BackPropagation

There will be some functions that start with the word "grader" ex: grader_sigmoid(), grader_forwardprop(), grader_backprop() etc, you should not change those function definition.

Every Grader function has to return True.

Loading data

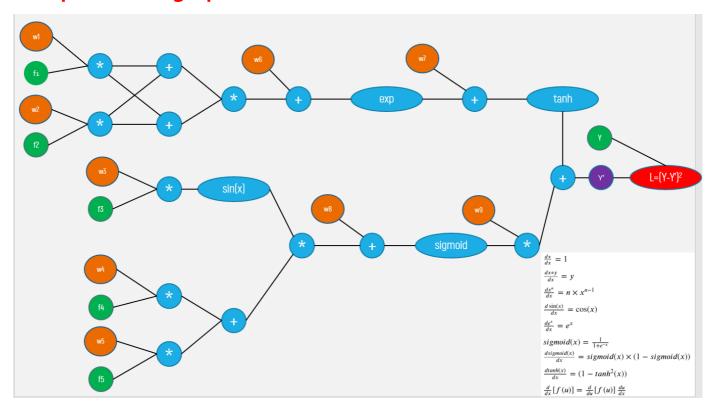
In [2]:

```
import pickle
import numpy as np
from tqdm import tqdm
import math
import matplotlib.pyplot as plt

with open('data.pkl', 'rb') as f:
    data = pickle.load(f)
print(data.shape)
X = data[:, :5]
y = data[:, -1]
print(X.shape, y.shape)

(506, 6)
(506, 5) (506,)
```

Computational graph



- If you observe the graph, we are having input features [f1, f2, f3, f4, f5] and 9 weights [w1, w2, w3, w4, w5, w6, w7, w8, w9].
- The final output of this graph is a value L which is computed as (Y-Y')^2

Task 1: Implementing backpropagation and Gradient checking

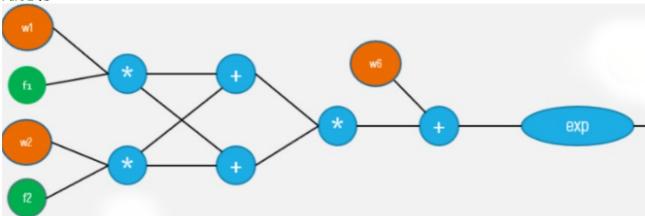
Check this video for better understanding of the computational graphs and back propagation

• Write two functions

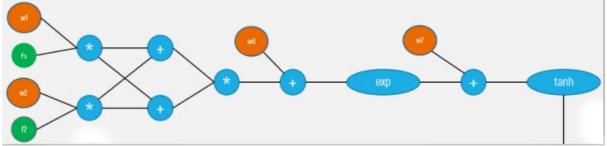
• Forward propagation(Write your code in def forward_propagation())

For easy debugging, we will break the computational graph into 3 parts.

Part 1

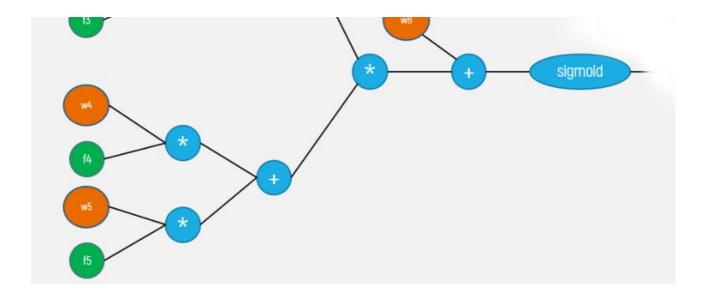


Part 2



Part 3





```
def forward_propagation(X, y, W):
```

return (dictionary, which you might need to use for back propagation)

Backward propagation(Write your code in def backward_propagation())

```
def backward_propagation(L, W, dictionary):

# L: the loss we calculated for the current point
# dictionary: the outputs of the forward_propagation() function
# write code to compute the gradients of each weight [w1, w2, w3,..., w9]
# Hint: you can use dict type to store the required variables
# return dW, dW is a dictionary with gradients of all the weights
return dW
```

Gradient clipping

Check this blog link for more details on Gradient clipping

we know that the derivative of any function is

 $\scriptstyle \$ \lim_{\epsilon\to0} \frac{f(x+\epsilon)-f(x-\epsilon)}{2\epsilon}

- The definition above can be used as a numerical approximation of the derivative. Taking an epsilon small enough, the calculated approximation will have an error in the range of epsilon squared.
- In other words, if epsilon is 0.001, the approximation will be off by 0.00001.

