Math Review

X and **Y** are independent iff $P(\mathbf{X}, \mathbf{Y}) = P(\mathbf{X})P(\mathbf{Y})$

X and Y are uncorrelated iff $\mathbb{E}(X,Y) = \mathbb{E}(X)\mathbb{E}(Y)$

Expected value of g(X): $E[g(X)] = \int_{-\infty}^{\infty} g(x)f(x)dx$

Variance
$$\sigma^2 = E[(X - \mu)^2] = E[X^2] - \mu^2$$

Determinant of matrix is product of its eigenvalues.

$$f(\mathbf{x}) = \mathbf{A}\mathbf{x} + \mathbf{x}'\mathbf{A} + \mathbf{x}'\mathbf{x} + \mathbf{x}'\mathbf{A}\mathbf{x} \Rightarrow \frac{df(\mathbf{x})}{d\mathbf{x}} = \mathbf{A}' + \mathbf{A} + 2\mathbf{x} + \mathbf{A}\mathbf{x} + \mathbf{A}'\mathbf{x}$$

$$\nabla_{x}(y \cdot z) = (\nabla_{x})z + (\nabla_{x})y \qquad \nabla_{x}f(y) = (\nabla_{x}y)(\nabla_{y}f(y))$$

$$\nabla_w w^T A w = (A + A^T) w \qquad \qquad \mathbf{H}_{i,j} = \frac{\partial^2 f}{\partial x_i \partial x_j}$$

Perceptron

$$f(\mathbf{x}) = \mathbf{w} \cdot \mathbf{x} + \alpha = \sum_{i=1}^{d} w_i x_i + \alpha,$$

 $f(\mathbf{x}) = \mathbf{w} \cdot \mathbf{x} + \alpha = \sum_{i=1}^d w_i x_i + \alpha$, Goal: find w s.t all constraints $y_i X_i \cdot w \geq 0$. Define a risk function and optimize it, where the loss is defined as $L(z, y_i) = -y_i z$ if $y_i z < 0$, else 0. Therefore risk $R(w) = \sum_{i \in V} -y_i X_i \cdot w$

Decision boundary, a hyperplane in
$$\mathbb{R}^d$$
:
 $H = \{ \mathbf{x} \in \mathbb{R}^d : f(\mathbf{x}) = 0 \} = \{ \mathbf{x} \in \mathbb{R}^d : \mathbf{w} \cdot \mathbf{x} + \alpha = 0 \}$

w is the **normal** of the hyperplane, α is the **offset** of the hyperplane from origin, $\frac{f(\mathbf{x})}{\|\mathbf{w}\|}$ is the **signed distance** from the **x** to hyperplane \mathcal{H} .

Perceptron algorithm,

Input:
$$(\mathbf{x}_1, y_1), \dots, (\mathbf{x}_n, y_n) \in \mathbb{R}^d \times \{\pm 1\}$$

while some $y_i \neq \operatorname{sign}(\mathbf{w} \cdot \mathbf{x}_i)$
pick some misclassified (\mathbf{x}_i, y_i)
 $\mathbf{w} \leftarrow \mathbf{w} + y_i \mathbf{x}_i$

Given a linearly separable data, perceptron algorithm will take no more than $\frac{R^2}{\gamma^2}$ updates to **converge**, where $R = \max_i \|\mathbf{x}_i\|$ is the radius of the data, $\gamma = \min_i \frac{y_i(\mathbf{w} \cdot \mathbf{x}_i)}{\|\mathbf{w}\|}$ is the margin. Also, $\frac{\mathbf{w} \cdot \mathbf{x}}{\|\mathbf{w}\|}$ is the signed distance from H to \mathbf{x} in the direction \mathbf{w} .

