

ROBUST STATISTICS FOR TESTING THE HOMOGENEITY OF COVARIANCE SCALE AND SHAPE

AN APPLICATION TO SAR CHANGE DETECTION

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ABOUT THIS TALK

We consider the problem of SAR change detection through covariance matrix equality testing.

Approach based on multivariate statistical analysis. Pre-requisites:

- Basic algebra
- Basic statistics

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PLAN OF THE PRESENTATION

1. The Change detection problem
2. Covariance-based approaches
3. Statistics of decision under Gaussian assumption
4. Extension to Elliptical distributions
5. Results on SAR images

THE CHANGE DETECTION PROBLEM

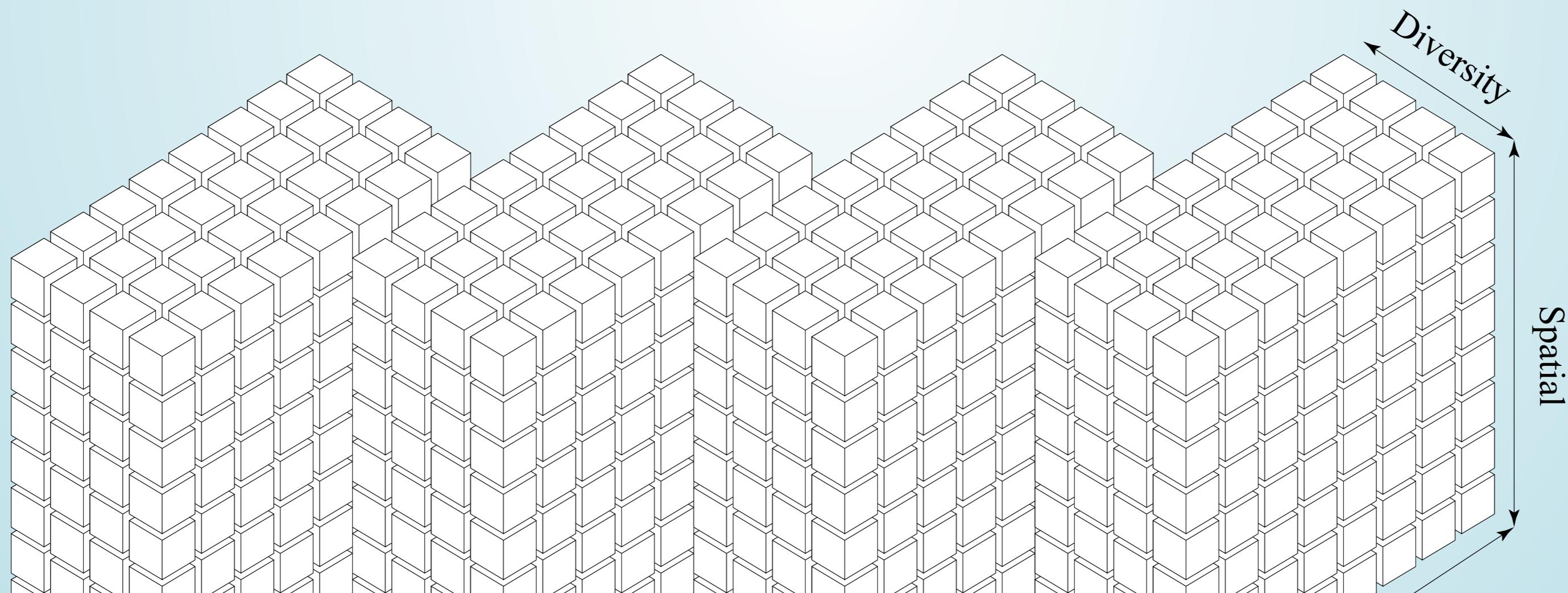
WHAT WE WANT TO DO?

Considering a **time series** of SAR images, we want to **detect** spatial areas where noticeable changes have occurred.



ASSUMPTIONS

- The images are co-registered
- Unsupervised methodology
- Data is complex and multivariate



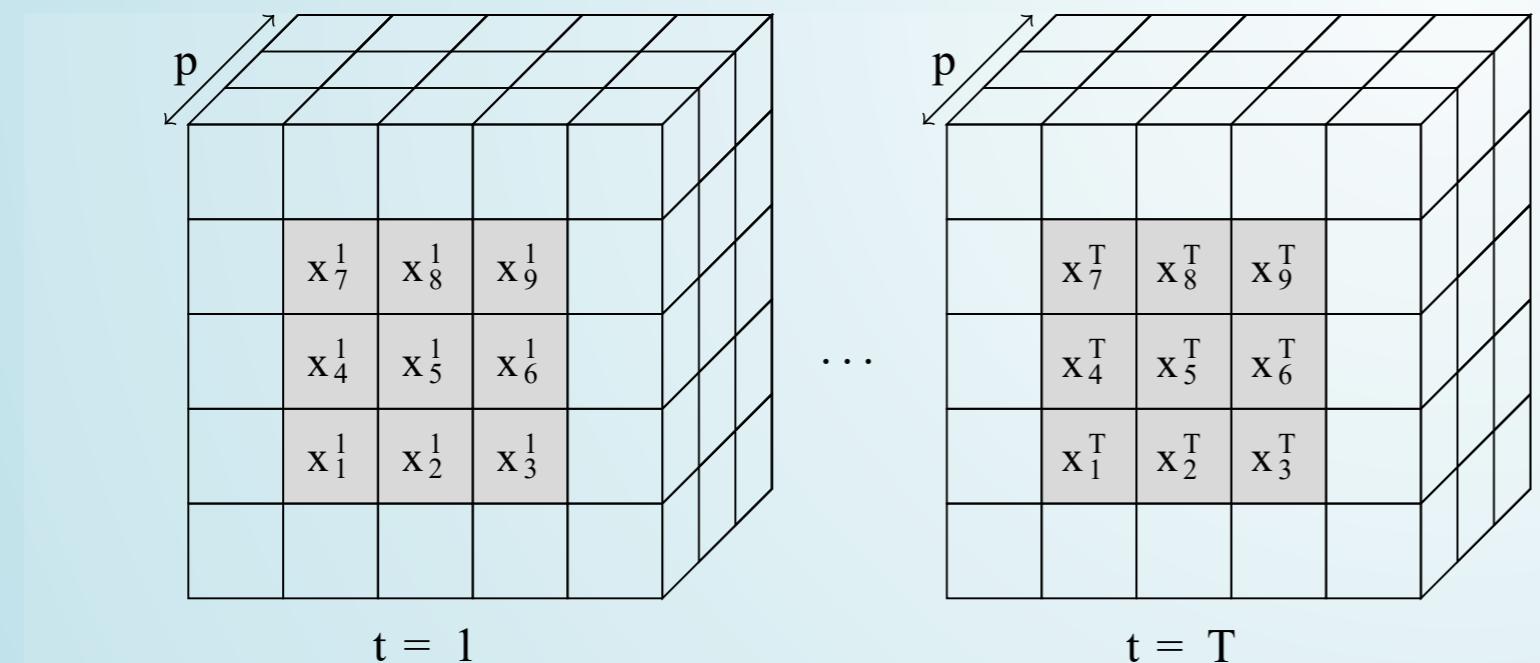
COVARIANCE-BASED APPROACHES

DESCRIPTION OF THE APPROACH

We consider a sliding windows approach to consider spatially local data.

On this window, we assume i.i.d observations:

$$\forall(k, t) \mathbf{x}_k^t \sim \mathcal{C}(\mathbf{0}_p, \Sigma_t)$$



Idea: Compare the covariances Σ_t over time.

INTEREST OF THE APPROACH

- The SAR data is typically **noisy** (speckle noise) and can be **multivariate** (polarimetric for example).
- Covariance accounts for the local correlations between the observed noisy data. A change in the scene is likely to impact this matrix in a way.
- Using statistical detection theory allow to have theoretical results on false alarms or detection performance.

THE DETECTION PROBLEM

Denote by $\{\mathbf{x}_1, \dots, \mathbf{x}_T\}$ a collection of T mutually independent samples of i.i.d p -dimensional complex vectors: $\mathbf{x}_t = [\mathbf{x}_1^t, \dots, \mathbf{x}_T^t]$.

We assume $\forall(k, t)$, $\mathbb{E}\{\mathbf{x}_k^t\} = \mathbf{0}_p$ and we denote $\Sigma_t = \tau_t \boldsymbol{\xi}_t$ the shared covariance matrices among the elements of \mathbf{x}_t . $\boldsymbol{\xi}_t$ is the shape matrix ($Tr(\boldsymbol{\xi}_t) = p$) and τ_t is the scale.

We want to choose between the following alternatives:

$$H_0 : \Sigma_1 = \dots = \Sigma_T = \Sigma_0,$$

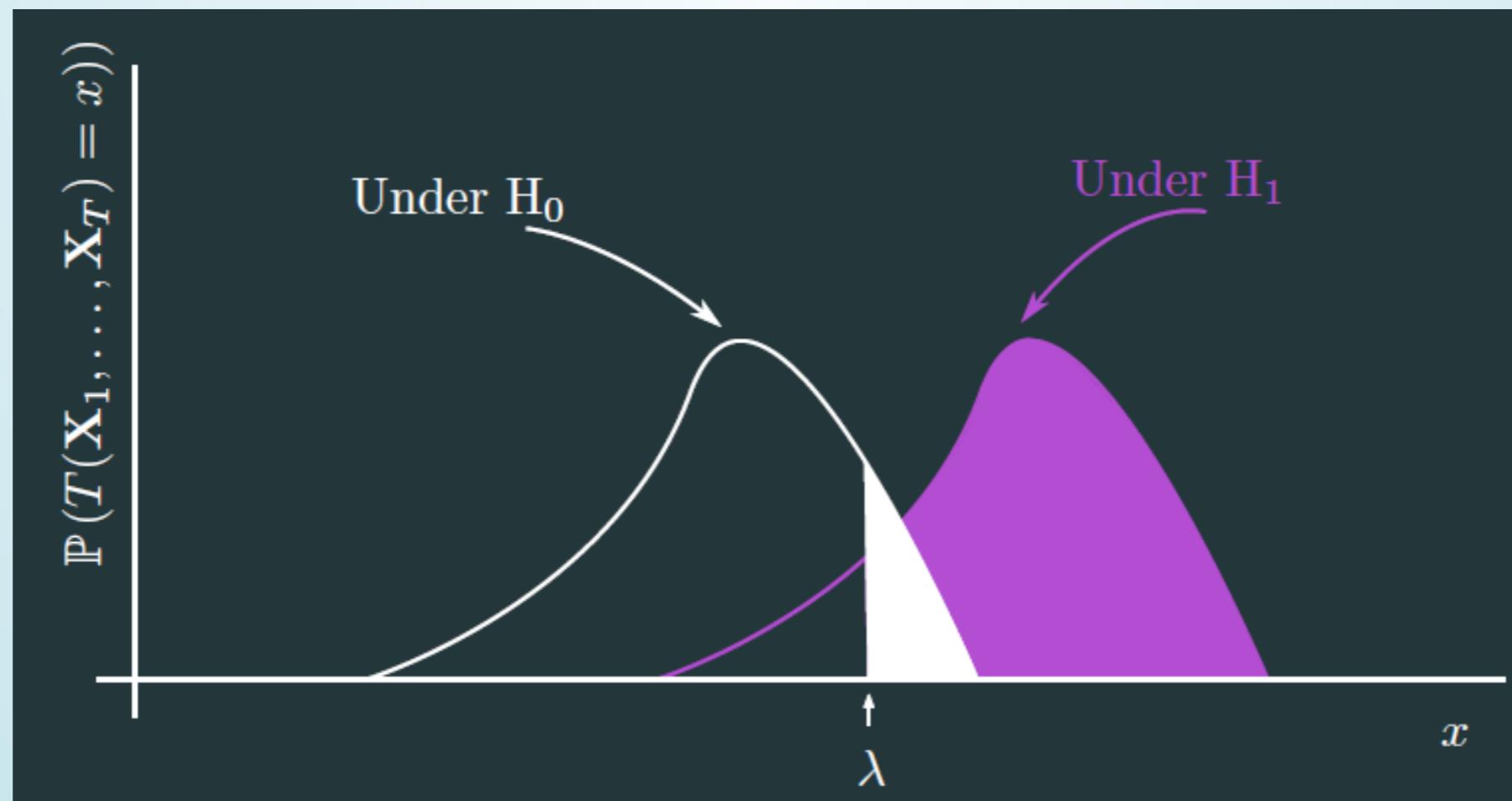
$$H_1 : \exists(t, t'), \Sigma_t \neq \Sigma_{t'}$$

STATISTIC OF DECISION

We want to obtain:

- a statistic of decision T : $\mathbb{C}^{p \times} \times \cdots \times \mathbb{C}^{p \times} \rightarrow \mathbb{R}^+$
 $x_1, \dots, x_T \rightarrow T(x_1, \dots, x_T)$
- a threshold λ

So that $\mathbb{P}(T(x_1, \dots, x_T) > \lambda | H_1)$ is high while $\mathbb{P}(T(x_1, \dots, x_T) > \lambda | H_0)$ is low.



STATISTICS OF DECISION UNDER GAUSSIAN ASSUMPTION

STATISTICS OF DECISION UNDER GAUSSIAN ASSUMPTION (1/2)

Suppose $\forall t, \forall k, \mathbf{x}_k^t \sim \mathcal{C}(\mathbf{0}_p, \boldsymbol{\Sigma}_t)$ so that $p_{\mathbf{x}_k^t; \boldsymbol{\Sigma}_t}(\mathbf{x}_k^t; \boldsymbol{\Sigma}_t) = \frac{1}{\pi^p |\boldsymbol{\Sigma}_t|} \text{exp} \text{tr} \{ \mathbf{S}_k^t \boldsymbol{\Sigma}_t^{-1} \}$, where $\mathbf{S}_k^t = \mathbf{x}_k^t \mathbf{x}_k^t \mathbf{H}$.

Many statistic exists but the options can be reduced to¹ :

- The Generalized Likelihood Ratio Test (GLRT) statistic:

$$\hat{\Lambda}_G = \frac{\left| \hat{\boldsymbol{\Sigma}}_0^{\text{SC}} \right|^T}{\left| \sum_{t=1}^T \hat{\boldsymbol{\Sigma}}_t^{\text{SC}} \right|^T} \begin{matrix} H_1 \\ H_0 \end{matrix} \lambda, \text{ where :}$$

$$\forall t, \hat{\boldsymbol{\Sigma}}_t^{\text{SC}} = \frac{1}{k} \sum_{k=1}^T \mathbf{S}_k^t \text{ and } \hat{\boldsymbol{\Sigma}}_0^{\text{SC}} = \frac{1}{T} \sum_{t=1}^T \hat{\boldsymbol{\Sigma}}_t^{\text{SC}}.$$

¹ D. Ciuonzo, V. Carotenuto and A. De Maio, "On Multiple Covariance Equality Testing with Application

STATISTICS OF DECISION UNDER GAUSSIAN ASSUMPTION (2/2)

- The t_1 statistic obtained from either Terell or Rao tests:

$$\hat{\Lambda}_{t_1} = \sum_{t=1}^T \text{Tr}(\hat{\Sigma}_t^{\text{SC}} (\hat{\Sigma}_0^{\text{SC}})^{-1}) - \mathbf{I}_p \begin{matrix} & 2 \\ & \text{H}_1 \\ \text{H}_0 & \end{matrix} \lambda.$$

- The Wald statistic:

$$\begin{aligned} \hat{\Lambda}_{\text{ald}} = & \sum_{t=2}^T \text{Tr}(\mathbf{I}_p - \hat{\Sigma}_1^{\text{SC}} (\hat{\Sigma}_t^{\text{SC}})^{-1})^2 \\ & - q \sum_{t=1}^T (\hat{\Sigma}_t^{\text{SC}})^{-T} \otimes (\hat{\Sigma}_t^{\text{SC}})^{-1}, \text{vec} \sum_{t=2}^T \begin{matrix} & 2 \\ & \text{H}_1 \\ \text{H}_0 & \end{matrix} \lambda, \end{aligned}$$

SOME PROPERTIES OF THE STATISTICS

CFARness:

The GLRT, t_1 and Wald statistic have the CFAR property with regards to the covariance parameter.

Proof: The statistics are invariant for the group of transformation $\mathcal{G} = \{ |\mathbf{x}_k^t|, \in \mathbb{S}_p^{\mathbb{H}} \}$.

Distribution under H_0 (F-Approximation¹):

Under null hypothesis, we have: $2(1 - c) \ln(\hat{\Lambda}_B) \sim \chi^2((T - 1)p(p + 1))$ where

$$c = \frac{T^2 - 1}{T(T - 1)} \times \frac{2p^2 + 3p - 1}{6(T - 1)(p + 1)}$$
 and $\hat{\Lambda}_B$ is a modified version of $\hat{\Lambda}_G$

There are similar results for others statistics.

