LERa Module

Instruction

Cut a tomato slice, refrigerate it, place it on a sponge

Current Task Plan

open(fridge)

put(fridge)
close(fridge)
open(fridge)

pick_up(tomatosliced)
 close(fridge)

move(sidetable) put(sidetable)

Observation



Look

The robot attempted to perform the open("fridge") action. It failed. Explain why.

VLM

The image you provided shows a fridge that is already open.
Therefore, the robot cannot open it again.

Explain

What would be the **correct plan** to accomplish the goal if the first step of the current plan failed?

VLM

- 1. The **first step** of the current plan **has failed** because **the fridge is already open**.
- 2. The next step would be to put the tomato slice in the fridge and close the fridge door, since the robot cannot open it any further.

Replan

What is **correct plan**? Description:

1. The first step of the current plan has failed because the fridge is already open...

VLM

put(fridge)

close(fridge)

open(fridge)

pick_up(tomatosliced)

close(fridge)

move(sidetable)

put(sidetable)