Gradient descent view of perceptron, minimize margin cost function $J(\mathbf{w}) = \sum_{i} (-y_i(\mathbf{w} \cdot \mathbf{x}_i))_+$ with $\mathbf{w} \leftarrow \mathbf{w} - \eta \nabla J(\mathbf{w})$

Support Vector Machine

Hard margin SVM,

This method makes the margin as wide as possible. The signed distance from the hyperplane to X_i is $\frac{f(\mathbf{x}_i)}{\|\mathbf{x}\|}$ Hence the margin is $\min_i \frac{1}{\|w\|} |w \cdot X_i + \alpha| \geq \frac{1}{\|w\|} \implies \min_{\mathbf{w}} \|\mathbf{w}\|^2, \text{ such that }$ $y_i \mathbf{w} \cdot \mathbf{x}_i \ge 1 (i = 1, \dots, n)$ Soft margin SVM, $\min_{\mathbf{w}} \|\mathbf{w}\|^{\overline{2}} + C \sum_{i=1}^{n} \xi_i$

Regularization and SVMs: Simulated data with many features $\phi(\mathbf{x})$; C controls trade-off between margin $1/\|\mathbf{w}\|$ and fit to data; Large C: focus on fit to data (small margin is ok). More overfitting. Small C: focus on large margin, less tendency to overfit. Overfitting increases with: less data, more features.

Decision Theory

Bayes Theorem:
$$P(Y = C|X) = \frac{P(X|Y = C) P(Y = C)}{P(X)}$$
 Assume

(X, Y) are chosen i.i.d according to some probability distribution on $\mathcal{X} \times \mathcal{Y}$. **Risk** is misclassification probability:

$$R(r) = \mathbb{E}(L(r(\mathbf{X}), \mathbf{Y})) = Pr(r(\mathbf{X}) \neq \mathbf{Y}) = \sum_{\mathbf{x}} \left[L(r(\mathbf{x}), 1)P(Y = 1|x) + L(r(x), -1)P(Y = -1|X = \mathbf{x}) \right] \times P(\mathbf{x})$$

$$= P(Y=1) \sum_{x} L(r(\mathbf{x}), 1) P(\mathbf{x}|Y=1) + P(Y=-1) \sum_{x} L(r(\mathbf{x}), -1) P(\mathbf{x}|Y=-1)$$

Bayes Decision Rule is

$$r^*(x) = \begin{cases} 1, & \text{if } L(-1,1)P(\mathbf{Y} = 1|x) > L(1,-1)P(\mathbf{Y} = -1|x) \\ -1, & \text{otherwise.} \end{cases}$$

and the optimal risk (Bayes risk) $R^* = \inf_r R(r) = R(r^*)$

Risk in Regression is expected squared error: $R(f) = \mathbb{E}l(f(\mathbf{X}), \mathbf{Y}) = \mathbb{E}\mathbb{E}[f(\mathbf{X}) - \mathbf{Y}^2 | \mathbf{X}]$

Bias-variance decomposition:

$$R(f) = \mathbb{E}[\underbrace{(f(\mathbf{X}) - \mathbb{E}[\mathbf{Y}|\mathbf{X}])^{2}}_{\text{bias}^{2}}] + \mathbb{E}[\underbrace{(\mathbb{E}[\mathbf{Y}|\mathbf{X}] - \mathbf{Y})^{2}}_{\text{variance}}]$$

$$R(f) = \mathbb{E}[(f(\mathbf{X}) - f^{*}(\mathbf{X}))^{2}] + \mathbb{E}[(f^{*}(\mathbf{X}) - \mathbf{Y})^{2}]$$

$$R(f) = \mathbb{E}[(f(\mathbf{X}) - f^{*}(\mathbf{X}))^{2}] + R(f^{*})$$

$$R(f) - R(f^{*}) = \mathbb{E}[(f(\mathbf{X}) - f^{*}(\mathbf{X}))^{2}], f^{*}(\mathbf{X}) = \mathbb{E}[\mathbf{Y}|\mathbf{X}]$$

Generative and Discriminative

Discriminative models: P(X, Y) = P(X)P(Y|X). Estimate $P(\mathbf{Y}|\mathbf{X})$, then pretend out estimate $\hat{P}(\mathbf{Y}|\mathbf{X})$ is the actual $P(\mathbf{Y}|\mathbf{X})$ and plug in bayes rule expression.

Generative model: P(X, Y) = P(Y)P(X|Y).

Estimate $P(\mathbf{Y})$ and $P(\mathbf{X}|\mathbf{Y})$, then use bayes theorem to calculate $P(\mathbf{Y}|\mathbf{X})$ and use discriminative model.

