Machine Learning 4771

Instructor: Tony Jebara

Topic 18

- •The Junction Tree Algorithm
- Collect & Distribute
- Algorithmic Complexity
- ArgMax Junction Tree Algorithm

Review: Junction Tree Algorithm

- Send message from each clique to its separators of what it thinks the submarginal on the separator is.
- Normalize each clique by incoming message from its separators so it agrees with them

If agree:
$$\sum_{V\setminus S} \psi_V = \phi_S = p(S) = \phi_S = \sum_{W\setminus S} \psi_W$$
 ...Done!

Else: Send message From V to W...

$$\phi_S^* = \sum_{V \setminus S} \psi_V$$

$$\psi_W^* = \frac{\phi_S^*}{\phi_S} \psi_W$$

$$\psi_V^* = \psi_V$$

Send message From W to V...

$$\begin{aligned} \varphi_S^{**} &= \sum_{W \setminus S} \psi_W^* \\ \psi_V^{**} &= \frac{\varphi_S^{**}}{\varphi_S^*} \psi_V^* \\ \psi_W^{**} &= \psi_W^* \end{aligned}$$

Now they Agree...Done!

JTA with Evidence

•Example: if evidence is observed, say variable A=1

Initialize as before...

$$\psi_{AB} = p(A, B) \qquad \psi_{BC} = p(C \mid B) \qquad \phi_B = 1$$

Update with slice...

$$\phi_{B}^{*} = \sum_{A} \psi_{AB} \delta(A = 1) = \sum_{A} p(A, B) \delta(A = 1) = p(A = 1, B)$$

$$\psi_{BC}^{*} = \frac{\phi_{S}^{*}}{\phi_{S}} \psi_{BC} = \frac{p(A = 1, B)}{1} p(C \mid B) = p(A = 1, B, C)$$

$$\psi_{AB}^{*} = \psi_{AB} = p(A = 1, B)$$

All ψ, ϕ become marginals *conditioned* on evidence

$$p(B,C \mid A=1) = \frac{\psi_{BC}^*}{\sum_{B,C} \psi_{BC}^*}$$

JTA with many cliques

•Problem: what if we have more than two cliques?

1) Update AB & BC



2) Update BC & CD



•Problem: AB has not heard about CD!

After BC updates, it will be inconsistent for AB

- Need to iterate the pairwise updates many times
- •This will eventually converge to consistent marginals
- •But, inefficient... can we do better?

JTA: Collect & Distribute

- Trees: recursive, no need to reiterate messages mindlessly!
- Send your message only after hearing from all neighbors...

```
initialize(DAG){ Pick root
                                 Set all variables as: \psi_{C} = p(x_i \mid \pi_i), \phi_S = 1 }
collectEvidence(node) {
     for each child of node {
          update(node,collectEvidence(child)); }
     return(node); }
distributeEvidence(node) {
     for each child of node {
          update(child,node);
         distributeEvidence(child); } }
\begin{array}{l} \textbf{normalize(DAG) \{} \ p\left(X_{C}\right) = \frac{\psi_{C}}{\sum_{X_{C}}\psi_{C}}, p\left(X_{S}\right) = \frac{\varphi_{S}}{\sum_{X_{S}}\varphi_{S}} \ \ \} \\ \textbf{update(node } \psi, \textbf{evidence } \phi) \ \{ \quad \psi_{C}^{*} = \frac{\varphi_{S}}{\sum_{C \setminus S}\psi_{C}} \psi_{C} \ \ \} \end{array}
```

Junction Tree Algorithm

Convert Directed Graph to Junction Tree

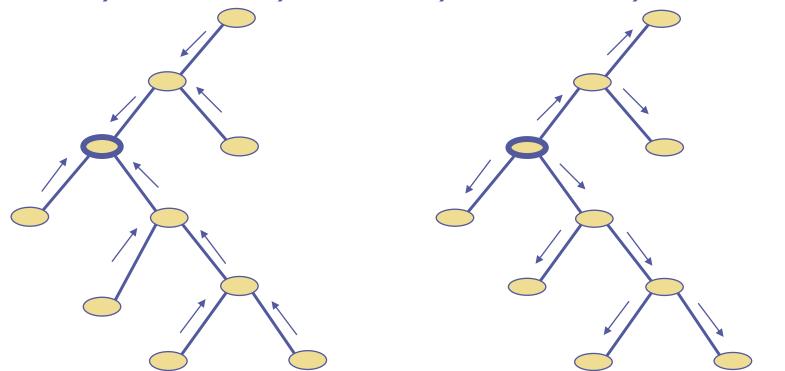


• Initialize separators to 1 (and Z=1) and set clique tables to the CPTs in the Directed Graph

