## Correct Scan Format

Wire Profile, WB [str] 1 2 X Location,0 [float] 3 Total Sample Length,61 [float] 4 Pts/rev,720 [int] 5 DataState,Corrected [str] 6 TimeStamp, 3/23/2018 9:55 AM [str] 7 0.00000, 0.00002, 0.00004, 0.00006, 0.00008, 0.00010, 0.00012, 0.00014, 0.00016, 8 -5.2463, -5.3066, -5.3105, -5.3048, -5.2983, -5.2943, -5.3002, -5.3048, -5.3056, -5.2911,9 -5.2896, -5.3000, -5.2971, -5.3112, -5.3276, -5.3306, -5.3127, -5.2942, -5.2784, -5.2732, 10 -5.2765, -5.2917, -5.2811, -5.2715, -5.2638, -5.2988, -5.3061, -5.3041, -5.3092, -5.3141,-5.3163, -5.3147, -5.3080, -5.3046, -5.3042, -5.2914, -5.2898, -5.2969, -5.2986, -5.3067,11 12 -5.3166, -5.3251, -5.2953, -5.2715, -5.2659, -5.2996, -5.3073, -5.2930, -5.2873, -5.2852, -5.2854, -5.2853, -5.2930, -5.2968, -5.2877, -5.2868, -5.2908, -5.2993, -5.2897, -5.3008, 13 14 -5.3168, -5.2841, -5.2745, -5.2803, -5.2809, -5.2554, -5.2256, -5.2459, -5.2665, -5.2809, -5.2861, -5.2794, -5.2782, -5.2816, -5.2787, -5.2767, -5.2769, -5.2841, -5.2762, -5.2675, 15 16 -5.2682, -5.2614, -5.2592, -5.2694, -5.2792, -5.2918, -5.3015, -5.2841, -5.2762, -5.2736, 17 -5.2701, -5.2792, -5.2892, -5.2907, -5.2822, -5.2757, -5.2743, -5.2743, -5.2825, -5.2960, -5.2914, -5.2929, -5.2943, -5.2850, -5.2678, -5.2577, -5.2860, -5.2858, -5.2789, -5.2681, 18 19 -5.2647, -5.2678, -5.2782, -5.2965, -5.2987, -5.2962, -5.3052, -5.2953, -5.2892, -5.3050, 20 -5.3059, -5.3102, -5.3195, -5.3049, -5.2969, -5.2944, -5.2931, -5.2891, -5.2851, -5.2883, 21 -5.2796, -5.2736, -5.2896, -5.2858, -5.2771, -5.2659, -5.2762, -5.2844, -5.2875, -5.2857, -5.2818, -5.2778, -5.2805, -5.2765, -5.2765, -5.2962, -5.2970, -5.2974, -5.3007, -5.2927, 22 23 -5.3012, -5.3197, -5.3127, -5.2979, -5.2802, -5.2649, -5.2854, -5.2992, -5.2730, -5.2847, 24 -5.2920, -5.2841, -5.2859, -5.2865, -5.2850, -5.2752, -5.2731, -5.2764, -5.2832, -5.2851, 25 -5.2832, -5.2766, -5.2787, -5.2881, -5.3050, -5.3073, -5.3018, -5.2923, -5.2980, -5.2935, 26 -5.2857,-5.2846,-5.2871,-5.2913,-5.2969,-5.3005,-5.2955,-5.2799,-5.2748,-5.2829, 27 -5.3027, -5.3042, -5.2938, -5.2800, -5.2820, -5.2934, -5.2994, -5.2845, -5.2856, -5.2919, 28 -5.3008, -5.2931, -5.2905, -5.2938, -5.2909, -5.2927, -5.2966, -5.2936, -5.2978, -5.3009, 29 -5.2926, -5.2905, -5.2933, -5.3023, -5.3019, -5.2991, -5.2947, -5.2963, -5.2992, -5.3021, 30 -5.2988, -5.2905, -5.2842, -5.2932, -5.2896, -5.2853, -5.2860, -5.2912, -5.2982, -5.3060, 31 -5.2939, -5.2869, -5.2854, -5.2971, -5.2963, -5.2909, -5.2907, -5.2889, -5.2904, -5.3000, 32 -5.3052, -5.3064, -5.3034, -5.3136, -5.3069, -5.2893, -5.2875, -5.2909, -5.2939, -5.2833, 33 -5.2895, -5.2949, -5.2844, -5.2848, -5.2805, -5.2663, -5.2769, -5.2839, -5.2847, -5.2837, 34 -5.2909, -5.3005, -5.2972, -5.2901, -5.2885, -5.3064, -5.3034, -5.2980, -5.2949, -5.2854, 35 -5.2879, -5.3025, -5.2873, -5.2765, -5.2717, -5.2874, -5.2920, -5.2918, -5.2910, -5.2752, -5.2677, -5.2849, -5.2835, -5.2865, -5.2964, -5.2773, -5.2656, -5.2614, -5.2689, -5.2731, 36 37 -5.2745, -5.2717, -5.2772, -5.2776, -5.2608, -5.2710, -5.2779, -5.2725, -5.2704, -5.2669, 38 -5.2622, -5.2634, -5.2697, -5.2793, -5.2899, -5.2799, -5.2661, -5.2643, -5.2658, -5.2587, 39 -5.2347, -5.2482, -5.2500, -5.2317, -5.2507, -5.2646, -5.2727, -5.2698, -5.2743, -5.2790, 40 -5.2696, -5.2722, -5.2725, -5.2592, -5.2603, -5.2624, -5.2625, -5.2613, -5.2694, -5.2847, -5.2720, -5.2757, -5.2852, -5.2713, -5.2739, -5.2805, -5.2787, -5.2738, -5.2706, -5.2719, 41 42 -5.2674,-5.2704,-5.2832,-5.2949,-5.3050,-5.3126,-5.3089,-5.3008,-5.2891,-5.2721, 43 -5.2718, -5.2765, -5.2794, -5.2866, -5.2883, -5.2806, -5.2837, -5.2869, -5.2894, -5.2850,

Scanner Index: j = 0,1,...,799 (800 Points)

-5.2819, -5.2805, -5.2829, -5.2726, -5.2645, -5.2804, -5.2826, -5.2805, -5.2767, -5.3005,

## Notes:

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- (1) Line 6 uses the same time/date as the original raw data file. This is to ensure that there is no confusion about what file the corrected scan was derived from. The time/date that the conversion takes place is listed in the console log that is bundled with the corrected scans!
- (1) Line 7 contains the axial position of the sensor points based on the starting position. These positions correspond to the Scanner Index.