

# Integrating Factors for Linear Systems

*Exponential solution formula for linear systems of differential equations*

## Objectives

To generalize the integrating factor method from one linear differential equation to systems of linear differential equations. We will need to use several properties of the exponential of a function discussed in a previous Dive.

## Introduction

The integrating factor method is a way to find solutions to a linear differential equation

$$y' = a y + b,$$

where  $a, b$  are constants. One multiplies the equation above by the integrating factor

$$\mu(t) = e^{-at},$$

then we get

$$e^{-at} y' - a e^{-at} y = e^{-at} b.$$

But the left-side is a total derivative,

$$(e^{-at} y)' = e^{-at} b,$$

which leads us to the final formula

$$e^{-at} y(t) - y(0) = \int_0^t e^{-a\tau} b d\tau \quad \Rightarrow \quad e^{-at} y(t) - y(0) = -\frac{b}{a} e^{-at} + \frac{b}{a}.$$

Then we get that

$$y(t) = \left( y(0) + \frac{b}{a} \right) e^{at} - \frac{b}{a}.$$

The idea of this project is to *generalize* this solution formula to *systems* of linear differential equations.

## Further Reading

Students may need to read Section 6.3, “General Linear Systems” and Section 6.4, “Solutions Formulas” in our textbook. Make sure you download the last version of our textbook.

## Homogeneous Systems

**Question 1:** (*20 points*) Generalize the integrating factor method used to solve linear scalar equations to prove the following statement: If  $A$  is an  $n \times n$  matrix and  $\mathbf{x}_0$  is an  $n$ -vector, then the initial value problem

$$\mathbf{x}'(t) = A \mathbf{x}(t), \quad \mathbf{x}(0) = \mathbf{x}^0$$

has a unique solution given by

$$\mathbf{x}(t) = e^{At} \mathbf{x}^0.$$

**Note:** Highlight every property of the matrix exponential you use in your proof.

**Question 2:** (20 points) In the case that an  $n \times n$  matrix  $A$  is diagonalizable, with eigenpairs given by  $\lambda_i, \mathbf{v}_i$ , for  $i = 1, \dots, n$ , we know that the general solution of the linear system

$$\mathbf{x}'(t) = A \mathbf{x}(t)$$

is given by

$$\mathbf{x}(t) = c_1 e^{\lambda_1 t} \mathbf{v}_1 + \dots + c_n e^{\lambda_n t} \mathbf{v}_n.$$

Use this formula for the general solution to show that the unique solution of the initial value problem

$$\mathbf{x}'(t) = A \mathbf{x}(t), \quad \mathbf{x}(0) = \mathbf{x}^o$$

can actually be written in the way given in the question above, that is,

$$\mathbf{x}(t) = e^{At} \mathbf{x}^o.$$

**Question 3:** (20 points) Compute the exponential function  $e^{At}$  and use it to express the vector-valued function  $\mathbf{x}(t)$  solution to the initial value problem

$$\mathbf{x}' = A \mathbf{x}, \quad A = \begin{bmatrix} -1 & 4 \\ 4 & -1 \end{bmatrix}, \quad \mathbf{x}(0) = \mathbf{x}^0 = \begin{bmatrix} x_1^0 \\ x_2^0 \end{bmatrix}.$$



## Non-Homogeneous Systems

**Question 4:** (20 points) Prove that the integrating factor method can be generalized to non-homogeneous linear differential systems, that is, prove the following: If  $A$  is an  $n \times n$  *invertible* matrix,  $\mathbf{x}^0$  is an  $n$ -vector, and  $\mathbf{b}$  is a constant  $n$ -vector, then the initial value problem

$$\mathbf{x}'(t) = A \mathbf{x}(t) + \mathbf{b}, \quad \mathbf{x}(0) = \mathbf{x}^0$$

has a unique solution given by

$$\mathbf{x}(t) = e^{At} (\mathbf{x}^0 + A^{-1} \mathbf{b}) - A^{-1} \mathbf{b}.$$

**Note:** Mention very carefully every property of the matrix exponential you use on each step of your proof.

**Question 5:** (20 points) Find the vector-valued solution  $\mathbf{x}(t)$  to the differential system

$$\mathbf{x}' = A \mathbf{x} + \mathbf{b}, \quad \mathbf{x}(0) = \begin{bmatrix} 2 \\ 3 \end{bmatrix}, \quad A = \begin{bmatrix} -1 & 4 \\ 4 & -1 \end{bmatrix}, \quad \mathbf{b} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}.$$