## Coordinate Systems and Vector Derivatives Formula Sheet

## Rectangular (Cartesian) Coordinates (x, y, z)

 $d\vec{\ell} = \hat{x} dx + \hat{y} dy + \hat{z} dz$ Line element:

 $d\tau = dx dy dz$ Volume element:

 $\vec{\nabla} f = \frac{\partial f}{\partial x} \hat{x} + \frac{\partial f}{\partial y} \hat{y} + \frac{\partial f}{\partial z} \hat{z}$ Gradient:

 $\vec{\nabla} \cdot \vec{v} = \frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} + \frac{\partial v_z}{\partial z}$ Divergence:

 $\vec{\nabla} \times \vec{v} \, = \, \left( \frac{\partial v_z}{\partial u} - \frac{\partial v_y}{\partial z} \right) \hat{x} + \left( \frac{\partial v_x}{\partial z} - \frac{\partial v_z}{\partial x} \right) \hat{y} + \left( \frac{\partial v_y}{\partial x} - \frac{\partial v_x}{\partial y} \right) \hat{z}$ Curl:

 $\nabla^2 f = \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial x^2}$ Laplacian:

## Spherical Coordinates $(r, \theta, \phi)$

Relations to rectangular (Cartesian) coordinates and unit vectors:

 $\hat{x} = \hat{r}\sin\theta\cos\phi + \hat{\theta}\cos\theta\cos\phi - \hat{\phi}\sin\phi$  $x = r \sin \theta \cos \phi$ 

 $\hat{y} = \hat{r}\sin\theta\sin\phi + \hat{\theta}\cos\theta\sin\phi + \hat{\phi}\cos\phi$  $y = r \sin \theta \sin \phi$ 

 $\hat{z} = \hat{r}\cos\theta - \hat{\theta}\sin\theta$  $z = r \cos \theta$ 

 $\begin{array}{ll} r = \sqrt{x^2 + y^2 + z^2} & \hat{r} = \hat{x} \sin \theta \cos \phi + \hat{y} \sin \theta \sin \phi + \hat{z} \cos \theta \\ \theta = \tan^{-1}(\sqrt{x^2 + y^2}/z) & \hat{\theta} = \hat{x} \cos \theta \cos \phi + \hat{y} \cos \theta \sin \phi - \hat{z} \sin \theta \\ \phi = \tan^{-1}(y/x) & \hat{\phi} = -\hat{x} \sin \phi + \hat{y} \cos \phi \end{array}$ 

 $d\vec{\ell} = \hat{r} dr + \hat{\theta} r d\theta + \hat{\phi} r \sin \theta d\phi$ Line element:

 $d\tau = r^2 \sin\theta \, dr \, d\theta \, d\phi$ Volume element:

 $\vec{\nabla}f = \frac{\partial f}{\partial r}\hat{r} + \frac{1}{r}\frac{\partial f}{\partial \theta}\hat{\theta} + \frac{1}{r\sin\theta}\frac{\partial f}{\partial \phi}\hat{\phi}$ Gradient:

 $\vec{\nabla} \cdot \vec{v} = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 v_r) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\sin \theta \, v_\theta) + \frac{1}{r \sin \theta} \frac{\partial v_\phi}{\partial \phi}$ Divergence:

 $\vec{\nabla} \times \vec{v} = \frac{1}{r \sin \theta} \left[ \frac{\partial}{\partial \theta} (\sin \theta \, v_{\phi}) - \frac{\partial v_{\theta}}{\partial \phi} \right] \hat{r} + \frac{1}{r} \left[ \frac{1}{\sin \theta} \frac{\partial v_{r}}{\partial \phi} - \frac{\partial}{\partial r} (r \, v_{\phi}) \right] \hat{\theta}$ Curl:  $+\frac{1}{\pi}\left[\frac{\partial}{\partial r}(r\,v_{\theta})-\frac{\partial v_{r}}{\partial \theta}\right]\hat{\phi}$ 

 $\nabla^2 f = \frac{1}{r} \frac{\partial^2}{\partial r^2} (rf) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left( \sin \theta \frac{\partial f}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 f}{\partial \phi^2}$ Laplacian:

## Cylindrical Coordinates $(r, \phi, z)$

Relations to rectangular (Cartesian) coordinates and unit vectors:

$$\begin{array}{ll} x = r\cos\phi & \hat{x} = \hat{r}\cos\phi - \hat{\phi}\sin\phi \\ y = r\sin\phi & \hat{y} = \hat{r}\sin\phi + \hat{\phi}\cos\phi \\ z = z & \hat{z} = \hat{z} \end{array}$$

$$r = \sqrt{x^2 + y^2}$$

$$\phi = \tan^{-1}(y/x)$$

$$\hat{r} = \hat{x}\cos\phi + \hat{y}\sin\phi$$

$$\hat{\phi} = -\hat{x}\sin\phi + \hat{y}\cos\phi$$

$$\hat{z} = \hat{z}$$

Line element:  $d\vec{\ell} = \hat{r} dr + \hat{\phi} r d\phi + \hat{z} dz$ 

Volume element:  $d\tau = r dr d\phi dz$ 

Gradient: 
$$\vec{\nabla} f = \frac{\partial f}{\partial r} \hat{r} + \frac{1}{r} \frac{\partial f}{\partial \phi} \hat{\phi} + \frac{\partial f}{\partial z} \hat{z}$$

Divergence: 
$$\vec{\nabla} \cdot \vec{v} = \frac{1}{r} \frac{\partial}{\partial r} (rv_r) + \frac{1}{r} \frac{\partial v_{\phi}}{\partial \phi} + \frac{\partial v_z}{\partial z}$$

Curl: 
$$\vec{\nabla} \times \vec{v} = \left[ \frac{1}{r} \frac{\partial v_z}{\partial \phi} - \frac{\partial v_\phi}{\partial z} \right] \hat{r} + \left[ \frac{\partial v_r}{\partial z} - \frac{\partial v_z}{\partial r} \right] \hat{\phi} + \frac{1}{r} \left[ \frac{\partial}{\partial r} (rv_\phi) - \frac{\partial v_r}{\partial \phi} \right] \hat{z}$$