Therefore, we can use this to approximate the gradient, and in turn make sure that backpropagation is implemented properly. This forms the basis of gradient checking!

Gradient checking example

```
lets understand the concept with a simple example: f(w_1,w_2,x_1,x_2)=w_{1}^{2}. x_{1}+w_{2}. x_{2}
from the above function , lets assume w_{1}=1, w_{2}=2, x_{1}=3, x_{2}=4 the gradient of $f$ w.r.t w_{1} is
\left(\frac{1}{2} \frac{1}{2} \right) \left(\frac{1}{2} \frac{1}{2} = \frac{1} &= 2.w_{1}.x_{1} \right) = \frac{2.1.3}{8} = \frac{1}{2} \left(\frac{1}{2} \right) = \frac{1}{2}
let calculate the aproximate gradient of $w_{1}$ as mentinoned in the above formula and considering $\epsilon=0.0001$
2.4 (11.00060003) - (10.99940003) 0.0002 & = 0.0002 - (10.99940003) 0.0002 & = 0.0002 - 0.0002 & = 0.0002 - 0.0002
Then, we apply the following formula for gradient check: gradient\_check = \frac{\text{frac}\left(\left(W-dW^{approx}\right)\right)}{\text{frac}}
\right\Vert_2}{\left\Vert\left (dW\rm\right) \right\Vert_2+\left\Vert\left (dW^{approx}\rm\right) \right\Vert_2}$
The equation above is basically the Euclidean distance normalized by the sum of the norm of the vectors. We use normalization in
case that one of the vectors is very small. As a value for epsilon, we usually opt for 1e-7. Therefore, if gradient check return a
value less than 1e-7, then it means that backpropagation was implemented correctly. Otherwise, there is potentially a mistake in
your implementation. If the value exceeds 1e-3, then you are sure that the code is not correct.
you can mathamatically derive the same thing like this
\frac{((w_{1}+\epsilon))^{2} . x_{1} + w_{2} . x_{2}) - ((w_{1}-\epsilon))^{2} . x_{1} + w_{2} . x_{2})} < ((w_{1}-\epsilon))^{2} . x_{1} + w_{2} . x_{2})} < (w_{1}-\epsilon)^{2} . x_{2})
```

Implement Gradient checking

 $\ensuremath{$\ensuremath{$}\ensuremath{}\ensuremath{$}\ensuremath{}\ensuremath{$}\ensuremath{}\ensuremath{$}\ensuremath{}\ensuremath{}\ensuremath{}\ensuremath{}\ensuremath{}\ensurema$

(Write your code in def gradient_checking())
Algorithm

```
W = initilize_randomly
def gradient_checking(data_point, W):
# compute the L value using forward_propagation()
# compute the gradients of W using backword propagation()</font>
approx gradients = []
for each wi weight value in W:<font color='grey'>
    # add a small value to weight wi, and then find the values of L with the updated weights
    # subtract a small value to weight wi, and then find the values of L with the updated
weights
    # compute the approximation gradients of weight wi</font>
    approx_gradients.append(approximation gradients of weight wi) < font color='grey'>
# compare the gradient of weights W from backword_propagation() with the aproximation gradients
of weights with <br > gradient_check formula</font>
return gradient_check</font>
NOTE: you can do sanity check by checking all the return values of gradient checking(),
 they have to be zero. if not you have bug in your code
```

Task 2 : Optimizers

- As a part of this task, you will be implementing 3 type of optimizers(methods to update weight)
- Use the same computational graph that was mentioned above to do this task
- Initilze the 9 weights from normal distribution with mean=0 and std=0.01

Check below video and this blog

from IPython.display import YouTubeVideo
YouTubeVideo('gYpoJMlgyXA',width="1000",height="500")

```
Out[ ]:
```

Algorithm

```
for each epoch (1-100):
        for each data point in your data:
           using the functions forward propagation() and backword propagation() compute the
gradients of weights
            update the weigts with help of gradients ex: w1 = w1-learning_rate*dw1
```

Implement below tasks

- Task 2.1: you will be implementing the above algorithm with Vanilla update of weights
- Task 2.2: you will be implementing the above algorithm with Momentum update of weights
- Task 2.3: you will be implementing the above algorithm with Adam update of weights

Note: If you get any assertion error while running grader functions, please print the variables in grader functions and check which variable is returning False . Recheck your logic for that variable .

