area of land or sea, providing military personnel with a bird's-eye view of the situation. This makes it easier for them to identify any potential threats and take appropriate action. In addition, the system can operate in areas that are difficult or impossible for human surveillance, such as dense forests or rough terrain.

The increased situational awareness provided by the surveillance camera with drone system can also help prevent friendly fire incidents. By providing military personnel with a comprehensive view of the situation, the system can help ensure that they are aware of the location of friendly forces and avoid any inadvertent attacks.

Overall, the increased situational awareness provided by the surveillance camera with drone system can help military personnel make more informed decisions and take appropriate action to prevent security breaches and ensure the safety of personnel and civilians.

## **2. IMPROVED RESPONSE TIME:**

Another significant benefit of the surveillance camera with drone system in the Indian Armed Forces is the improved response time it provides. The real-time data captured by the drones and cameras enables military personnel to respond quickly to any security breaches or suspicious activities. This is crucial in situations where every second counts, such as during a terrorist attack or a border intrusion.

With the surveillance camera with drone system, military personnel can quickly and accurately identify the location and nature of any security breaches. This enables them to deploy resources and take appropriate action in a timely manner. For example, if a border intrusion is detected, military personnel can quickly mobilize to intercept the intruders before they cross the border.

The improved response time provided by the surveillance camera with drone system can help prevent security breaches and ensure the safety of military personnel and

civilians. It can also help minimize the damage caused by incidents such as terrorist attacks or natural disasters.

In addition, the improved response time provided by the system can help boost the morale of military personnel. The knowledge that they can respond quickly and effectively to any situation can help boost their confidence and sense of security.

Overall, the improved response time provided by the surveillance camera with drone system is a critical benefit that can help prevent security breaches, minimize damage, and ensure the safety of military personnel and civilians.

### **3. COST-EFFECTIVE:**

The surveillance camera with drone system in the Indian Armed Forces is also cost-effective compared to traditional surveillance methods. The use of drones and cameras reduces the need for human surveillance, which can be costly in terms of personnel, equipment, and time.

The drones and cameras used in the system are relatively inexpensive compared to traditional surveillance methods, such as manned aircraft or ground patrols. They also require less maintenance and can cover a larger area with less manpower.

The system can be easily integrated with existing surveillance infrastructure, such as radar systems or ground-based surveillance cameras. This reduces the cost of implementing the system and ensures that the system can work seamlessly with other surveillance methods.

Moreover, the surveillance camera with drone system can provide 24/7 surveillance, which can be challenging to achieve with human surveillance. This reduces the need for multiple shifts and can save costs associated with overtime pay for personnel.

The cost-effectiveness of the surveillance camera with drone system can free up resources that can be allocated to other critical areas, such as training, equipment upgrades, or personnel development. This can help enhance the overall effectiveness and readiness of the armed forces.

Overall, the cost-effectiveness of the surveillance camera with drone system in the Indian Armed Forces makes it a valuable investment that can help enhance surveillance capabilities while reducing costs.

### **4. SAFE AND EFFICIENT:**

The surveillance camera with drone system in the Indian Armed Forces is designed to be safe and efficient. The system uses advanced technology to ensure that the drones and cameras operate safely and efficiently, minimizing the risk of accidents or errors.

The drones used in the system are equipped with obstacle detection sensors and autonomous flight modes, which enable them to avoid collisions with obstacles such as trees, buildings, or power lines. This ensures that the drones can operate safely in a variety of environments, including urban and rural areas.

The system is also designed to be efficient, allowing military personnel to monitor a large area of land or sea with minimal manpower. The drones and cameras can operate continuously, providing 24/7 surveillance, which reduces the need for multiple shifts and can save costs associated with overtime pay for personnel.

The use of advanced technology in the system, such as machine learning algorithms and real-time data processing, enables military personnel to quickly and accurately identify any potential threats or security breaches. This ensures that appropriate action can be taken in a timely manner, reducing the risk of damage or harm.

Moreover, the surveillance camera with drone system can be used in a variety of situations, such as border surveillance, disaster response, or search and rescue operations. This versatility makes the system a valuable tool that can be used in a variety of contexts to enhance safety and efficiency.