¹ Box, G. E. P. "A General Distribution Theory for a Class of Likelihood Criteria." Biometrika, vol. 36, no. 3/4, 1949, pp. 317–346.

FALSE ALARM/THRESHOLD RELATIONSHIP

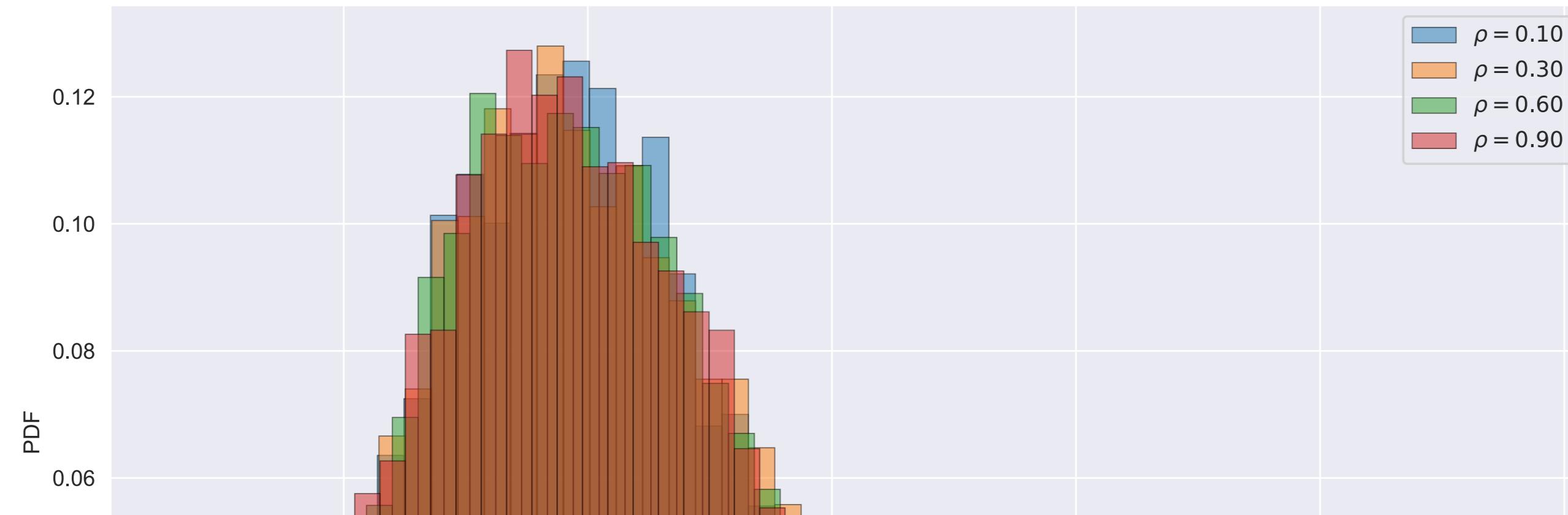
Under H_0 we have ¹:

$$\begin{aligned} P \quad 2\rho \log(\hat{\Lambda}_G) \leq z &\approx P\{\chi^2(f^2) \leq z\} + \omega_2 [P\{\chi^2(f^2 + 4) \leq z\} - P\{\chi^2(f^2) \leq z\}] \\ f = (T-1)p^2, \rho = 1 - \frac{(2p^2-1)}{6(T-1)p} &\quad \frac{T}{2} - \frac{1}{T}, \\ \omega_2 = \frac{p^2(p^2-1)}{24\rho^2} &\quad \frac{T}{2} - \frac{1}{(T)^2} - \frac{p^2(T-1)}{4} \quad \left(1 - \frac{1}{\rho}\right)^2 \end{aligned}$$

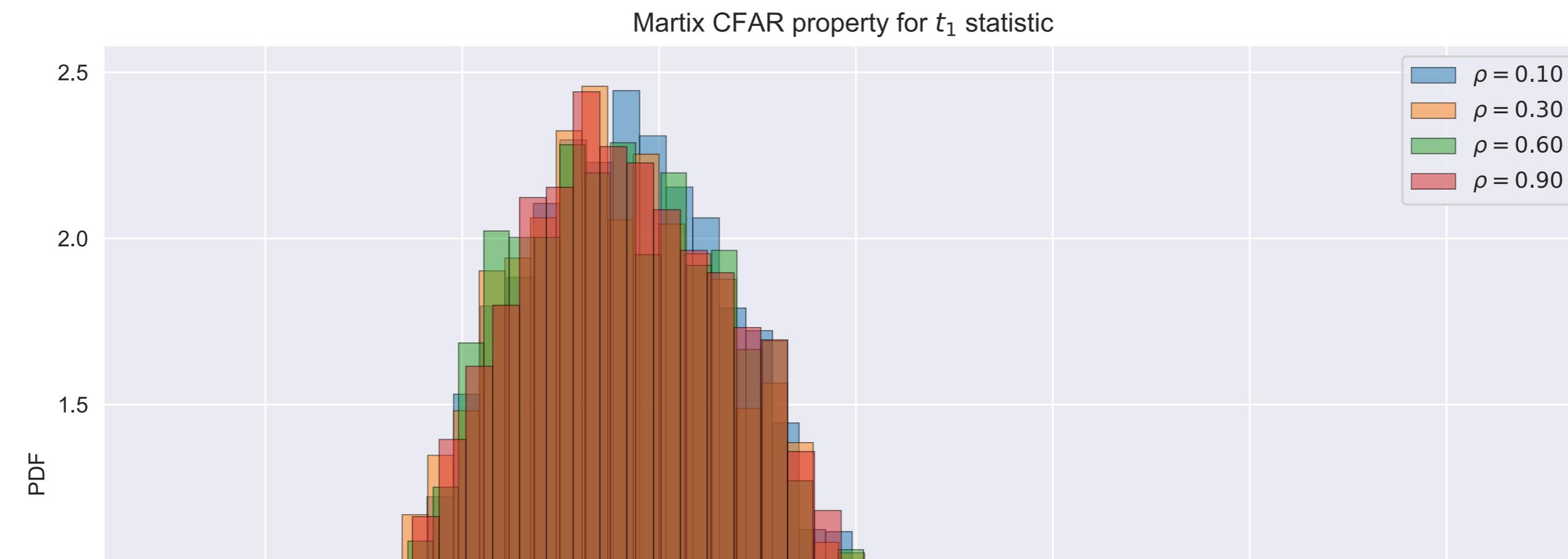
¹ Anderson, T. W. (1962). An introduction to multivariate statistical analysis (No. 519.9 A53). New York: Wiley.

EXPERIMENTAL VALIDATION OF MATRIX CFAR PROPERTY (1/2)

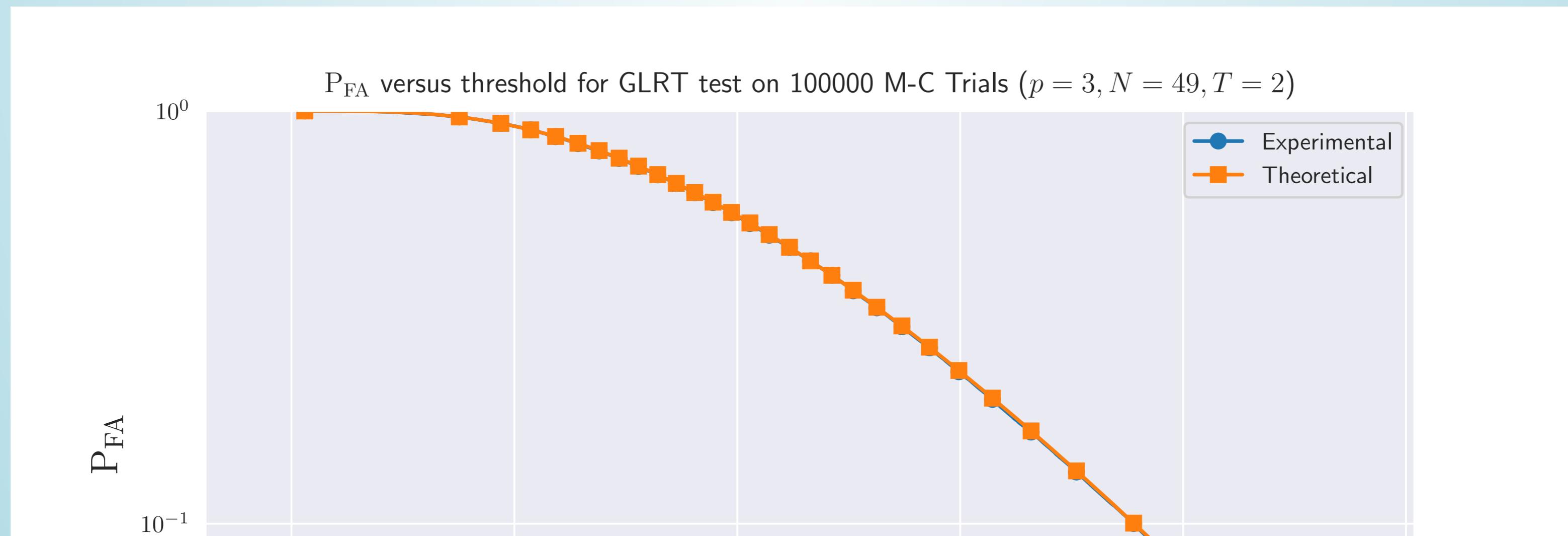
Martix CFAR property for Gaussian GLRT statistic



EXPERIMENTAL VALIDATION OF MATRIX CFAR PROPERTY (2/2)



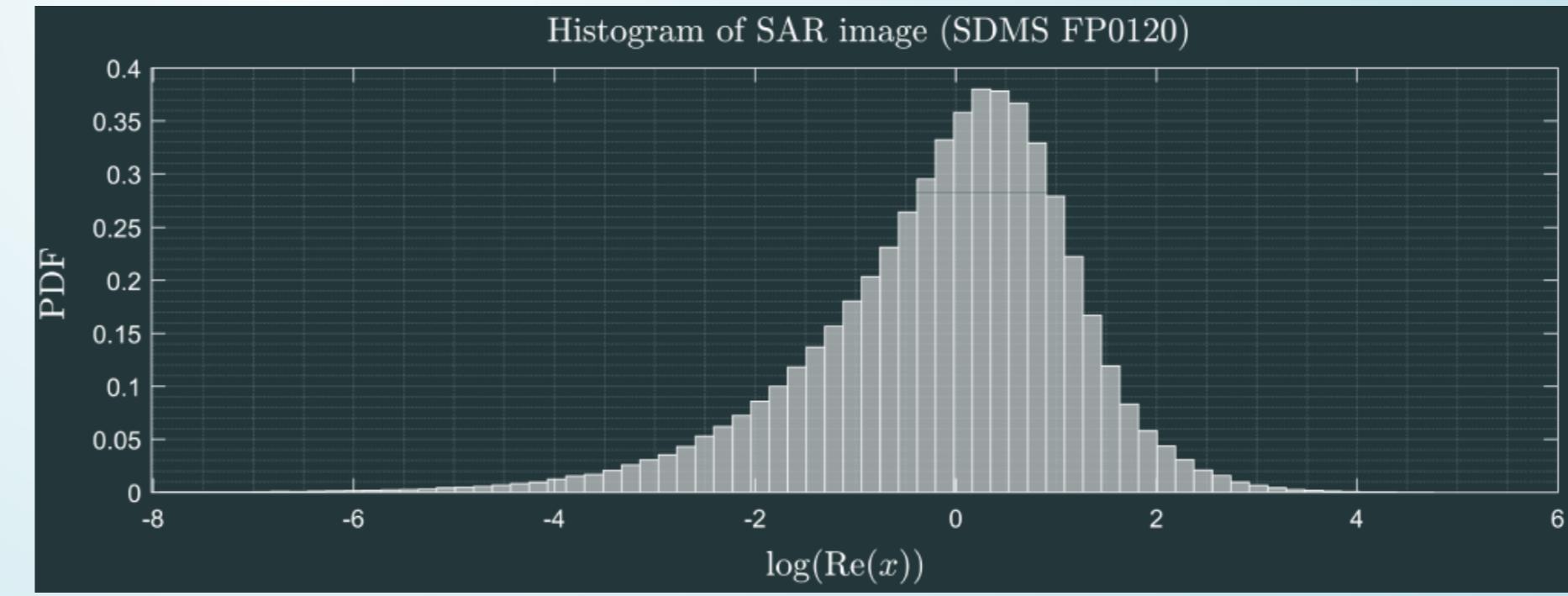
EXPERIMENTAL VALIDATION OF DISTRIBUTINO UNDER H_0



EXTENSION TO ELLIPTICAL DISTRIBUTIONS

NON-GAUSSIANITY HIGH-RESOLUTION IMAGES

Sometimes the Gaussian hypothesis is not accurate !



To model this kind of distribution the family of elliptical distributions have been introduced¹

CES DISTRIBUTIONS

Probability distribution:

$$p_{\mathbf{x};g;\Sigma}(\mathbf{x}; g; \Sigma) = \mathfrak{C}_{p,g} |\Sigma|^{-1} g(\mathbf{x}^H \Sigma^{-1} \mathbf{x})$$

where g is a density generator function with some regularity conditions, $\Sigma \in \mathbb{S}_p^{\mathbb{H}}$ is the scatter matrix and $\mathfrak{C}_{p,g}$ is a normalisation constant.

Example:

Multivariate Student-t:
$$\frac{\Gamma \frac{\nu+g}{2} |\Sigma|^{-1/2}}{(\pi\nu)^{\frac{1}{2}} \Gamma \frac{\nu}{2} 1 + \frac{\delta(\mathbf{y}, \mu, \Sigma)}{\nu}^{\frac{1}{2}(\nu+g)}}$$

Problem: How do we test the equality of scatter matrix in this model ? In particular, can we test scale and shape separately ?

APPROACH 1: BOOTSTRAPPING THE GAUSSIAN GLRT

Since the distribution of Gaussian-derived detector is known¹ under CES model it is possible to correct it in order to obtain one keeping the CFAR property in CES context.

Hallin proposed to use the following test²:

$$= 2 \sum_{\substack{;t,t' \\ 1 \leq t \leq t' \leq T}} \chi^2 \geq \frac{(T-1)p(p+1)}{2} \quad , \text{ where: } 1 - P_{FA}$$

$$\begin{aligned} ;t,t' &= \frac{1}{4(1 + \hat{\kappa}_p)} \operatorname{Tr} \left[(\hat{\Sigma}_0^{\text{SC}})^{-1} (\hat{\Sigma}_t^{\text{SC}} - \hat{\Sigma}_{t'}^{\text{SC}})^2 \right] - \\ &\quad \frac{\hat{\kappa}_p}{(p+2)\hat{\kappa}_p + 2} \operatorname{Tr}^2 \left[(\hat{\Sigma}_0^{\text{SC}})^{-1} (\hat{\Sigma}_t^{\text{SC}} - \hat{\Sigma}_{t'}^{\text{SC}}) \right] , \end{aligned}$$

and $\hat{\kappa}_p = p(p+1)/2$ $\sum_{t=1}^T \sum_{k=1}^{d^4(\mathbf{x}_k^t, \hat{\Sigma}_0^{\text{SC}})} - 1$ and $d(\mathbf{x}, \Sigma) = \|\Sigma^{-1/2}\mathbf{x}\|$

¹ Yanagihara, H., Tonda, T., and Matsumoto, C. (2005). The effects of nonnormality on asymptotic distributions of some likelihood ratio criteria for testing covariance structures under normal assumption. *Journal of Multivariate Analysis*, 96(2):237{264.

² Marc Hallin, Davy Paindaveine, Optimal tests for homogeneity of covariance, scale, and shape,

APPROACH 2: GLRT UNDER CES MODEL

We compute the following statistic:

$$\hat{\Lambda} = \frac{\max_{\Sigma_1, \dots, \Sigma_T} p_{(1, \dots, T; \Sigma_1, \dots, \Sigma_T)}(\cdot_1, \dots, \cdot_T; \Sigma_1, \dots, \Sigma_T / H_1)}{\max_{\Sigma_0} p_{(1, \dots, T; \Sigma_0)}(\cdot_1, \dots, \cdot_T; \Sigma_0 / H_0)}$$

which yields:

$$\hat{\Lambda}^g = \frac{|\hat{\Sigma}_0|^T}{\prod_{t=1}^T |\hat{\Sigma}_t|} \frac{\sum_{k=1}^T g(\mathbf{x}_k^{t^H} \{\hat{\Sigma}_0\}^{-1} \mathbf{x}_k^t)_{H_1}}{\sum_{t=1}^T \sum_{k=1}^T g(\mathbf{x}_k^{t^H} \{\hat{\Sigma}_t\}^{-1} \mathbf{x}_k^t)_{H_0}} \lambda,$$

$$\text{where: } \hat{\Sigma}_t = f_t(\hat{\Sigma}_t), \hat{\Sigma}_0 = \frac{1}{T} \sum_{t=1}^T f_t(\hat{\Sigma}_0) \text{ and } f_t(\Sigma) = \frac{1}{k=1} \frac{-g'(\mathbf{x}_k^{t^H} \{\hat{\Sigma}\}^{-1} \mathbf{x}_k^t)}{g(\mathbf{x}_k^{t^H} \{\hat{\Sigma}\}^{-1} \mathbf{x}_k^t)} \mathbf{x}_k^t \mathbf{x}_k^{t^H}$$

Problem: We need to know g !!!

