

Homework 7

Problem 1. *Give a one-to-one correspondence between $SO(3)$ and $\mathbb{R}P^3$.*

Proof. Note that we can view $\mathbb{R}P^3$ as a closed unit ball in \mathbb{R}^3 with the antipodal points of its boundary identified. Since $SO(3)$ is the group of rotations in 3 space, each element is defined by a direction and an angle to rotate by. But each point in $\mathbb{R}P^3$ can be described as $(\theta/2\pi)\mathbf{n}$ where \mathbf{n} is the unit normal vector and $\theta \in [0, 2\pi]$. These points then give both a direction and an angle to rotate by. Furthermore, antipodal points are identified so picking a direction or it's negative gives the same element of $SO(3)$. This shows surjectivity of our correspondence since given any point in $\mathbb{R}P^3$ we can find some rotation to which it corresponds.

Now if we pick two different elements of $SO(3)$ then they either have different directions, in which case they correspond to different unit normal vectors in $\mathbb{R}P^3$, or they have the same direction but with a different angle, in which case they correspond to two distinct points on the same unit normal vector in $\mathbb{R}P^3$. This shows injectivity. We thus have a bijective correspondence between $SO(3)$ and $\mathbb{R}P^3$. \square