# Learning the topology of graphs

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### 1 Installation

For installation instructions, please visit https://github.com/dppalomar/spectralGraphTopology

### 2 Problem Statement

The Laplacian matrix  $\Theta$  of a graph contains the information of its topology and weight connections. By definition a Laplacian matrix is positive semi-definite, symmetric, and with sum of rows equal to zero. The Laplacian linear operator  $\mathcal{L}\mathbf{w}$  maps a vector of weights  $\mathbf{w}$  into a valid Laplacian matrix so that the conditions are satisfied by construction.

The underlying optimization problem of learning a K-component graph may be expressed as follows:

$$\begin{array}{ll} \underset{\mathbf{w}, \mathbf{\Lambda}, \mathbf{U}}{\text{minimize}} & -\log \det(\mathbf{\Lambda}) + \operatorname{tr}\left(\mathbf{K}\mathcal{L}\mathbf{w}\right) + \frac{\beta}{2} \left\| \mathcal{L}\mathbf{w} - \mathbf{U}\mathbf{\Lambda}\mathbf{U}^T \right\|_F^2 \\ \text{subject to} & \mathbf{w} \geq 0, \mathbf{\Lambda} \in \mathcal{S}_{\mathbf{\Lambda}}, \text{ and } \mathbf{U}^T\mathbf{U} = \mathbf{I} \end{array}$$

where  $S_{\Lambda}$  further constrains the eigenvalues of Laplacian matrices  $\Theta = \mathcal{L}\mathbf{w}$  according to some topology (e.g., a K-component graph has K zero eigenvalues).

In order to solve this problem, we use a block coordinate descent algorithm to iteratively optimize each variable while helding the others fixed.

### 3 Usage of the package

We illustrate the usage of the package with simulated data, as follows:

```
library(spectralGraphTopology)
set.seed(123)

# Number of samples
T <- 200
# Vector to generate the Laplacian matrix of the graph
w <- runif(10)
# Laplacian matrix</pre>
```

```
Theta <- L(w)

# Sample data from a Multivariate Gaussian

N <- ncol(Theta)

Y <- MASS::mvrnorm(T, rep(0, N), MASS::ginv(Theta))

# Number of components of the graph

K <- 1

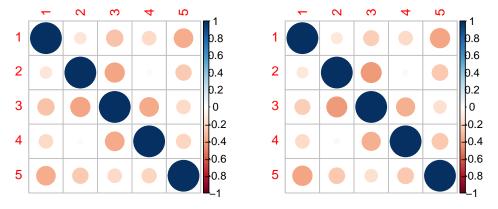
# Learn the Laplacian matrix

res <- learnGraphTopology(Y, K, beta = 10)
```

Let's visually inspect the true Laplacian and the estimated one:

```
Theta
                             [,3]
#>
           [,1]
                    [,2]
                                      [,4]
#> [1,] 2.3678770 -0.2875775 -0.7883051 -0.4089769 -0.8830174
#> [3,] -0.7883051 -0.9404673 3.1726265 -0.8924190 -0.5514350
#> [4,] -0.4089769 -0.0455565 -0.8924190 1.8035672 -0.4566147
#> [5,] -0.8830174 -0.5281055 -0.5514350 -0.4566147 2.4191726
res$Theta
#>
           [,1]
                     [,2]
                              [,3]
                                        [,4]
#> [1,] 2.2953931 -0.27079062 -0.6305267 -0.41598450 -0.9780912
#> [3,] -0.6305267 -1.02547743 2.9706229 -0.83893311 -0.4756856
#> [4,] -0.4159845 -0.06127561 -0.8389331 1.91751385 -0.6013206
#> [5,] -0.9780912 -0.59380196 -0.4756856 -0.60132063 2.6488995
```

```
library(corrplot)
par(mfrow = c(1, 2))
corrplot(cov2cor(Theta))
corrplot(cov2cor(res$Theta))
```



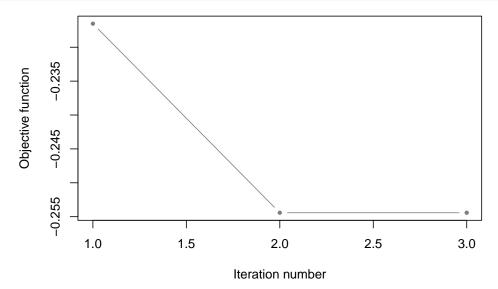
We evaluate the performance of the learning process in a more objective manner by computing two criterions:

- 1. relative error
- 2. percentage improvement in average loss (PRIAL)

```
relativeError <- function(Xtrue, Xest) {
    return (100 * norm(Xtrue - Xest, type = "F") / norm(Xtrue, type = "F"))
}</pre>
```

In this case, the naive estimation of the Laplacian matrix (i.e., generalized inverse of the sample covariance matrix) performs already quite well since the ratio T/N is large enough 40 for the sample covariance matrix to be accurately estimated.

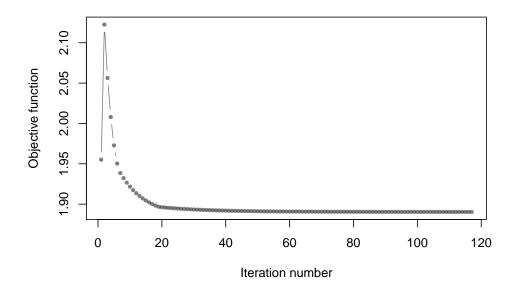
Let's also look at the convergence of the objective function versus iterations:

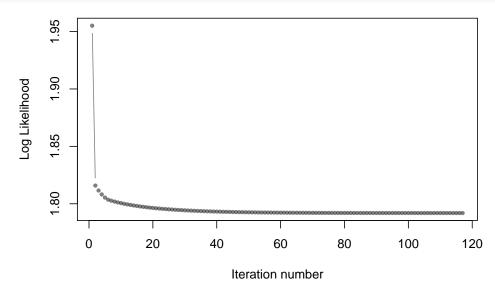


For K > 1, we can generate the Laplacian as a block diagonal matrix, as follows

```
library(spectralGraphTopology)
T <- 50
w1 <- runif(3)
w2 <- runif(3)
Theta1 <- L(w1)
Theta2 <- L(w2)</pre>
```

```
N1 <- ncol(Theta1)
N2 <- ncol(Theta2)
Theta <- rbind(cbind(Theta1, matrix(0, N1, N2)),
            cbind(matrix(0, N2, N1), Theta2))
Y <- MASS::mvrnorm(T, rep(0, N1 + N2), MASS::ginv(Theta))
K <- 2
res <- learnGraphTopology(Y, K, beta = 10)
Theta naive <- MASS::ginv(cov(Y))
rel_err <- c(proposed = relativeError(Theta, res$Theta),</pre>
          naive = relativeError(Theta, Theta_naive))
prial_avg <- c(proposed = prial(Theta, res$Theta),</pre>
            naive = prial(Theta, Theta_naive))
rel_err
#> proposed
             naive
#> 8.992709 14.027762
prial_avg
#> proposed
            naive
#> 99.39504 98.52794
Theta
#>
                    [.2]
                             [,3]
                                      [,4]
                                               [,5]
                                                        [.6]
           [.1]
#> [1,] 1.1183094 -0.8509632 -0.2673462 0.0000000 0.0000000 0.0000000
#> [4,] 0.0000000 0.0000000 0.0000000 1.6007581 -0.6085997 -0.9921584
#> [5,] 0.0000000 0.0000000 0.0000000 -0.6085997 0.7997897 -0.1911900
#> [6,] 0.0000000 0.0000000 0.0000000 -0.9921584 -0.1911900 1.1833484
res$Theta
           [,1]
                    [,2]
                              [,3]
                                       [,4]
                                                 [,5]
#> [1,] 1.1839191 -0.8535033 -0.33041578 0.0000000 0.00000000 0.000000000
#> [4,] 0.0000000 0.0000000 0.00000000 1.6398148 -0.67676874 -0.96304605
#> [5,] 0.0000000 0.0000000 0.00000000 -0.6767687 0.74520251 -0.06843377
#> [6,] 0.0000000 0.0000000 -0.04517265 -0.9630461 -0.06843377 1.07665247
N_iter <- length(res$fun)</pre>
plot(c(1:N_iter), res$fun, type = "b", pch=19, cex=.6, col = scales::alpha("black", .5),
    xlab = "Iteration number", ylab = "Objective function")
```





## 4 Explanation of the algorithms

In this section we describe in detail the algorithms designed to solve the graph topology learning problem.

### 4.1 learnGraphTopology: Learning the topology of graph

The goal of learnGraphTopology is to estimate the Laplacian matrix generated by the weight vector of a graph, w. The algorithm for the function learnGraphTopology is stated as follows:

```
Data: Y (data matrix), K (#{components}), \beta (regularization term), \mathbf{w}^{(0)}, \boldsymbol{\lambda}^{(0)}, \mathbf{U}^{(0)} (initial
            parameter estimates), \alpha_1, \alpha_2 (lower and upper bound on the eigenvalues of the Laplacian
            matrix), \rho (how much to increase beta per iteration).
Result: Θ (Laplacian matrix)
N \leftarrow \mathtt{ncol}(\mathbf{Y})
while objective function do not converged or max #{iterations} not reached do
     while parameters do not converged or max #{iterations} not reached do
           \mathbf{w}^{(k+1)} \leftarrow \mathtt{w\_update}(\mathbf{w}^{(k)}, \mathbf{U}^{(k)}, \boldsymbol{\lambda}^{(k)}, \beta, N, \mathbf{K})
           \mathbf{U}^{(k+1)} \leftarrow \mathtt{U\_update}(\mathbf{w}^{(k+1)}, N)
           \boldsymbol{\lambda}^{(k+1)} \leftarrow \texttt{lambda\_update}(\mathbf{w}^{(k+1)}, \mathbf{U}^{(k+1)}, \alpha_1, \alpha_2, \beta, N, K)
     end
     \beta \leftarrow \beta(\rho+1)
end
return \mathcal{L}(\mathbf{w}^{(k+1)})
Function w_update(w, U, \lambda, \beta, N, K):
    \nabla_{\mathbf{w}} f \leftarrow \mathcal{L}^{\star} \left( \mathcal{L} \left( \mathbf{w} \right) - \mathbf{U} \mathbf{diag}(\boldsymbol{\lambda}) \mathbf{U}^T + \frac{\mathbf{K}}{\beta} \right)
\mathbf{return} \ \max \left( 0, \mathbf{w} - \frac{\nabla_{\mathbf{w}} f}{2N} \right)
Function U_{update}(\mathbf{w}, N, K):
     return eigenvectors (\mathcal{L}(\mathbf{w}))[K+1:N] \# increasing order w.r.t. eigenvalues
Function lambda_update(w, \mathbf{U}, \alpha_1, \alpha_2, \beta, N, K):
      \mathbf{d} \leftarrow \mathtt{diag}\left(\mathbf{U}^T \mathcal{L}(\mathbf{w}) \mathbf{U}\right)
     \lambda \leftarrow \frac{1}{2} \left( \mathbf{d} + \sqrt{\mathbf{d} \odot \mathbf{d} + \frac{4}{\beta}} \right) \# \odot \text{ means element-wise multiplication}
     if \lambda has its elements in nondecreasing order and \min(\lambda) \geq \alpha_1 and \max(\lambda) \leq \alpha_2 then
           return \lambda
      else
           set to \alpha_1 the elements of \lambda whose values are less than \alpha_1
           set to \alpha_2 the elements of \lambda whose values are greater than \alpha_2
     if \lambda has its elements in nondecreasing order then
           return \lambda
      else
           raise Exception("eigenvalues are not in increasing order")
     end
```

### References