APPROACH 2BIS: SELECT $g = \frac{1}{x^p}$

The statistic reads:

$$\hat{\Lambda}^{1/x^p} = \frac{|\hat{\Sigma}_0|^T}{\prod_{t=1}^T |\hat{\Sigma}_t|} \frac{\sum_{k=1}^p \mathbf{x}_k^T \{\hat{\Sigma}_t\}^{-1} \mathbf{x}_k^T}{\sum_{k=1}^p \mathbf{x}_k^T \{\hat{\Sigma}_0\}^{-1} \mathbf{x}_k^T} \lambda,$$

Properties¹: - This statistic is valid for testing the **Shape matrix** for any elliptical distribution.

- The distribution of $2 \log(\hat{\Lambda}^g)$ under H_0 is asymptotically that of a $\chi^2((T-1)p(p+1))$

Problem: We can't test a change in the scale !

¹ A. Mian, J. Ovarlez, G. Ginolhac and A. M. Atto, "A Robust Change Detector for Highly Heterogeneous Multivariate Images," 2018 IEEE International Conference on Acoustics, Speech and Signal Processing (ICASSP), Calgary, AB, 2018, pp. 3429-3433.

APPROACH 3: COMPOUND-GAUSSIAN MODEL (1/2)

We consider the Compound-Gaussian model: $\mathbf{x}_k^t \sim \overline{\tau_k^t} \mathbb{C}(\mathbf{0}_p, \boldsymbol{\xi}_t)$, where τ_k^t are assumed to be **deterministic** and $Tr(\boldsymbol{\xi}) = p$. → We can integrate these unknown parameters in the GLRT¹:

$$\hat{\Lambda}_{\text{T}} = \frac{\left| \hat{\Sigma}_0^T \right|^T}{\prod_{t=1}^T \left| \hat{\Sigma}_t \right|} \frac{\sum_{t=1}^T \mathbf{x}_k^{t \text{H}} \{ \hat{\Sigma}_t^T \}^{-1} \mathbf{x}_k^t}{\sum_{t=1}^T \mathbf{x}_k^{t \text{H}} \{ \hat{\Sigma}_0 \}^{-1} \mathbf{x}_k^t} \stackrel{\text{Tp}}{\underset{\text{H}_0}{\underset{\text{H}_1}{\longrightarrow}}} \lambda, \text{ where :}$$

$$\hat{\Sigma}_t = \frac{p}{\sum_{k=1}^p \mathbf{x}_k^{t \text{H}} \{ \hat{\Sigma}_t \}^{-1} \mathbf{x}_k^t} \quad \text{and} \quad \hat{\Sigma}_0^T = \frac{p}{\sum_{t=1}^T \mathbf{x}_k^{t \text{H}} \{ \hat{\Sigma}_0^T \}^{-1} \mathbf{x}_k^t}$$

APPROACH 3: COMPOUND-GAUSSIAN MODEL (2/2)

We can also test the scale parameters only and ignoring a change in the shape matrix.
 → The GLRT¹ yields:

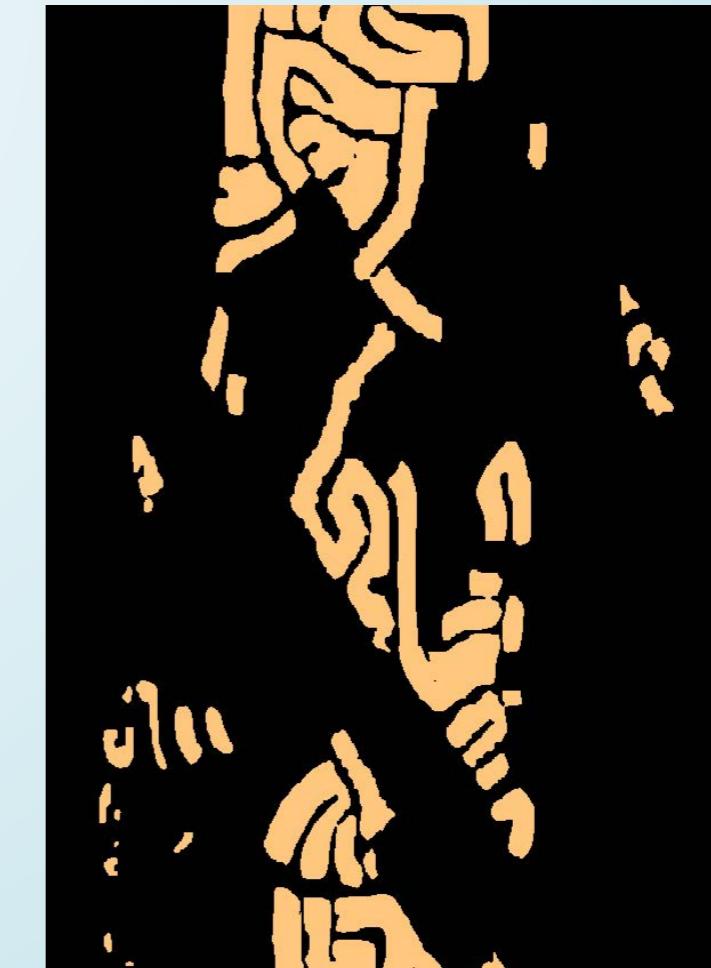
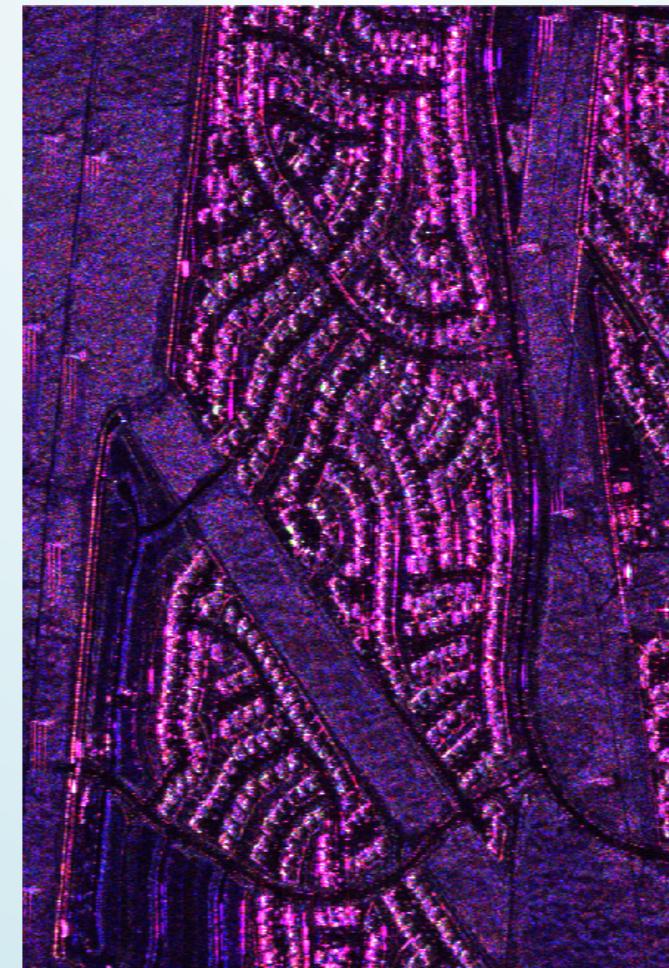
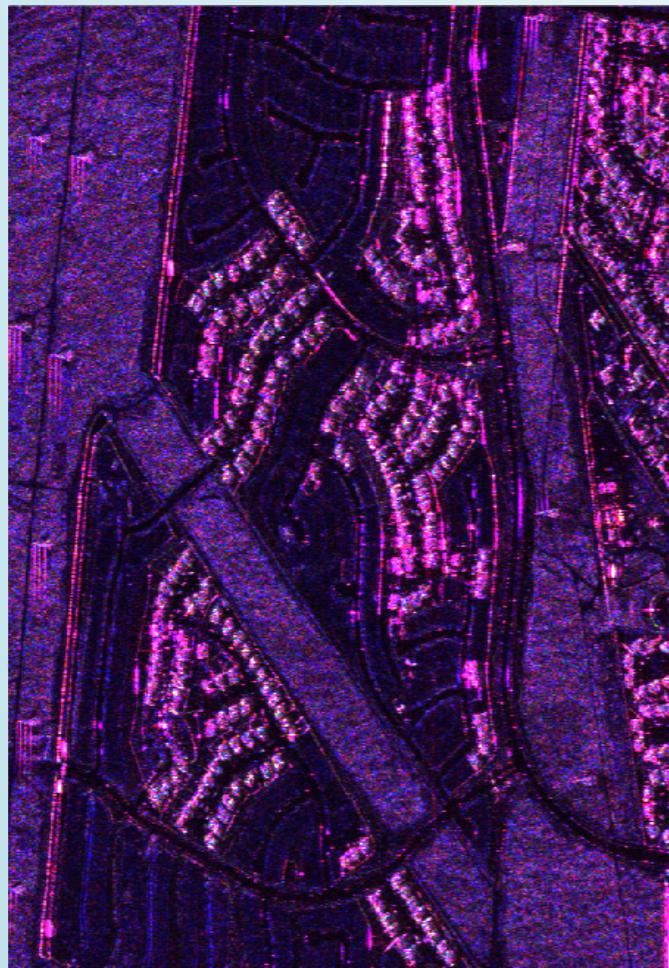
$$\hat{\Lambda}_{\text{Tex}} = \frac{\sum_{t=1}^T |\hat{\Sigma}_t^{\text{Tex}}|}{\sum_{t=1}^T |\hat{\Sigma}_t|} \frac{\sum_{k=1}^T \mathbf{x}_k^{t^H} \{ \hat{\Sigma}_t^{\text{Tex}} \}^{-1} \mathbf{x}_k^t}{\sum_{t=1}^T \mathbf{x}_k^{t^H} \{ \hat{\Sigma}_0 \}^{-1} \mathbf{x}_k^t} \stackrel{H_1}{\xrightarrow{p}} \lambda, \text{ where :}$$

$$\hat{\Sigma}_t = \frac{p}{\sum_{k=1}^T \mathbf{x}_k^{t^H} \{ \hat{\Sigma}_0 \}^{-1} \mathbf{x}_k^t} \quad \text{and} \quad \hat{\Sigma}_t^{\text{Tex}} = \frac{p}{\sum_{t=1}^T \mathbf{x}_k^{t^H} \{ \hat{\Sigma}_t^{\text{Tex}} \}^{-1} \mathbf{x}_k^t}$$

RESULTS ON SAR IMAGES

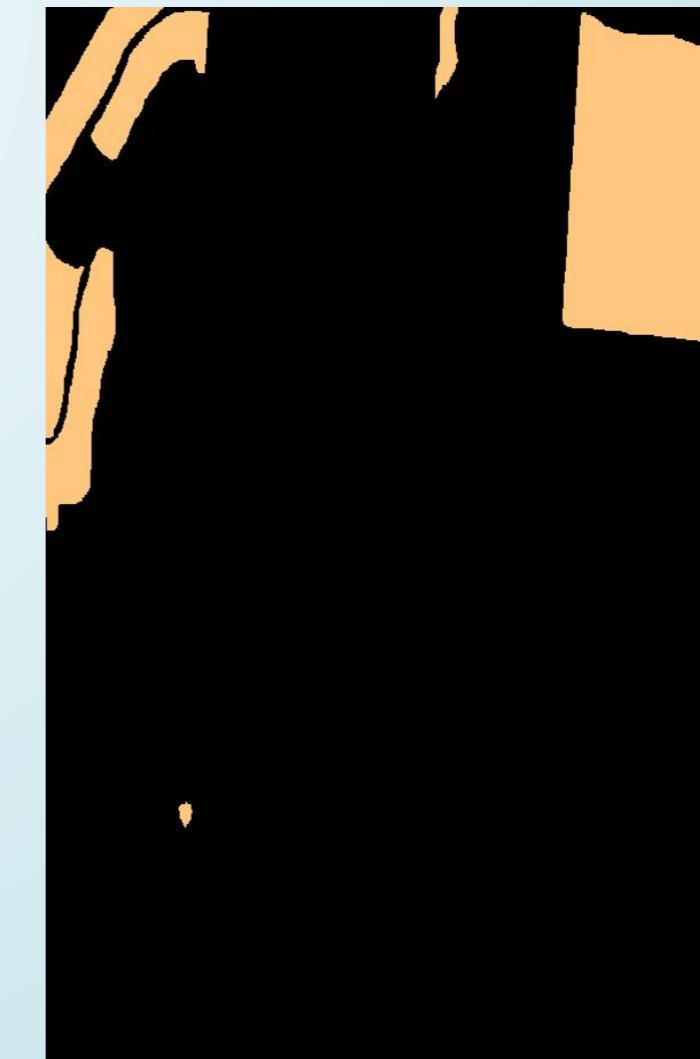
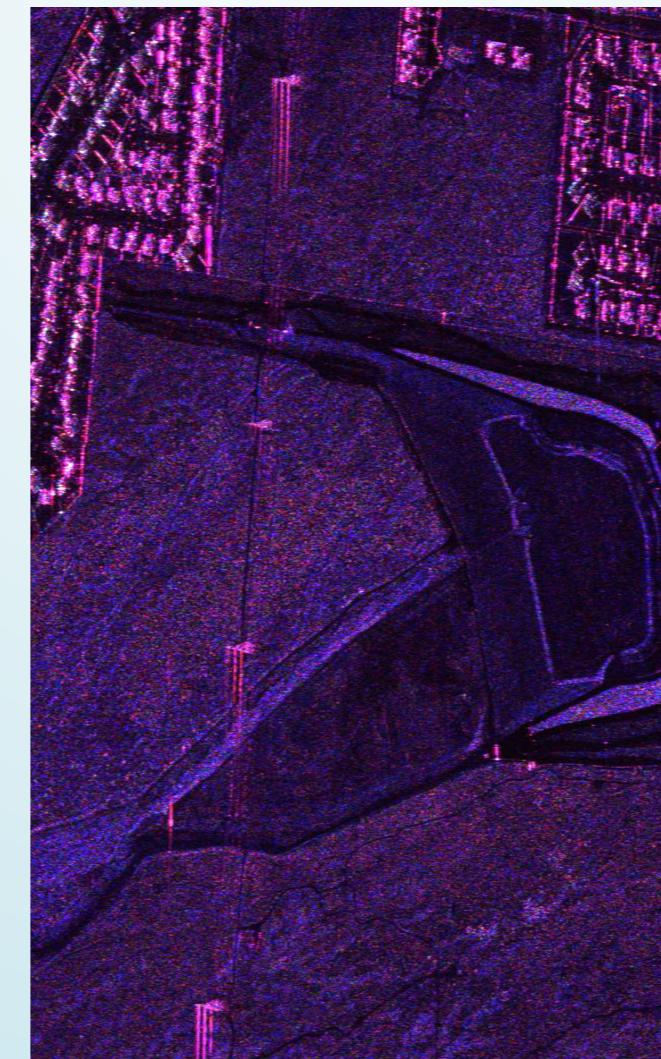
THE UAVSAR DATASET

- Polarimetric data ($p = 3$)
- Dimensions: 2360px by 600 px
- Resolution: 1m67 (Range) and 1m (Azimuth)

