

## Assembly Level Program 1a – Binary Search

Write an Assembly Level Program to search a key element in a list of 'n' 16-bit numbers using the Binary Search Algorithm.

### Program

```
.model SMALL

.data
    ARRAY dw    1234h, 2345h, 3456h, 4567h, 5678h, 6789h
    LEN    dw    ($-ARRAY)/2
    KEY    dw    6789h

    STR1   db    10, 13, 'Element Found at Position '
    POS    db    ?, 10, 13, '$'
    STR2   db    10, 13, 'Element Not Found!$'

.code

    ; Initialize Data Segment
    MOV AX, @DATA
    MOV DS, AX

    ; Clear AX Register
    MOV AX, 00h

    MOV CX, LEN
    MOV DX, KEY

Search:
    CMP CX, AX
    JB NotFound

    MOV BX, CX
    ADD BX, AX
    SHR BX, 01h ; Divides by 2

    MOV SI, BX
    SHL SI, 01h ; Multiply with 2
```

```
CMP ARRAY[SI], DX
JB newLow
JE Found
```

```
CMP BX, 00h
JE NotFound
```

newHigh:

```
DEC BX
MOV CX, BX
JMP Search
```

newLow:

```
INC BX
MOV AX, BX
JMP Search
```

Found:

```
INC BL
MOV POS, BL
LEA DX, STR1
JMP Display
```

NotFound:

```
LEA DX, STR2
```

Display:

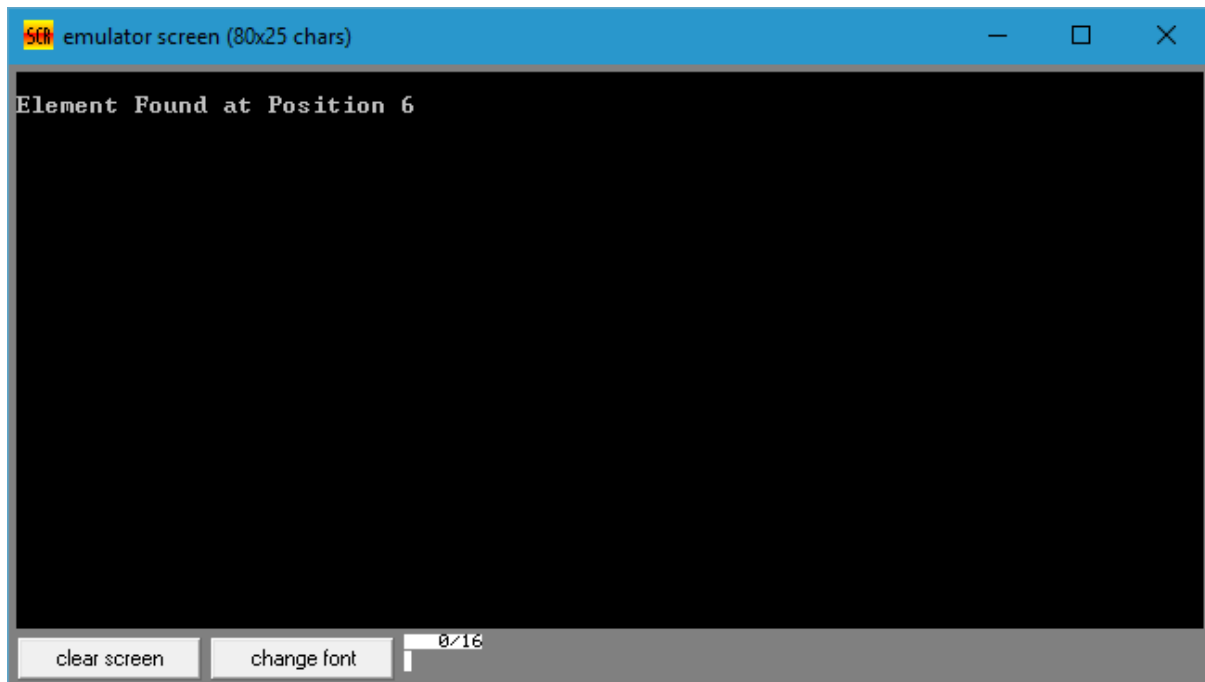
```
; Display Message
MOV AH, 09h
INT 21h
```

Exit:

```
; Terminate the Program
MOV AH, 4Ch
INT 21h
```

END

## Output



## Assembly Level Program 1b – Parity Checker

Read the status of eight input bits from the Logic Controller Interface and display 'FF' if it is the parity of the input read is even; otherwise display 00.

### Program

```
.model SMALL
```

```
.data
```

```
PA    EQU    0E400h
PB    EQU    0E401h
PC    EQU    0E402h
CR    EQU    0E403h
CW    dB     82h
```

```
M1    dB     10, 13, 'Select an 8-bit Number from the Logic Controller
Interface...$'
```

```
.code
```

```
; Initialize Data Segment
MOV AX, @DATA
MOV DS, AX
```

```
; Set Control Word Format
MOV DX, CR
MOV AL, CW
OUT DX, AL
```

```
; Display Message
LEA DX, M1
MOV AH, 09h
INT 21h
```

```
; Take Input from Logic Controller Interface
MOV DX, PB
IN AL, DX
```

```
; Dummy Operation to Set Flags  
OR AL, AL  
JP0 OddParity
```

```
; IF Even Parity  
MOV DX, PA  
MOV AL, 0FFh  
OUT DX, AL  
JMP Exit
```

OddParity:

```
; IF Odd Parity  
MOV DX, PA  
MOV AL, 00h  
OUT DX, AL
```

Exit:

```
; Terminate the Program  
MOV AH, 4Ch  
INT 21h
```

END

## Assembly Level Program 2a – Reading & Printing String

Write 2 ALP modules stored in two different files; one module is to read a character from the keyboard and the other one is to display a character. Use the above two modules to read a string of characters from the keyboard terminated by the carriage return and print the string on the display in the next line.

### PrintCharacter.inc

```
PRINTCH MACRO CHAR
    MOV DL, CHAR
    MOV AH, 02h
    INT 21h
ENDM
```

### ReadCharacter.inc

```
READCH MACRO
    MOV AH, 01h
    INT 21h
ENDM
```

### Program

```
.model SMALL

Include ReadCharacter.inc
Include PrintCharacter.inc

.data
    LOC    dB    100    DUP(0)
    STR1   dB    10, 13, 'Enter a String: $'
    STR2   dB    10, 13, 'Entered String is: $'

.code
    ; Initialize Data Segment
    MOV AX, @DATA
    MOV DS, AX
```

```
; Clear Counter Register
MOV CX, 00h

; Display Message
LEA DX, STR1
MOV AH, 09h
INT 21h

; Point SI to First Position of LOC
LEA SI, LOC
```

Read:

```
; Call READCH Macro
READCH

; Check if Return/Enter Key was pressed
CMP AL, 0Dh
JE Display

MOV [SI], AL
INC SI
INC CL
JMP Read
```

Display:

```
; Display Message
LEA DX, STR2
MOV AH, 09h
INT 21h

; Point SI to First Position of LOC
LEA SI, LOC
```

Print:

```
; Call PRINTCH Macro
PRINTCH [SI]
INC SI
Loop Print
```

Exit:

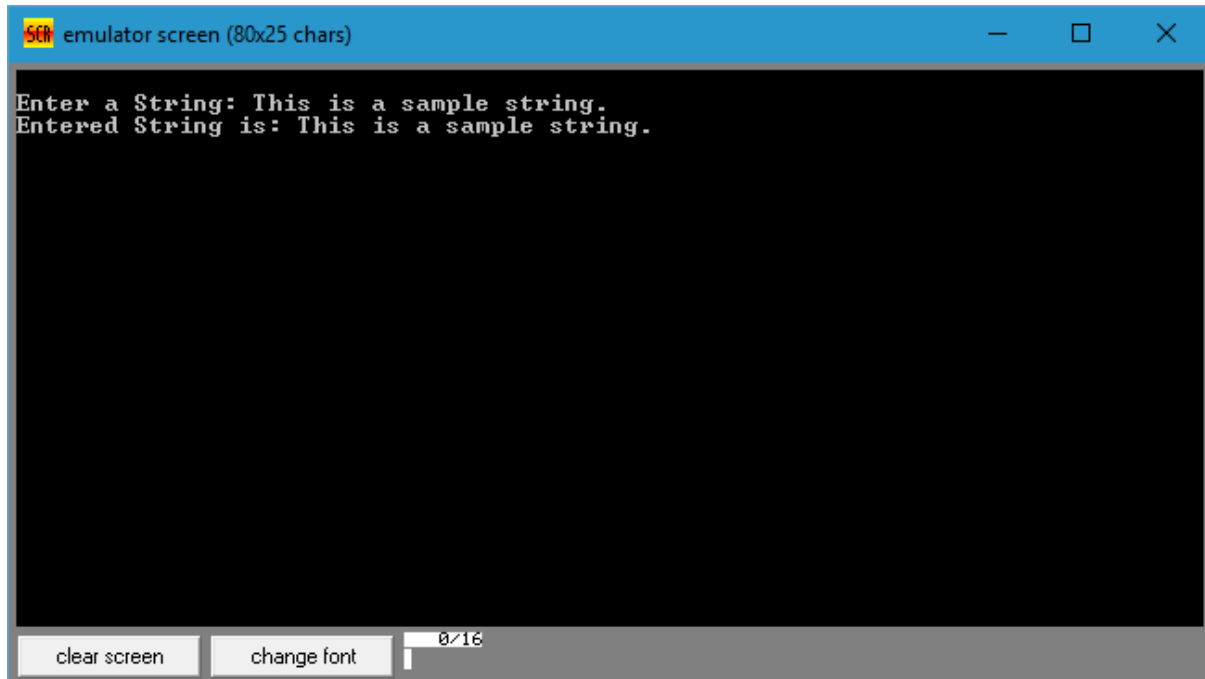
    ; Terminate the Program

    MOV AH, 4Ch

    INT 21h

END

## Output





## Assembly Level Program 2b – BCD Up/Down Counter

Implement a BCD Up-Down Counter on the Logic Controller Interface.

### Program

```
.model SMALL

.data
    PA    EQU    0E400h
    PB    EQU    0E401h
    PC    EQU    0E402h
    CR    EQU    0E403h
    CW    dB     80h

.code
    ; Initialize Data Segment
    MOV AX, @DATA
    MOV DS, AX

    ; Set Control Word Format
    MOV DX, CR
    MOV AL, CW
    OUT DX, AL

    ; Set Counter to 00
    MOV DX, PA
    MOV AL, 00h

UpCounter:
    OUT DX, AL
    CALL Delay

    INC AL
    ; Decimal Adjust AL after Addition
    DAA

    CMP AL, 00h
    JNZ UpCounter
```

```
; Set Counter to 99
MOV DX, PA
MOV AL, 99h
```

DownCounter:

```
OUT DX, AL
CALL Delay

DEC AL
; Decimal Adjust AL after Subtraction
DAS

CMP AL, 99h
JNZ DownCounter
```

Exit:

```
; Terminate the Program
MOV AH, 4Ch
INT 21h
```

Delay PROC NEAR

```
MOV SI, 0FFFFh
Loop1:
MOV DI, 04FFFh
Loop2:
DEC DI
JNZ Loop2
DEC SI
JNZ Loop1
RET
```

Delay ENDP

END

## Assembly Level Program 3a – Bubble Sort

Write an Assembly Level Program to sort a given set of 'n' numbers in ascending and descending orders using the Bubble Sort algorithm.

### Program

```
.model SMALL

.data
    ARRAY dB    05h, 07h, 06h, 04h, 0Ah, 09h
    LEN    dB    $-ARRAY

.code
    ; Initialize Data Segment
    MOV AX, @DATA
    MOV DS, AX

    ; Clear Counter Register
    MOV CX, 00h

    MOV CL, LEN
    DEC CL

OuterLoop:
    MOV BX, CX

    ; Point SI to First Position of ARRAY
    LEA SI, ARRAY

InnerLoop:
    MOV AL, [SI]
    INC SI
    CMP [SI], AL
    JAE NoSwap

    XCHG [SI], AL
    MOV [SI-1], AL
```

NoSwap:

DEC BX

JNZ InnerLoop

LOOP OuterLoop

Exit:

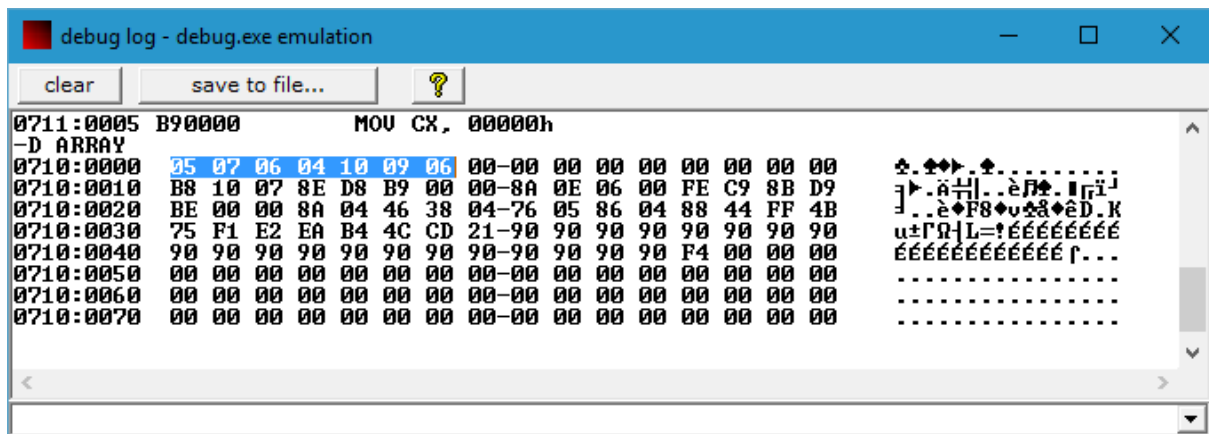
; Terminate the Program

MOV AH, 4Ch

INT 21h

END

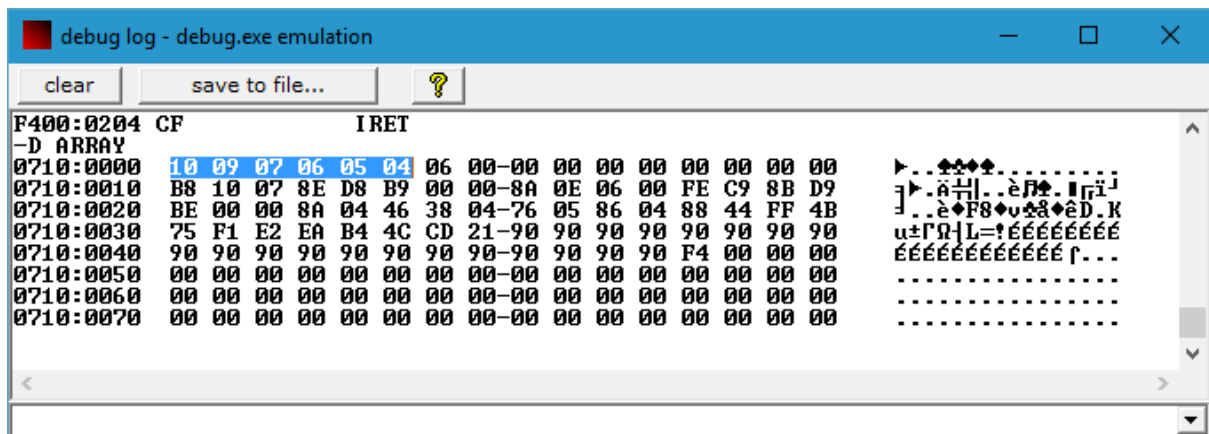
## Output



```

debug log - debug.exe emulation
clear save to file... ?
0711:0005 B90000 MOV CX, 000000h
-D ARRAY
0710:0000 05 07 06 04 10 09 06 00-00 00 00 00 00 00 00 00 00
0710:0010 B8 10 07 8E D8 B9 00 00-8A 0E 06 00 FE C9 8B D9
0710:0020 BE 00 00 8A 04 46 38 04-76 05 86 04 88 44 FF 4B
0710:0030 75 F1 E2 EA B4 4C CD 21-90 90 90 90 90 90 90
0710:0040 90 90 90 90 90 90 90 90-90 90 90 F4 00 00 00
0710:0050 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00
0710:0060 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00
0710:0070 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00

```



```

debug log - debug.exe emulation
clear save to file... ?
F400:0204 CF IRET
-D ARRAY
0710:0000 10 09 07 06 05 04 06 00-00 00 00 00 00 00 00 00
0710:0010 B8 10 07 8E D8 B9 00 00-8A 0E 06 00 FE C9 8B D9
0710:0020 BE 00 00 8A 04 46 38 04-76 05 86 04 88 44 FF 4B
0710:0030 75 F1 E2 EA B4 4C CD 21-90 90 90 90 90 90 90
0710:0040 90 90 90 90 90 90 90 90-90 90 90 F4 00 00 00
0710:0050 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00
0710:0060 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00
0710:0070 00 00 00 00 00 00 00 00-00 00 00 00 00 00 00

```

## Assembly Level Program 3b – Read & Multiply from LCI

Read the status of two 8-bit inputs (X & Y) from the Logic Controller Interface and display X\*Y.

### Program

```
.model SMALL
```

```
.data
```

```
PA    EQU    0E400h
PB    EQU    0E401h
PC    EQU    0E402h
CR    EQU    0E403h
CW    dB     80h
```

```
M1    dB     10, 13, 'Enter the first 8-bit Number...$'
M2    dB     10, 13, 'Enter the second 8-bit Number...$'
```

```
.code
```

```
; Initialize Data Segment
MOV AX, @DATA
MOV DS, AX
```

```
; Set Control Word Format
MOV DX, CR
MOV AL, CW
OUT DX, AL
```

```
; Display Message
LEA DX, M1
MOV AH, 09h
INT 21h
```

```
; Read Input from Keyboard, without Echo
MOV AH, 08h
INT 21h
```

```
; Read Input from Logic Controller Interface
MOV DX, PB
IN AL, DX
```

```
MOV BL, AL
```

```
; Display Message
LEA DX, M1
MOV AH, 09h
INT 21h
```

```
; Read Input from Keyboard, without Echo
MOV AH, 08h
INT 21h
```

```
; Read Input from Logic Controller Interface
MOV DX, PB
IN AL, DX
```

```
; Multiply BL x AL
MUL BL
```

```
; Display First Byte of AX (AL)
MOV DX, PA
OUT DX, AL
```

```
CALL Delay
```

```
; Display Last Byte of AX (AH)
MOV DX, PA
MOV AL, AH
OUT DX, AL
```

Exit:

```
; Terminate the Program
MOV AH, 4Ch
INT 21h
```

Delay PROC NEAR

MOV SI, 0FFFFh

Loop1:

MOV DI, 04FFFh

Loop2:

DEC DI

JNZ Loop2

DEC SI

JNZ Loop1

RET

Delay ENDP

END

## Assembly Level Program 4a – ASCII Code

Write an Assembly Level Program to read an alphanumeric character and display its equivalent ASCII code at the center of the screen.

### Program

```
.model SMALL

.data
    MSG1  db    10, 13, 'Enter an alphanumeric character: $'

.code

    ; Initialize Data Segment
    MOV AX, @DATA
    MOV DS, AX

    ; Clear Screen
    MOV AH, 00h
    MOV AL, 03h
    INT 10h

    ; Print Message in Data Segment
    LEA DX, MSG1
    MOV AH, 09h
    INT 21h

    ; Read Character from User
    MOV AH, 01h
    INT 21h

    MOV AH, 00h
    MOV BX, 10d
    PUSH BX
```



## Conversion:

`MOV DX, 00h``DIV BX``PUSH DX``CMP AX, 00h``JNE Conversion``; Set Cursor to Center of the Screen``MOV AH, 02h``MOV BH, 00h``MOV DH, 12d``MOV DL, 39d``INT 10H`

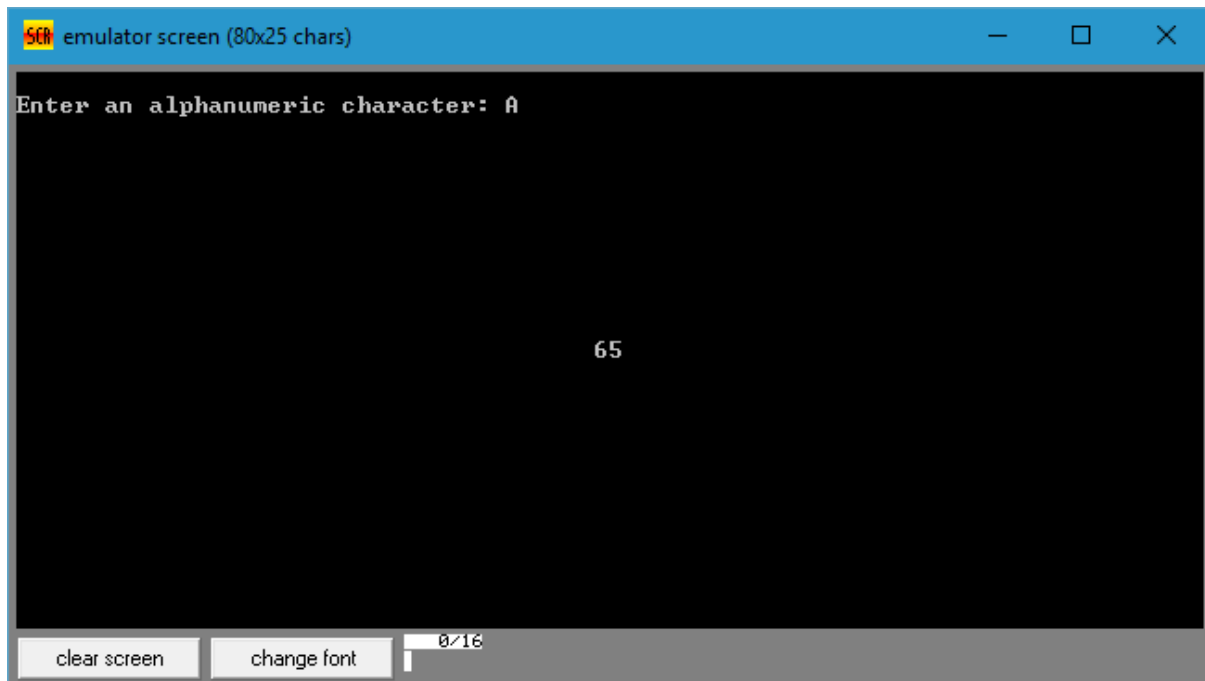
## Display:

`POP DX``CMP DX, 10``JE Exit``ADD DL, 30h``MOV AH, 02h``INT 21h``JMP Display`

## Exit:

`; Terminate the Program``MOV AH, 4Ch``INT 21h``END`

## Output



## Assembly Level Program 4b – Fire & Help Display

Display messages FIRE and HELP alternately with flickering effects on a 7-segment display interface for a suitable period of time. Ensure a flashing rate that makes it easy to read both the messages (Examiner does not specify these delay values nor is it necessary for the student to compute these values).

### Program

```
.model SMALL
```

```
.data
```

```
PA    EQU    0E400h
PB    EQU    0E401h
PC    EQU    0E402h
CR    EQU    0E403h
CW    dB     80h
```

```
M1    dB     86h, 0AFh, 0F9h, 8Eh    ; E, R, I, F
M2    dB     8Ch, 0C7h, 86h, 89h    ; P, L, E, H
```

```
.code
```

```
    ; Initialize Data Segment
    MOV AX, @DATA
    MOV DS, AX
```

```
    ; Set Control Word Format
    MOV DX, CR
    MOV AL, CW
    OUT DX, AL
```

```
Looper:
```

```
    ; Point SI to First Position of M1
    LEA SI, M1
```

```
    CALL Display
    CALL Delay
```

```
; Point SI to First Position of M2  
LEA SI, M2
```

```
CALL Display  
CALL Delay
```

```
; Wait for User Keyboard Input Interrupt  
MOV AH, 01h  
INT 16h  
JZ Looper
```

Exit:

```
; Terminate the Program  
MOV AH, 4Ch  
INT 21h
```

Display PROC NEAR

```
; Each Message Contains 4 Bytes  
MOV CX, 04h
```

L2:

```
; Each Character Contains 8 Bits  
MOV BL, 08h  
MOV AL, [SI]
```

L1:

```
; Rotate AL without Carry  
ROL AL, 01h  
MOV DX, PB  
OUT DX, AL
```

PUSH AX

```
; Toggle 0 to Port C  
MOV DX, PC  
MOV AL, 00h  
OUT DX, AL
```

```
        ; Toggle 1 to Port C
        MOV DX, PC
        MOV AL, 01h
        OUT DX, AL

        POP AX

        DEC BL
        JNZ L1

        INC SI
        LOOP L2

        RET
Display ENDP

Delay PROC NEAR
        MOV SI, 0FFFFh
        Loop1:
        MOV DI, 04FFFh
        Loop2:
        DEC DI
        JNZ Loop2
        DEC SI
        JNZ Loop1
        RET
Delay ENDP

END
```

## Assembly Level Program 5a – Palindrome Checker

Write an ALP to reverse a given string and check whether it is a palindrome or not.

### Program

```
.model SMALL
.data
    BUF1  dB      20d
    LEN1  dB      ?
    STR1  dB      20d    DUP(0)

    RSTR  dB      20d    DUP(0)

    MSG1  dB      10, 13, 'Enter a String: $'
    MSG2  dB      10, 13, 'String is a Palindrome!$'
    MSG3  dB      10, 13, 'String is not a Palindrome!$'

.code
    ; Initialize Data & Extra Segment
    MOV AX, @DATA
    MOV DS, AX
    MOV ES, AX

    ; Display Message
    LEA DX, MSG1
    MOV AH, 09h
    INT 21h

    ; Read String from Keyboard
    LEA DX, BUF1
    MOV AH, 0Ah
    INT 21h

    ; Point SI to First Position of STR1
    LEA SI, STR1
    ; Decrement to Skip Reading 0Dh
    DEC SI
```

```
; Clear and Set Counter Register
MOV CX, 00h
MOV CL, LEN1

; Point DI to Last Position of STR1
ADD SI, CX
MOV DI, SI

; Point SI to First Position of RSTR
LEA SI, RSTR
```

CopyString:

```
MOV AL, [DI]
MOV [SI], AL
INC SI
DEC DI
LOOP CopyString

; Point SI to First Position of STR1
LEA SI, STR1
; Point DI to First Position of STR1
LEA DI, RSTR

; Clear and Set Counter Register
MOV CX, 00h
MOV CL, LEN1

; Clear Direction Flag
CLD

; Repeatedly Compare String Byte-by-Byte
REPE CMPSB
JE Palindrome

; Display Message
LEA DX, MSG3
MOV AH, 09h
INT 21h
JMP Exit
```

Palindrome:

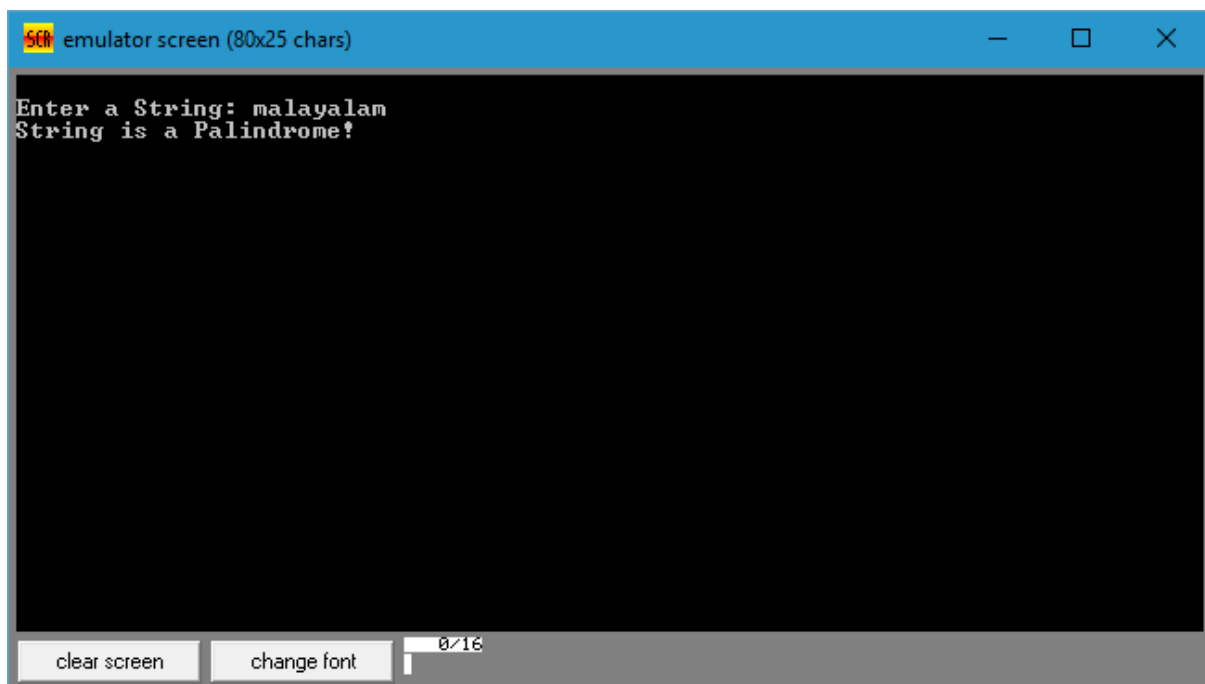
```
; Display Message  
LEA DX, MSG2  
MOV AH, 09h  
INT 21h
```

Exit:

```
; Terminate the Program  
MOV AH, 4Ch  
INT 21h
```

END

## Output





## Assembly Level Program 5b – Rolling LCD Display

Assume any suitable message of 12 characters' length and display it in the rolling fashion on a 7-segment display interface for a suitable period of time. Ensure a flashing rate that makes it easy to read both the messages. (Examiner does not specify these delay values nor is it necessary for the student to compute these values).

### Program

```
.model SMALL
```

```
.data
```

```
PA    EQU    0E400h
PB    EQU    0E401h
PC    EQU    0E402h
CR    EQU    0E403h
CW    dB     80h
```

```
MSG    dB     0FFh, 0FFh, 0FFh, 0FFh, 8Eh, 0F9h,
            88h, 86h, 89h, 86h, 0C7h, 8Ch
```

```
.code
```

```
; Initialize Data Segment
MOV AX, @DATA
MOV DS, AX
```

```
; Set Control Word Format
MOV DX, CR
MOV AL, CW
OUT DX, AL
```

```
Looper:
```

```
; Message Contains 12 Bytes
MOV CX, 12d

; Point SI to First Position of Message
LEA SI, MSG
```

RepeatDisplay:

CALL Display

CALL Delay

INC SI

LOOP RepeatDisplay

; Wait for User Keyboard Input Interrupt

MOV AH, 01h

INT 16h

JZ Looper

Exit:

; Terminate the Program

MOV AH, 4Ch

INT 21h

Display PROC NEAR

; Each Character Contains 8 Bits

MOV BL, 08h

MOV AL, [SI]

L1:

; Rotate AL without Carry

ROL AL, 01h

MOV DX, PB

OUT DX, AL

PUSH AX

; Toggle 0 to Port C

MOV DX, PC

MOV AL, 00h

OUT DX, AL

```
        ; Toggle 1 to Port C
        MOV DX, PC
        MOV AL, 01h
        OUT DX, AL

        POP AX

        DEC BL
        JNZ L1

        RET
Display ENDP

Delay PROC NEAR
        MOV SI, 0FFFFh
        Loop1:
        MOV DI, 04FFFh
        Loop2:
        DEC DI
        JNZ Loop2
        DEC SI
        JNZ Loop1
        RET
Delay ENDP

END
```

## Assembly Level Program 6a – String Equality

Write an ALP to read two strings, store them in locations STR1 and STR2. Check whether they are equal or not and display appropriated messages. Also display the length of the stored strings.

### Program

```
.model SMALL

.data
    BUF1  dB      20d
    LEN1  dB      ?
    STR1  dB      20d DUP(0)

    BUF2  dB      20d
    LEN2  dB      ?
    STR2  dB      20d DUP(0)

    MSG1  dB      10, 13, 'Enter String 1: $'
    MSG2  dB      10, 13, 'Enter String 2: $'

    MSG3  dB      10, 13, 'Length of String 1: $'
    MSG4  dB      10, 13, 'Length of String 2: $'

    MSG5  dB      10, 13, 'Strings are Equal!$'
    MSG6  dB      10, 13, 'Strings are Not Equal!$'

.code
    ; Initialize Data & Extra Segment
    MOV AX, @DATA
    MOV DS, AX
    MOV ES, AX

    ; Display Message
    LEA DX, MSG1
    MOV AH, 09h
    INT 21h
```

```
; Read String from Keyboard
READSTR BUF1

; Display Message
LEA DX, MSG2
MOV AH, 09h
INT 21h

; Read String from Keyboard
READSTR BUF2

; Display Message
LEA DX, MSG3
MOV AH, 09h
INT 21h

; Display Length of First String
MOV AL, LEN1
ADD AL, 30h
MOV AH, 02h
INT 21h

; Display Message
LEA DX, MSG4
MOV AH, 09h
INT 21h

; Display Length of Second String
MOV AL, LEN2
ADD AL, 30h
MOV AH, 02h
INT 21h

; Compare Size of Both Strings
MOV CL, LEN1
CMP CL, LEN2
JNE NotEqual
```

```
; Point SI to First Position of STR1
LEA SI, STR1
; Point DI to First Position of STR2
LEA DI, STR2

; Clear and Set Counter Register
MOV CH, 00h
MOV CL, LEN1

; Clear Direction Flag
CLD

; Repeatedly Compare String Byte-by-Byte
REPE CMPSB
JE Equal
```

NotEqual:

```
; Display Message
LEA DX, MSG6
MOV AH, 09h
INT 21h
JMP Exit
```

Equal:

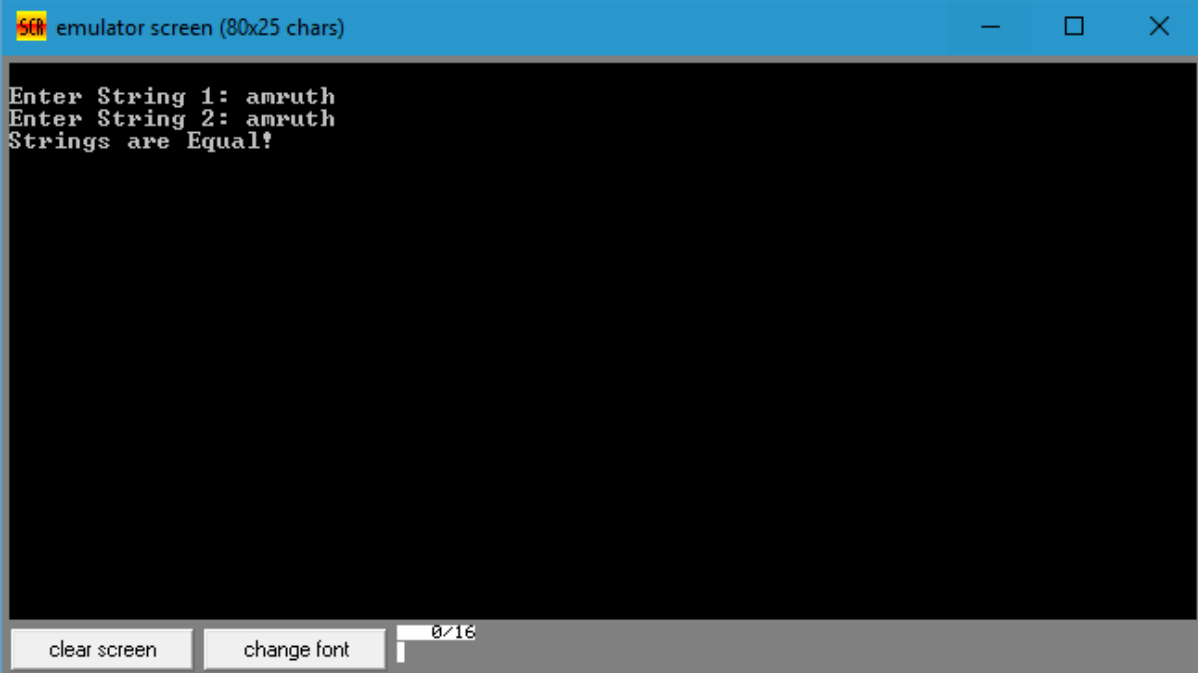
```
; Display Message
LEA DX, MSG5
MOV AH, 09h
INT 21h
```

Exit:

```
; Terminate the Program
MOV AH, 4Ch
INT 21h
```

END

## Output



The screenshot shows a window titled "emulator screen (80x25 chars)". The main area is black with white text. The text displayed is: "Enter String 1: amruth", "Enter String 2: amruth", and "Strings are Equal!". At the bottom, there is a grey bar containing two buttons: "clear screen" and "change font". To the right of these buttons is a small white box containing the text "0/16".

```
emulator screen (80x25 chars)
Enter String 1: amruth
Enter String 2: amruth
Strings are Equal!
clear screen  change font  0/16
```

## Assembly Level Program 6b – BCD Display

Convert a 16-bit binary value (assumed to be an unsigned integer) to BCD and display it from left to right and right to left for specified number of times on a 7-segment display interface.

### Program

```
.model SMALL
```

```
.data
```

```
PA    EQU    0E400h
PB    EQU    0E401h
PC    EQU    0E402h
CR    EQU    0E403h
CW    dB     80h
```

```
BCD    dB     5d    DUP(0)
NUM    dB     0FFFFh ; 65535 in Hexadecimal
TABLE  dB     0C0h, 0FPh, 0A4h, 0B0h, 99h,
              92h, 82h, 0F8h, 80h, 98h
LIST   dB     0FFh, 0FFh, 0FFh, 0FFh, ?, ?, ?, ?, ?,
              0FFh, 0FFh, 0FFh, 0FFh
```

```
.code
```

```
; Initialize Data Segment
MOV AX, @DATA
MOV DS, AX

; Set Control Word Format
MOV DX, CR
MOV AL, CW
OUT DX, AL

; Point SI to First Position of BCD
LEA SI, BCD
MOV AX, NUM
```



```
MOV BX, 10000d
CALL CONV
```

```
MOV BX, 1000d
CALL CONV
```

```
MOV BX, 100d
CALL CONV
```

```
MOV BX, 10d
CALL CONV
```

```
MOV [SI], DL
MOV CX, 05h
```

```
; Point SI to First Position of BCD
LEA SI, BCD
LEA DI, LIST+8
```

Loop1:

```
MOV AL, [SI]
LEA BX, TABLE
XLAT
MOV [DI], AL
INC SI
DEC DI
LOOP Loop1
```

```
MOV BH, 10h
LEA DI, LIST
```

Loop2:

```
MOV SI, DI
CALL Display
CALL Delay
```

```
INC DI
DEC BH
JMP Loop2
```

```
MOV BH, 09H
LEA DI, LIST + 8
```

Loop3:

```
MOV SI,DI
CALL Display
CALL Delay
DEC DI
DEC BH
```

JNZ L3

Exit:

```
; Terminate the Program
MOV AH, 4Ch
INT 21h
```

Convert PROC NEAR

```
XOR DX, DX
DIV BX
MOV [SI], AL
MOV AX, DX
INC SI
RET
```

Convert ENDP

Display PROC NEAR

```
; Each Message Contains 4 Bytes
MOV CX, 04h
```

L2:

```
; Each Character Contains 8 Bits
MOV BL, 08h
MOV AL, [SI]
```

L1:

```
; Rotate AL without Carry
ROL AL, 01h
MOV DX, PB
OUT DX, AL
```

```
        PUSH AX

        ; Toggle 0 to Port C
        MOV DX, PC
        MOV AL, 00h
        OUT DX, AL

        ; Toggle 1 to Port C
        MOV DX, PC
        MOV AL, 01h
        OUT DX, AL

        POP AX

        DEC BL
        JNZ L1

        INC SI
        LOOP L2

        RET
Display ENDP

Delay PROC NEAR
        MOV SI, 0FFFFh
        Loop1:
        MOV DI, 04FFFh
        Loop2:
        DEC DI
        JNZ Loop2
        DEC SI
        JNZ Loop1
        RET
Delay ENDP

END
```

## Assembly Level Program 7a – What Is Your Name?

Write an Assembly Level Program to read your name from the keyboard and display it at a specified location on the screen in front of the message What is your name?

You must clear the entire screen before display.

### Program

```
.model SMALL

.data
    MSG1  dB      10, 13, 'Enter your name: $'
    MSG2  dB      10, 13, 'What is your name? $'

    ARRAY dB      40h    DUP(?)

.code
    ; Initialize Data Segment
    MOV AX, @DATA
    MOV DS, AX

    ; Point SI to First Position of ARRAY
    MOV SI, ARRAY

    ; Display Message
    LEA DX, MSG1
    MOV AH, 09h
    INT 21h

ReadName:
    ; Read Input from Keyboard
    MOV AH, 01h
    INT 21h

    ; Copy Input to ARRAY
    MOV [SI], AL
    INC SI
```

```
; Check for Return/Enter Key
CMP AL, 0Dh
JNZ ReadName

; Add Terminating Character at End of String
MOV [SI], '$'

; Clear Screen
MOV AH, 00h
MOV AL, 03h
INT 10h

; Set Cursor to 2x20
MOV AH, 02h
MOV BH, 00h
MOV DH, 2d
MOV DL, 20d
INT 10h

; Display Message
LEA DX, MSG2
MOV AH, 09h
INT 21h
```

DisplayName:

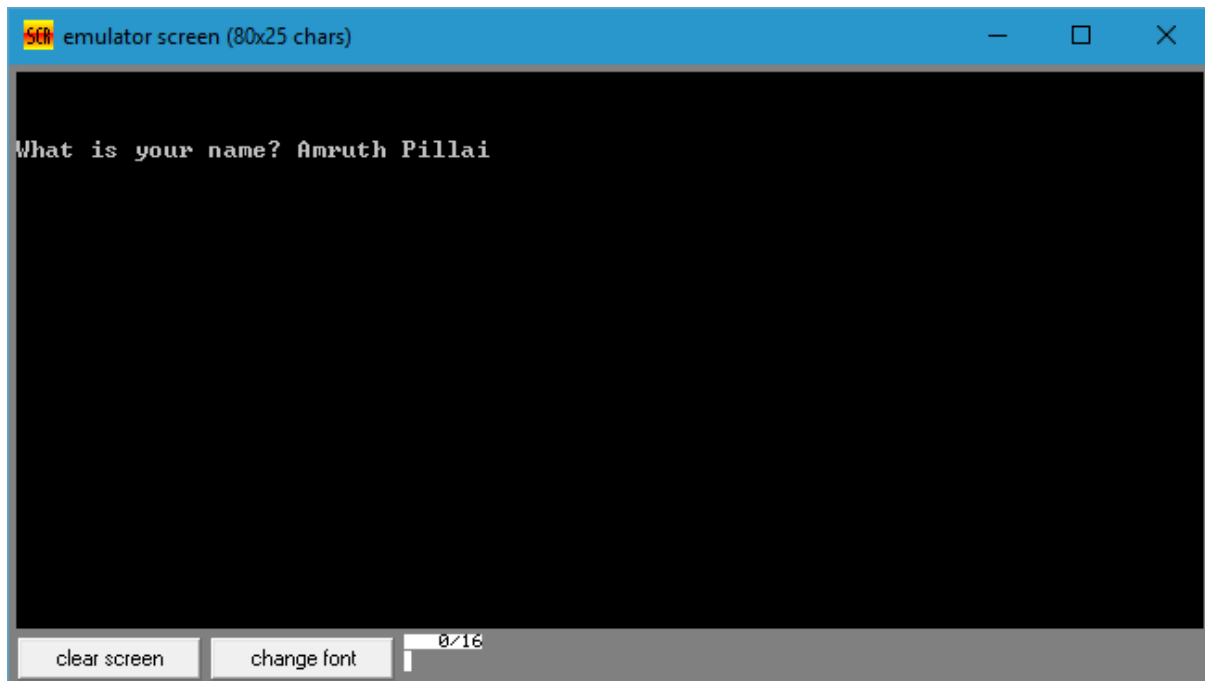
```
; Display Message
LEA DX, ARRAY
MOV AH, 09h
INT 21h
```

Exit:

```
; Terminate the Program
MOV AH, 4Ch
INT 21h
```

END

## Output



## Assembly Level Program 7b – 8x3 Keypad

Scan a 8 x 3 keypad for key closure and to store the code of the key pressed in a memory location or display on screen. Also display row and column numbers of the key pressed.

### Program

```
.model SMALL
```

```
PRINTMSG MACRO MSG
```

```
    LEA DX, MSG
```

```
    MOV AH, 09h
```

```
    INT 21h
```

```
ENDM
```

```
PRINTNUM MACRO NUM
```

```
    MOV DL, NUM
```

```
    MOV AH, 02h
```

```
    INT 21h
```

```
ENDM
```

```
.data
```

```
PA    EQU    0E400h
```

```
PB    EQU    0E401h
```

```
PC    EQU    0E402h
```

```
CR    EQU    0E403h
```

```
CW    dB     90h
```

```
MSG1  dB     10, 13, 'Row Number: $'
```

```
MSG2  dB     10, 13, 'Column Number: $'
```

```
MSG3  dB     10, 13, 'Code: $'
```

```
ROW   dB     ?
```

```
COL   dB     ?
```

```
KEYS  dB     '0123456789ABCDEFGHIJKLMN'
```

.code

; Initialize Data Segment

MOV AX, @DATA

MOV DS, AX

; Set Control Word Format

MOV DX, CR

MOV AL, CW

OUT DX, AL

Looper:

; Listen for Key Press at First Row

MOV DX, PC

MOV AL, 01h

OUT DX, AL

; Scan for User Input from Keypad

MOV DX, PA

IN AL, DX

CMP AL, 00h

JNZ FirstRow

; Listen for Key Press at Second Row

MOV DX, PC

MOV AL, 02h

OUT DX, AL

; Scan for User Input from Keypad

MOV DX, PA

IN AL, DX

CMP AL, 00h

JNZ SecondRow

; Listen for Key Press at Third Row

MOV DX, PC

MOV AL, 04h

OUT DX, AL



```
; Scan for User Input from Keypad
```

```
MOV DX, PA
```

```
IN AL, DX
```

```
CMP AL, 00h
```

```
JNZ ThirdRow
```

```
JMP Looper
```

```
FirstRow:
```

```
MOV ROW, 31h
```

```
MOV COL, 31h
```

```
LEA SI, KEYS
```

```
Loop1:
```

```
SHR AL, 01h
```

```
JC Display
```

```
INC COL
```

```
INC SI
```

```
JMP Loop1
```

```
SecondRow:
```

```
MOV ROW, 32h
```

```
MOV COL, 31h
```

```
LEA SI, KEYS+8
```

```
Loop2:
```

```
SHR AL, 01h
```

```
JC Display
```

```
INC COL
```

```
INC SI
```

```
JMP Loop2
```

ThirdRow:

```
MOV R0W, 33h
MOV COL, 31h
LEA SI, KEYS+16
```

Loop3:

```
SHR AL, 01h
JC Display
```

```
INC COL
INC SI
```

```
JMP Loop3
```

Display:

```
PRINTMSG MSG1
PRINTNUM R0W
```

```
PRINTMSG MSG2
PRINTNUM COL
```

```
PRINTMSG MSG3
PRINTNUM [SI]
```

Exit:

```
MOV AH, 4Ch
INT 21h
```

END

## Assembly Level Program 8a – Calculate NCR

Write an Assembly Level Program to compute  $nCr$  using recursive procedure. Assume that 'n' and 'r' are non-negative integers.

### Program

```
.model SMALL

.data
    N      dB      21d
    R      dB      19d
    NCR    dW      00h

.code

    ; Initialize Data Segment
    MOV AX, @DATA
    MOV DS, AX

    ; Clear NCR
    MOV AX, 00h
    MOV AL, N
    MOV BL, R

    CALL NCRProcedure

Exit:
    MOV AH, 4Ch
    INT 21h

NCRProcedure PROC NEAR
    CMP AX, BX
    JE IncrementBy1

    CMP BX, 00h
    JE IncrementBy1
```

```
CMP BX, 01h
JE IncrementByN
```

```
DEC AX
```

```
CMP AX, BX
JE IncrementByNPlus1
```

```
PUSHA
CALL NCRProcedure
POPA
```

```
DEC BX
```

```
PUSHA
CALL NCRProcedure
POPA
```

```
RET
```

```
IncrementBy1:
```

```
INC NCR
RET
```

```
IncrementByN:
```

```
ADD NCR, AX
RET
```

```
IncrementByNPlus1:
```

```
ADD NCR, AX
INC NCR
RET
```

```
NCRProcedure ENDP
```

```
END
```

## Output

```

debug log - debug.exe emulation
clear save to file... ?
0711:0005 B80000      MOV AX, 000000h
-d NCR
0710:0002 00 00 00 00 00 00 00-00 00 00 00 00 00 B8 10  .....
0710:0012 07 8E D8 B8 00 00 A0 00-00 8A 1E 01 00 C7 06 02  .A+..ä..è▲@.||+
0710:0022 00 00 00 E8 04 00 B4 4C-CD 21 3B C3 74 1F 83 FB  ..ø♦.}L=;!;|tva√
0710:0032 00 74 1A 83 FB 01 74 1A-48 3B C3 74 1A 50 53 E8  .t→âJ@t→H;|t→PSø
0710:0042 E8 FF 5B 58 4B 50 53 E8-E0 FF 5B 58 C3 FF 06 02  ø.[XKPSøα.[X|+.+
0710:0052 00 C3 01 06 02 00 C3 01-06 02 00 FF 06 02 00 C3  .|@+@.|@+@.++|
0710:0062 90 90 90 90 90 90 90-90 90 90 90 90 90 90 90  éééééééééééééééé
0710:0072 90 90 90 90 F4 00 00 00-00 00 00 00 00 00 00  éééééééééééééééé

```

```

debug log - debug.exe emulation
clear save to file... ?
F400:0204 CF      IRET
-d NCR
0710:0002 0A 00 00 00 00 00 00-00 00 00 00 00 00 B8 10  .....
0710:0012 07 8E D8 B8 00 00 A0 00-00 8A 1E 01 00 C7 06 02  .A+..ä..è▲@.||+
0710:0022 00 00 00 E8 04 00 B4 4C-CD 21 3B C3 74 1F 83 FB  ..ø♦.}L=;!;|tva√
0710:0032 00 74 1A 83 FB 01 74 1A-48 3B C3 74 1A 50 53 E8  .t→âJ@t→H;|t→PSø
0710:0042 E8 FF 5B 58 4B 50 53 E8-E0 FF 5B 58 C3 FF 06 02  ø.[XKPSøα.[X|+.+
0710:0052 00 C3 01 06 02 00 C3 01-06 02 00 FF 06 02 00 C3  .|@+@.|@+@.++|
0710:0062 90 90 90 90 90 90 90-90 90 90 90 90 90 90 90  éééééééééééééééé
0710:0072 90 90 90 90 F4 00 00 00-00 00 00 00 00 00 00  éééééééééééééééé

```

## Assembly Level Program 8b – Stepper Motor

Drive a Stepper Motor interface to rotate the motor in specified direction (clockwise or counter-clockwise) by N steps (Direction and N are specified by the examiner). Introduce suitable delay between successive steps. (Any arbitrary value for the delay may be assumed by the student).

### Program

```
.model SMALL
```

```
.data
```

```
PA    EQU    0E400h
PB    EQU    0E401h
PC    EQU    0E402h
CR    EQU    0E403h
CW    dB     80h
```

```
.code
```

```
; Initialize Data Segment
MOV AX, @DATA
MOV DS, AX
```

```
; Set Control Word Format
MOV DX, CR
MOV AL, CW
OUT DX, AL
```

```
; 360 Degree Rotation (200x1.8)
MOV CX, 200d
MOV DX, PA
MOV AL, 88h
```

```
Rotate:
```

```
; Rotate Clockwise
ROR AL, 01h
```

```
; Rotate Counter-Clockwise
; ROL AL, 01h
```

```
OUT DX, AL
```

```
CALL Delay
```

```
LOOP Rotate
```

```
Exit:
```

```
    ; Terminate the Program
```

```
    MOV AH, 4Ch
```

```
    INT 21h
```

```
Delay PROC NEAR
```

```
    MOV SI, 0FFFFh
```

```
    Loop1:
```

```
    MOV DI, 04FFFh
```

```
    Loop2:
```

```
    DEC DI
```

```
    JNZ Loop2
```

```
    DEC SI
```

```
    JNZ Loop1
```

```
    RET
```

```
Delay ENDP
```

```
END
```

## Assembly Level Program 9a – System Time

Write an Assembly Level Program to read the current time from the system and display it in the standard format on the screen.

### Program

```
.model SMALL

DISPLAY MACRO
    ; ASCII Adjust after Multiplication
    AAM
    MOV BX, AX

    ; Print Higher Nibble
    MOV DL, BH
    ADD DL, 30h
    MOV AH, 02h
    INT 21h

    ; Print Lower Nibble
    MOV DL, BL
    ADD DL, 30h
    MOV AH, 02h
    INT 21h
ENDM

COLON MACRO
    MOV DL, ':'
    MOV AH, 02h
    INT 21h
ENDM

.data
    MSG1  db    10, 13, 'The Current System Time is $'
```



```
.code
    ; Initialize Data Segment
    MOV AX, @DATA
    MOV DS, AX

    ; Display Message
    LEA DX, MSG1
    MOV AH, 09h
    INT 21h

    ; Interrupt to Fetch System Time
    MOV AH, 2Ch
    INT 21h

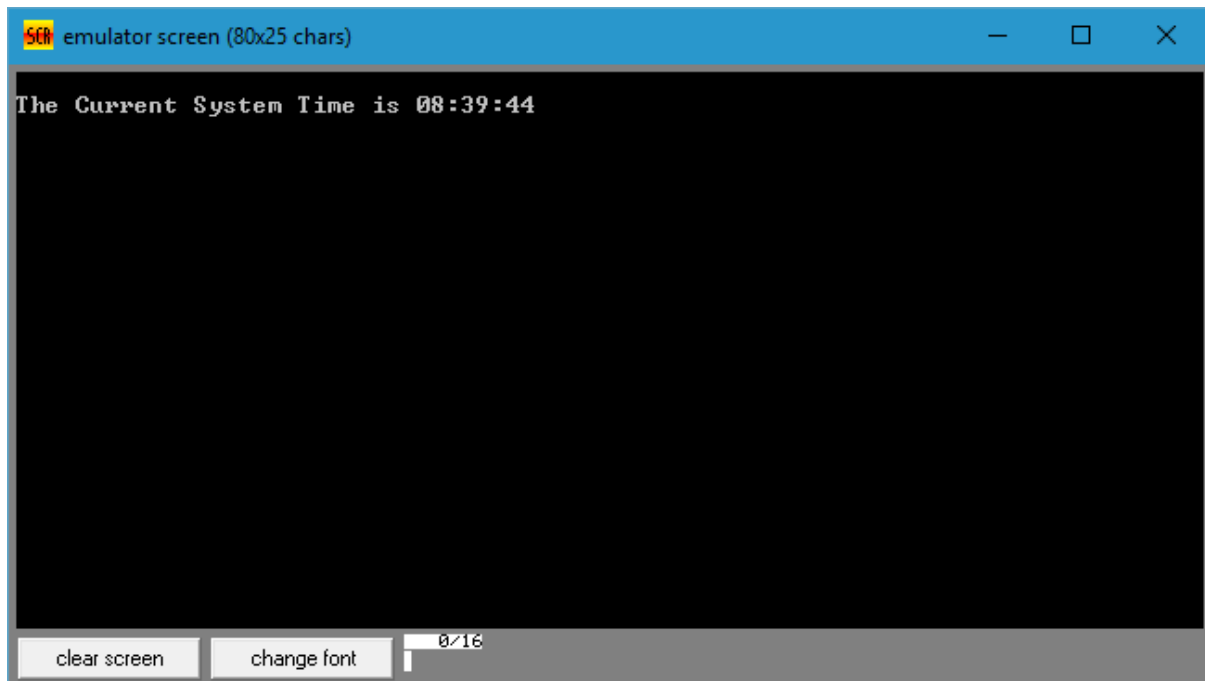
    ; CH -> Hours
    MOV AL, CH
    DISPLAY
    COLON

    ; CL -> Minutes
    MOV AL, CL
    DISPLAY
    COLON

    ; DH -> Seconds
    MOV AL, DH
    DISPLAY

Exit:
    ; Terminate the Program
    MOV AH, 4Ch
    INT 21h
END
```

## Output



## Assembly Level Program 9b – Sine Wave

Generate the Sine Wave using Digital-to-Analog Converter interface (The output of the DAC is to be displayed on the CRO).

### Program

```
.model SMALL
```

```
.data
```

```
PA    EQU    0E400h
PB    EQU    0E401h
PC    EQU    0E402h
CR    EQU    0E403h
CW    dB     80h
```

```
TABLE dB    127, 144, 161, 177, 191, 204, 214, 221, 225,
            227, 225, 221, 214, 204, 191, 177, 161, 144,
            127, 110, 93, 77, 63, 50, 40, 33, 29, 27,
            29, 33, 40, 50, 63, 77, 93, 110, 127
```

```
.code
```

```
; Initialize Data Segment
MOV AX, @DATA
MOV DS, AX

; Set Control Word Format
MOV DX, CR
MOV AL, CW
OUT DX, AL
```

Looper:

```
; Number of Values in TABLE
MOV CX, 37d

; Point SI to the First Position of TABLE
LEA SI, TABLE
```

MOV DX, PA

Repeater:

    ; Clear Direction Flag

    CLD

    ; Loads [SI] to AL and Auto-Advances SI

    LODSB

    ; Send AL to DAC Interface

    OUT DX, AL

LOOP Repeater

    ; Wait for User Keyboard Input Interrupt

MOV AH, 01h

INT 16h

JZ Looper

Exit:

    ; Terminate the Program

MOV AH, 4Ch

INT 16h

END

## Assembly Level Program 10a – Decimal Up Counter

Write an Assembly Level Program to simulate a Decimal Up Counter to display 00 to 99.

### Program

```
.model SMALL

.code
    ; Load 0 (in ASCII) to AL
    MOV AL, 30h

FirstLoop:
    ; Print Higher Digit on Screen
    MOV DL, AL
    MOV AH, 02h
    INT 21h

    PUSH AX

    ; Load 0 (in ASCII) to BL
    MOV BL, 30h

SecondLoop:
    ; Print Lower Digit on Screen
    MOV DL, BL
    MOV AH, 02h
    INT 21h

    INC BL

    ; Get Current Cursor Position
    MOV AH, 03h
    INT 10h

    ; Set Cursor to 2nd Column
    MOV AH, 02h
    MOV DL, 01h
    INT 10h
```

```
CMP BL, 039h
JLE SecondLoop

; Set Cursor to 1st Column
MOV AH, 02h
MOV DL, 00h
INT 10h

POP AX

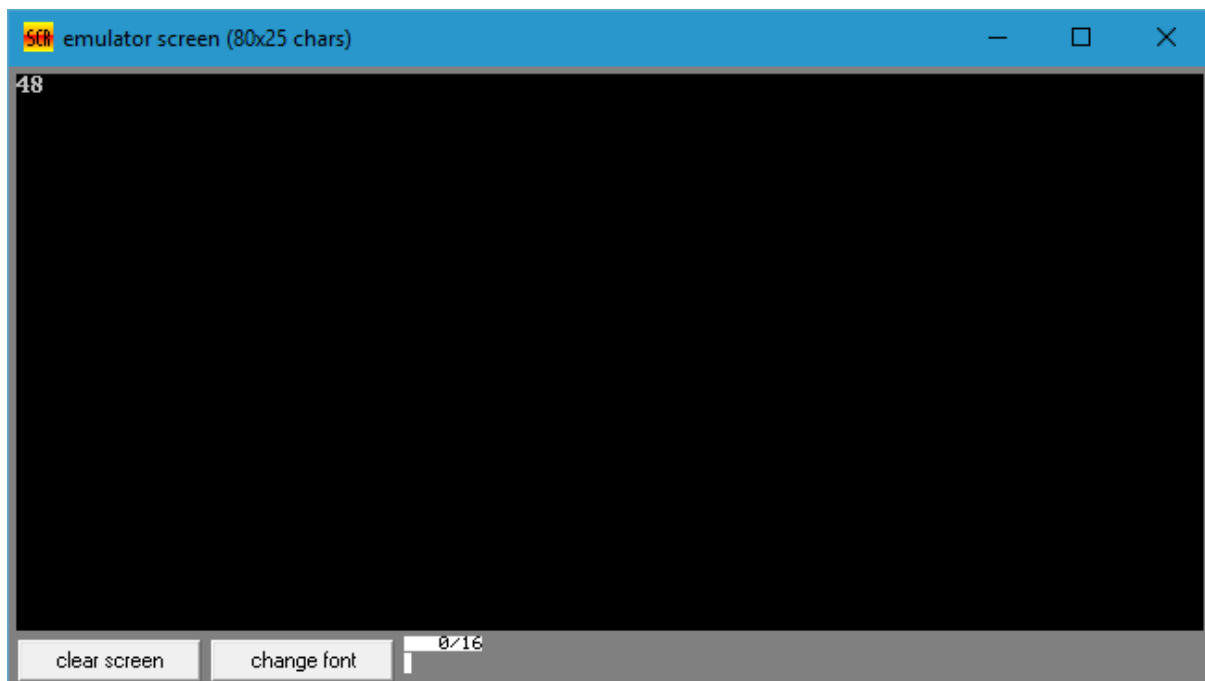
INC AL

; Check if Digit has exceeded 9
CMP AL, 039h
JLE FirstLoop

Exit:
; Terminate the Program
MOV AH, 4Ch
INT 21h

END
```

## Output



## Assembly Level Program 10b – Half Rectified Sine Wave

Generate a Half Rectified Sine Wave form using the DAC interface. (The output of the DAC is to be displayed on the CRO).

### Program

```
.model SMALL
```

```
.data
```

```
PA    EQU    0E400h
PB    EQU    0E401h
PC    EQU    0E402h
CR    EQU    0E403h
CW    dB     80h
```

```
TABLE dB    127, 144, 161, 177, 191, 204, 214, 221, 225,
            227, 225, 221, 214, 204, 191, 177, 161, 144,
            127, 127, 127, 127, 127, 127, 127, 127, 127,
            127, 127, 127, 127, 127, 127, 127, 127, 127, 127
```

```
.code
```

```
; Initialize Data Segment
MOV AX, @DATA
MOV DS, AX

; Set Control Word Format
MOV DX, CR
MOV AL, CW
OUT DX, AL
```

```
Looper:
```

```
; Number of Values in TABLE
MOV CX, 37d

; Point SI to the First Position of TABLE
LEA SI, TABLE
```

MOV DX, PA

Repeater:

    ; Clear Direction Flag

    CLD

    ; Loads [SI] to AL and Auto-Advances SI

    LODSB

    ; Send AL to DAC Interface

    OUT DX, AL

LOOP Repeater

    ; Wait for User Keyboard Input Interrupt

MOV AH, 01h

INT 16h

JZ Looper

Exit:

    ; Terminate the Program

MOV AH, 4Ch

INT 16h

END



## Assembly Level Program 11a – Cursor Movement

Write an Assembly Level Program to read a pair of input co-ordinates in BCD and move the cursor to the specified location on the screen.

### Program

```
.model SMALL

.data
    MSGX  dB    10, 13 , 'Enter X Coordinates: $'
    MSGY  dB    10, 13 , 'Enter Y Coordinates: $'
    X      dB    ?
    Y      dB    ?

.code
    ; Initialize Data Segment
    MOV AX, @DATA
    MOV DS, AX

    ; Display Message
    LEA DX, MSGX
    MOV AH, 09h
    INT 21h

    CALL ReadBCD
    MOV X, BH

    ; Display Message
    LEA DX, MSGY
    MOV AH, 09h
    INT 21h

    CALL ReadBCD
    MOV Y, BH
```

```
; Clear Screen
MOV AH, 00h
MOV AL, 03h
INT 10h

; Set Cursor Interrupt
MOV AH, 02h
MOV DH, X ; Row Position
MOV DL, Y ; Column Position
MOV BH, 00h ; Page Number
INT 10h

; Direct Console Output
MOV DL, '-'
MOV AH, 06h
INT 21h
```

Exit:

```
; Terminate the Program
MOV AH, 4Ch
INT 21h
```

ReadBCD PROC NEAR

```
; Read 1st Digit from User
MOV AH, 01h
INT 21h
MOV BH, AL

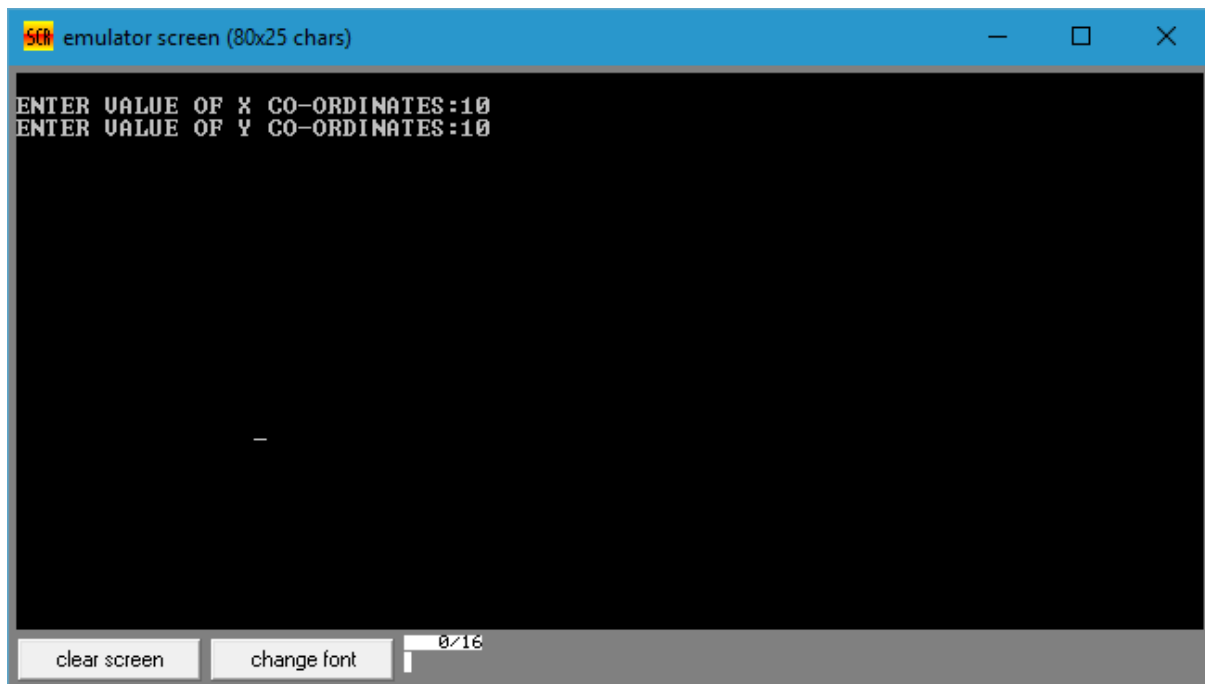
; Read 2nd Digit from User
MOV AH, 01h
INT 21h
MOV BL, AL
```

```
MOV CL, 04h
; Convert ASCII to BCD
SUB BH, 30h
SUB BL, 30h

SHL BH, CL
OR BH, BL
RET
ReadBCD ENDP

END
```

## Output



## Assembly Level Program 11b – Fully Rectified Sine Wave

Generate a Fully Rectified Sine waveform using the DAC interface. (The output of the DAC is to be displayed on the CRO).

### Program

```
.model SMALL
```

```
.data
```

```
PA    EQU    0E400h
PB    EQU    0E401h
PC    EQU    0E402h
CR    EQU    0E403h
CW    dB     80h
```

```
TABLE dB    127, 144, 161, 177, 191, 204, 214, 221, 225, 227,
            225, 221, 214, 204, 191, 177, 161, 144, 127
```

```
.code
```

```
; Initialize Data Segment
MOV AX, @DATA
MOV DS, AX
```

```
; Set Control Word Format
MOV DX, CR
MOV AL, CW
OUT DX, AL
```

```
Looper:
```

```
; Number of Values in TABLE
MOV CX, 19d
```

```
; Point SI to the First Position of TABLE
LEA SI, TABLE
```

MOV DX, PA

Repeater:

    ; Clear Direction Flag

    CLD

    ; Loads [SI] to AL and Auto-Advances SI

    LODSB

    ; Send AL to DAC Interface

    OUT DX, AL

LOOP Repeater

    ; Wait for User Keyboard Input Interrupt

MOV AH, 01h

INT 16h

JZ Looper

Exit:

    ; Terminate the Program

MOV AH, 4Ch

INT 16h

END

## Assembly Level Program 12a – File Handling

Write an Assembly Level Program to create a file (input file) and to delete an existing file.

### CreateFile.asm

```
.model SMALL
```

```
.data
```

```
    FNAME      dB      'SampleFile.txt', 00h
    SUCCESS    dB      10, 13, 'File has been created successfully!$'
    FAILURE     dB      10, 13, 'An Error Occured during File Creation!$'
```

```
.code
```

```
    ; Initialize Data Segment
    MOV AX, @DATA
    MOV DS, AX

    ; Set File Attribute
    MOV CX, 20h

    ; Interrupt to Create a File
    LEA DX, FNAME
    MOV AH, 3Ch
    INT 21h
    JC ErrorOccured

    ; Display Success Message
    LEA DX, SUCCESS
    MOV AH, 09h
    INT 21h
    JMP Exit
```

```
ErrorOccured:
```

```
    ; Display Error Message
    LEA DX, FAILURE
    MOV AH, 09h
    INT 21h
```

Exit:

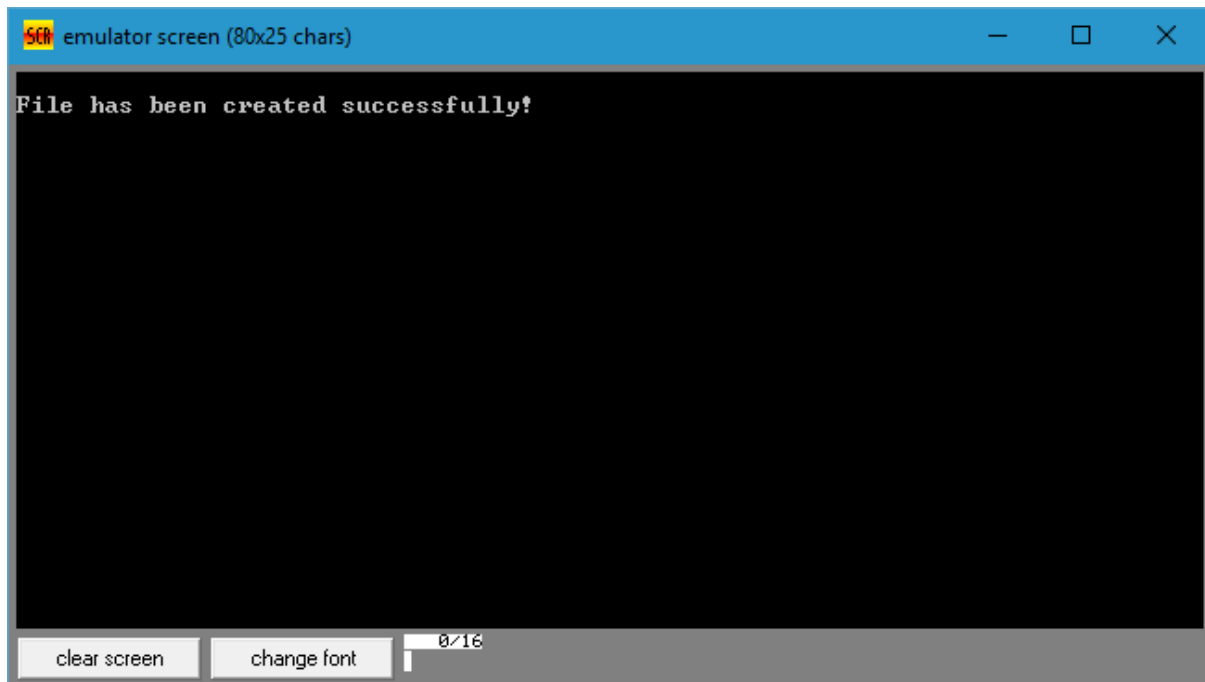
; Terminate the Program

MOV AH, 4Ch

INT 21h

END

## Output



## DeleteFile.am

```
.model SMALL
```

```
.data
```

```
    FNAME      dB      'SampleFile.txt', 00h
    SUCCESS    dB      10, 13, 'File has been deleted successfully!$'
    FAILURE     dB      10, 13, 'An Error Occured during File Deletion!$'
```

```
.code
```

```
    ; Initialize Data Segment
    MOV AX, @DATA
    MOV DS, AX

    ; Set File Attribute
    MOV CX, 20h

    ; Interrupt to Delete a File
    LEA DX, FNAME
    MOV AH, 41h
    INT 21h
    JC ErrorOccured

    ; Display Success Message
    LEA DX, SUCCESS
    MOV AH, 09h
    INT 21h
    JMP Exit
```

```
ErrorOccured:
```

```
    ; Display Error Message
    LEA DX, FAILURE
    MOV AH, 09h
    INT 21h
```



Exit:

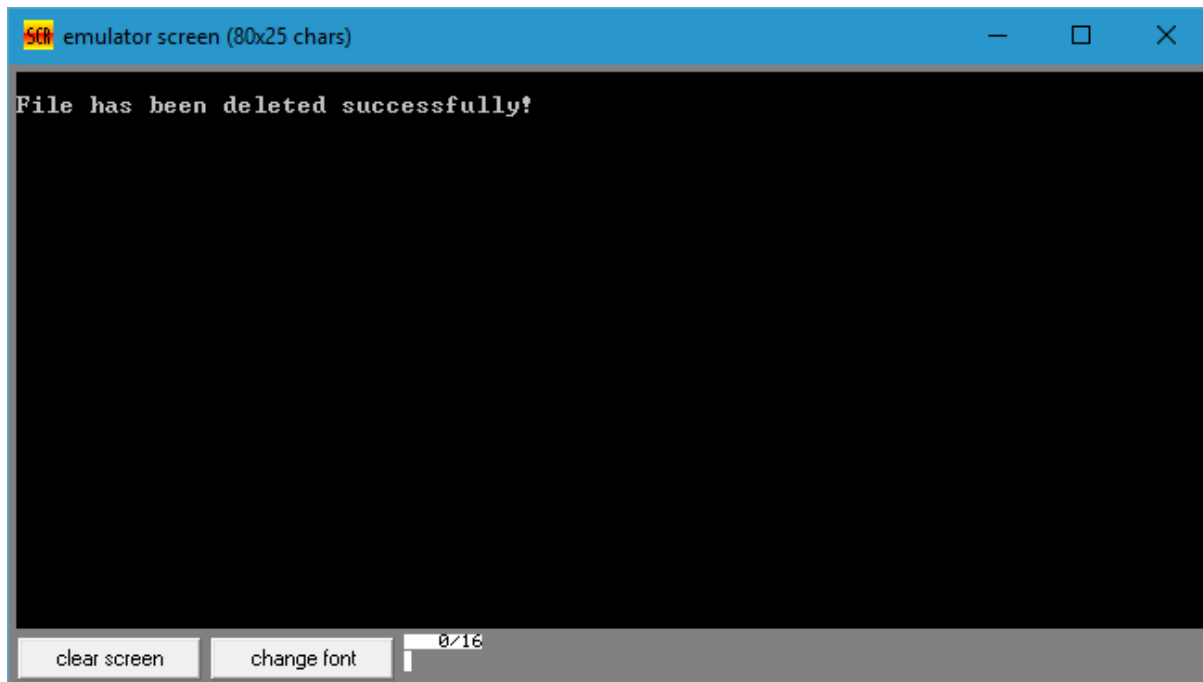
; Terminate the Program

MOV AH, 4Ch

INT 21h

END

## Output



## Assembly Level Program 12b – Elevator Interface

Drive an elevator interface in the following way:

- i. Initially the elevator should be in the ground floor, with all requests in OFF state.
- ii. When a request is made from a floor, the elevator should move to that floor, wait there for a couple of seconds (approximately), and then come down to ground floor and stop.  
If some requests occur during going up or coming down, they should be ignored.

### Program

```
.model SMALL

.data
    PA    EQU    0E400h
    PB    EQU    0E401h
    PC    EQU    0E402h
    CR    EQU    0E403h
    CW    dB     82h

    CLEAR dB    0E0h, 0D0h, 0B0h, 70h

.code
    ; Initialize Data Segment
    MOV AX, @DATA
    MOV DS, AX

    ; Set Control Word Format
    MOV DX, CR
    MOV AL, CW
    OUT DX, AL

    ; Move to Ground Floor Initially
    MOV DX, PA
    MOV AL, 0Fh
    OUT DX, AL
```

```
; Point SI to First Position of CLEAR Table  
LEA SI, CLEAR
```

NoRequest:

```
CALL Request  
JZ NoRequest
```

```
SHR AL, 01h  
JNC GroundFloor  
SHR AL, 01h  
JNC FirstFloor  
SHR AL, 01h  
JNC SecondFloor  
JMP ThirdFloor
```

GroundFloor:

```
CALL Delay  
CALL Reset  
JMP Exit
```

FirstFloor:

```
MOV CX, 03h  
LEA SI, CLEAR+1  
  
CALL MoveUp  
CALL Delay  
CALL Reset  
  
MOV CX, 03h  
CALL MoveDown  
JMP Exit
```

## SecondFloor:

```
MOV CX, 06h
LEA SI, CLEAR+2
```

```
CALL MoveUp
CALL Delay
CALL Reset
```

```
MOV CX, 06h
CALL MoveDown
JMP Exit
```

## ThirdFloor:

```
MOV CX, 09h
LEA SI, CLEAR+3
```

```
CALL MoveUp
CALL Delay
CALL Reset
```

```
MOV CX, 09h
CALL MoveDown
```

## Exit:

```
MOV AH, 4Ch
INT 21h
```

## Request PROC NEAR

```
; Wait for Key Press from User
MOV DX, PB
IN AL, DX

; Logical AND with Lower Nibble of AL
AND AL, 0Fh

CMP AL, 0Fh
RET
```

## Request ENDP

Reset PROC NEAR

PUSH AX

MOV DX, PA

; Fetch Value from CLEAR Table

MOV AL, [SI]

OUT DX, AL

POP AX

RET

Reset ENDP

MoveUp PROC NEAR

MOV AL, 0F0H

MOV DX, PB

GoUp:

OUT DX, AL

CALL Delay

INC AL

Loop GoUp

OUT DX, AL

RET

MoveUp ENDP

MoveDown PROC NEAR

MOV DX, PB

GoDown:

OUT DX, AL

CALL Delay

DEC AL

Loop GoDown

OUT DX, AL

RET

MoveDown ENDP

```
Delay PROC NEAR
    MOV SI, 0FFFFh
    Loop1:
    MOV DI, 04FFFh
    Loop2:
    DEC DI
    JNZ Loop2
    DEC SI
    JNZ Loop1
    RET
Delay ENDP

END
```