Task 1

Forward propagation

```
In [3]:
def sigmoid(z):
    '''In this function, we will compute the sigmoid(z)'''
    # we can use this function in forward and backward propagation
    sig = 1 / (1 + math.exp(-z))
    return sig
                                                                                                      In [15]:
def forward_propagation(x, y, w):
    '''In this function, we will compute the forward propagation '''
    # X: input data point, note that in this assignment you are having 5-d data points
    # y: output varible
```

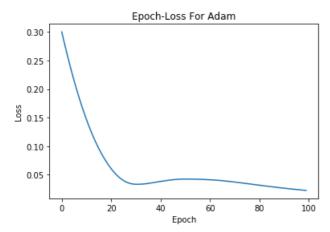
```
# you have to return the following variables
    # exp= part1 (compute the forward propagation until exp and then store the values in exp)
    sqr = pow(((x[0] * w[0]) + (x[1] * w[1])), 2)
    exp = math.exp(sqr + w[5])
    # tanh =part2(compute the forward propagation until tanh and then store the values in tanh)
    tanh = np.tanh(exp + w[6])
    # sig = part3(compute the forward propagation until sigmoid and then store the values in sig)
    sin = math.sin(w[2] * x[2])
    add = (w[3] * x[3]) + (w[4] * x[4])
    sig = sigmoid((sin * add) + w[7])
    \# now compute remaining values from computional graph and get y'
    y \text{ pred} = \tanh + (\text{sig} * w[8])
     # write code to compute the value of L=(y-y')^2
    1 = pow((y - y_pred), 2)
    # compute derivative of L w.r.to Y' and store it in dl
    d1 = -2 * (y - y pred)
    # Create a dictionary to store all the intermediate values
    # store L, exp, tanh, sig variables
    output dict = dict()
    output_dict['sigmoid'] = siq
    output_dict['tanh'] = tanh
    output_dict['exp'] = exp
    output dict['loss'] = 1
    output_dict['dy_pr'] = dl
    output_dict['y_pred'] = y_pred
    output dict['sin'] = sin
    output_dict['add'] = add
    output dict['sqr'] = sqr
    return output dict
Grader function - 1
                                                                                                        In [4]:
def grader sigmoid(z):
  val=sigmoid(z)
  assert(val==0.8807970779778823)
  return True
grader_sigmoid(2)
                                                                                                       Out[4]:
Grader function - 2
                                                                                                       In [16]:
def grader forwardprop(data):
    dl = (data['dy_pr']==-1.9285278284819143)
    loss=(data['loss']==0.9298048963072919)
    part1=(data['exp']==1.1272967040973583)
    part2=(data['tanh']==0.8417934192562146)
    part3=(data['sigmoid']==0.5279179387419721)
    assert(dl and loss and part1 and part2 and part3)
    return True
w=np.ones(9)*0.1
d1=forward propagation(X[0],y[0],w)
grader_forwardprop(d1)
                                                                                                      Out[16]:
True
Backward propagation
                                                                                                       In [33]:
def backward_propagation(x, w, d):
    '''In this function, we will compute the backward propagation '''
    # L: the loss we calculated for the current point
    # dictionary: the outputs of the forward_propagation() function
    # write code to compute the gradients of each weight [w1,w2,w3,...,w9]
    # Hint: you can use dict type to store the required variables
    dy = d['dy_pr']
    dtanh = dy
    dsig = w[8] * dy
    dw9 = d['sigmoid'] * dy
    dexp = (1 - pow(d['tanh'], 2)) * dtanh
    dw7 = dexp
    dw8 = (d['sigmoid'] * (1 - d['sigmoid'])) * dsig
    dsin = d['add'] * dw8
```

