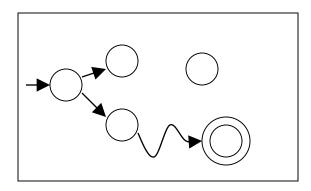
Variations of the Turing Machine

The Standard Model

Infinite Tape

Read-Write Head (Left or Right)

Control Unit



Deterministic

Variations of the Standard Model

Turing machines with:

- Stay-Option
 - Semi-Infinite Tape
 - · Off-Line
 - Multitape
 - Multidimensional
 - Nondeterministic

The variations form different Turing Machine Classes

We want to prove:

Each Class has the same power as the Standard Model

Same Power of two classes means:

The two classes of Turing machines accept the same languages

Same Power of two classes means:

For any machine $\,M_1\,$ of first class there is a machine $\,M_2\,$ of second class

such that:
$$L(M_1) = L(M_2)$$

And vice-versa

Simulation: a technique to prove same power

Simulate the machine of one class with a machine of the other class

<u>First Class</u> Original Machine

 M_1

Second Class
Simulation Machine

 M_2 M_1

Turing Machines with Stay-Option

The head can stay in the same position

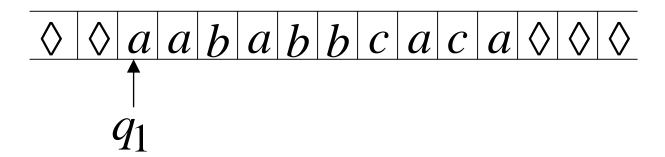
$$\delta: Q \times \Gamma \rightarrow Q \times \Gamma \times \{L, R, S\}$$

Left, Right, Stay

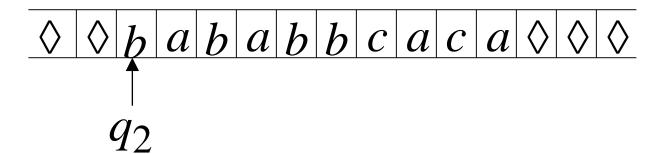
L,R,S: moves

Example:

Time 1



Time 2



$$q_1 \xrightarrow{a \to b, S} q_2$$

Theorem:

Stay-Option Machines have the same power as Standard Turing machines

Proof:

Part 1: Stay-Option Machines are at least as powerful as Standard machines

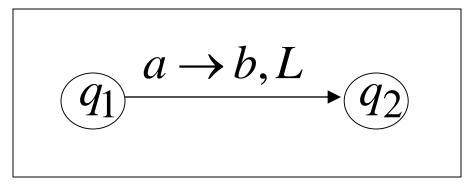
Proof: a Standard machine is also a Stay-Option machine (that never uses the S move)

Proof:

Part 2: Standard Machines are at least as powerful as Stay-Option machines

Proof: a standard machine can simulate a Stay-Option machine

Stay-Option Machine

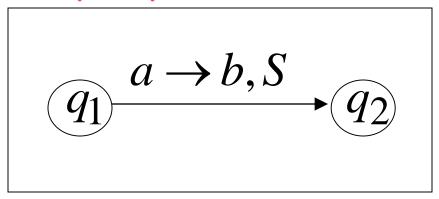


Simulation in Standard Machine

$$\begin{array}{c}
a \to b, L \\
\hline
q_1 \\
\end{array}$$

Similar for Right moves

Stay-Option Machine

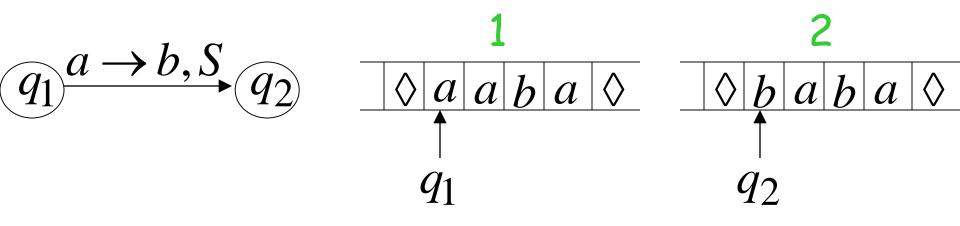


Simulation in Standard Machine

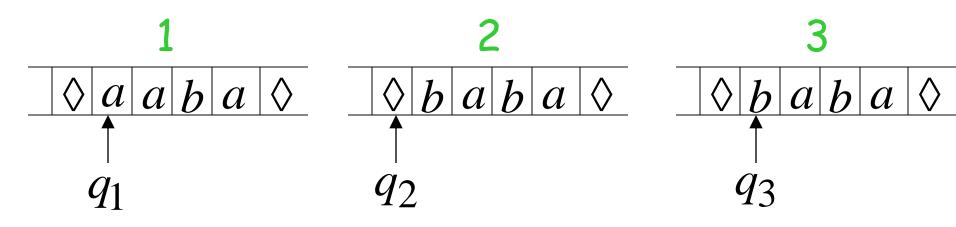
For every symbol X

Example

Stay-Option Machine:



Simulation in Standard Machine:

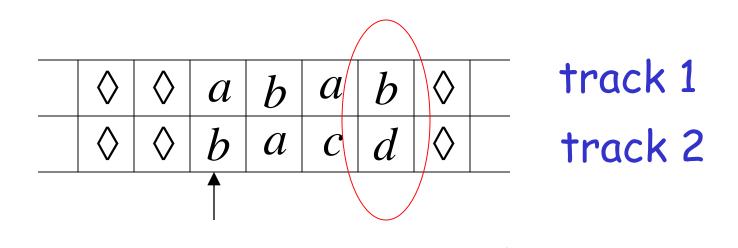


Standard Machine--Multiple Track Tape

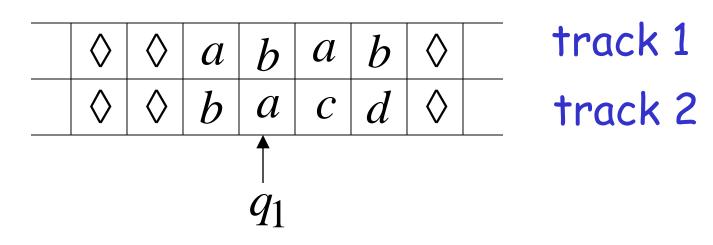
| \Diamond | \Diamond | a | b | a | b | \Diamond | track 1 |
|------------|------------|---|---|---|---|------------|---------|
| \Diamond | \Diamond | b | a | С | d | \Diamond | track 2 |
| | | | | | | | |

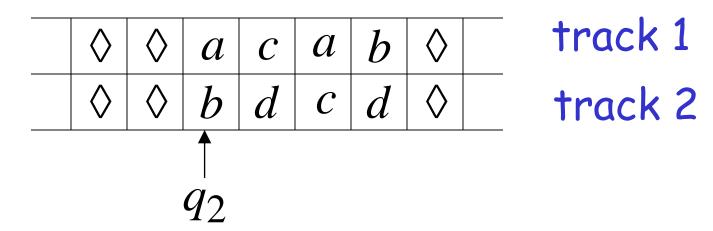
Proof of equivalence?

