Calibration results
====================
Camera-system parameters:
cam0 (/tello/image_raw):
type: <class 'aslam_cv.libaslam_cv_python.EquidistantDistortedPinholeCameraGeometry'>
distortion: [0.36348985 -0.83046627   7.05719828 -13.29987983] +- [0.01963402 0.25244309 1.30801528 2.28061402]
projection: [911.99433389 911.74871247 487.87844162 385.56640129] +- [5.15109684 5.24512419 1.23464409
1.61519579]
reprojection error: [-0.000005, -0.000001] +- [0.493954, 0.534331]

Target configuration
====================
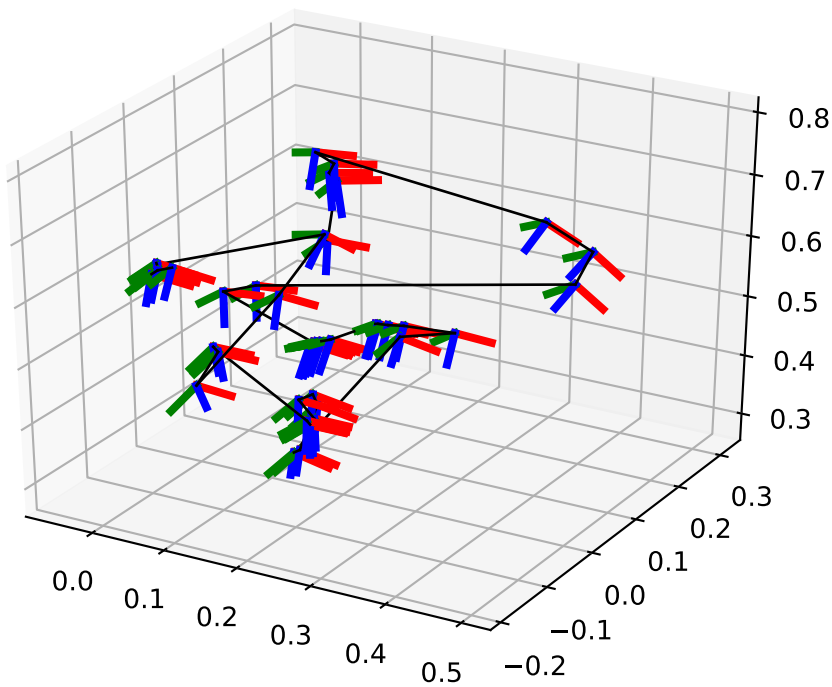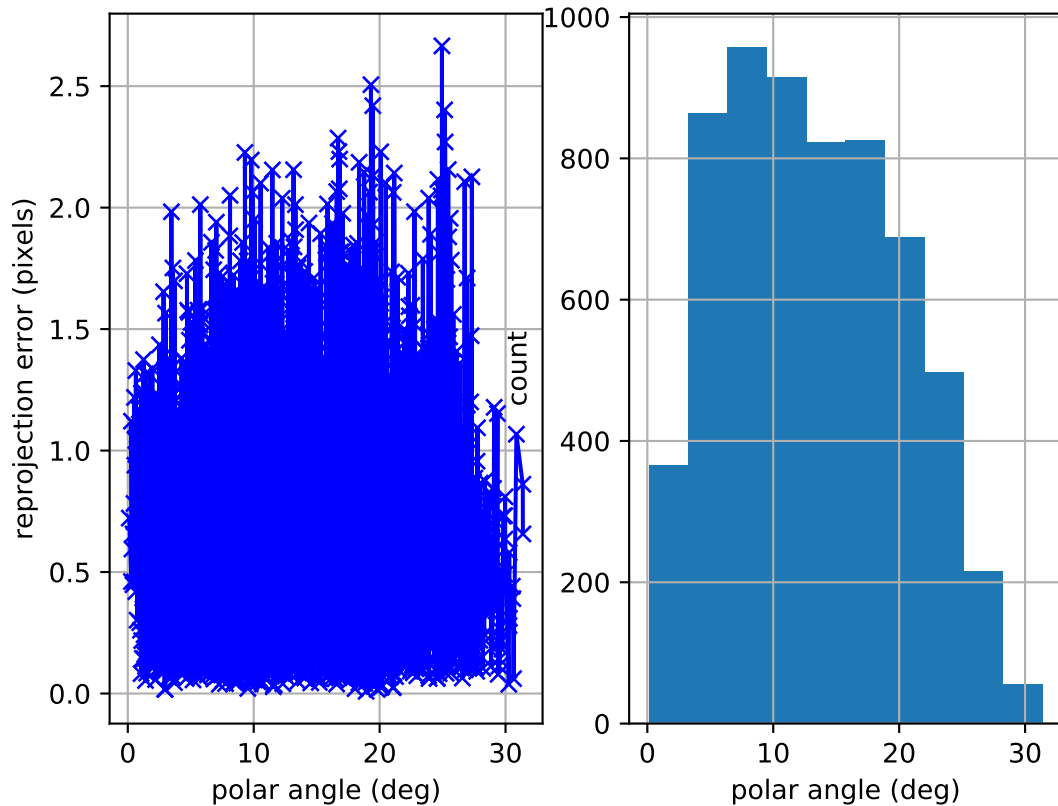
Type: aprilgrid
Tags:
Rows: 6
Cols: 6
Size: 0.0205 [m]
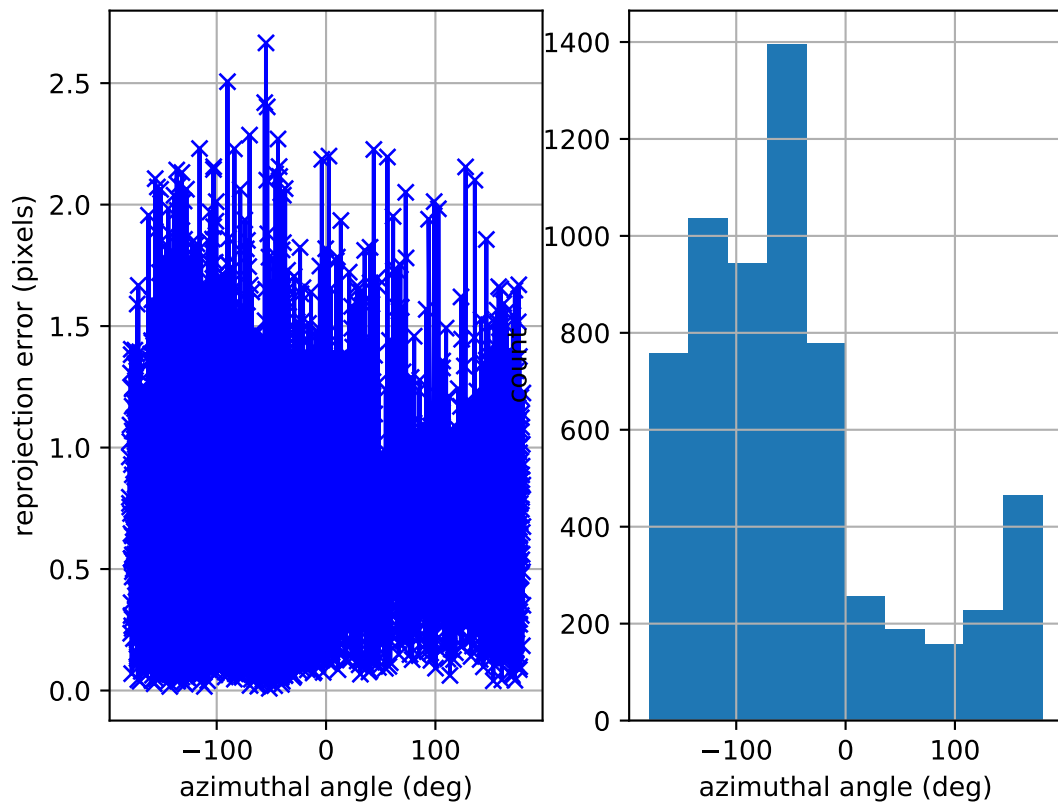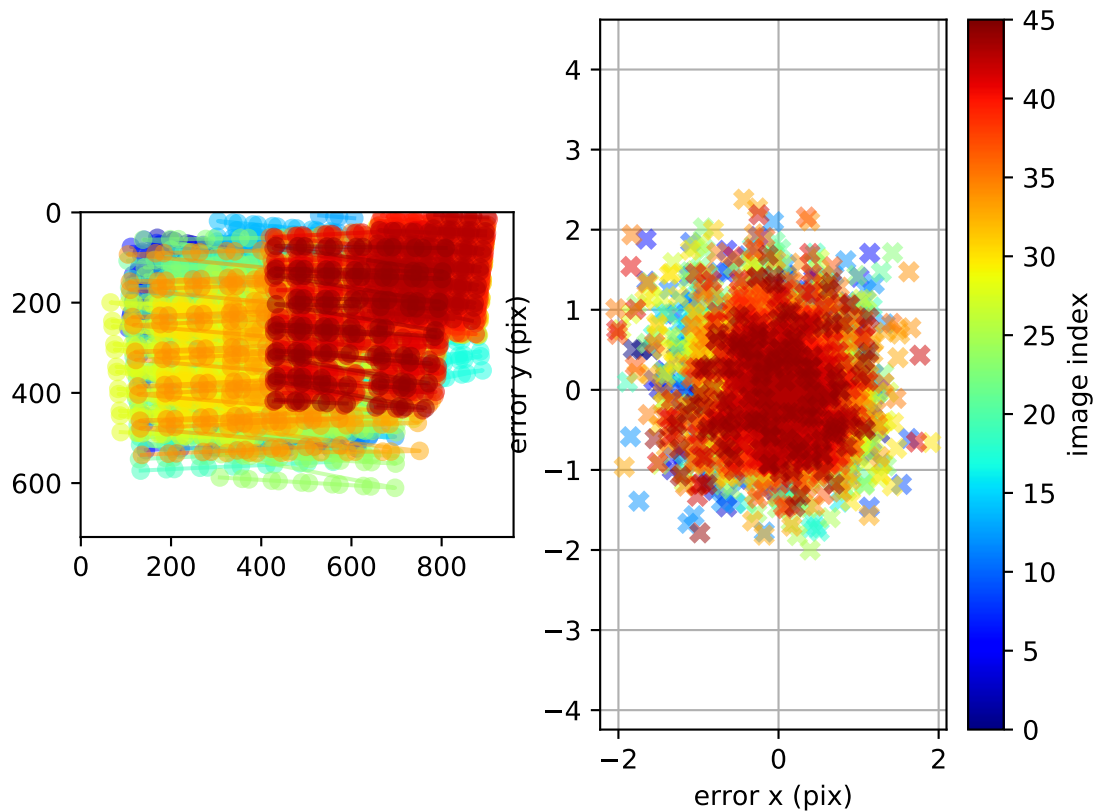Spacing 0.005945 [m]

cam0: estimated poses

cam0: polar error

cam0: azimuthal error

cam0: reprojection errors

Location of removed outlier corners

cam0