$$\begin{split} p\left(X\right) &= p\left(x_{_{\!1}}\right)p\left(x_{_{\!2}}\mid x_{_{\!1}}\right)p\left(x_{_{\!3}}\mid x_{_{\!2}}\right)p\left(x_{_{\!4}}\mid x_{_{\!3}}\right)p\left(x_{_{\!5}}\mid x_{_{\!3}}\right)p\left(x_{_{\!6}}\mid x_{_{\!5}}\right)p\left(x_{_{\!7}}\mid x_{_{\!5}}\right) \\ p\left(X\right) &= \frac{1}{Z}\frac{\prod_{_{C}}\psi\left(X_{_{C}}\right)}{\prod_{_{S}}\phi\left(X_{_{\!S}}\right)} \\ &= \frac{1}{1}\frac{p\left(x_{_{\!1}},x_{_{\!2}}\right)p\left(x_{_{\!3}}\mid x_{_{\!2}}\right)p\left(x_{_{\!4}}\mid x_{_{\!3}}\right)p\left(x_{_{\!5}}\mid x_{_{\!3}}\right)p\left(x_{_{\!6}}\mid x_{_{\!5}}\right)p\left(x_{_{\!7}}\mid x_{_{\!5}}\right)}{1\times1\times1\times1\times1} \end{split}$$

Junction Tree Algorithm

•JTA: 1) *Initialize* 2) *Collect* 3) *Distribute* 4) *Normalize*



- •Note: leaves do not change their ψ during *collect*
- •Note: the first cliques *collect* changes are parents of leaves
- •Note: root does not change its ψ during *distribute*

Algorithmic Complexity

•The 5 steps of JTA are all efficient:

OFFLINE

1) Moralization

Polynomial in # of nodes

2) Introduce Evidence (fixed or constant)

Polynomial in # of nodes (convert pdf to slices)

3) Triangulate (Tarjan & Yannakakis 1984)

Suboptimal=Polynomial, Optimal=NP

4) Construct Junction Tree (Kruskal)

Polynomial in # of cliques

ONLINE (for each query, new evidence, etc.)

5) Propagate Probabilities (Junction Tree Algorithm)

Polynomial (linear) in # of cliques, Exponential in Clique Cardinality

ArgMax Junction Tree Algorithm

- We can also use JTA for finding the max not the sum over the joint to get argmax of marginals & conditionals
- •Say have some evidence: $p(X_F, \overline{X}_E) = p(x_1, ..., x_n, \overline{x}_{n+1}, ..., \overline{x}_N)$
- •Most likely (highest p) X_F ? $X_F^* = \arg \max_{X_F} p(X_F, \bar{X}_E)$
- •What is most likely state of patient with fever & headache?

$$\begin{split} p_F^* &= \max_{x_2, x_3, x_4, x_5} \, p \Big(x_1 = 1, x_2, x_3, x_4, x_5, x_6 = 1 \Big) \\ &= \max_{x_2} \, p \Big(x_2 \mid x_1 = 1 \Big) \, p \Big(x_1 = 1 \Big) \max_{x_3} \, p \Big(x_3 \mid x_1 = 1 \Big) \\ &\max_{x_4} \, p \Big(x_4 \mid x_2 \Big) \max_{x_5} \, p \Big(x_5 \mid x_3 \Big) \, p \Big(x_6 = 1 \mid x_2, x_5 \Big) \end{split}$$

•Solution: update in JTA uses max instead of sum:

$$\phi_S^* = \max_{V \setminus S} \psi_V \quad \psi_W^* = \frac{\phi_S^*}{\phi_S} \psi_W \quad \psi_V^* = \psi_V$$

- •Final potentials aren't marginals: $\psi(X_C) = \max_{U \setminus C} p(X)$
- •Highest value in potential is most likely: $X_C^* = \arg\max_C \psi(X_C)$