Standard Machine--Multiple Track Tape



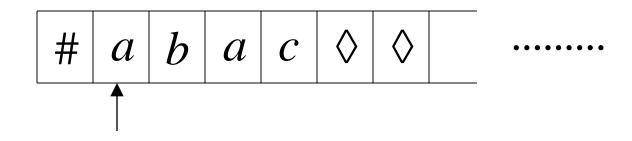
one symbol

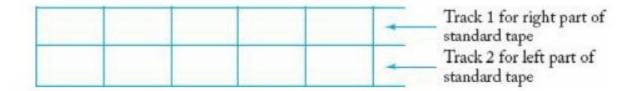




$$\underbrace{q_1} \xrightarrow{(b,a) \to (c,d),L} \underbrace{q_2}$$

Semi-Infinite Tape



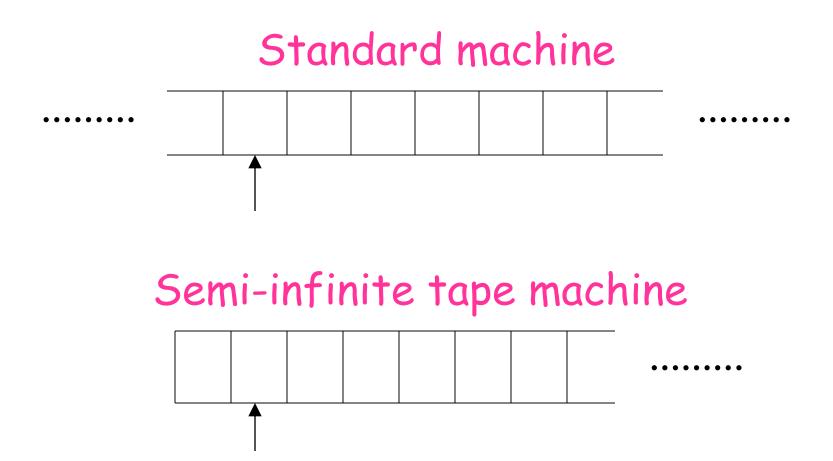


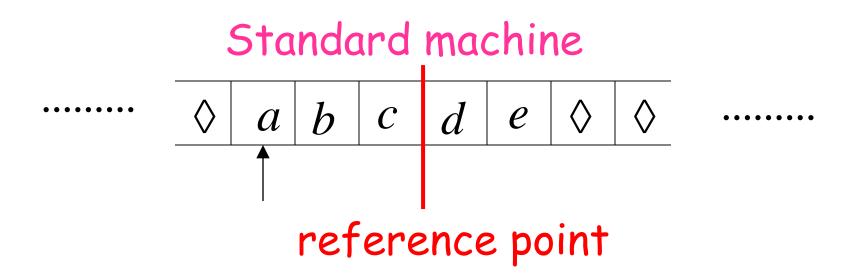
Proof of equivalence?

Standard Turing machines simulate Semi-infinite tape machines:

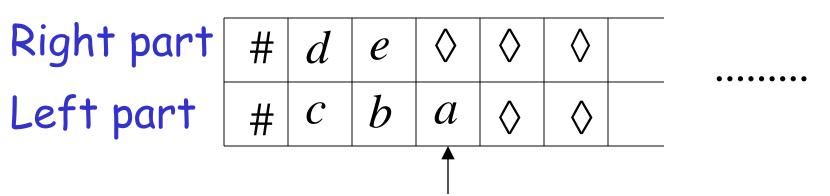
Trivial

Semi-infinite tape machines simulate Standard Turing machines:

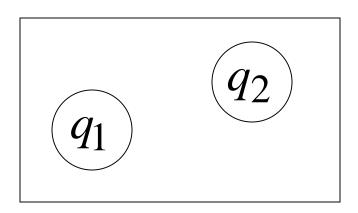




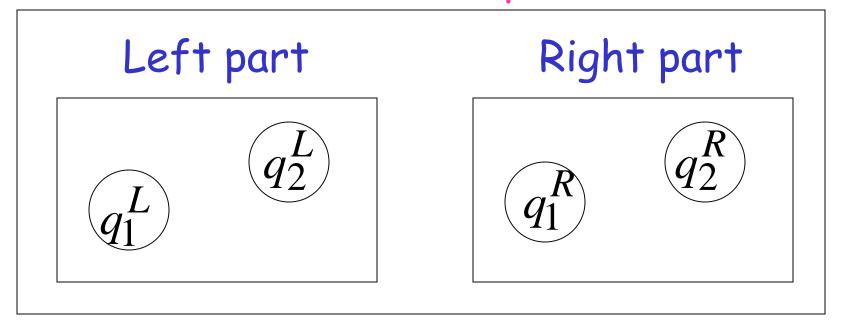
Semi-infinite tape machine with two tracks



Standard machine



Semi-infinite tape machine



Standard machine

$$\underbrace{q_1} \quad \stackrel{a \to g, R}{\longrightarrow} \underbrace{q_2}$$

Semi-infinite tape machine

Right part

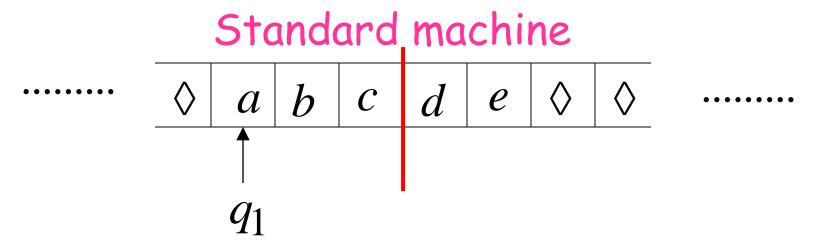
$$\underbrace{q_1^R} \xrightarrow{(a,x) \to (g,x),R} \underbrace{q_2^R}$$