W: weight array, its of length 9, W[0] corresponds to w1 in graph, W[1] corresponds to w2 in graph

```
dadd = d['sin'] * dw8
    dw3 = x[2] * math.sqrt(1 - pow(d['sin'], 2)) * dsin
    dw4 = x[3] * dadd
    dw5 = x[4] * dadd
    dw6 = d['exp'] * dexp
    dsqr = dw6
    dw1 = x[0] * 2 * ((x[0] * w[0]) + (x[1] * w[1])) * dsqr
    dw2 = x[1] * 2 * ((x[0] * w[0]) + (x[1] * w[1])) * dsqr
    output_dict = dict()
    output_dict['dw1'] = dw1
    output_dict['dw2'] = dw2
    output_dict['dw3'] = dw3
    output dict['dw4'] = dw4
    output dict['dw5'] = dw5
    output_dict['dw6'] = dw6
    output_dict['dw7'] = dw7
    output dict['dw8'] = dw8
    output_dict['dw9'] = dw9
    return output dict
Grader function - 3
                                                                                                       In [26]:
def grader_backprop(data):
    dw1=(data['dw1']==-0.22973323498702003)
    dw2=(data['dw2']==-0.021407614717752925)
    dw3=(data['dw3']==-0.005625405580266319)
    dw4=(data['dw4']==-0.004657941222712423)
    dw5=(data['dw5']==-0.0010077228498574246)
    dw6=(data['dw6']==-0.6334751873437471)
    dw7=(data['dw7']==-0.561941842854033)
    dw8=(data['dw8']==-0.04806288407316516)
    dw9=(data['dw9']==-1.0181044360187037)
    assert(dw1 and dw2 and dw3 and dw4 and dw5 and dw6 and dw7 and dw8 and dw9)
    return True
w=np.ones(9)*0.1
d1=forward_propagation(X[0],y[0],w)
d1=backward_propagation(X[0],w,d1)
grader backprop(d1)
                                                                                                      Out[26]:
True
Implement gradient checking
                                                                                                       In [77]:
W = np.ones(9)*0.1
def gradient\_checking(x, y, W):
    d1 = forward_propagation(x, y, W)
    d2 = backward propagation(x, W, d1)
    gradients = np.array([val for val in d2.values()], dtype='float')
    approx gradients = []
    e = 0.0001
    for i in range(W.size):
        w1 = np.copy(W)
        w2 = np.copy(W)
         # add a small value to weight wi, and then find the values of L with the updated weights
         # subtract a small value to weight wi, and then find the values of L with the updated weights
         # compute the approximation gradients of weight wi
        w1[i] += e
        w2[i] -= e
        11 = forward_propagation(x, y, w1)['loss']
        12 = forward propagation(x, y, w2)['loss']
        dwi_app = (11 - 12) / (2 * e)
        approx gradients.append(dwi app)
     \# compare the gradient of weights 	exttt{W} from backword propagation() with the aproximation gradients of 	exttt{w}_1
    approx_gradients = np.array(approx_gradients)
    nu = np.linalg.norm(gradients - approx_gradients)
    de = np.linalg.norm(gradients) + np.linalg.norm(approx_gradients)
    gradient check = nu / de
    output dict = dict()
    output_dict['gradient_check'] = gradient_check
    output_dict['gradients'] = gradients
    return output_dict
```