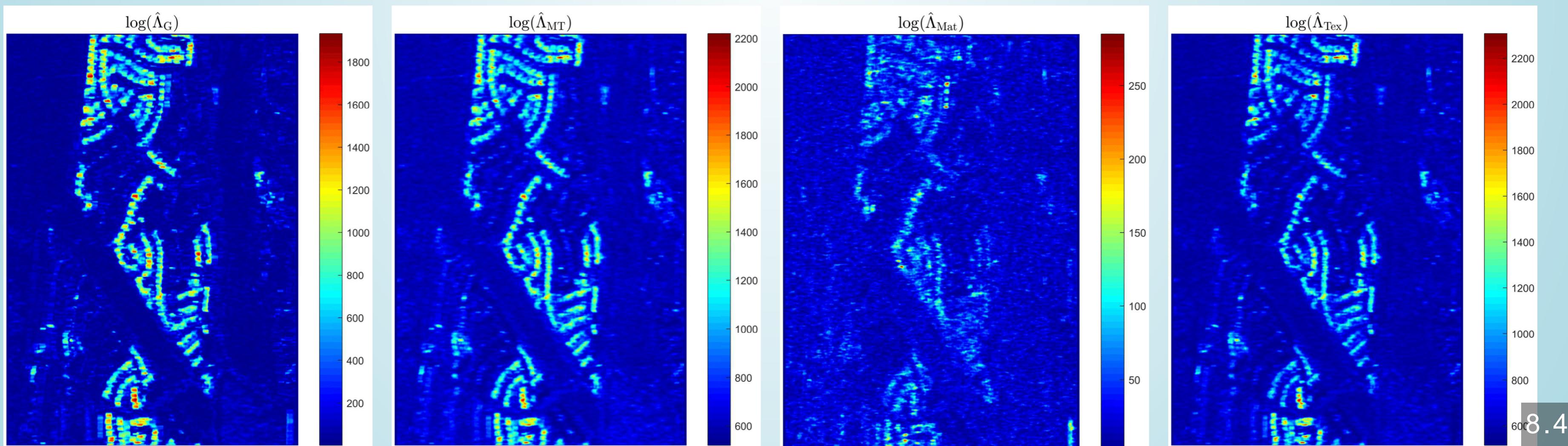


THE UAVSAR DATASET (2/2)

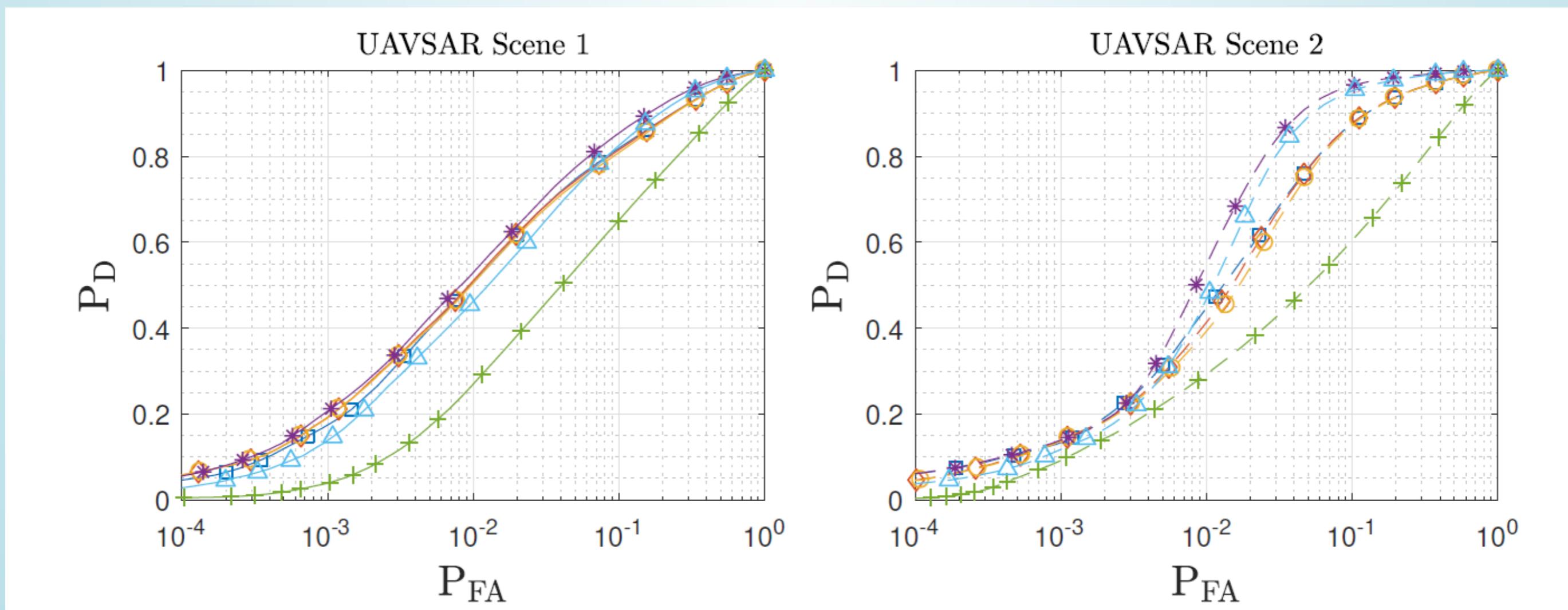
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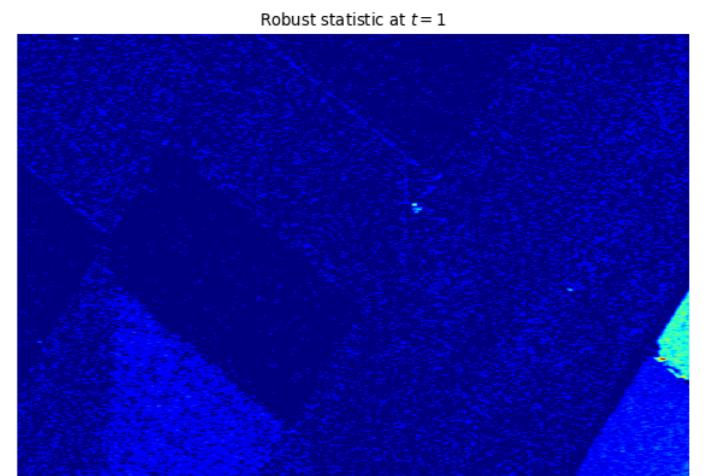
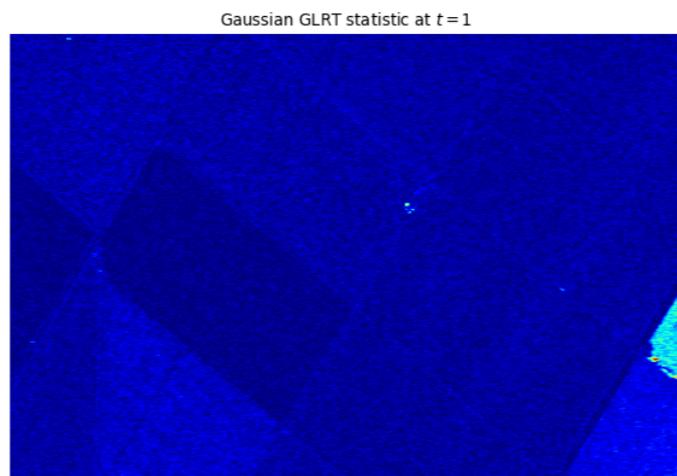
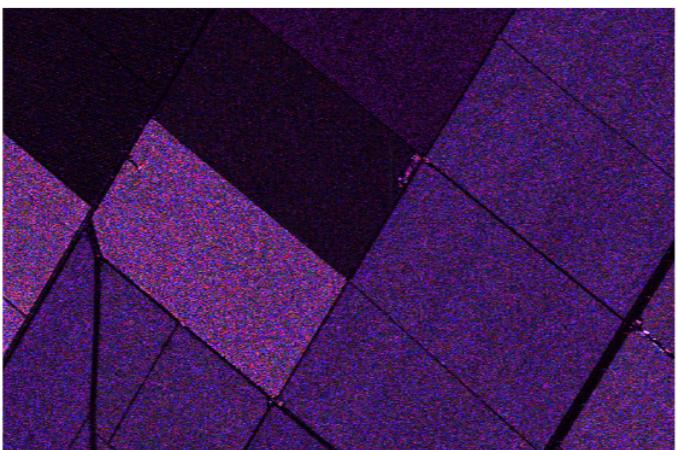
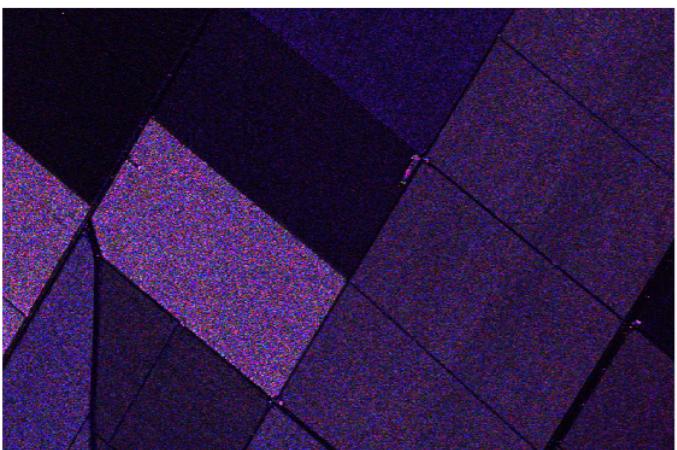
RESULTS (1/2)



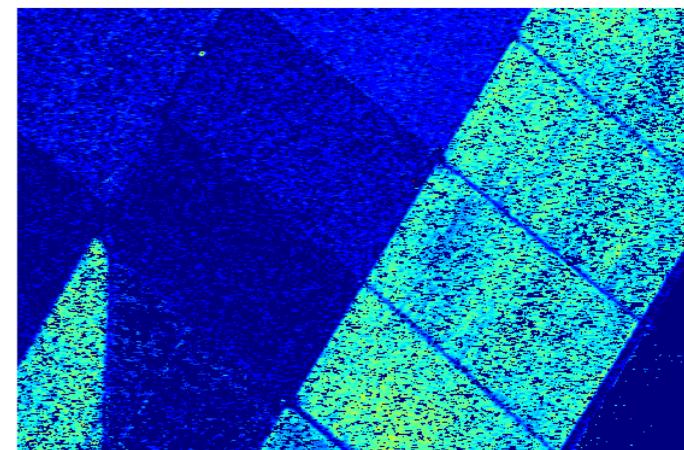
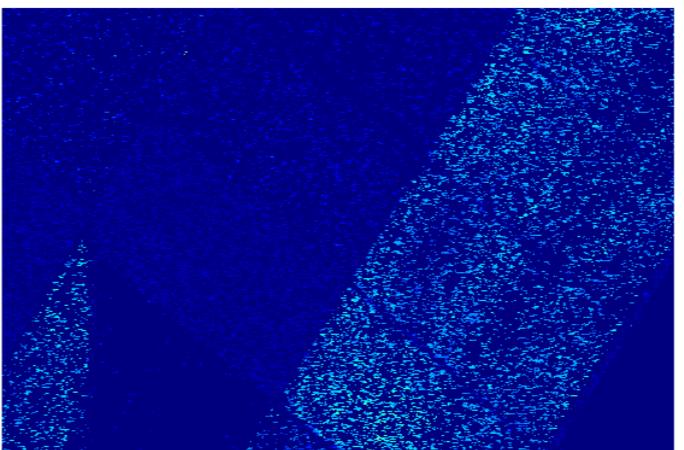
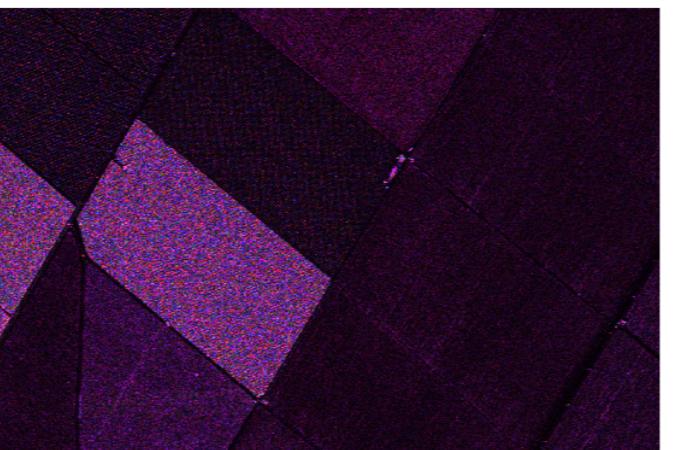
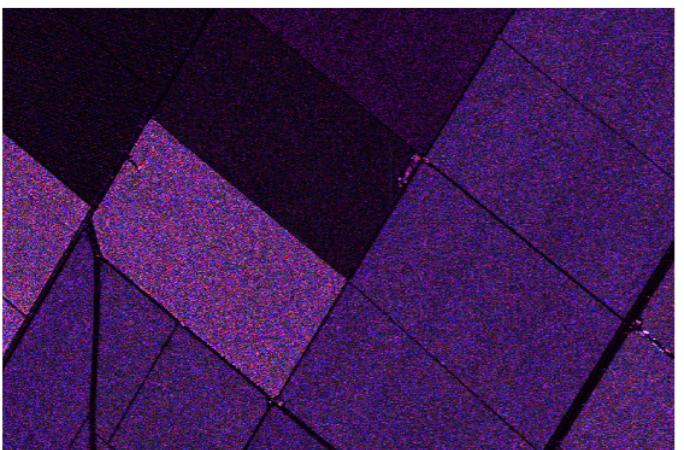
RESULTS (2/2)



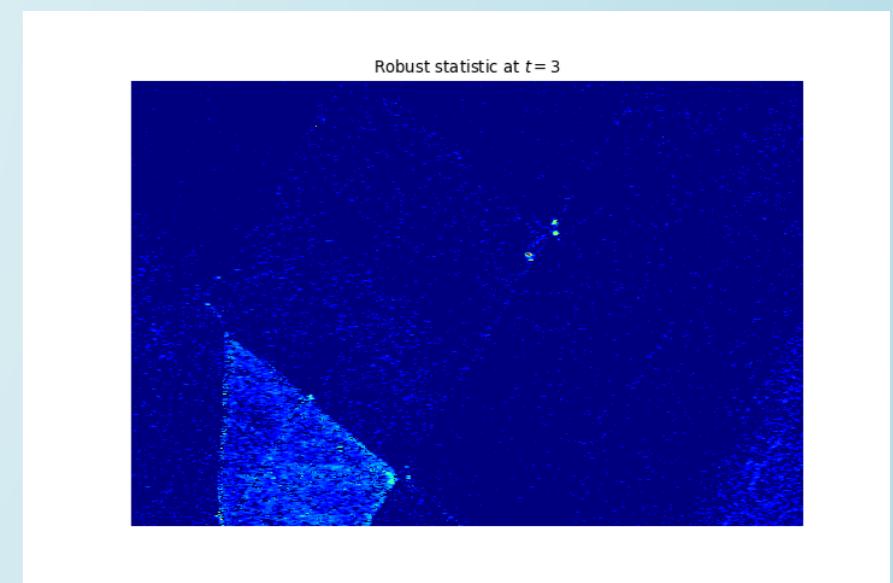
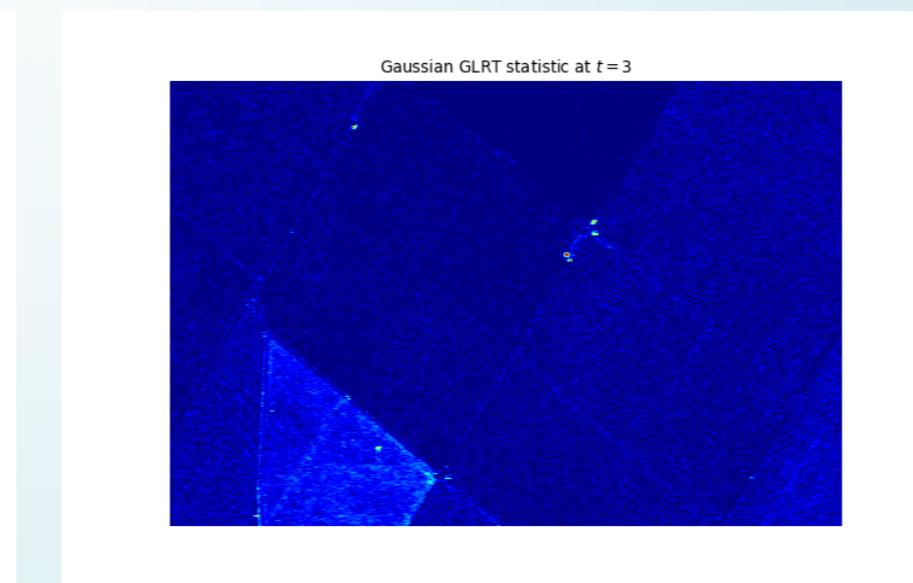
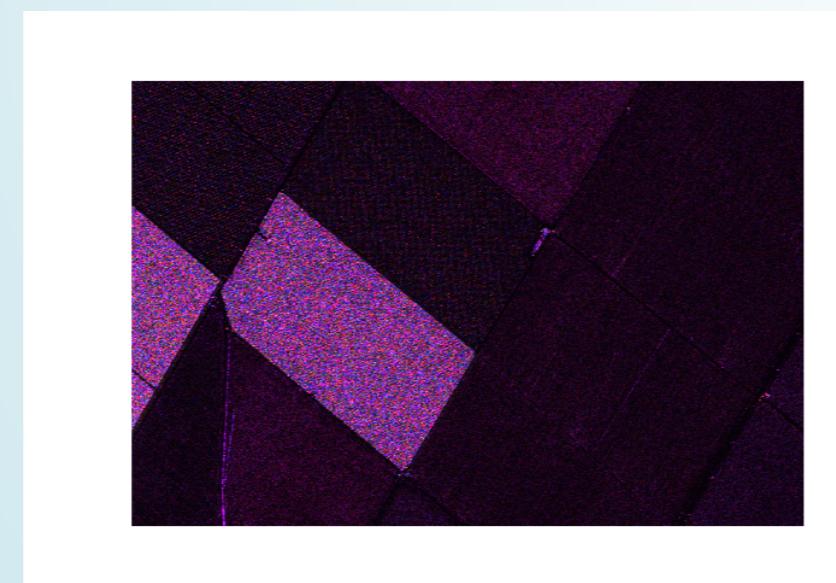
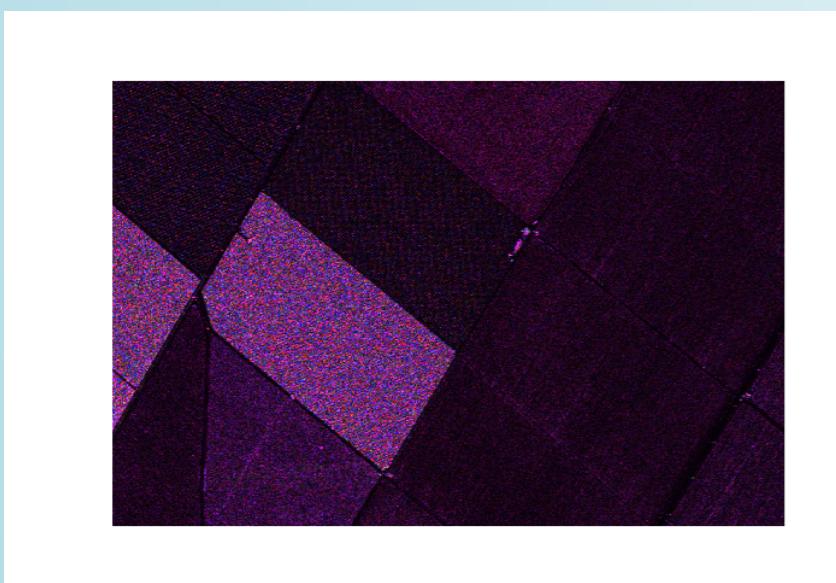
RESULT ON ANOTHER DATASET