Left part

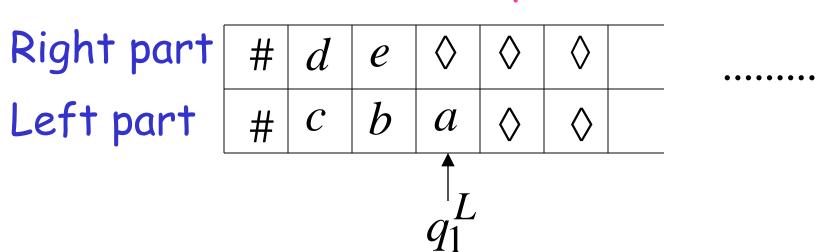
$$\underbrace{q_1^L} \xrightarrow{(x,a) \to (x,g),L} \underbrace{q_2^L}$$

For all symbols x

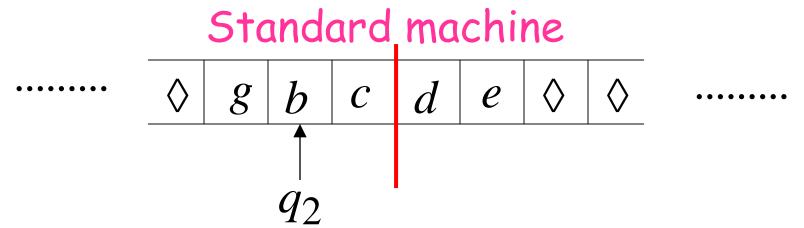
Time 1



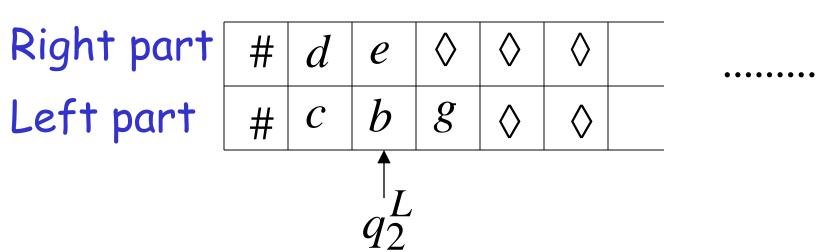
Semi-infinite tape machine



Time 2



Semi-infinite tape machine



At the border:

Semi-infinite tape machine

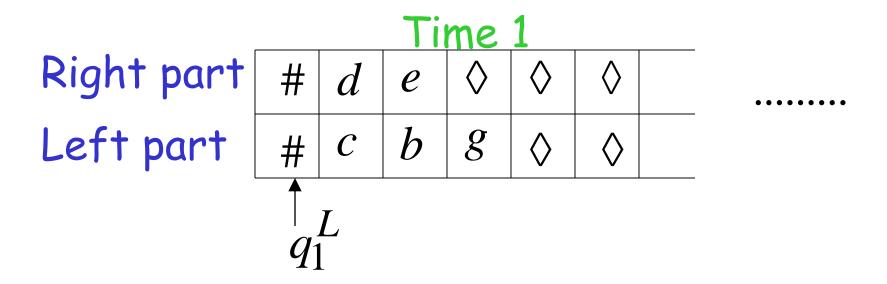
Right part

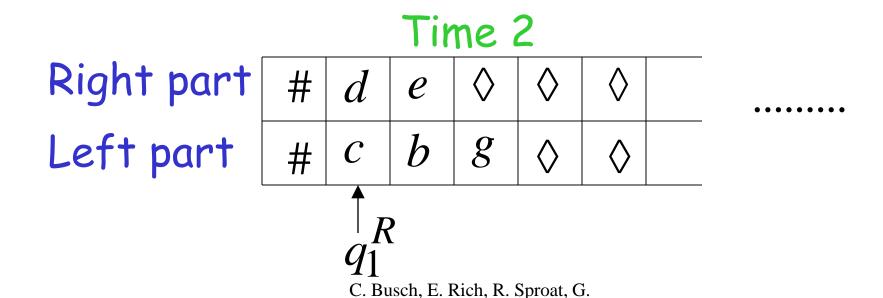
$$\overbrace{q_1^R} \xrightarrow{(\#,\#) \to (\#,\#), R} \overbrace{q_1^L}$$

