

Machine Learning

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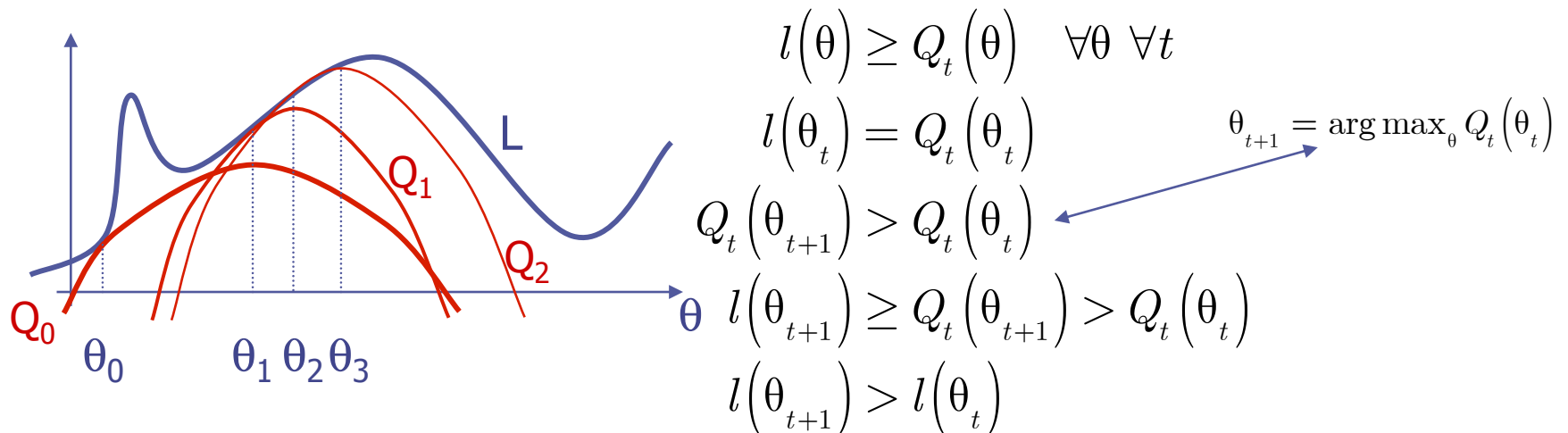
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Topic 13

- Expectation Maximization as Bound Maximization
- EM for Maximum A Posteriori

EM as Bound Maximization

- Let's now show that EM indeed maximizes likelihood
- **Bound Maximization:** optimize a lower bound on $l(\theta)$
- Since log-likelihood $l(\theta)$ not concave, can't max it directly
- Consider an auxiliary function $Q(\theta)$ which is concave
- $Q(\theta)$ kisses $l(\theta)$ at a point and is less than it elsewhere



- Monotonically increases log-likelihood
- But how to find a bound and guarantee we max it?



Jensen's Inequality

- An important general bound from Jensen (1906)

- For convex f :
$$f\left(E\{x\}\right) \leq E\{f(x)\}$$

- For concave f :
$$f\left(E\{x\}\right) \geq E\{f(x)\}$$

- Expectation in discrete case is sum weight by probability

- For convex f :
$$f\left(\sum_{i=1}^M p_i x_i\right) \leq \sum_{i=1}^M p_i f(x_i) \text{ when } \sum_{i=1}^M p_i = 1, p_i \geq 0$$

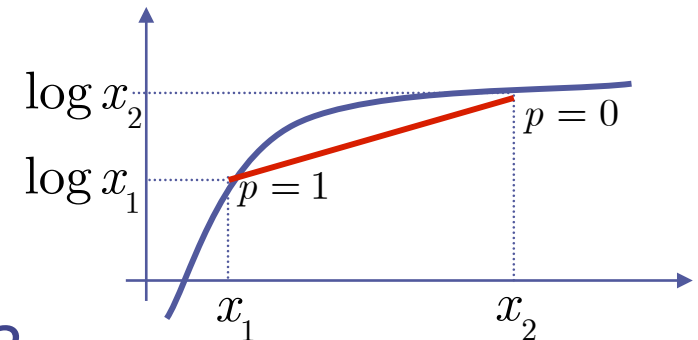
- For concave f :
$$f\left(\sum_{i=1}^M p_i x_i\right) \geq \sum_{i=1}^M p_i f(x_i) \text{ when } \sum_{i=1}^M p_i = 1, p_i \geq 0$$

- Example: $f(x)=\log(x)$ =concave and $M=2$

$$\log\left(px_1 + (1-p)x_2\right) \geq p \log x_1 + (1-p) \log x_2$$

- Bound $\log(\text{sum})$ with $\text{sum}(\log)$

- How to apply this to mixture models?



Expectation-Maximization

$$\begin{aligned}
 l(\theta) &= \sum_{n=1}^N \log p(x_n | \theta) && \text{Original Log-Likelihood} \\
 &= \sum_{n=1}^N \log \sum_z p(x_n, z | \theta) && \text{Has Hidden Variables (messy)} \\
 &= \sum_{n=1}^N \log \sum_z p(x_n, z | \theta) \frac{p(z | x_n, \theta_t)}{p(z | x_n, \theta_t)} && \text{Multiply by 1} \\
 &= \sum_{n=1}^N \log \sum_z p(z | x_n, \theta_t) \frac{p(x_n, z | \theta)}{p(z | x_n, \theta_t)} && \text{Ratio of hidden posterior density} \\
 &\geq \sum_{n=1}^N \sum_z p(z | x_n, \theta_t) \log \frac{p(x_n, z | \theta)}{p(z | x_n, \theta_t)} && \text{Rearrange} \\
 &= \sum_{n=1}^N \sum_z p(z | x_n, \theta_t) \log p(x_n, z | \theta) && \text{Jensen log}(\sum_i p_i x_i) \\
 &\quad - \sum_{n=1}^N \sum_z p(z | x_n, \theta_t) \log p(z | x_n, \theta_t) \\
 &= Q(\theta | \theta_t) - \text{const} && \text{New auxiliary function called Q (not messy)}
 \end{aligned}$$

EM as Bound Maximization

- Now have the following bound and maximize it:

$$\begin{aligned}
 l(\theta) &\geq Q(\theta | \theta_t) - \sum_{n=1}^N \sum_z p(z | x_n, \theta_t) \log p(z | x_n, \theta_t) \\
 \theta^{t+1} &= \arg \max_{\theta} Q(\theta | \theta_t) = \arg \max_{\theta} \sum_{n=1}^N \sum_z p(z | x_n, \theta_t) \log p(x_n, z | \theta) \\
 &= \arg \max_{\theta} \sum_{n=1}^N \sum_z \tau_{n,z} \log p(x_n, z | \theta)
 \end{aligned}$$

- $Q(\theta | \theta_t)$ is called **Auxiliary Function**... take derivatives of it
- This is easy for e-families... just weighted max likelihood!
- For example, Gaussian mixture:

$$\begin{aligned}
 \frac{\partial Q(\theta)}{\partial \vec{\mu}_k} &= \frac{\partial}{\partial \vec{\mu}_k} \sum_{n=1}^N \sum_k \tau_{n,k} \log \pi_k N(\vec{x}_n | \vec{\mu}_k, \Sigma_k) \\
 0 &= \sum_{n=1}^N \tau_{n,k} \frac{\partial}{\partial \vec{\mu}_k} \left(-\frac{1}{2} (\vec{x}_n - \vec{\mu}_k)^T \Sigma_k^{-1} (\vec{x}_n - \vec{\mu}_k) \right) \\
 \vec{\mu}_k &= \frac{\sum_{n=1}^N \tau_{n,k} \vec{x}_n}{\sum_{n=1}^N \tau_{n,k}}
 \end{aligned}$$

... similarly get π_k and Σ_k

EM as Expected Likelihood

- Can also view $Q(\theta | \theta_t)$ as the **Expected Complete Likelihood**

$$Q(\theta | \theta_t) = \sum_{n=1}^N \sum_z p(z | x_n, \theta_t) \log p(x_n, z | \theta) - \text{const}$$

- **Incomplete Likelihood:** $l(\theta) = \sum_{n=1}^N \log \sum_z p(x_n, z | \theta)$

- **Complete Likelihood:** $l^C(\theta) = \sum_{n=1}^N \log p(x_n, z_n | \theta)$

- Since we don't know z , use expected values of z using current model θ_t in other words: $\prod_n p(z_n | x_n, \theta_t)$

$$\begin{aligned} E\{l^C(\theta)\} &= \sum_{z_1} \cdots \sum_{z_N} \prod_n p(z_n | x_n, \theta_t) l^C(\theta) \\ &= \sum_{z_1} \cdots \sum_{z_N} \prod_n p(z_n | x_n, \theta_t) \sum_n \log p(x_n, z_n | \theta) \\ &= \sum_n \sum_{z_n} p(z_n | x_n, \theta_t) \log p(x_n, z_n | \theta) \sum_{z_1} \cdots \sum_{z_{i \neq n}} \cdots \sum_{z_N} \prod_{i \neq n} p(z_i | x_i, \theta_t) \\ &= \sum_n \sum_{z_n} p(z_n | x_n, \theta_t) \log p(x_n, z_n | \theta) \\ &= Q(\theta | \theta_t) + \text{const} \end{aligned}$$

EM for Max A Posteriori

- We can also do MAP instead of ML with EM (stabilizes sol'n)

$$posterior(\theta) = \sum_{n=1}^N \log \sum_z p(x_n, z | \theta) + \log p(\theta)$$

- Prior doesn't have log-sum
- The E-step remains the same: lower bound log-sum

$$posterior(\theta) = l(\theta) + \log p(\theta) \geq E\{l^c(\theta)\} + const + \log p(\theta)$$

- The M-step becomes slightly different for each model

- For example, mixture of Gaussians with prior on covariance

$$posterior(\theta) = \sum_{n=1}^N \log \sum_k \pi_k N(\vec{x}_n | \vec{\mu}_k, \Sigma_k) + \log \prod_k p(\Sigma_k | S, \eta)$$

$$posterior(\theta) \geq \sum_{n=1}^N \sum_k \tau_{n,k} \log \pi_k N(\vec{x}_n | \vec{\mu}_k, \Sigma_k) + \sum_k \log p(\Sigma_k | S, \eta) + const$$

- Updates on π and μ stay the same, only Σ is:

$$\Sigma_k \leftarrow \frac{1}{\sum_{n=1}^N \tau_{n,k} + \eta} \left(\sum_{n=1}^N \tau_{n,k} (\vec{x}_n - \vec{\mu}_k)(\vec{x}_n - \vec{\mu}_k)^T + \eta S \right)$$

- Typically, we use the identity matrix I for S and a small eta.