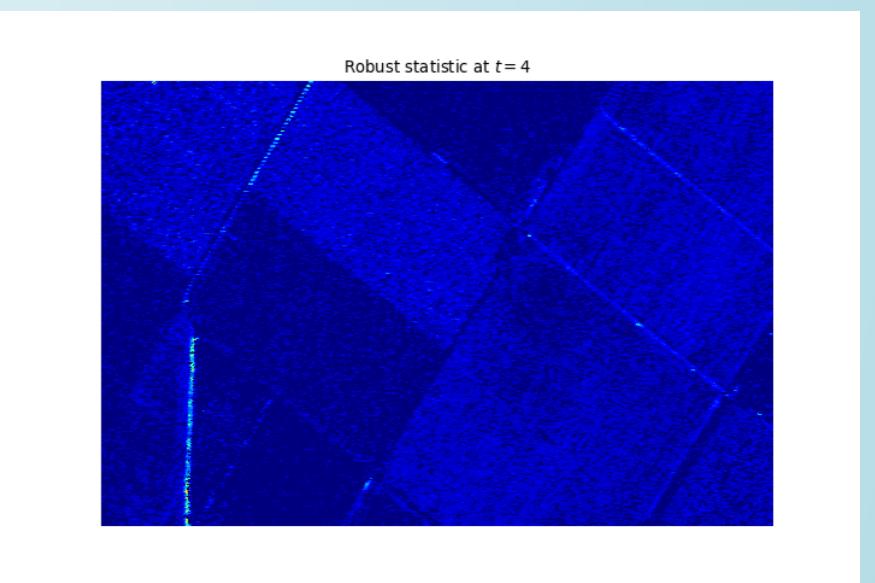
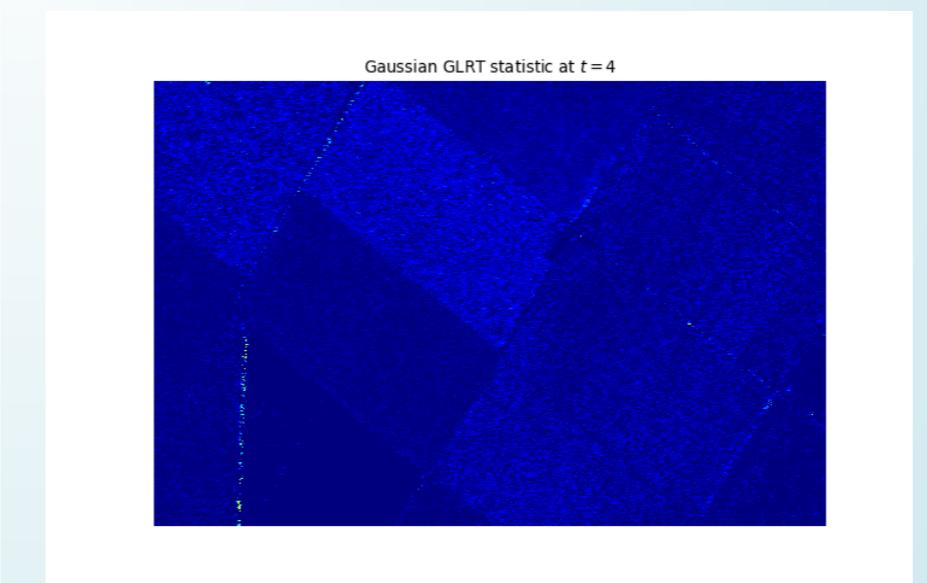
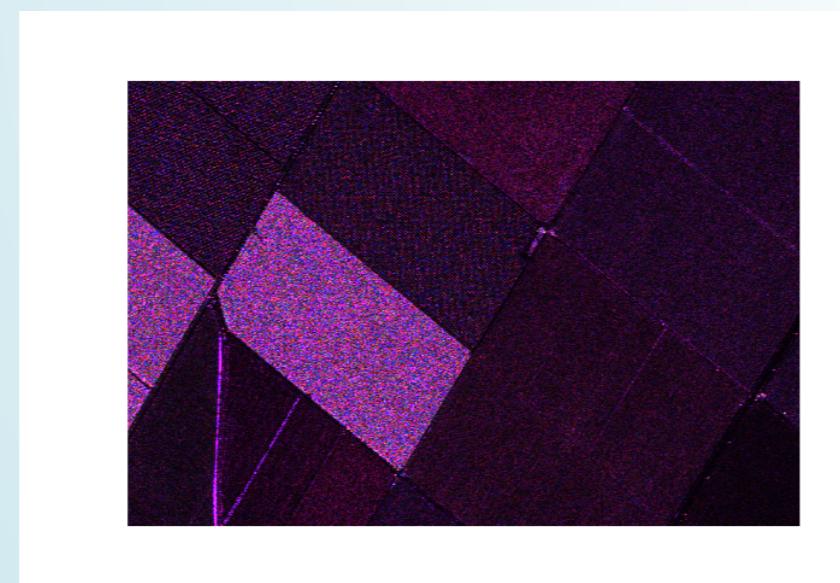
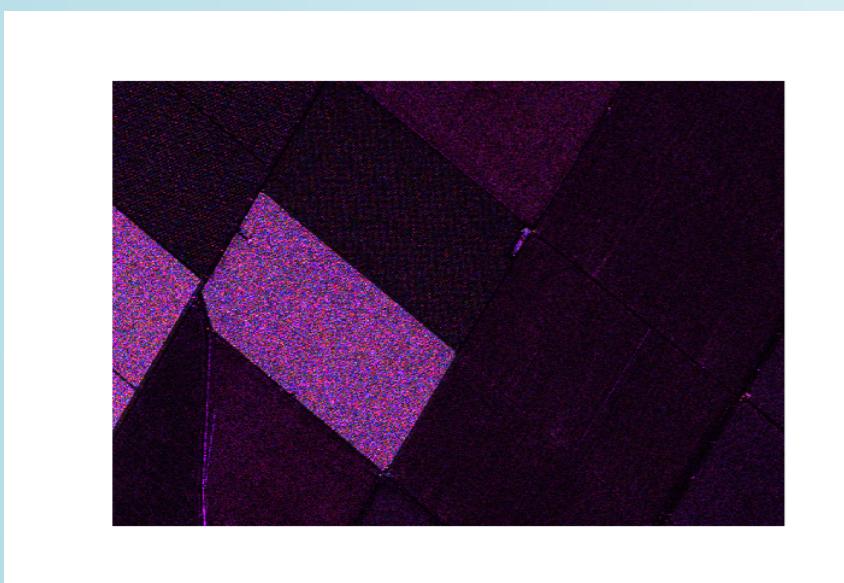
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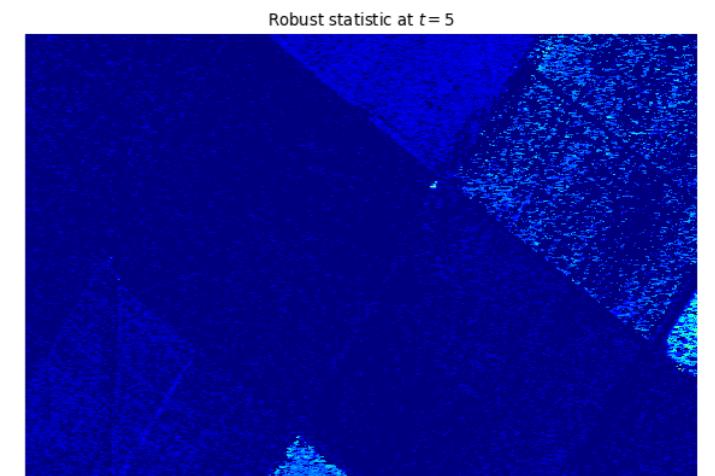
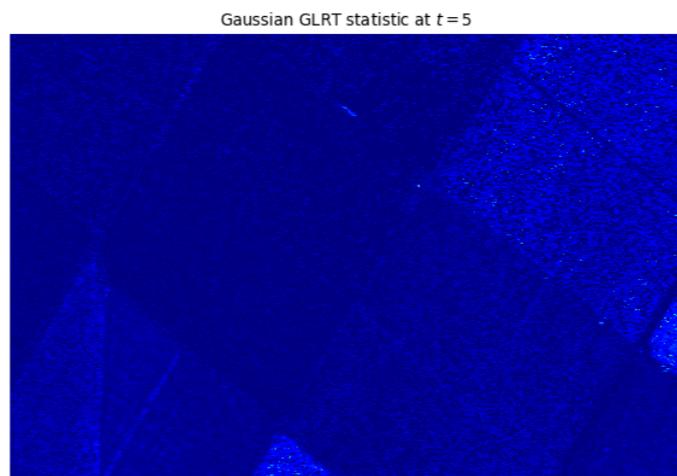
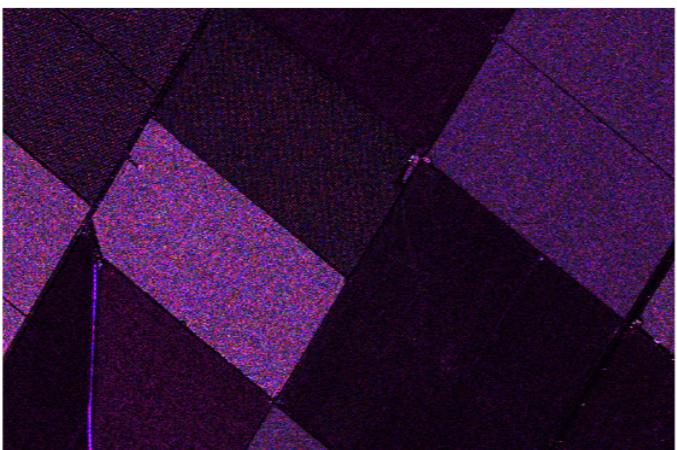
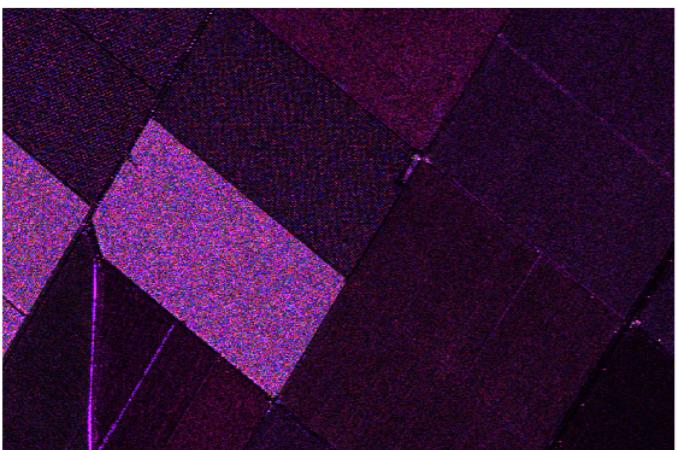
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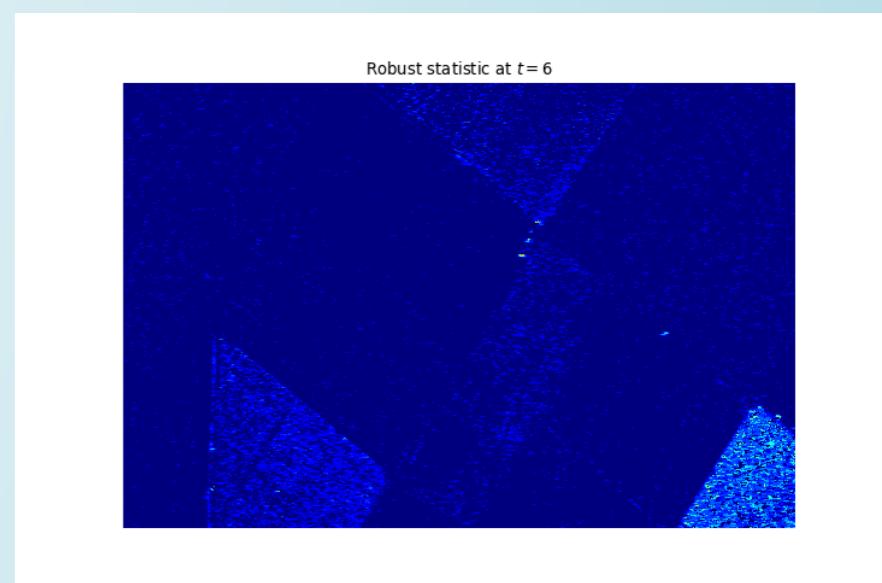
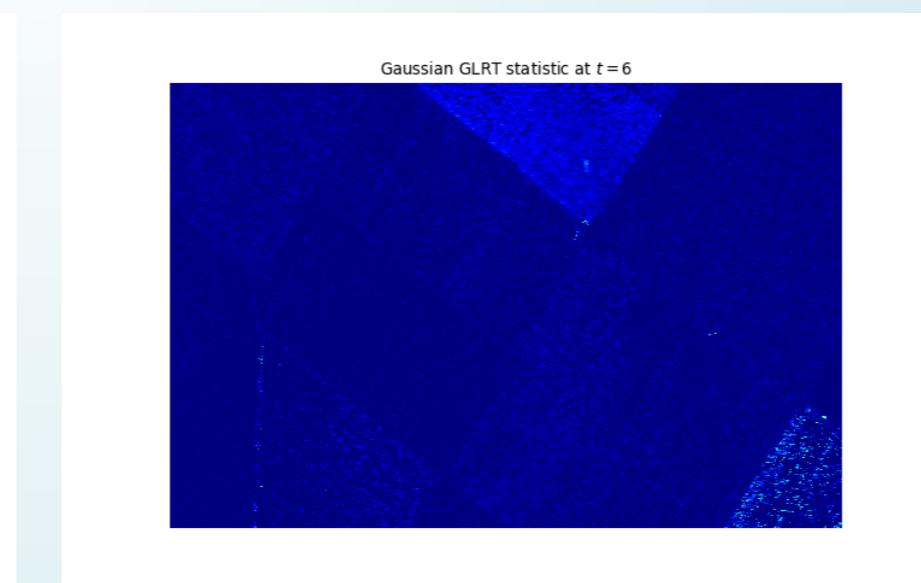
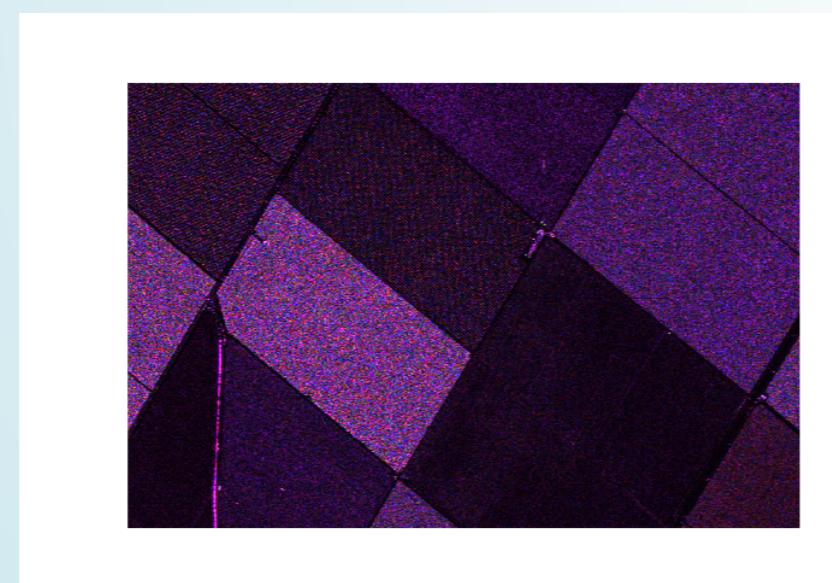
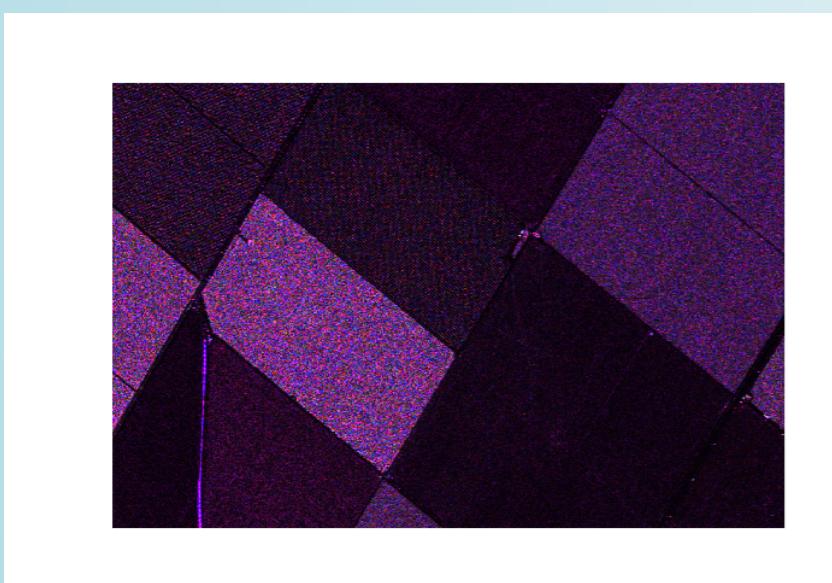
RESULT ON ANOTHER DATASET