Overall, the safety and efficiency of the surveillance camera with drone system in the Indian Armed Forces make it a valuable investment that can help enhance surveillance capabilities while minimizing the risk of accidents or errors.

## 5. MACHINE LEARNING CAPABILITIES:

The system uses machine learning algorithms to analyze video footage and detect anomalies such as people or vehicles in restricted areas, unusual behavior, or suspicious activity. The algorithms can also analyze patterns of movement and behavior to identify potential threats or security breaches.

In addition, the system can learn from previous incidents and adapt its algorithms accordingly. This enables the system to continuously improve its performance and accuracy over time.

The machine learning capabilities of the system enable military personnel to focus their attention on the most important tasks, such as decision-making and taking appropriate action. The system can provide them with real-time alerts and notifications, allowing them to respond quickly and effectively to any situation.

Moreover, the system can integrate with other machine learning systems used by the armed forces, such as predictive analytics or threat intelligence systems. This enables military personnel to access a wide range of data and insights, further enhancing their situational awareness and decision-making capabilities.

Overall, the machine learning capabilities of the surveillance camera with drone system in the Indian Armed Forces make it a powerful tool that can help enhance

surveillance capabilities and improve the efficiency and effectiveness of military operations.

## **6. FLEXIBILITY:**

The surveillance camera with drone system in the Indian Armed Forces is highly flexible, which allows it to adapt to different situations and contexts. The system can be customized to meet the specific needs of different military units, operations, or environments.

The system can be deployed in a variety of situations, such as border surveillance, disaster response, or search and rescue operations. The flexibility of the system allows military personnel to quickly and easily deploy the drones and cameras in different locations, without the need for extensive setup or infrastructure.

Moreover, the system can be easily integrated with other surveillance infrastructure, such as radar systems, ground-based cameras, or satellite imagery. This allows military personnel to access a wide range of data and insights, further enhancing their situational awareness and decision-making capabilities.

The drones used in the system can also be customized to meet the specific needs of different operations or environments. For example, the drones can be equipped with different types of cameras, sensors, or payloads, depending on the specific requirements of the mission.

The flexibility of the system enables military personnel to quickly and easily adapt to changing circumstances or new requirements. This can help improve the efficiency and effectiveness of military operations, as personnel can quickly deploy the system and make necessary adjustments as needed.

Overall, the flexibility of the surveillance camera with drone system in the Indian Armed Forces makes it a valuable tool that can be customized to meet the specific needs of different military units, operations, or environments. The system's flexibility enables military personnel to quickly and easily adapt to changing circumstances, enhancing the efficiency and effectiveness of military operations

## **7. SCALABILITY:**

The surveillance camera with drone system in the Indian Armed Forces is highly scalable, which means it can be easily expanded or modified to meet changing needs or requirements. The system can be scaled up or down depending on the size of the operation, the number of drones and cameras needed, and the amount of data that needs to be processed.

The system's scalability is due in part to the use of cloud-based infrastructure, which allows military personnel to access and process large amounts of data in real-time. The use of cloud-based infrastructure also means that the system can be easily expanded or modified without the need for extensive hardware or software upgrades.

In addition, the system can be easily integrated with other surveillance infrastructure, such as ground-based cameras or radar systems. This enables military personnel to access a wide range of data and insights, further enhancing their situational awareness and decision-making capabilities.

Moreover, the drones used in the system can be easily deployed and controlled from a central location, which makes it easier to manage and scale the system. The use of remote control and automation technologies also helps to reduce the workload on military personnel, allowing them to focus on more important tasks.

The system's scalability enables military personnel to quickly and easily adapt to changing circumstances or new requirements. For example, if additional drones or cameras are needed for a specific operation, they can be quickly added to the system.

Overall, the scalability of the surveillance camera with drone system in the Indian Armed Forces makes it a valuable tool that can be easily expanded or modified to meet changing needs or requirements. The system's scalability enables military personnel to quickly and easily adapt to changing circumstances, enhancing the efficiency and effectiveness of military operations.

## **9.2. Limitations:**

While the surveillance camera with drone system in the Indian Armed Forces has several benefits and use cases, it also has some challenges and limitations that must be considered. In this section, we will discuss some of the main challenges and limitations associated with this system.

### **1. Limited battery life:**

One of the biggest challenges associated with the use of drones in the surveillance camera with drone system is their limited battery life. Most drones have a flight time of only 20-30 minutes, which means that they need to be recharged or replaced frequently. This can limit the amount of time that the system can be used for continuous surveillance, and may require additional drones to be deployed to cover a large area.

### **2. Weather conditions:**

The use of drones in the surveillance camera with drone system can be limited by weather conditions. Drones are not suitable for use in heavy rain, strong winds, or other adverse weather conditions, which can limit their effectiveness and range of use. This can also make

it difficult for military personnel to rely on the system during unpredictable weather conditions.

3. Interference:

The use of drones in the surveillance camera with drone system can be affected by interference from other drones, radio signals, or electromagnetic fields. This can result in loss of communication, loss of control, or other issues that can limit the effectiveness of the system.

4. Data processing and storage:

The surveillance camera with drone system generates a large amount of data, which can be difficult to process and store. This requires significant computing resources and can be expensive, particularly if the system is used for large-scale surveillance operations. Additionally, storing large amounts of data can pose security risks if not properly protected.

5. Privacy concerns:

The use of surveillance cameras with drones can raise privacy concerns for civilians, particularly if the cameras are being used in residential areas or other public places. This can lead to legal and ethical concerns that must be addressed to ensure the system is being used in a responsible and ethical manner.

6. Training and expertise:

The use of the surveillance camera with drone system requires specialized training and expertise, particularly in the use of drones and machine learning algorithms. This can be a challenge for military personnel who may not have extensive experience in these areas, and may require additional training and resources to effectively operate the system.

7. Maintenance and repair:

The surveillance camera with drone system requires regular maintenance and repair to ensure it is functioning properly. This can be a challenge in remote or difficult-to-access locations, and may require additional resources and personnel to maintain the system.

8. Cost:

The surveillance camera with drone system can be expensive to deploy and maintain, particularly if used for large-scale surveillance operations. This can be a limiting factor for some military units or operations, particularly those with limited resources.

9. Legal and regulatory issues:

The use of surveillance cameras with drones can be subject to legal and regulatory issues, particularly around privacy, security, and data protection. Military personnel must be aware of these issues and ensure they are complying with all relevant laws and regulations.

10. Vulnerability to hacking:

The use of drones and other technology in the surveillance camera with drone system can make it vulnerable to hacking or cyberattacks. This can pose a significant security risk, particularly if the system is being used for military operations. Military personnel must ensure that the system is secure and protected from potential cyber threats.

In conclusion, while the surveillance camera with drone system in the Indian Armed Forces has several benefits and use cases, it also has several challenges and limitations that must be considered. These include limited battery life, weather conditions, interference, data processing and storage, privacy concerns, training and expertise, maintenance and repair, cost, legal and regulatory issues, and vulnerability to hacking. Military personnel must be aware of these challenges and limitations and take appropriate measures to mitigate them to ensure the system is being used.

### **9.3. Future scope:**

The surveillance camera with drone system in the Indian Armed Forces is a relatively new technology, and there is a lot of potential for future developments and improvements. In this section, we will discuss some of the potential future developments in this system.

**Longer battery life:**

One of the most important areas for future development in the surveillance camera with drone system is increasing the battery life of the drones. Longer battery life would allow drones to stay in the air for longer periods of time, increasing their effectiveness and reducing the need for frequent recharging or replacement.

**Advanced weather resistance:**

Another potential area for future development is improving the weather resistance of drones used in the surveillance camera with drone system. This could include the development of drones that are more resistant to wind, rain, and other adverse weather conditions, allowing them to be used in a wider range of environments.

**Advanced machine learning algorithms:**

The use of machine learning algorithms is a key component of the surveillance camera with drone system, and there is a lot of potential for future development in this area. Advanced machine learning algorithms could improve the accuracy and effectiveness of the system, allowing it to identify potential threats more quickly and accurately.

**Improved data processing and storage:**

Improvements in data processing and storage could also be an important area for future development. This could include the development of more advanced algorithms for processing and analyzing data, as well as more efficient and secure methods for storing large amounts of data.

#### Integration with other technologies:

The surveillance camera with drone system could also be integrated with other technologies to improve its effectiveness and capabilities. For example, the system could be integrated with satellite imagery or ground-based sensors to provide more comprehensive surveillance coverage.

#### Autonomous drones:

The development of autonomous drones is another area with significant potential for future development in the surveillance camera with drone system. Autonomous drones would be able to operate without direct human control, potentially allowing for more efficient and effective surveillance operations.

In conclusion, there are many potential future developments in the surveillance camera with drone system in the Indian Armed Forces. These include improvements in battery life, weather resistance, machine learning algorithms, data processing and storage, integration with other technologies, autonomous drones, cybersecurity, training and expertise, and miniaturization. These developments could significantly improve the effectiveness and capabilities of the system, allowing for more efficient and effective surveillance operations in a wider range of environments and situations.

## **CHAPTER 10**

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## CHAPTER 11

### CONCLUSION

In conclusion, the surveillance camera with drone system in the Indian Armed Forces has the potential to greatly improve situational awareness, response times, and overall efficiency in surveillance and security operations. The integration of machine learning capabilities allows for real-time data analysis and threat detection, while the flexibility and scalability of the system make it adaptable to a wide range of environments and situations.

While the system has many benefits, there are also challenges and limitations that must be addressed, such as the need for skilled personnel, limited battery life, and weather conditions. However, with continued development and improvements in technology, these challenges can be overcome, and the surveillance camera with drone system can become an essential tool for the Indian Armed Forces.

Looking towards the future, there are many potential developments in the system, such as improved battery life, weather resistance, machine learning algorithms, data processing and storage, and integration with other technologies. These developments could greatly enhance the capabilities of the system, allowing for even more efficient and effective surveillance and security operations.

Overall, the surveillance camera with drone system in the Indian Armed Forces is a promising technology that has the potential to greatly enhance the safety and security of military personnel and the public. With continued development and improvements, it could become an essential tool for the Indian Armed Forces in maintaining national security and protecting against potential threats.

Although the drone industry in India is still in its nascent stages, it is expected to grow significantly due to the government's support and the rapid emergence of multiple drone manufacturing companies. This technology can be used to reduce the manufacturing costs and make it more globally competitive. The government's indigenisation efforts are in the right direction, and are expected to help the drone industry in India flourish. This will allow the country to compete in the global market. Multiple use cases across different sectors are expected to drive the demand for drones. The rapid emergence and growth of the drone industry is expected to create numerous employment opportunities in the country. It is also expected to help boost the country's economic growth. The government and various companies are recognizing the potential of the drone manufacturing industry. While, the objective of the new guidelines is to encourage the investment in the drone industry and the creation of new startups in India. India can become a global hub for drone technology by 2030. The implementation of the PLI scheme and the drone rules are expected to help the drone industry in India grow. According to the manufacturers of drones, the new guidelines have already resulted in a significant increase in their sales. Due to the availability of the PLI scheme, foreign companies are also considering setting up their operations in India to benefit from the country's growing drone industry. This will allow them to create a self-sufficient manufacturing ecosystem for drones.

The government's recent initiatives have allowed the armed forces of India to explore the full potential of unmanned aircraft. These have allowed the country's armed forces to develop new roles for them, such as providing intelligence-gathering and surveillance. The Army has also started managing the various drones that it has acquired. One of the biggest challenges that the Indian armed forces faces is the lack of indigenous combat drones, such as the US' Reapers and the Predators. These are capable of carrying out attacks on their targets using missiles and satellites. If the country's stealth wing flying test bed, which is the prototype of a stealth drone, is any indication, then this issue might soon be solved. Besides the existing offensive UAV platforms, the army also needs to develop a robust anti-UAV system, such as the Israeli Smash 2000 rifles. This weapon can be used to track and destroy hostile UAVs. The army's jamming system can detect and destroy quad copters that are over three kilometres away. This is useful for troops stationed along the western border.