Gaussian class conditional densities $P(\mathbf{X}|Y=+1), P(\mathbf{X}|Y=-1)$ (with the same variance), the posterior probability is logistic:

$$P(Y = +1|\mathbf{x}) = \frac{1}{1 + \exp(-\mathbf{x} \cdot \mathbf{w} - \beta_0)},$$

$$\mathbf{w} = \Sigma^{-1}(\boldsymbol{\mu}_1 - \boldsymbol{\mu}_0), \ \beta_0 = \frac{\boldsymbol{\mu}_0' \Sigma^{-1} \boldsymbol{\mu}_0 - \boldsymbol{\mu}_1 \Sigma^{-1} \boldsymbol{\mu}_1}{2} + \log \frac{P(Y=1)}{2}$$

Multivariate Normal Distribution

$$\mathbf{x} \in \mathbb{R}^d : p(x) = \frac{1}{(2\pi)^{d/2} |\mathbf{\Sigma}|^{1/2}} e^{(-\frac{1}{2}(\mathbf{x} - \boldsymbol{\mu})' \mathbf{\Sigma}^{-1}(\mathbf{x} - \boldsymbol{\mu}))}$$

QDA: Class-conditional densities $X_C \sim \mathcal{N}((\cdot, \mu_C, \Sigma_C))$. Optimal decision rule $r^*(x)$ for 0-1 loss: Choose class C that maxes $P(Y=C|X) \propto f_C(x)\pi_C$. Parameters estimated via MLE: LDA: Assumes equal covariance matrices across classes $(\Sigma_C = \Sigma)$, simplifying to linear decision surfaces.

$$\begin{split} & \boldsymbol{\Sigma} = \mathbb{E}(\mathbf{X} - \boldsymbol{\mu})(\mathbf{X} - \boldsymbol{\mu})' \\ & \text{Symmetric: } \boldsymbol{\Sigma}_{i,j} = \boldsymbol{\Sigma}_{j_i} \\ & \text{Non-negative diagonal entries: } \boldsymbol{\Sigma}i, i \geq 0 \\ & \text{Positive semidefinite: } \forall \mathbf{v} \in \mathbb{R}^d, \mathbf{v}' \boldsymbol{\Sigma} \mathbf{v} > 0 \end{split}$$

Given a d-dimensional Gaussian $\mathbf{X} \sim \mathcal{N}(\boldsymbol{\mu}, \boldsymbol{\Sigma})$, matrix $\mathbf{A} \in \mathbb{R}^{m \times d}$ and vector $\mathbf{b} \in \mathbb{R}^m$, define $\mathbf{Y} = \mathbf{A}\mathbf{X} + \mathbf{b}$. Then $\mathbf{Y} \sim \mathcal{N}(\mathbf{A}\boldsymbol{\mu} + \mathbf{b}, \mathbf{A}\boldsymbol{\Sigma}\mathbf{A}')$

Given a d-dimensional Gaussian $\mathbf{X} \sim \mathcal{N}(\boldsymbol{\mu}, \boldsymbol{\Sigma})$, with Σ positive definite,

$$\mathbf{Y} = \mathbf{\Sigma}^{-rac{1}{2}}(\mathbf{X} - oldsymbol{\mu}) \sim \mathcal{N}(\mathbf{0}, \mathbf{I},)$$

MLE's

Maximum a posterior probability: the mode of the posterior. If uniform prior, MAP is MLE; if not uniform prior, MAP is Penalized MLE.

Prior: $\hat{\pi}_C = P(Y = C) = \frac{N_C}{r}$

Mean:
$$\hat{\mu}_C = \mathbb{E}[\mathbf{X}|Y=C] = \frac{1}{N_C} \sum_{i:Y_i=C} X_i$$

Covariance:
$$\hat{\Sigma}_C = \frac{1}{N_C} \sum_{i:Y_i=C} (X_i - \hat{\mu}_C)(X_i - \hat{\mu}_C)^{\top}$$

Pooled Cov:
$$\hat{\Sigma} = \frac{1}{n} \sum_{C_k} \sum_{i:Y_i = C_k} (X_i - \hat{\mu}_{C_k}) (X_i - \hat{\mu}_{C_k})^{\top}$$