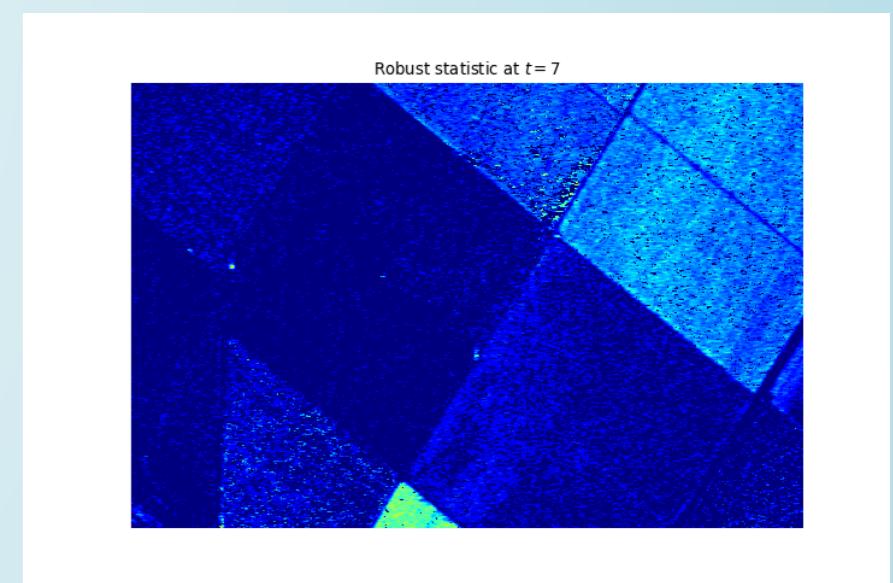
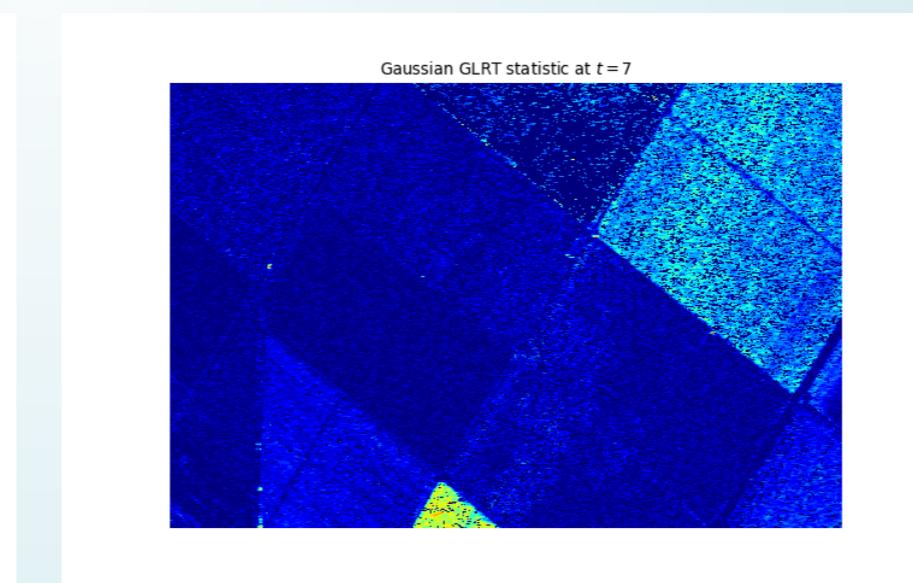
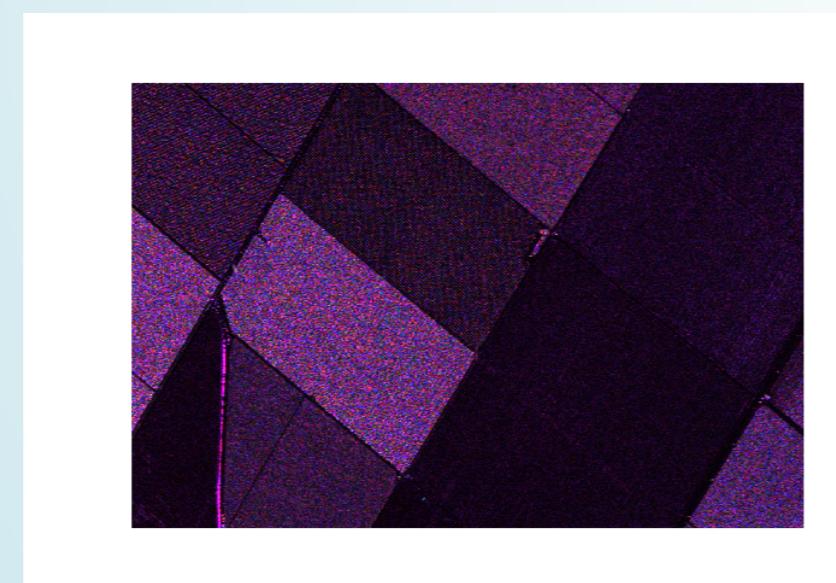
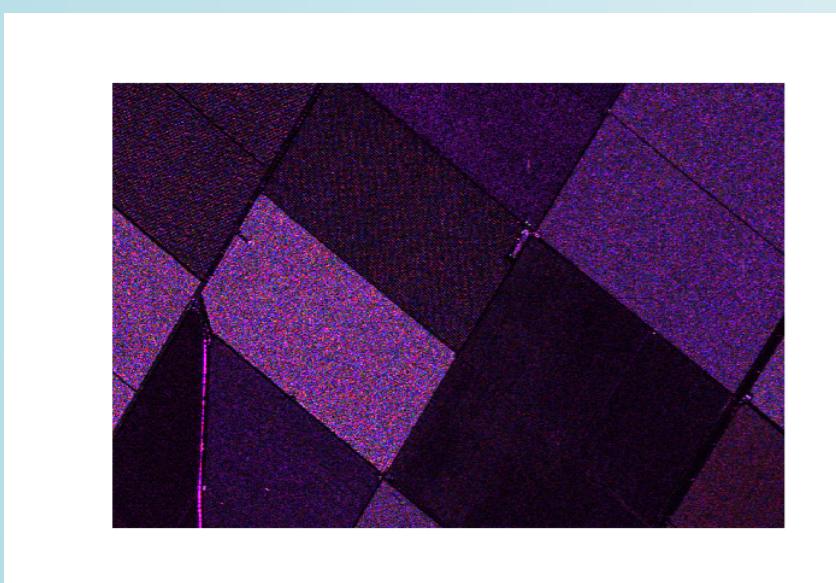
RESULT ON ANOTHER DATASET



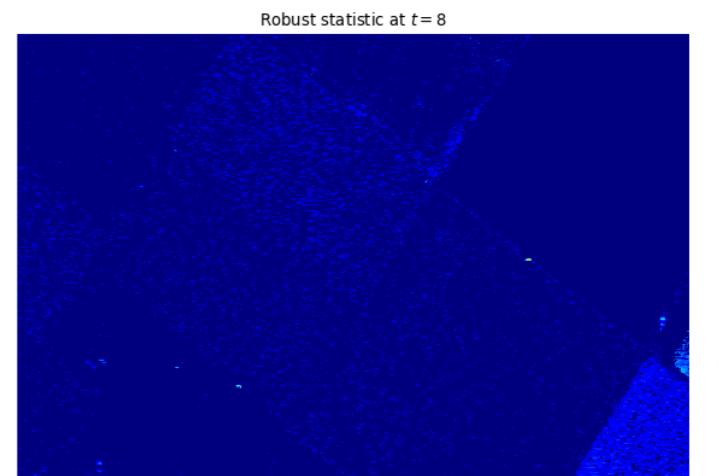
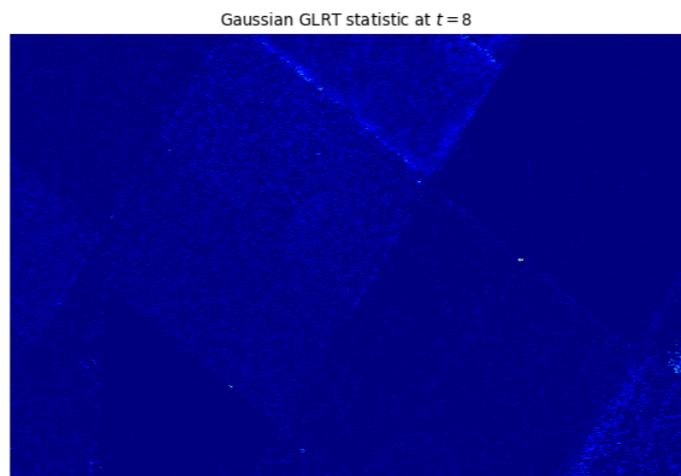
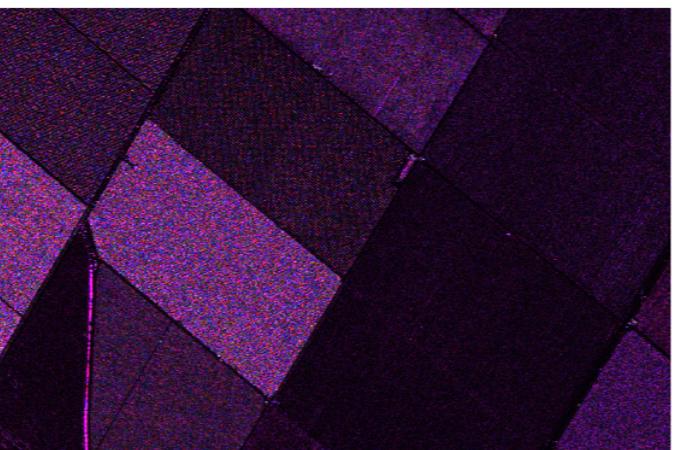
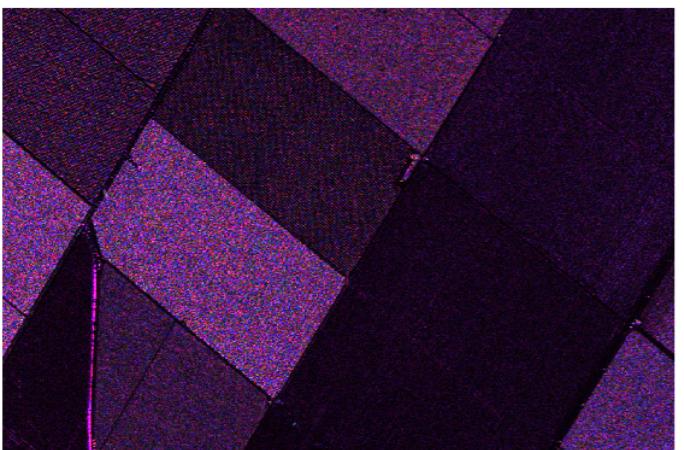
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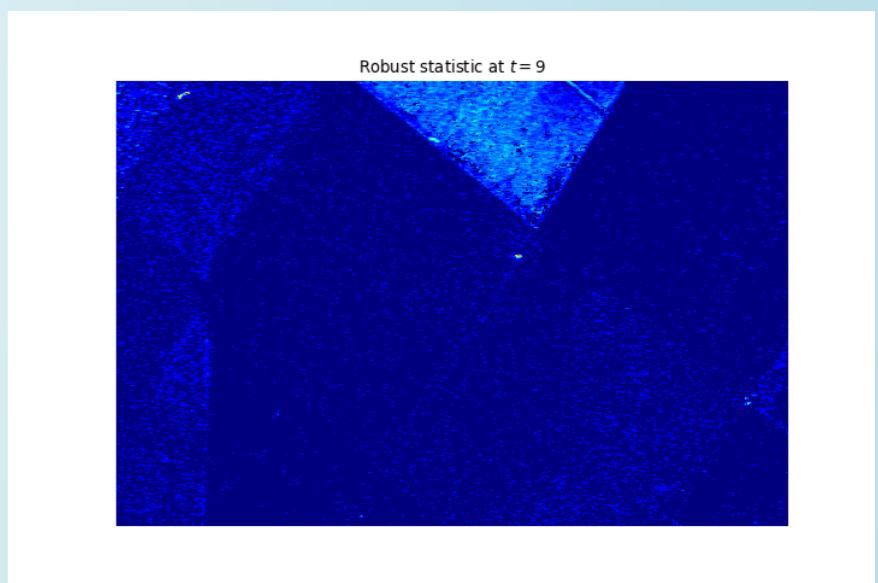
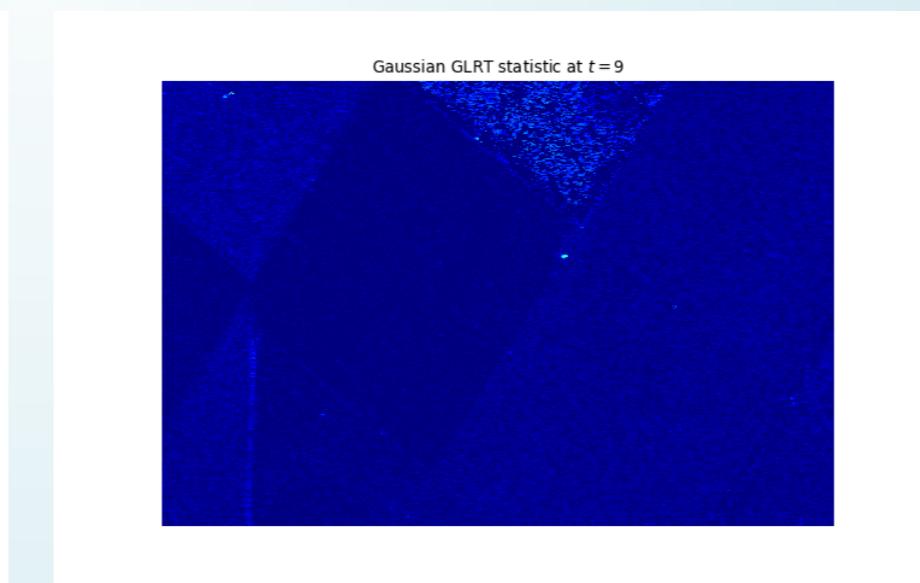
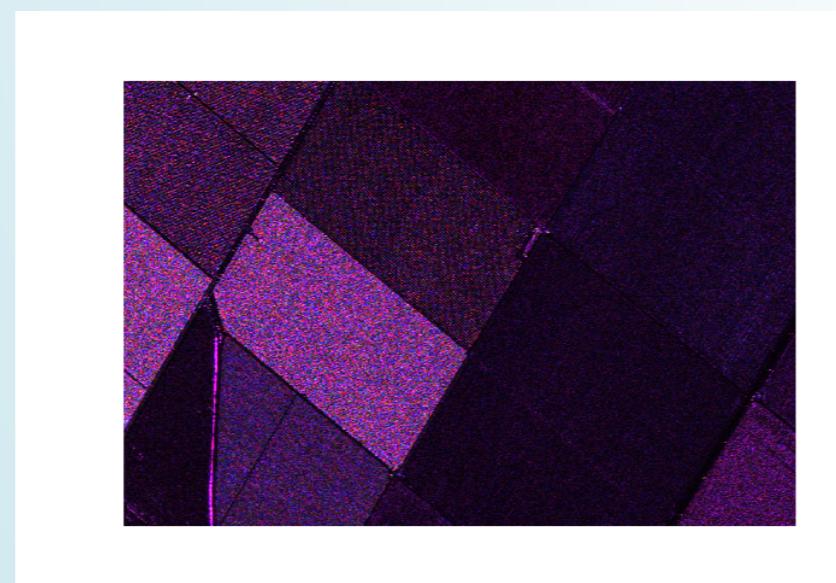
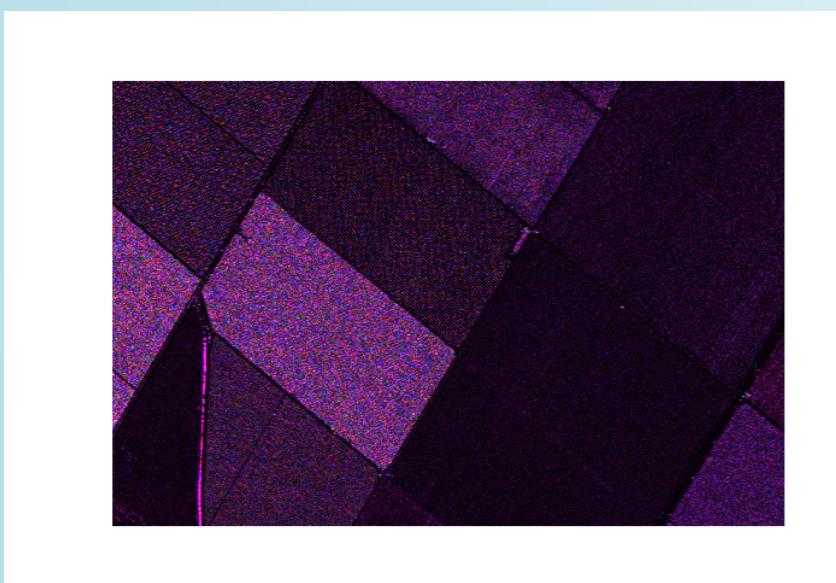
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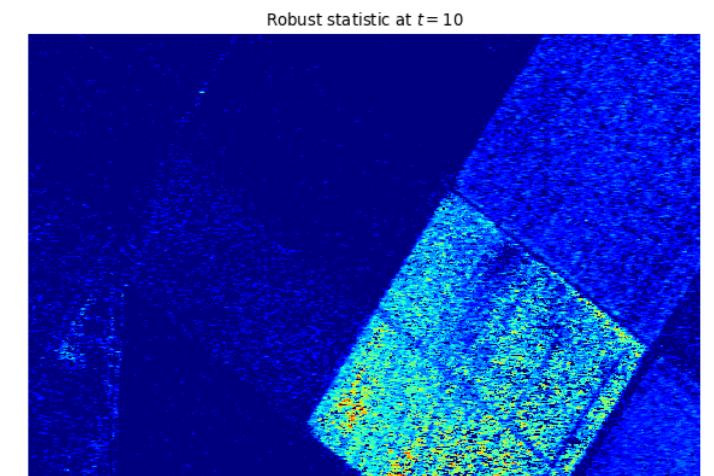
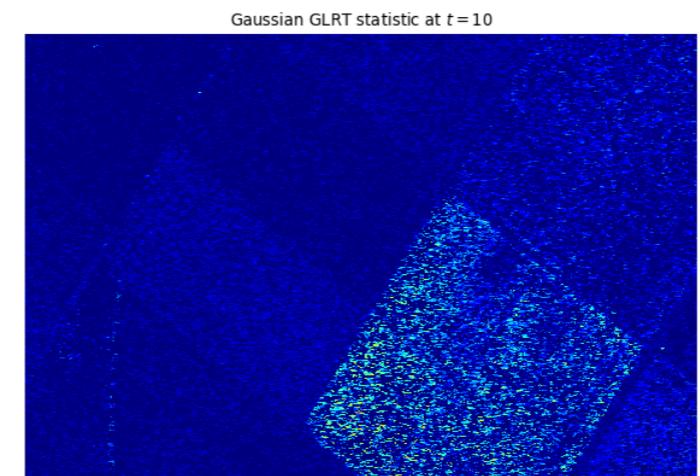
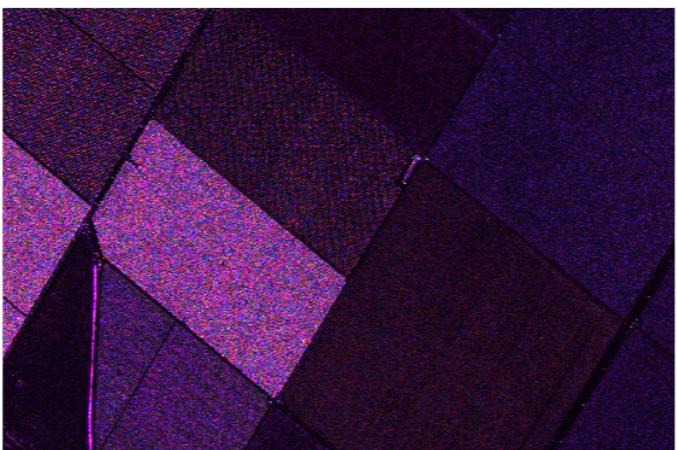
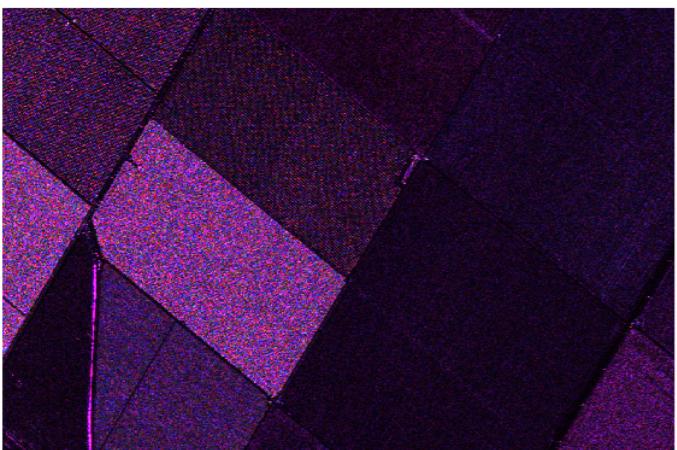
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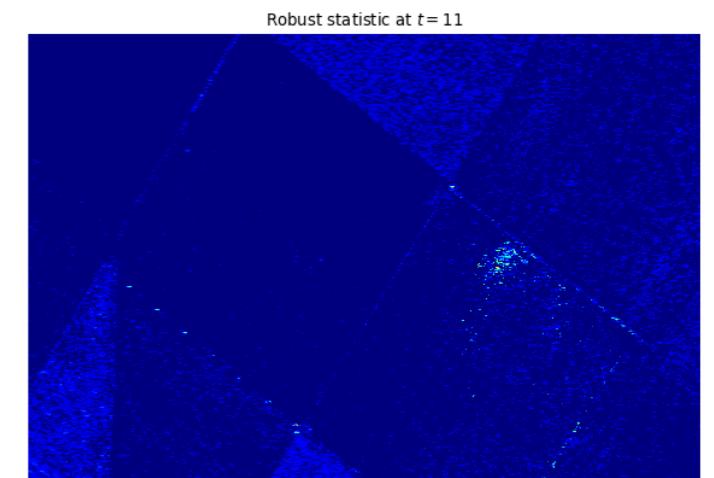
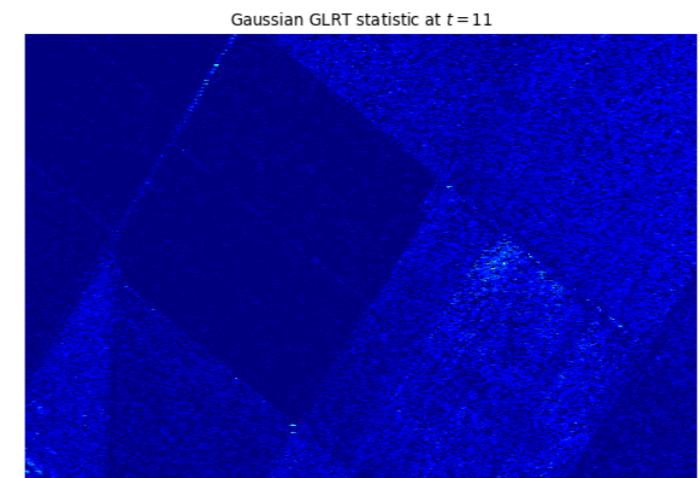
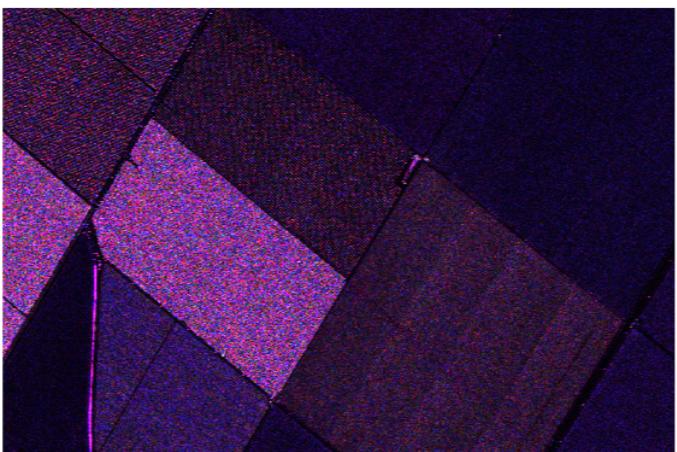
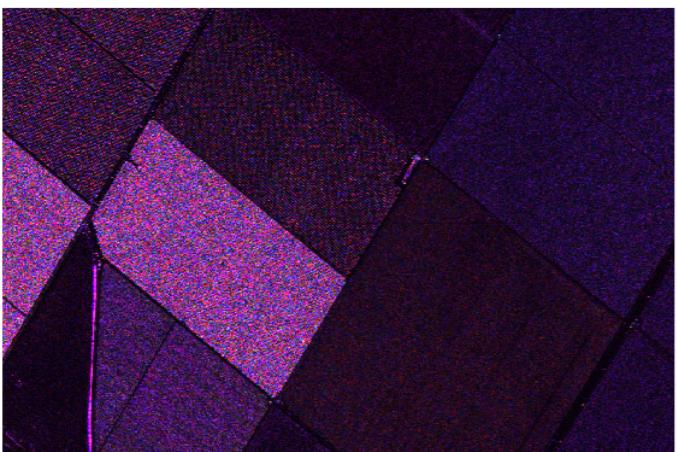
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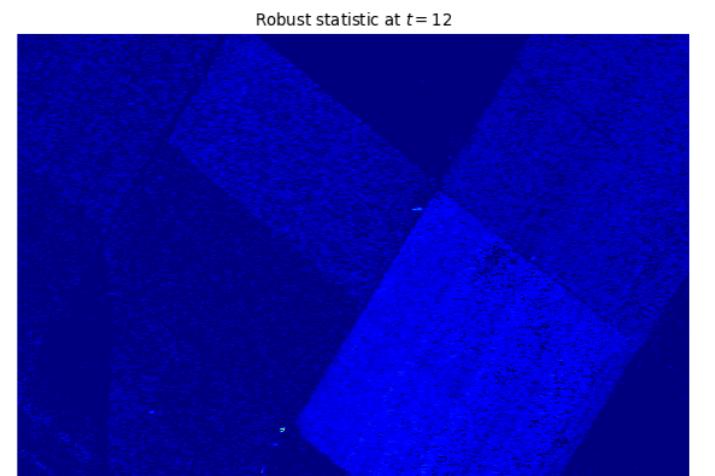
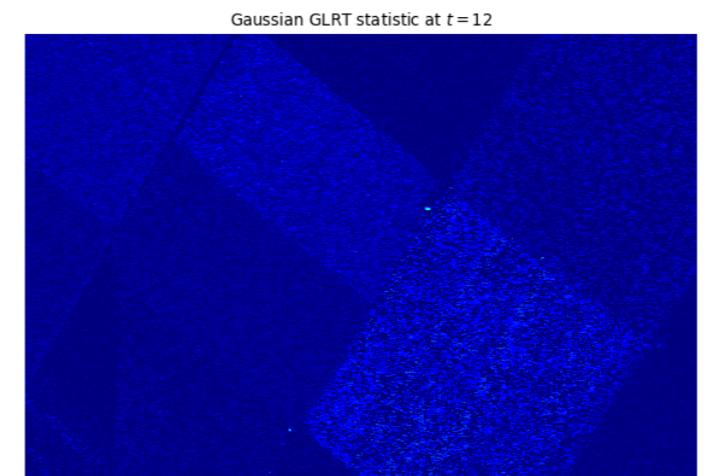
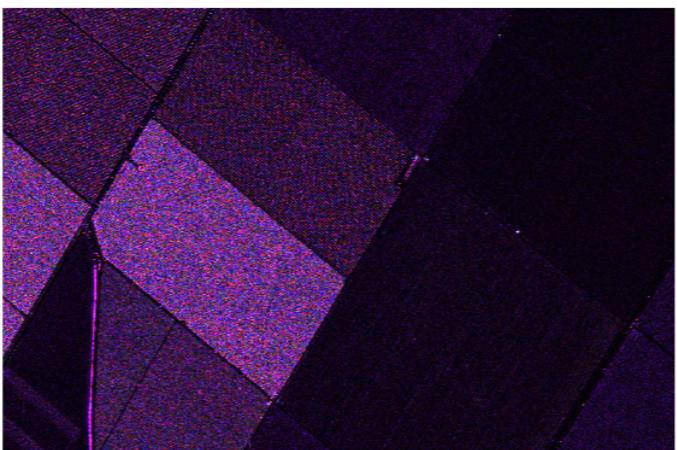
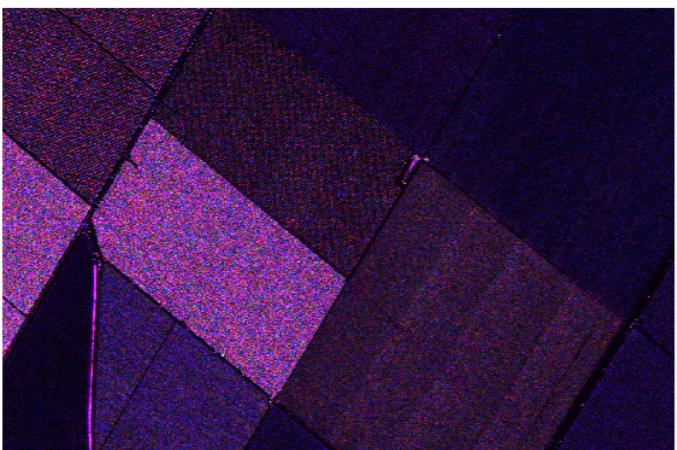
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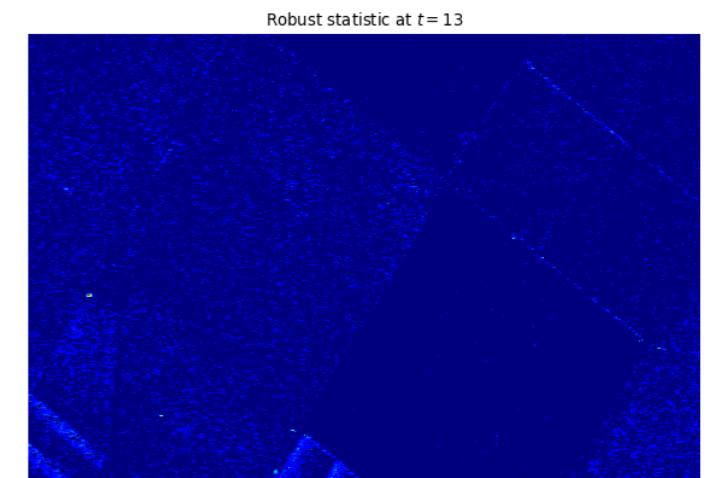
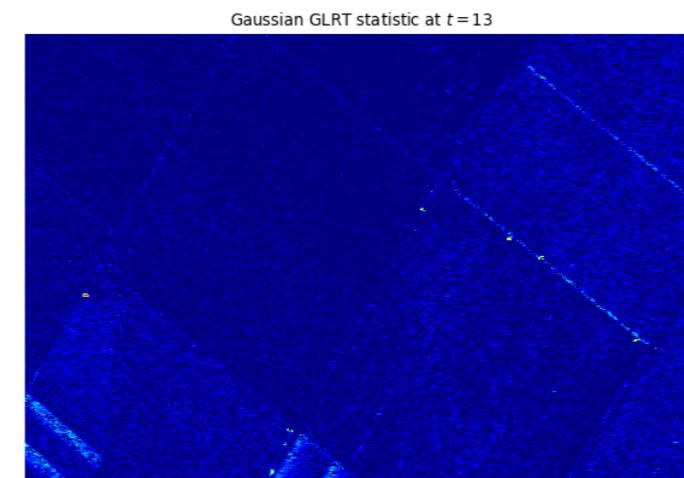
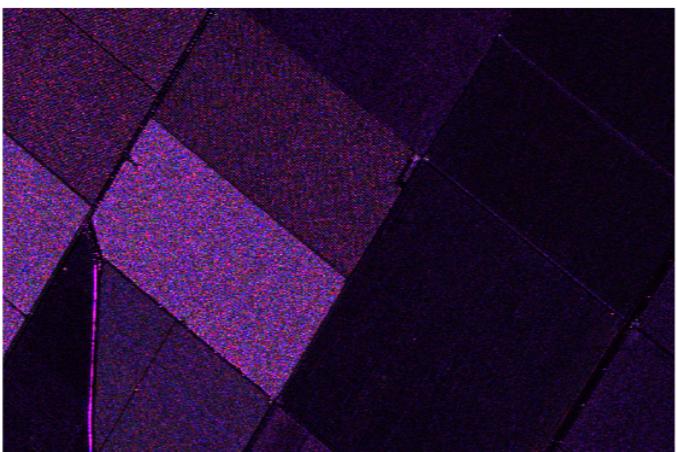
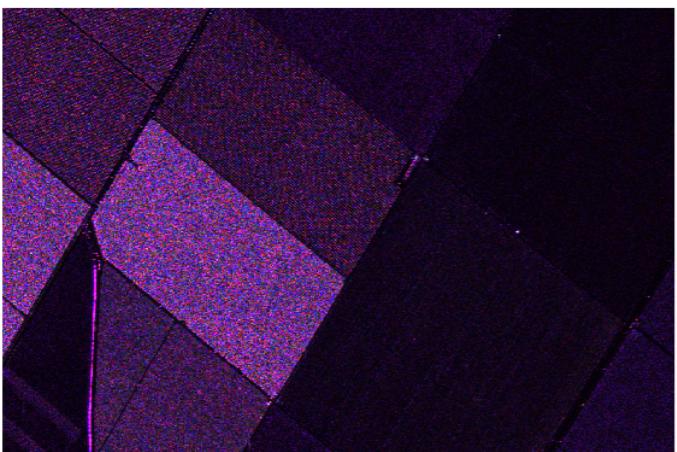
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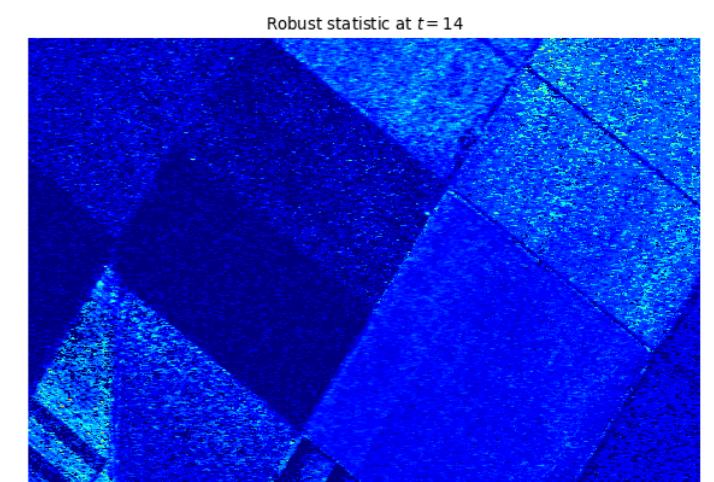
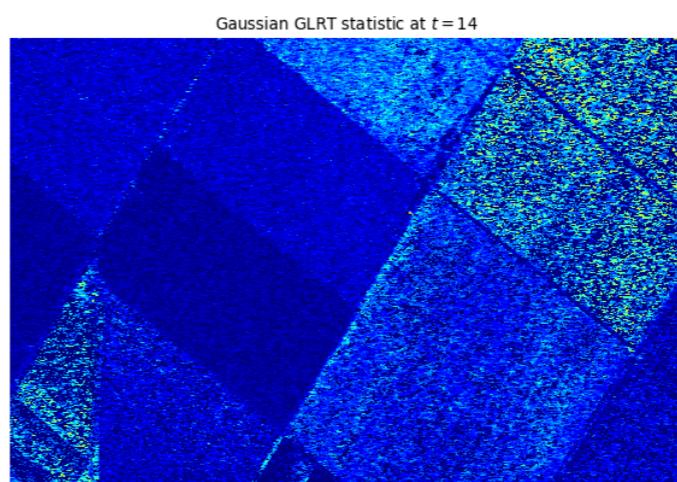
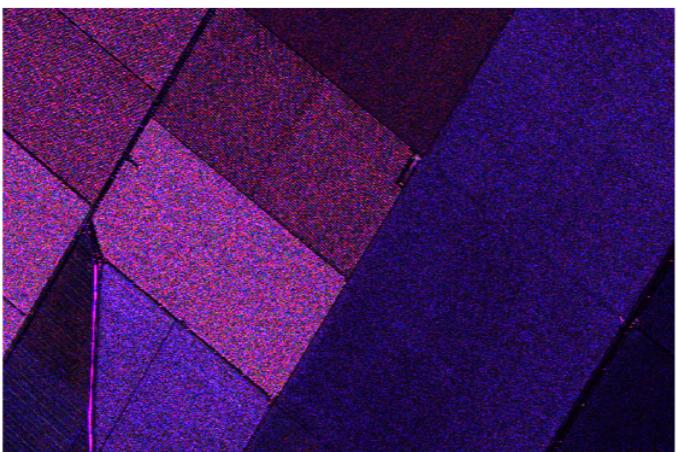
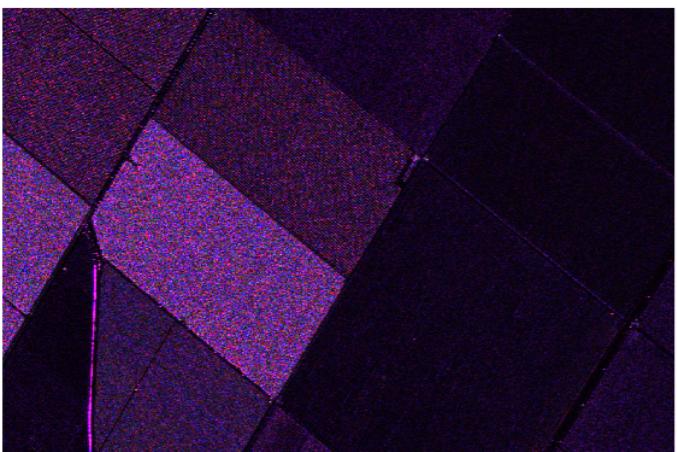
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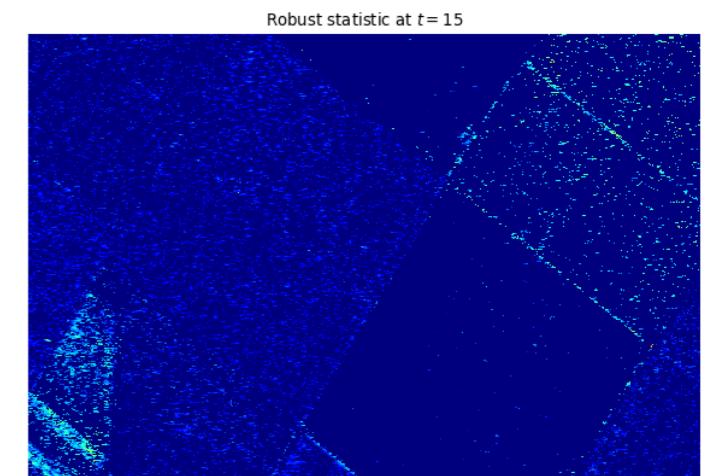
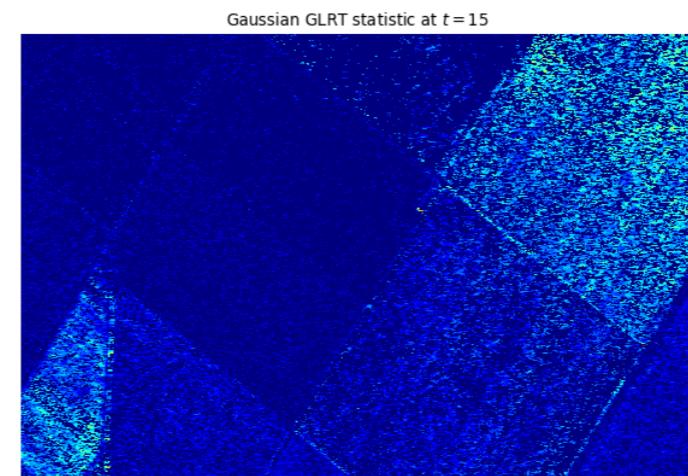
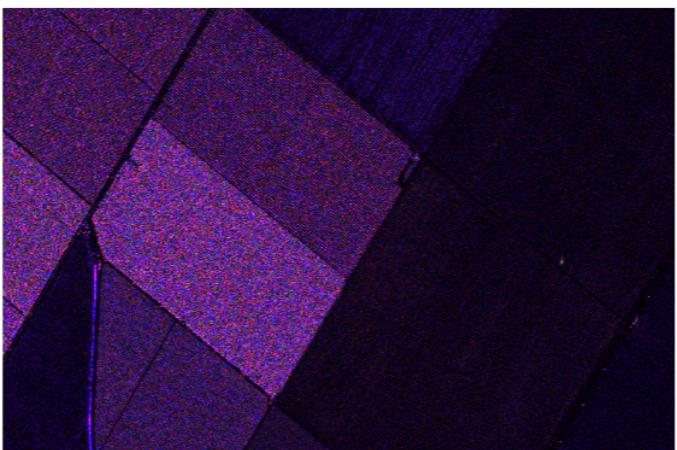
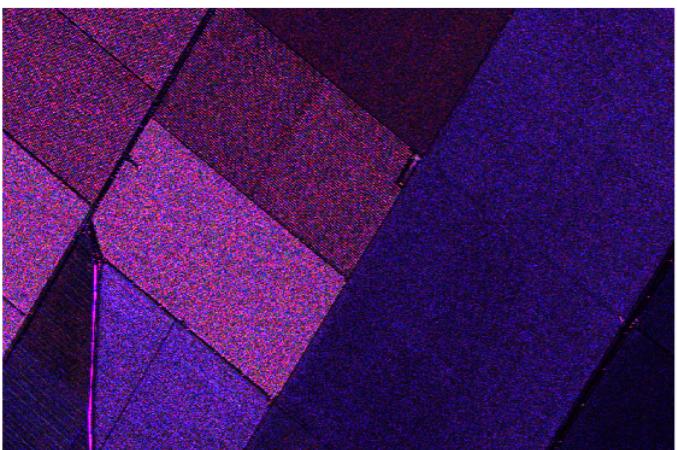
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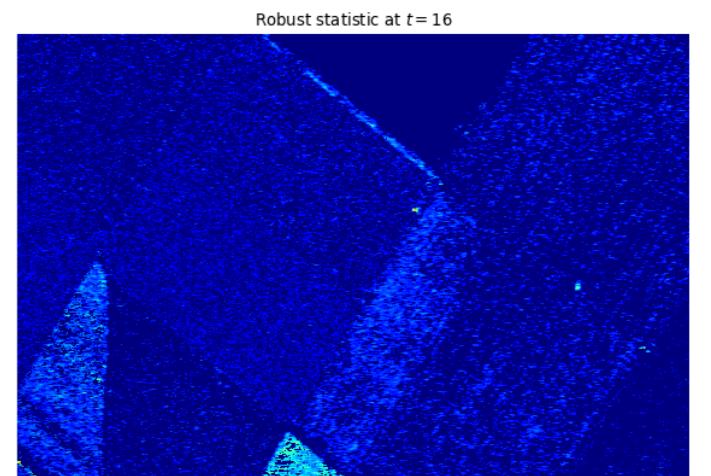
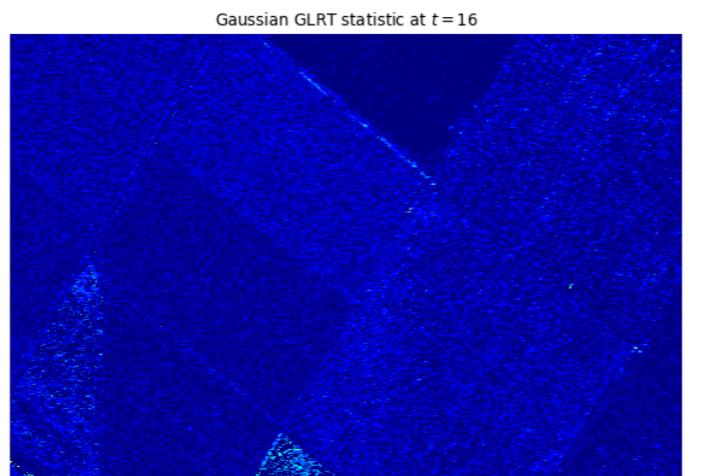
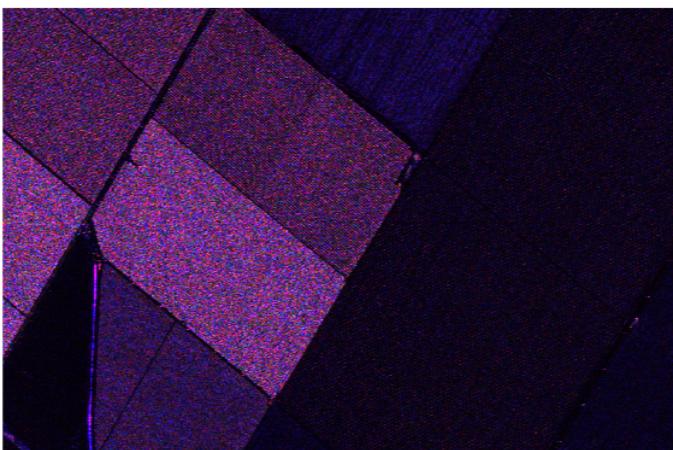
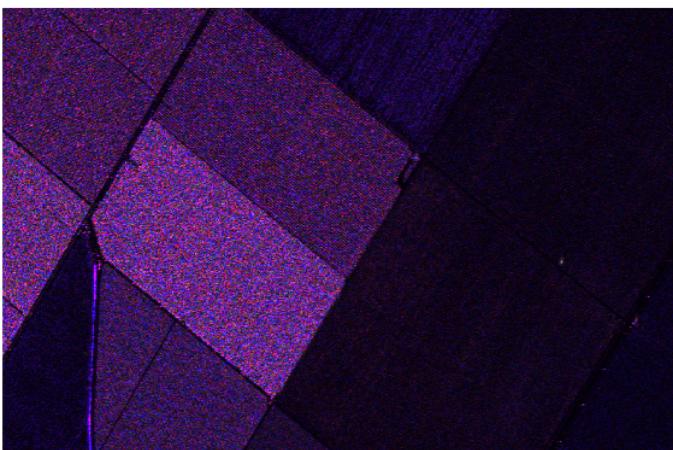
RESULT ON ANOTHER DATASET



RESULT ON ANOTHER DATASET



RESULT ON ANOTHER DATASET



THANKS FOR YOUR ATTENTION!