# AMJAD YAGHI

## Portfolio & Blog | amjadclnyaghi@gmail.com | LinkedIn | GitHub

#### **EDUCATION**

#### Bachelor of Applied Science, Engineering Physics (Co-Op)

Sep. 2021 – Apr. 2026

University of British Columbia

Vancouver, BC

- Relevant Coursework: Data Structures & Algorithms, Applied Linear Algebra, Signals & Systems, Machine Learning
- Including a four-month exchange at Nanyang Technological University, Singapore

#### **PROJECTS**

## **OPPOSITION :** Projection-Mapped Interactive String | Processing, OpenCV

Dec. 2024 - Present

- Created an interactive guitar string projection using **Processing**, allowing users to "pluck" the string by casting shadows with a finger
- Integrated a custom chord-selection system inspired by music theory, enhancing the interactive experience
- Utilized OpenCV for real-time contour detection to trigger string vibrations and display visual effects

## **Multitasking Simulation Agent** | Python, Gazebo, OpenCV, TensorFlow

Sep. 2024 - Dec. 2024

- Developed a Gazebo agent for terrain navigation and text recognition, ensuring safe multitasking through state-machine control
- Implemented PID control for precise driving on track marks and tracking moving targets in off-road navigation
- Utilized **OpenCV** for pedestrian detection and image preprocessing, optimizing input to a **Convolutional Neural Network** in **TensorFlow** to achieve >90% classification accuracy on blurry and rotated symbols

### Fitness Sync Music Platform | Node.js, Express, Axios

Aug. 2024 – Sep. 2024

- Built a backend server with Express.js integrating Fitbit and Spotify APIs for fitness-driven music experiences
- Used OAuth 2.0 to sync heart rate data with Spotify and match songs to real-time BPM from friends' streams

#### **Autonomous Mario Kart Robot** | Arduino, STM32, Bluepill

May 2023 – Aug. 2023

- Spearheaded the software development of a unique autonomous robot for a head-to-head competition, being one of only two teams out of 17 to successfully use the **zipline mechanism**
- Designed and implemented a convolution algorithm using Arduino to enable precise infrared beacon tracking
- Engineered an autonomous coin-collection claw, triggered by sonar sensor feedback, which slid down a steel pipe to collect magnetically-attached coins in the competition
- Integrated buck converters to stabilize power across four motors, enhancing the robot's overall performance

#### **EXPERIENCE**

# **Process** Rocket Payload Designer

Sep. 2022 – Aug. 2023

UBC Rocket

Vancouver, BC

- Designed and launched an experiment to test tPA effects on blood clots in microgravity using linear actuators, solenoid valves, and housed in a 3U+ CubeSat launched to 30,000ft
- Developed a Processing GUI to control actuators and monitor limit switches via Arduino, enhancing data collection

#### **Project Coordinator**

Jan. 2023 – Apr. 2023

EllisDon Corporation

Vancouver, BC

- Automated departmental processes with Google Sheets scripts, improving document accessibility and efficiency
- Presented innovative computer science solutions to EllisDon's international VDC team, earning accolades
- Managed 100+ RFIs and submittals, ensuring clear communication among project stakeholders

## **SKILLS & INTERESTS**

**Technical Skills**: Git, MATLAB, Arduino, Circuitry, Google Apps Script, OpenCV, TensorFlow, State Machines **Programming**: Java, JavaScript, Python, C/C++, Bash

**Languages**: English (Fluent), French (Fluent - 12 years of immersion), Arabic (Proficient), Chinese (Beginner) **Interests**: Projection Mapping, Interactive Environments, Traveling, Music Production, Video Editing, Gymnastics