Linear Regression

Empirical risk minimization

Empirical risk is the sample average of squared error: $\hat{R}(r) = \hat{\mathbb{E}}_n L(r(\mathbf{X}), Y) = \frac{1}{n} \sum_{i=1}^{n} n(r(\mathbf{X}_i) - Y_i)^2$ Choose $\hat{f} := \arg \min_{f \in F_{\text{lin}}} \hat{\mathbb{E}}_n L(f(\mathbf{X}), Y)$

Find
$$\hat{r}: \mathbf{x} \mapsto \mathbf{x}^T \hat{\mathbf{w}}$$
, such that $\hat{\mathbf{w}} = \arg\min_{\mathbf{w} \in \mathbb{R}^p} \sum_{i=1}^n (\mathbf{X}_i' \mathbf{w} - Y_i)^2 = \arg\min_{\mathbf{w} \in \mathbb{R}^p} \underbrace{\|\mathbf{X} \mathbf{w} - \mathbf{y}\|^2}_{\text{RSS}}$ where **design matrix** $\mathbf{X} \in \mathbb{R}^{n \times p}$ and **response vector** $\mathbf{y} \in \mathbb{R}^n$.

Normal equations: $\mathbf{X}'\mathbf{X}\mathbf{w} = \mathbf{X}'\mathbf{y} \Rightarrow \hat{\mathbf{w}} = (\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\mathbf{y}$

Projection Theorem also leads to normal equations:
$$(\mathbf{y} - \hat{\mathbf{y}})^{-1}\mathbf{X} = 0 \Leftrightarrow \mathbf{X}'(\mathbf{y} - \mathbf{X}\mathbf{w}) = 0 \Leftrightarrow \mathbf{X}'\mathbf{y} = \mathbf{X}'\mathbf{X}\mathbf{w}$$

Linear model with additive Gaussian noise

Typical model of reality: $y_i = q(X_i) + \epsilon_i : \epsilon \sim \mathcal{N}(\mathbf{0}, \sigma^2)$. The goal of regression is to find h that estimates g, the ground truth. Ideal h: $h(x) = E_Y[Y|X = x] = g(x) + E[\epsilon] = g(x)$

$$\implies u_i \sim \mathcal{N}(g(X_i), \sigma^2)$$

$$\implies P(Y|\mathbf{X} = \mathbf{x}) = \mathcal{N}(\mathbf{x}'\mathbf{w}, \sigma^2)$$

Equivalently: $Y = \mathbf{x}'\mathbf{w} + \epsilon$, where $\epsilon \sim \mathcal{N}(\mathbf{0}, \sigma^2)$

Maximum likelihood is least square, fix X. Provided $\mathbb{E}\mathbf{v} = \mathbf{X}\mathbf{w}$ and $Cov(\mathbf{y}) = \sigma^2 \mathbf{I}$

Bayesian analysis: Treat w as a r.v. with prior distribution $\mathcal{N}(\mathbf{0}, \tau^2 \mathbf{I})$, then compute posterior distribution $P(\mathbf{w}|\mathbf{X}, Y)$.

$$P(\mathbf{w}|\mathbf{X}_1, Y_1, \dots, \mathbf{X}_n, Y_n) \propto P(Y_1, \dots, Y_n|\mathbf{w}, \mathbf{X}_1, \dots, \mathbf{X}_n)P(\mathbf{w})$$

$$P(\mathbf{w}|\mathbf{X}_1, Y_1, \dots, \mathbf{X}_n, Y_n) \propto exp(-\frac{1}{2}(\sum_{i=1}^n \frac{(Y_i - \mathbf{X}_i'\mathbf{w})^2}{\sigma^2} + \frac{1}{\tau^2} ||\mathbf{w}||^2))$$

Linear Regression Regularization

Trading off bias and variance: some increase in bias can give a big decrease in variance

Ridge regression is like L2 regularization:

$$\hat{\mathbf{w}} = \arg \min_{\mathbf{w}} \left(\sum_{i=1}^{n} (y_i - \mathbf{x}_i' \mathbf{w})^2 + \lambda \sum_{j=1} p \beta_j^2 \right) \\ \hat{\mathbf{w}}^{\text{ridge}} = (\mathbf{X}' \mathbf{X} + \lambda \mathbf{I})^{-1} \mathbf{x}' \mathbf{v}$$

Lasso regression is like L1 regularization:

 $\hat{\mathbf{w}} = \arg\min_{\mathbf{w}} \left(\sum_{i=1}^{n} (y_i - \mathbf{x}_i' \mathbf{w})^2 + \lambda \sum_{j=1} p |\beta_j| \right)$ While ridge regression leads to reduced, but rare non-zero values of the weights, Lasso regression forces some weights to be zero.

Bayesian analysis: Ridge regression is equivalent to a MAP estimate with a gaussian prior. Lasso regression is equivalent to a MAP estimate with a Laplace prior.

Logistic Regression

$$P(Y = 1|\mathbf{x}) = \frac{1}{1 + \exp(-\mathbf{w}'\mathbf{x})} = \sigma(\mathbf{w}'\mathbf{x})$$

Given data $(\mathbf{X}_1, Y_1), \dots, (\mathbf{X}_n, Y_n) \in \mathbb{R}^d \times \{0, 1\}$, estimate \mathbf{w} with maximum likelihood.

Log likelihood:

$$\ell(\mathbf{w}) = \sum_{i=1}^{n} y_i \log s_i) + (1 - y_i) \log(1 - s_i),$$

where $s_i = P(Y = 1 | \mathbf{X} = \mathbf{x}_i, \mathbf{w}) = \frac{1}{1 + \exp(-\mathbf{w}' \mathbf{x}_i)} = \sigma(\mathbf{w}' \mathbf{x}_i)$

$$\nabla_{\mathbf{w}} s_i = s_i (1 - s_i) \mathbf{x}_i$$

$$\nabla_{\mathbf{w}} \ell(\mathbf{w}) = \mathbf{X}'(\mathbf{s} - \mathbf{y})$$

$$\nabla_{\mathbf{w}}^{2} \ell(\mathbf{w}) = \mathbf{X}' \operatorname{diag}(\boldsymbol{\mu}(1-\boldsymbol{\mu}))\mathbf{X}$$

Gradient ascent:

$$\mathbf{w}^{(t+1)} = \mathbf{w}^{(t)} - \eta \nabla_{\mathbf{w}} R(\mathbf{w}^{(t)}) : O(nd) \text{ per step}$$

Stochastic gradient ascent:

$$\mathbf{w}^{(t+1)} = \mathbf{w}^{(t)} - \eta \nabla R_i(\mathbf{w}^{(t)}) : O(d) \text{ per step}$$

Newton's method:

$$\mathbf{w}^{(t+1)} = \mathbf{w}^{(t)} - [\nabla_{\mathbf{w}}^2 R(\mathbf{w}^{(t)})]^{-1} \nabla_{\mathbf{w}} R(\mathbf{w}^{(t)})$$

Discriminant Analysis

Discriminant Fn (For LDA and QDA):

$$Q_C(\mathbf{x}) = \ln\left((2\pi)^{-\frac{d}{2}} f_{\mathbf{X}|Y=C}(\mathbf{x}) \pi_C\right) = -\frac{1}{2} (\mathbf{x} - \boldsymbol{\mu}_C)^T \boldsymbol{\Sigma}_C^{-1} (\mathbf{x} - \boldsymbol{\mu}_C) - \frac{1}{2} \ln|\boldsymbol{\Sigma}_C| + \ln \pi_C.$$

For Multi-class LDA: choose C that maxes linear Q_C : $\mu_C^T \Sigma^{-1} \mathbf{x} - \frac{1}{2} \mu_C^T \Sigma^{-1} \mu_C + \ln \pi_C$

Linear Decision Function:

$$\underbrace{Q_C(\mathbf{x}) - Q_D(\mathbf{x}) =}_{\mathbf{w}^T \mathbf{x}} \underbrace{-\frac{1}{2} \boldsymbol{\mu}_C^T \boldsymbol{\Sigma}^{-1} \boldsymbol{\mu}_C - \frac{1}{2} \boldsymbol{\mu}_D^T \boldsymbol{\Sigma}^{-1} \boldsymbol{\mu}_D + \ln \pi_C - \ln \pi_D}_{\boldsymbol{\alpha}}.$$

Misc

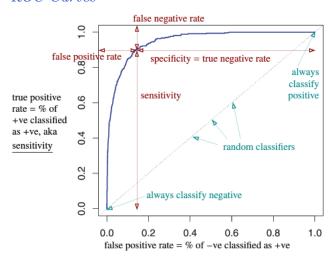
Centering X: This involves subtracting μ^T from each row of X. Symbolically, X transforms into $\bar{\mathbf{X}}$.

Decorrelating X: This process applies a rotation $\mathbf{Z} = \bar{\mathbf{X}}\mathbf{V}$, where $\text{Var}(\mathbf{R}) = \mathbf{V}\mathbf{\Lambda}\mathbf{V}^T$. This step rotates the sample points to the eigenvector coordinate system.

Sphering: $\bar{\mathbf{X}}$: applying transform $\mathbf{W} = \bar{\mathbf{X}} \operatorname{Var}(\mathbf{R})^{-\frac{1}{2}}$

whitening X: centering + sphering, $X \rightarrow W$

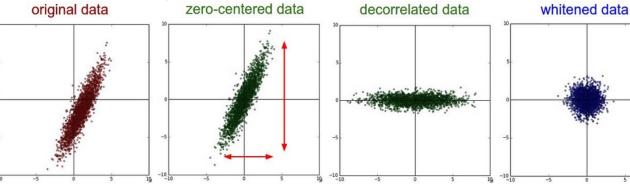
ROC Curves



Past Exams Q/A

Support Vector Machine

- * True: If the data is not linearly separable, there is no solution to hard margin SVM.
- * True: Complementarity slackness implies that every training point that is misclassified by a soft margin SVM is a support vector.
- * True: When we solve the SVM with the dual problem, we need only the dot product of x_i and x_j for all i, j.



Logistic Regression

- * True: Logistic regression can be used for classification.
- * Logistic regression can be motivated from log odds equated to an affine function of x and generative models with gaussian class conditionals.

Linear Regression

- * L2 regularization is equivalent to imposing a Gaussian prior in linear regression.
- * If we have 2 two-dimensional Gaussians, the same covariance matrix for both will result in a linear decision boundary.
- * The normal equations can be derived from minimizing empirical risk, assuming normally distributed noise, and assuming P(Y|X) is distributed normally with mean $B^{\top}X$ and variance σ^2 .

Perceptron

* The perceptron algorithm will converge only if the data is linearly separable.

Decision Theory

* True: a discriminative classifier explicitly models P(Y|X).

Optimization

- · True: Newton's method is typically more expensive to calculate than gradient descent per iteration.
- · True: for quadratic equations, Newton's method typically requires fewer iterations than gradient descent.
- False: Gradient descent can be viewed as iteratively reweighted least squares.
- · True: we use Lagrange multipliers in an optimization problem with inequality constraints.

Multivariate Gaussian

* False: For multivariate gaussian, the eigenvalues of the covariance matrix are inversely proportional to the lengths of the ellipsoid axes that determine the isocontours of the density.

General Machine Learning Practices

* True: It is not good machine learning practice to use the test set to help adjust the hyperparameters.

Decision Trees

cuts x-space into rectangular cells, and works well with both categorical and quantitative features.

Two types of nodes:

end if end function

- 1. internal: test feature values & branch accordingly
- 2. **leaf**: they specify the class h(x)

For classification the learning algorithm is a greedy, top-down learning heuristic. Let S be subset of sample pts indices Learning algorithm function GROWTREE(S) if all $y_i = C$ for all $i \in S$ and some class C then return $new\ leaf(C)$ else $\text{Choose best splitting feature } j \text{ and splitting value } \beta$ $S_L = \{i \in S: X_{ij} < \beta\}$ $S_R = \{i \in S: X_{ij} \geq \beta\}$ $\text{return } new\ node(j, \beta, \text{GROWTREE}(S_L), \text{GrowTree}(S_R))$