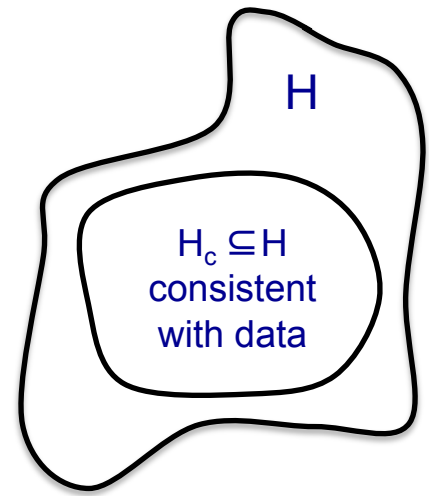


How big should your validation set be?

- In PS1, you tried many configurations of your algorithms (avg vs. regular perceptron, max # of iterations) and chose the one that had smallest validation error
- Suppose in total you tested $|H|=40$ different classifiers on the validation set of m held-out e-mails
- The best classifier obtains 98% accuracy on these m e-mails!!!
- But, what is the true classification accuracy?
- How large does m need to be so that we can guarantee that the best configuration (measured on validate) is truly good?

A simple setting...



- Classification
 - m data points
 - **Finite** number of possible hypothesis (e.g., 40 spam classifiers)
- A learner finds a hypothesis h that is **consistent** with training data
 - Gets zero error in training: $error_{train}(h) = 0$
 - I.e., assume for now that one of the classifiers gets 100% accuracy on the m e-mails (we'll handle the 98% case afterward)
- What is the probability that h has more than ϵ **true** error?
 - $error_{true}(h) \geq \epsilon$

How likely is a **bad** hypothesis to get m data points right?

- Hypothesis h that is **consistent** with validate data
 - got m i.i.d. points right
 - h “bad” if it gets all this data right, but has high true error
 - What is the probability of this happening?
- Probability that h with $\text{error}_{\text{true}}(h) \geq \epsilon$ classifies a randomly drawn data point correctly:
 1. $\Pr(h \text{ gets data point } \textit{wrong} \mid \text{error}_{\text{true}}(h) = \epsilon) = \epsilon$ E.g., probability of a biased coin coming up tails
 2. $\Pr(h \text{ gets data point } \textit{wrong} \mid \text{error}_{\text{true}}(h) \geq \epsilon) \geq \epsilon$
 3. $\Pr(h \text{ gets data point } \textit{right} \mid \text{error}_{\text{true}}(h) \geq \epsilon) = 1 - \Pr(h \text{ gets data point } \textit{wrong} \mid \text{error}_{\text{true}}(h) \geq \epsilon) \leq 1 - \epsilon$
- Probability that h with $\text{error}_{\text{true}}(h) \geq \epsilon$ gets m iid data points correct:
$$\Pr(h \text{ gets } m \textit{ iid data points right} \mid \text{error}_{\text{true}}(h) \geq \epsilon) \leq (1-\epsilon)^m \leq e^{-\epsilon m}$$

E.g., probability of m biased coins coming up heads

Are we done?

$$\Pr(h \text{ gets } m \text{ iid data points right} \mid \text{error}_{\text{true}}(h) \geq \varepsilon) \leq e^{-\varepsilon m}$$

- Says “if h gets m data points correct, then with very high probability (i.e. $1 - e^{-\varepsilon m}$) it is close to perfect (i.e., will have error $\leq \varepsilon$)”
- This only considers **one** hypothesis!
- Suppose 1 billion classifiers were tried, and each was a *random* function
- For **m** small enough, one of the functions will classify all points correctly – but all have very large true error

How likely is learner to pick a bad hypothesis?

$$\Pr(h \text{ gets } m \text{ iid data points right} \mid \text{error}_{\text{true}}(h) \geq \varepsilon) \leq e^{-\varepsilon m}$$

Suppose there are $|H_c|$ hypotheses consistent with the m data points

- How likely is learner to pick a bad one, i.e. with *true* error $\geq \varepsilon$?
- We need a bound that holds for all of them!

$$P(\text{error}_{\text{true}}(h_1) \geq \varepsilon \text{ OR } \text{error}_{\text{true}}(h_2) \geq \varepsilon \text{ OR } \dots \text{ OR } \text{error}_{\text{true}}(h_{|H_c|}) \geq \varepsilon)$$

$$\leq \sum_k P(\text{error}_{\text{true}}(h_k) \geq \varepsilon) \quad \leftarrow \text{Union bound}$$

$$\leq \sum_k (1-\varepsilon)^m \quad \leftarrow \text{bound on individual } h_j\text{s}$$

$$\leq |H|(1-\varepsilon)^m \quad \leftarrow |H_c| \leq |H|$$

$$\leq |H| e^{-m\varepsilon} \quad \leftarrow (1-\varepsilon) \leq e^{-\varepsilon} \text{ for } 0 \leq \varepsilon \leq 1$$

Generalization error of finite hypothesis spaces [Haussler '88]

We just proved the following result:

Theorem: Hypothesis space H finite, dataset D with m i.i.d. samples, $0 < \epsilon < 1$: for any learned hypothesis h that is consistent on the training data:

$$P(\text{error}_{\text{true}}(h) > \epsilon) \leq |H|e^{-m\epsilon}$$

Using a PAC bound

Typically, 2 use cases:

- 1: Pick ϵ and δ , compute m
- 2: Pick m and δ , compute ϵ

Argument: Since for all h we know that

$$P(\text{error}_{\text{true}}(h) > \epsilon) \leq |H|e^{-m\epsilon}$$

... with probability $1-\delta$ the following holds... (either case 1 or case 2)

$$p(\text{error}_{\text{true}}(h) \geq \epsilon) \leq |H|e^{-m\epsilon} \leq \delta$$

Says: we are willing to tolerate a δ probability of having $\geq \epsilon$ error

$$\epsilon = \delta = .01, |H| = 40$$

$$\text{Need } m \geq 830$$

$$\ln(|H|e^{-m\epsilon}) \leq \ln \delta$$

$$\ln |H| - m\epsilon \leq \ln \delta$$

Case 1

$$m \geq \frac{\ln |H| + \ln \frac{1}{\delta}}{\epsilon}$$

Log dependence on $|H|$,
OK if exponential size (but
not doubly)

ϵ has stronger
influence than δ

Case 2

$$\epsilon \geq \frac{\ln |H| + \ln \frac{1}{\delta}}{m}$$

ϵ shrinks at rate $O(1/m)$

Limitations of Haussler '88 bound

- There may be no consistent hypothesis h (where $error_{train}(h)=0$)
- Size of hypothesis space
 - What if $|H|$ is really big?
 - What if it is continuous?
- **First Goal:** Can we get a bound for a learner with $error_{train}(h)$ in the data set?

Question: What's the expected error of a hypothesis?

- The probability of a hypothesis incorrectly classifying: $\sum_{(\vec{x}, y)} p(\vec{x}, y) 1[h(\vec{x}) \neq y]$
- Let's now let Z_i^h be a random variable that takes two values, 1 if h correctly classifies data point i , and 0 otherwise
- The Z variables are **independent** and **identically distributed** (i.i.d.) with

$$\Pr(Z_i^h = 0) = \sum_{(\vec{x}, y)} p(\vec{x}, y) 1[h(\vec{x}) \neq y]$$

- Estimating the true error probability is like estimating the parameter of a coin!
- **Chernoff bound:** for m i.i.d. coin flips, X_1, \dots, X_m , where $X_i \in \{0, 1\}$. For $0 < \epsilon < 1$:

$$P\left(\theta - \frac{1}{m} \sum_i x_i > \epsilon\right) \leq e^{-2m\epsilon^2}$$

True error
probability

Observed fraction of
points incorrectly classified

$$p(X_i = 1) = \theta$$

$$E\left[\frac{1}{m} \sum_{i=1}^m X_i\right] = \frac{1}{m} \sum_{i=1}^m E[X_i] = \theta$$

(by linearity of expectation)

Generalization bound for $|H|$ hypothesis

Theorem: Hypothesis space H finite, dataset D with m i.i.d. samples, $0 < \epsilon < 1$: for any learned hypothesis h :

$$\Pr(\text{error}_{\text{true}}(h) - \text{error}_D(h) > \epsilon) \leq |H|e^{-2m\epsilon^2}$$

Why? Same reasoning as before. Use the Union bound over individual Chernoff bounds

PAC bound and Bias-Variance tradeoff

for all h , with probability at least $1-\delta$:

$$\text{error}_{\text{true}}(h) \leq \underbrace{\text{error}_D(h)}_{\text{"bias"}} + \underbrace{\sqrt{\frac{\ln |H| + \ln \frac{1}{\delta}}{2m}}}_{\text{"variance"}}$$

- For large $|H|$
 - low bias (assuming we can find a good h)
 - high variance (because bound is looser)
- For small $|H|$
 - high bias (is there a good h ?)
 - low variance (tighter bound)

PAC bound: How much data?

$$\Pr(\text{error}_{\text{true}}(h) - \text{error}_D(h) > \epsilon) \leq |H|e^{-2m\epsilon^2}$$

$$\text{error}_{\text{true}}(h) \leq \text{error}_D(h) + \sqrt{\frac{\ln |H| + \ln \frac{1}{\delta}}{2m}}$$

- Given δ, ϵ how big should m be?

$$m \geq \frac{1}{2\epsilon^2} \left(\ln |H| + \ln \frac{1}{\delta} \right)$$