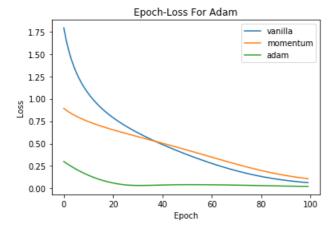
```
result = gradient_checking(X[0],y[0], W)
                                                                                                         In [79]:
print(result['gradient_check'])
print(result['gradients'])
2.235141456281688e-09
[-2.29733235e-01 -2.14076147e-02 -5.62540558e-03 -4.65794122e-03
 -1.00772285e-03 -6.33475187e-01 -5.61941843e-01 -4.80628841e-02
 -1.01810444e+00]
Task 2: Optimizers
Algorithm with Vanilla update of weights
                                                                                                        In [112]:
def sgd_vanilla(epochs, learning_rate):
     W = np.random.normal(0, 1, 9)
     epoch_loss = []
     for epoch in tqdm(range(epochs)):
         loss = []
         for i in range(X.shape[0]):
             d1 = forward_propagation(X[i], y[i], W)
             d2 = backward_propagation(X[i], W, d1)
             gradients = np.array([val for val in d2.values()], dtype='float')
             loss.append(d1['loss'])
             W -= (learning_rate * gradients)
         avg loss = sum(loss) / len(loss)
         epoch_loss.append(avg_loss)
     return epoch_loss
                                                                                                        In [113]:
epoch_loss_vanilla = sgd_vanilla(100, 0.0001)
                                                                                        100/100
[00:01<00:00, 59.02it/s]
Plot between epochs and loss
                                                                                                        In [114]:
import matplotlib.pyplot as plt
plt.plot(range(100), epoch_loss_vanilla)
plt.xlabel('Epoch')
plt.ylabel('Loss')
plt.title("Epoch-Loss For Vanilla")
plt.show()
                   Epoch-Loss For Vanilla
  1.75
  1.50
  1.25
  1.00
  0.75
  0.50
  0.25
  0.00
Algorithm with Momentum update of weights
                                                                                                        In [115]:
def sgd_momentum(epochs, learning_rate, gamma):
     W = np.random.normal(0, 1, 9)
     momentum = np.zeros(9)
     epoch_loss = []
     for epoch in tqdm(range(epochs)):
         loss = []
         for i in range(X.shape[0]):
             d1 = forward_propagation(X[i], y[i], W)
             d2 = backward_propagation(X[i], W, d1)
             gradients = np.array([val for val in d2.values()], dtype='float')
             loss.append(d1['loss'])
```

```
v_t = np.add((gamma * momentum), (learning_rate * gradients))
             w -= v_t
         avg loss = sum(loss) / len(loss)
         epoch_loss.append(avg_loss)
    return epoch_loss
                                                                                                         In [116]:
epoch loss momentum = sgd momentum(100, 0.0001, 0.9)
                                                                                         100/100
[00:02<00:00, 46.46it/s]
Plot between epochs and loss
                                                                                                         In [117]:
plt.plot(range(100), epoch_loss_momentum)
plt.xlabel('Epoch')
plt.ylabel('Loss')
plt.title("Epoch-Loss For Momentum")
plt.show()
                Epoch-Loss For Momentum
  0.9
  0.8
  0.7
  0.6
ξ 0.5
  0.4
  0.3
  0.2
  0.1
       ò
              20
                              60
                                      80
                                             100
Algorithm with Adam update of weights
                                                                                                         In [118]:
def sgd_adam(epochs, alpha, b1, b2):
     e = 0.0001
    W = np.random.normal(0, 1, 9)
    m_t = np.zeros(9)
    v_t = np.zeros(9)
     epoch_loss = []
     for epoch in tqdm(range(epochs)):
         loss = []
         for i in range(X.shape[0]):
             d1 = forward_propagation(X[i], y[i], W)
             d2 = backward_propagation(X[i], W, d1)
             gradients = np.array([val for val in d2.values()], dtype='float')
             loss.append(d1['loss'])
             m_t = np.add((b1 * m_t), ((1 - b1) * gradients))
             v t = np.add((b2 * v t), ((1 - b2) * np.power(gradients, 2)))
             m_t = m_t / (1 - pow(b1,2))
             v_t = v_t / (1 - pow(b2,2))
             W -= (alpha * np.divide(m_t_, np.sqrt(v_t_ + e)))
         avg_loss = sum(loss) / len(loss)
         epoch_loss.append(avg_loss)
     return epoch_loss
                                                                                                         In [119]:
epoch_loss_adam = sgd_adam(100, 0.0001, 0.001, 0.05)
                                                                                         100/100
100%
[00:02<00:00, 37.32it/s]
Plot between epochs and loss
                                                                                                         In [120]:
plt.plot(range(100), epoch loss adam)
plt.xlabel('Epoch')
plt.ylabel('Loss')
plt.title("Epoch-Loss For Adam")
plt.show()
```



Comparision plot between epochs and loss with different optimizers

```
plt.plot(range(100), epoch_loss_vanilla, label='vanilla')
plt.plot(range(100), epoch_loss_momentum, label = 'momentum')
plt.plot(range(100), epoch_loss_adam, label = 'adam')
plt.xlabel('Epoch')
plt.ylabel('Loss')
plt.title("Epoch-Loss For Adam")
plt.legend()
plt.show()
```





In [123]:

