

Week-1

Source code:

```
from collections import defaultdict

class Graph:

    def __init__(self):
        self.value = defaultdict(list)

    def drawGraph(self, parent, child):
        self.value[parent].append(child)

    def DFS(self, start):
        visited = []
        stack = [start]

        print("DFS Traversal:", end=" ")

        while stack:
            s = stack.pop()

            if s not in visited:
                print(s, end=" ")
                visited.append(s)

                for neighbor in reversed(self.value[s]):
                    if neighbor not in visited:
                        stack.append(neighbor)

    def BFS(self, start):
        visited = []
        queue = [start]

        print("\nBFS Traversal:", end=" ")

        while queue:
            x = queue.pop(0)

            if x not in visited:
```

```
print(x, end=" ")
visited.append(x)

for neighbor in self.value[x]:
    if neighbor not in visited:
        queue.append(neighbor)
```

```
# Create a graph and add edges.
```

```
g = Graph()
g.drawGraph(1, 4)
g.drawGraph(1, 2)
g.drawGraph(2, 3)
g.drawGraph(2, 6)
g.drawGraph(4, 5)
g.drawGraph(4, 7)
g.drawGraph(7, 96)
```

```
# Perform DFS and BFS traversals.
```

```
g.DFS(1)
g.BFS(1)
```

output:

DFS Traversal: 1 4 5 7 96 2 3 6

BFS Traversal: 1 4 2 5 7 3 6 96

Week-3a:

Source code:

```
from sys import maxsize
from itertools import permutations
```

V=4

```

def travellingSalespersonProblem(graph,s):

    vertex=[]

    for i in range(V):

        if i!=s:

            vertex.append(i)

    min_path = maxsize

    next_permutation=permutations(vertex)

    for i in next_permutation:

        print(i)

        current_pathweight=0

        k=s

        for j in i:

            current_pathweight += graph[k][j]

            k=j

        current_pathweight += graph[k][s]

        min_path = min(min_path, current_pathweight)

    return min_path

if __name__ == "__main__":

    graph = [[0,10,15,20],[10,0,35,25],[15,35,0,30],[20,25,30,0]]

    s=0

    print(travellingSalespersonProblem(graph,s))

```

output:

(1, 2, 3)

(1, 3, 2)

(2, 1, 3)

(2, 3, 1)

(3, 1, 2)

(3, 2, 1)

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Week-3b:

Source code:

```
colors=['red','blue','green','yellow','black']
states=['andhra','karnataka','tamilnadu','kerela']
neighbors={}
neighbors['andhra']=['karnataka','tamilnadu']
neighbors['karnataka']=['andhra','tamilnadu','kerela']
neighbors['tamilnadu']=['andhra','kerela','karnataka']
neighbors['kerela']=['karnataka','tamilnadu']
colors_of_states={}
def promising(state,color):
    for neighbor in neighbors.get(state):
        colors_of_neighbor=colors_of_states.get(neighbor)
        if colors_of_neighbor==color:
            return False
    return True

def get_color_for_state(state):
    for color in colors:
        if promising(state,color):
            return color

def main():
    for state in states:
        colors_of_states[state]=get_color_for_state(state)
    print(colors_of_states)

main()
```

output:

```
{'andhra': 'red', 'karnataka': 'blue', 'tamilnadu': 'green', 'kerela': 'red'}
```

Week-4:

Source code:

```
from sympy import symbols, Or, Not, Implies, satisfiable

Rain = symbols('Rain')

Harry_Visited_Hagrid = symbols('Harry_Visited_Hagrid')

Harry_Visited_Dumbledore = symbols('Harry_Visited_Dumbledore')

sentence_1 = Implies(Not(Rain), Harry_Visited_Hagrid)

sentence_2 = Or (Harry_Visited_Hagrid, Harry_Visited_Dumbledore) &
Not(Harry_Visited_Hagrid & Harry_Visited_Dumbledore)

sentence_3 = Harry_Visited_Dumbledore

knowledge_base = sentence_1 & sentence_2 & sentence_3

solution = satisfiable(knowledge_base, all_models=True)

for model in solution:

    if model[Rain]:

        print("It rained today.")

    else:

        print("It did not rain today.")
```

output:

it rained today

week-5:

source code:

```
import numpy

from pomegranate import *

guest = DiscreteDistribution({'A':1./3,'B':1./3,'C':1./3})

prize = DiscreteDistribution({'A':1./3,'B':1./3,'C':1./3})

monty = ConditionalProbabilityTable(

    [['A','A','A',0.0],

     ['A','A','B',0.5],

     ['A','A','C',0.5],
```

```

['A','B','A',0.0],
['A','B','B',0.0],
['A','B','C',1.0],
['A','C','A',0.0],
['A','C','B',1.0],
['A','C','C',0.0],
['B','A','A',0.0],
['B','A','B',0.0],
['B','A','C',1.0],
['B','B','A',0.5],
['B','B','B',0.0],
['B','B','C',0.5],
['B','C','A',1.0],
['B','C','B',0.0],
['B','C','C',0.0],
['C','A','A',0.0],
['C','A','B',1.0],
['C','A','C',0.0],
['C','B','A',1.0],
['C','B','B',0.0],
['C','B','C',0.0],
['C','C','A',0.5],
['C','C','B',0.5],
['C','C','C',0.0]], [guest,prize])
s1 = State(guest, name="guest")
s2 = State(prize, name="prize")
s3 = State(monty, name="monty")
model = BayesianNetwork("monty Hall Problem")
model.add_states(s1,s2,s3)
model.add_edge(s1,s3)

```

```
model.add_edge(s2,s3)

model.bake()

print(model.probability([[ 'A','B','C'],[ 'A','A','C'],[ 'A','C','C']]))

print(model.predict([[ 'A',None,'C'],[ 'A','A',None],[ None,'B','A']]))
```

week-6:

source code:

```
import numpy as np
import itertools
import pandas as pd

#create state space and initial state probabilities
states=['sleeping','eating','pooping']
hidden_states=['healthy','sick']
pi=[0.5,0.5]

state_space=pd.Series(pi, index=hidden_states,name='states')
print(state_space)

a_df=pd.DataFrame(columns=hidden_states,index=hidden_states)
a_df.loc[hidden_states[0]]=[0.7,0.3]
a_df.loc[hidden_states[1]]=[0.4,0.6]
print(a_df)

observable_states=states
b_df=pd.DataFrame(columns=observable_states,index=hidden_states)
b_df.loc[hidden_states[0]]=[0.2,0.6,0.2]
b_df.loc[hidden_states[1]]=[0.4,0.1,0.5]
print(b_df)
```

```

def HMM(obsq,a_df,b_df,pi,states,hidden_states):
    hidst=list(itertools.product(hidden_states,repeat=len(obsq)))
    print(hidst)
    sum=0
    for k in hidst:
        prod=1
        for j in range(len(k)):
            c=0
            for i in obsq:
                if c==0:
                    prod*=a_df[i][k[j]]*pi[hidden_states.index(k[j])]
                    c=1
            else:
                prod*=b_df[k[j]][k[j-1]]*a_df[i][k[j]]
        sum+=prod
    c=0
    return sum

```

```

def vertibi(obsq,a_df,b_df,pi,states,hidden_states):
    sum=0
    hidst=list(itertools.product(hidden_states,repeat=len(obsq)))
    for k in hidst:
        sum1=0
        prod=1
        for j in range(len(k)):
            c=0
            for i in obsq:
                if c==0:
                    prod*=a_df[i][k[j]]*pi[hidden_states.index(k[j])]
                    c=1
            else:

```



```

        prod*=b_df[k[j]][k[j-1]]*a_df[i][k[j]]
    c=0
    sum1+=prod
    if(sum1>sum):
        sum=sum1
        hs=k
    return sum,hs

```

```

obsq=['eating','sleeping','sleeping']
print(HMM(obsq,b_df,a_df,pi,states,hidden_states))
print(vertibi(obsq,b_df,a_df,pi,states,hidden_states))

```

output:

```

healthy  0.5
sick     0.5
Name: states, dtype: float64

healthy sick
healthy    0.7 0.3
sick       0.4 0.6

sleeping eating pooping
healthy    0.2 0.6 0.2
sick       0.4 0.1 0.5

[('healthy', 'healthy', 'healthy'), ('healthy', 'healthy', 'sick'), ('healthy', 'sick', 'healthy'),
 ('healthy', 'sick', 'sick'), ('sick', 'healthy', 'healthy'), ('sick', 'healthy', 'sick'), ('sick', 'sick',
 'healthy'), ('sick', 'sick', 'sick')]

2.6351481599999999e-07
(2.03297471999999986e-07, ('healthy', 'healthy', 'healthy'))

```

week-7:

source code:

```

import numpy as np

```

```
import pandas as pd
import matplotlib.pyplot as plt
from sklearn.model_selection import train_test_split
from sklearn.linear_model import LinearRegression
dataset = pd.read_csv('Salary_Data.csv')
dataset.head()
X = dataset.iloc[:, :-1].values
y = dataset.iloc[:, -1].values
X_train, X_test, y_train, y_test = train_test_split(X, y, test_size=0.3, random_state=0)
regressor = LinearRegression()
regressor.fit(X_train, y_train)
y_pred = regressor.predict(X_test)
y_pred
y_test
plt.scatter(X_train, y_train, color='red')
plt.plot(X_train, regressor.predict(X_train), color='blue')
plt.title("Salary vs Experience (Training set)")
plt.xlabel("Years of Experience")
plt.ylabel("Salary")
plt.show()
```



Week-9:

Source code:

```
import matplotlib.pyplot as plt
from sklearn import datasets
from sklearn.cluster import KMeans
import pandas as pd
import numpy as np

iris = datasets.load_iris()
x = pd.DataFrame(iris.data)
x.columns = ['sepal_length', 'sepal_width', 'petal_length', 'petal_width']
y = pd.DataFrame(iris.target, columns=['target'])

plt.figure(figsize=(14, 7))
colormap = np.array(['red', 'lime', 'black'])

plt.subplot(1, 2, 1)
plt.scatter(x.sepal_length, x.sepal_width, c=colormap[y.target], s=40)
plt.title('Sepal')
```

```
model = KMeans(n_clusters=3)
model.fit(x)
print(model.labels_)
```

```
plt.subplot(1, 2, 2)

plt.scatter(x.petal_length, x.petal_width, c=model.labels_, s=40)

plt.title('KMeans Classification')
```

output:

Week-10:

Source code:

```
import pandas as pd
from sklearn.datasets import load_iris
from sklearn.model_selection import train_test_split
iris = load_iris()
print(iris.keys())
df = pd.DataFrame(iris['data'])
print(df)
print(iris['target_names'])
print(iris['feature_names'])
print(iris['target'])
X = df
y = iris['target']
from sklearn.neighbors import KNeighborsClassifier
X_train, X_test, y_train, y_test = train_test_split(X, y, test_size=0.33, random_state=42)
knn = KNeighborsClassifier(n_neighbors=3)
knn.fit(X_train, y_train)
from sklearn.metrics import confusion_matrix, accuracy_score, classification_report
y_pred = knn.predict(X_test)
cm = confusion_matrix(y_test, y_pred)
print("Correct prediction", accuracy_score(y_test, y_pred))
print("Wrong prediction", (1 - accuracy_score(y_test, y_pred)))
y_test_train = knn.predict(X_train)
cm1 = confusion_matrix(y_train, y_test_train)
print(cm1)
```

output:

```
dict_keys(['data', 'target', 'frame', 'target_names', 'DESCR', 'feature_names', 'filename', 'data_module'])
```

```
0  1  2  3
```



```
x = np.array([[2, 9], [1, 5], [3, 6]], dtype=float)
print(x)
```

```
y = np.array([[92], [86], [89]], dtype=float)
y = y / 100
print(y)
```

```
def sigmoid(x):
    return 1 / (1 + np.exp(-x))
```

```
def derivatives_sigmoid(x):
    return x * (1 - x)
```

```
epoch = 1000
lr = 0.01
input_layer_neurons = 2
hidden_layer_neurons = 2
output_neurons = 1
```

```
wh = np.random.uniform(size=(input_layer_neurons, hidden_layer_neurons))
bh = np.random.uniform(size=(1, hidden_layer_neurons))
wout = np.random.uniform(size=(hidden_layer_neurons, output_neurons))
bout = np.random.uniform(size=(1, output_neurons))
```

```
for i in range(epoch):
    hinp1 = np.dot(x, wh)
    hinp = hinp1 + bh
    hlayer_act = sigmoid(hinp)
    outinp1 = np.dot(hlayer_act, wout)
    outinp = outinp1 + bout
```

```

output = sigmoid(outinp)
EO = (y - output)
outgrad = derivatives_sigmoid(output)
d_output = EO * outgrad
EH = d_output.dot(wout.T)
hiddengrad = derivatives_sigmoid(hlayer_act)
d_hiddenlayer = EH * hiddengrad
wout += hlayer_act.T.dot(d_output) * lr
bout += np.sum(d_output, axis=0, keepdims=True) * lr
wh += x.T.dot(d_hiddenlayer) * lr
bh += np.sum(d_hiddenlayer, axis=0, keepdims=True) * lr
print("Actual output:" + str(y))
print("Predicted output:" + str(output))
print("Error:" + str(EO))

```

output:

[0.87169281]

[0.87292951]]

Error:[[0.04699477]

[-0.01169281]

[0.01707049]]

Actual output:[[0.92]

[0.86]

[0.89]]

Predicted output:[[0.87302452]

[0.87171213]

[0.87294881]]

Error:[[0.04697548]

[-0.01171213]

[0.01705119]]

Actual output:[[0.92]

[0.86]

[0.89]]

Predicted output:[[0.87304378]

[0.87173142]

[0.87296808]]

Error:[[0.04695622]

[-0.01173142]

[0.01703192]]

Actual output:[[0.92]

[0.86]

[0.89]]

Predicted output:[[0.87306302]

[0.87175068]

[0.87298732]]

Error:[[0.04693698]

[-0.01175068]

[0.01701268]]

.

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Week-12:

Source code:

```
from sklearn.datasets import load_breast_cancer
import matplotlib.pyplot as plt
from sklearn.inspection import DecisionBoundaryDisplay
from sklearn.svm import SVC
cancer = load_breast_cancer()
x = cancer.data[:, :2]
y = cancer.target
```

```
svm = SVC(kernel="rbf", gamma=0.5, C=1.0)
svm.fit(x, y)
```

```
DecisionBoundaryDisplay.from_estimator(
    svm,
    x,
    response_method="predict",
    cmap=plt.cm.Spectral,
    alpha=0.8,
    xlabel=cancer.feature_names[0],
    ylabel=cancer.feature_names[1]
)
```

```
plt.scatter(x[:, 0], x[:, 1],
            c=y,
            s=20, edgecolors="k")
plt.show()
```

output:

