

## **ME 533: Nonlinear Dynamics Analysis**

**(Actually more Nonlinear Dynamics and Control Analysis)**

**Spring 2018**

**4 Credits** □

### **Instructor**

Prof. Ravi Balasubramanian  
ravi.balasubramanian@oregonstate.edu  
Graf Hall 315

### **Class hours:**

MW 12–2 PM, BAT 144

### **Instructor office hours:**

Tu 330—430 PM, Graf 315

### **Textbook**

Applied Nonlinear Control  
J-J. E. Slotine and Weiping Li  
Prentice Hall, 1991

### **Reference material for fundamental/linear control system topics**

Any one and any edition of the following books:

- 1) N. S. Nise, Control Systems Engineering, Wiley, 6<sup>th</sup> edition, 2010.
- 2) K. Ogata, Modern Control Engineering, 5<sup>th</sup> edition, Prentice Hall, 2009.

### **Course description**

This course seeks to present the fundamental results of modern nonlinear dynamics and control and demonstrate their use in the design of practical nonlinear control systems. The course starts by providing fundamental analytical tools such as phase-space analysis and then move on to more advanced techniques such as Lyapunov methods, linearization, and Lie Algebra techniques and perform stability analysis. The course will also introduce how nonlinear control systems are prevalent in everyday dynamic systems such as human musculoskeletal movements and locomotion systems. Finally, the course will include a short project applying the concepts learned.

### **Grading**

Class participation (including topic presentations by students): 30%

Homeworks: 10%

Final project proposal: 20%

Final project proposal presentation: 10%

Final project paper: 20%

Final project presentation: 10%

### Final Project

Focusing on the models/chapters/papers covered in class or your own research problem, the students in groups of two will prepare a four-page term paper (single-line spaced, double column, 11 pt font) on a topic of interest in consultation with the instructor. The project must include a computational model (say in Matlab or Mathematica) of some nonlinear dynamic system. It must also include a literature survey of the topic and discuss the importance of the topic to research in the field of nonlinear dynamics.

### Learning Outcomes

By the end of this course students will:

- 1) Have an understanding of how nonlinear dynamics and control is a key aspect of everyday systems.
- 2) Have an introduction to key tools for nonlinear control analysis.
- 3) Identify what tools will be useful for a specific nonlinear dynamics/control problem.
- 4) Conduct a research project that explores one specific problem in nonlinear control and write a research paper on it.

### Tentative Course Schedule (subject to change):

Date	Lecture	Tentative Deadlines
M 4/2	Nonlinear systems: introduction	
W 4/4	Phase space analysis (chapter 2)	HW1 out
M 4/9	Basic Lyapunov theory (sections 3.3, 3.4.1, 3.4.2)	
W 4/11	Instructor traveling	HW 2 out
M 4/16	Lyapunov stability analysis (section 3.4.3)	
W 4/18	Convergence to invariant sets (sections 3.4.3 and 3.6)	
M 4/23	Stability of time varying systems (sections 4.2, 4.5)	HW 3 out
W 4/25	Sliding variables (section 7.1)	
M 4/30	Robust control (sections 7.2, 7.3)	HW 4 out
W 5/2	Adaptive control (chapter 8)	

M 5/7	Robust adaptive control (section 8.8)	
W 5/9	Adaptive robot control (chapter 9) Example Systems: Guest lecture?	HW 5 out
M 5/14	Feedback linearization (section 6.1) Example Systems: Guest lecture?	
W 5/16	Basic differential geometry tools (section 6.2)	
M 5/21	Controllability, integrability, and backstepping (section 6.3 and pp. 258—262) Example systems: Guest lecture?	Begin thinking about term paper
W 5/23	Example systems: Neuro-musculo-skeletal control system Error-recovery for mobile robots	
M 5/28	Synchronization (if time permits)	Term paper proposal due
W 5/30		Term paper proposal presentations due
M 6/4	Work on term paper ideas	
W 6/6	Work on term paper ideas	
3/14-3/18	Finals week	Term paper due 3/14. Presentation on 3/16.

### **Statement Regarding Students With Disabilities:**

Accommodations are collaborative efforts between students, faculty and Disability Access Services (DAS). Students with accommodations approved through DAS are responsible for contacting the faculty member in charge of the course prior to or during the first week of the term to discuss accommodations. Students who believe they are eligible for accommodations but who have not yet obtained approval through DAS should contact DAS immediately at 737-4098.

### **Student Conduct Code and Academic Integrity:**

Link to student conduct code:

<http://oregonstate.edu/studentconduct/code/index.php>