Left part

$$\underbrace{q_1^L} \xrightarrow{(\#,\#) \to (\#,\#), R} \underbrace{q_1^R}$$

Semi-infinite tape machine

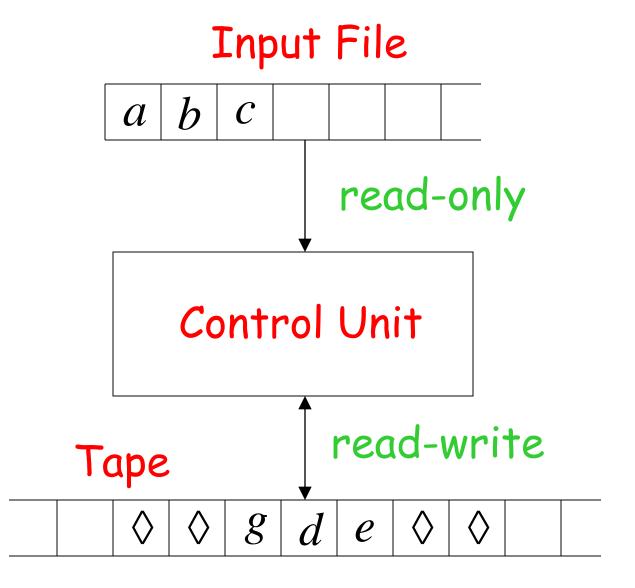




Theorem:

Semi-infinite tape machines have the same power as Standard Turing machines

The Off-Line Machine



Proof of equivalence?

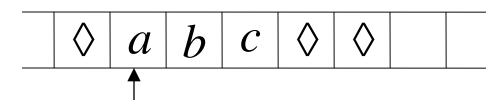
Off-line machines simulate Standard Turing Machines:

Off-line machine:

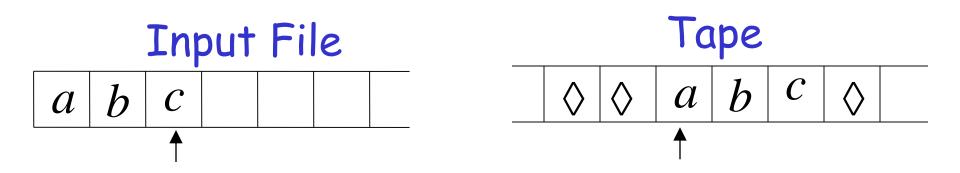
1. Copy input file to tape

2. Continue computation as in Standard Turing machine

Standard machine

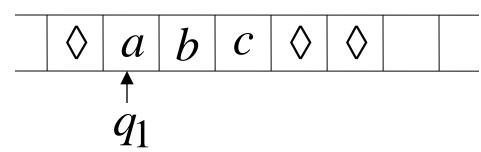


Off-line machine

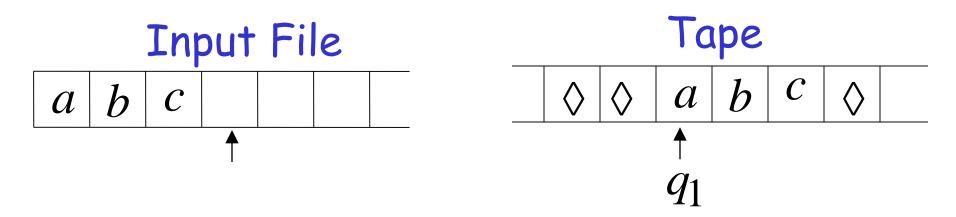


1. Copy input file to tape

Standard machine



Off-line machine

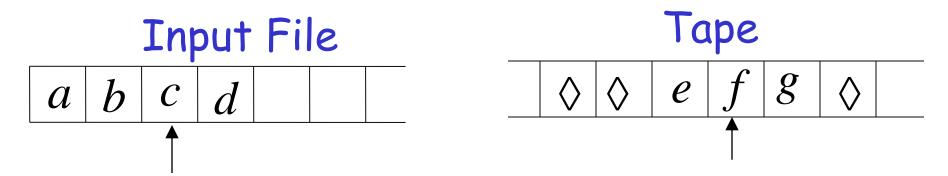


2. Do computations as in Turing machine

Standard Turing machines simulate Off-line machines:

Use a Standard machine with four track tape to keep track of the Off-line input file and tape contents

Off-line Machine

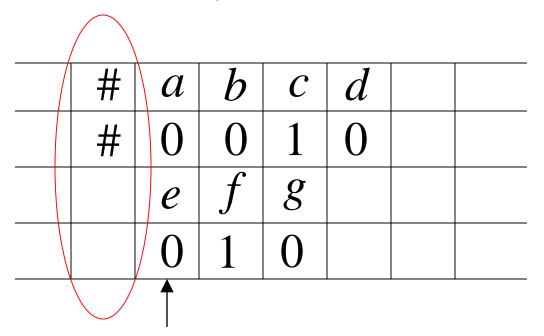


Four track tape -- Standard Machine

| # | а | b | C | d | Input File |
|---|----------|---|---|---|---------------|
| # | 0 | 0 | 1 | 0 | head position |
| | e | f | g | | Tape |
| | 0 | 1 | 0 | | head position |
| • | ↑ | 1 | ı | 1 | <u> </u> |

C. Busch, E. Rich, R. Sproat, G.

Reference point



Input File
head position
Tape
head position

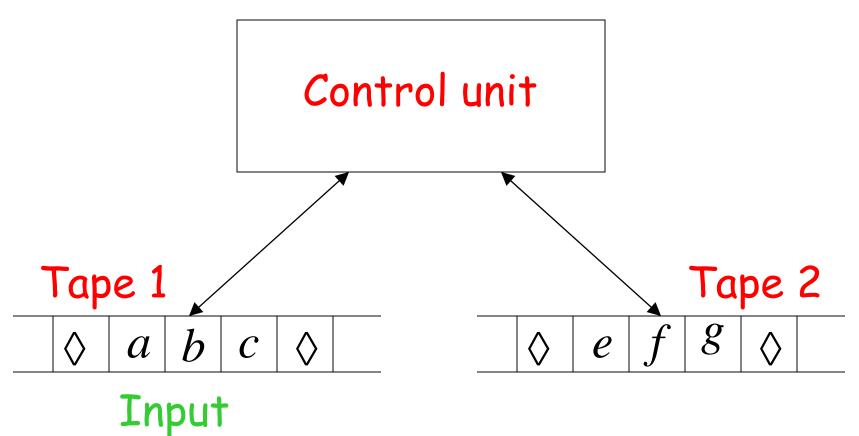
Repeat for each state transition:

- Return to reference point
- Find current input file symbol
- · Find current tape symbol
- Make transition

Theorem:

Off-line machines have the same power as Standard machines

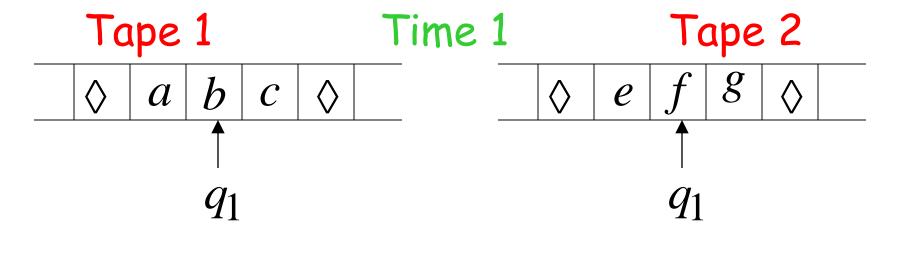
Multitape Turing Machines



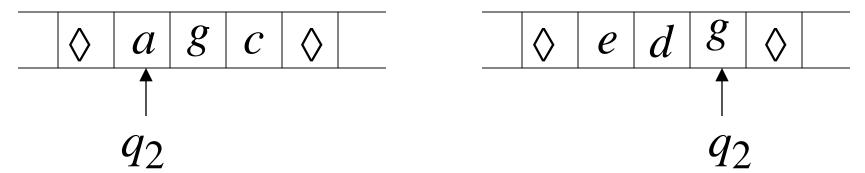
$$\delta: Q \times \Gamma^n \to Q \times \Gamma^n \times \{L, R\}^n$$

$$\delta(q_0, a, e) = (q_1, x, y, L, R)$$

C. Busch, E. Rich, R. Sproat, G.



Time 2



$$\underbrace{q_1}^{(b,f) \to (g,d),L,R} \underbrace{q_2}$$

Proof of equivalence?

Multitape machines simulate Standard Machines:

Use just one tape

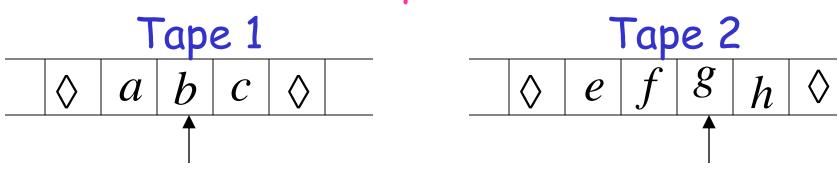
Standard machines simulate Multitape machines:

Standard machine:

· Use a multi-track tape

 A tape of the Multiple tape machine corresponds to a pair of tracks

Multitape Machine

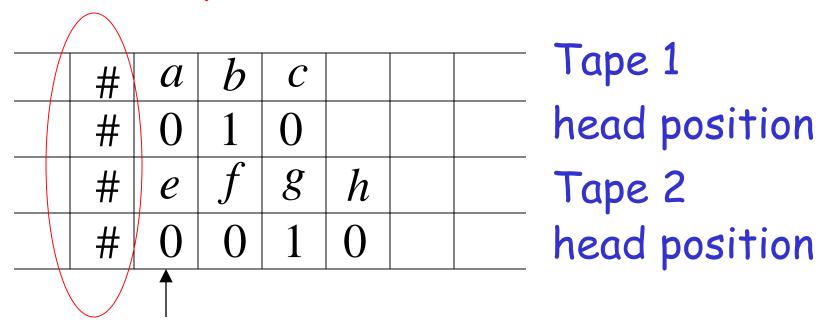


Standard machine with four track tape

| а | b | C | | Tape 1 |
|---|---|---|---|---------------|
| 0 | 1 | 0 | | head position |
| e | f | g | h | Tape 2 |
| 0 | 0 | 1 | 0 | head position |
| 1 | 1 | 1 | • | |

C. Busch, E. Rich, R. Sproat, G.

Reference point



Repeat for each state transition:

- ·Return to reference point
- ·Find current symbol in Tape 1
- ·Find current symbol in Tape 2
- Make transition

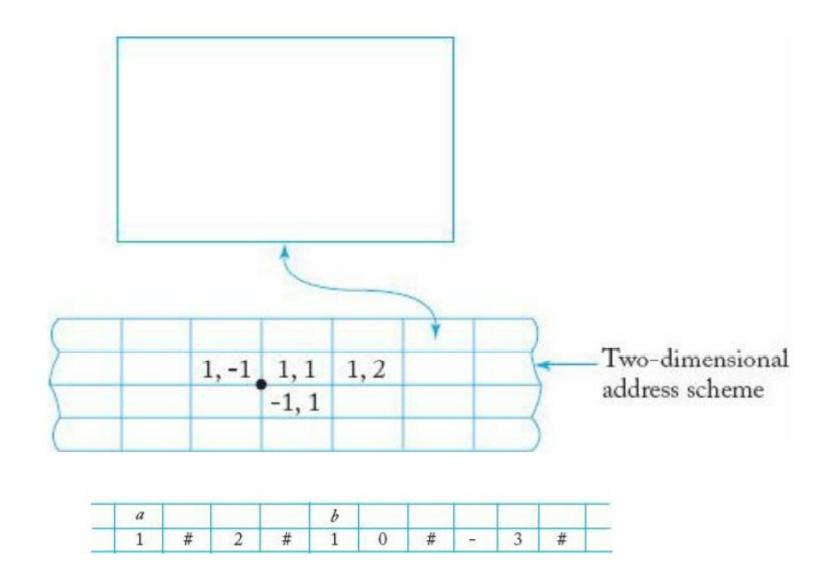
C. Busch, E. Rich, R. Sproat, G.

Theorem:

Multi-tape machines have the same power as Standard Turing Machines

Multidimensional Turing Machines

$$\delta: Q \times \Gamma \rightarrow Q \times \Gamma \times \{L, R, U, D\},\$$



C. Busch, E. Rich, R. Sproat, G. Taylor and M. Volk

A limitation of Turing Machines:

Turing Machines are "hardwired"

they execute only one program

Real Computers are re-programmable

Solution: Universal Turing Machine

Attributes:

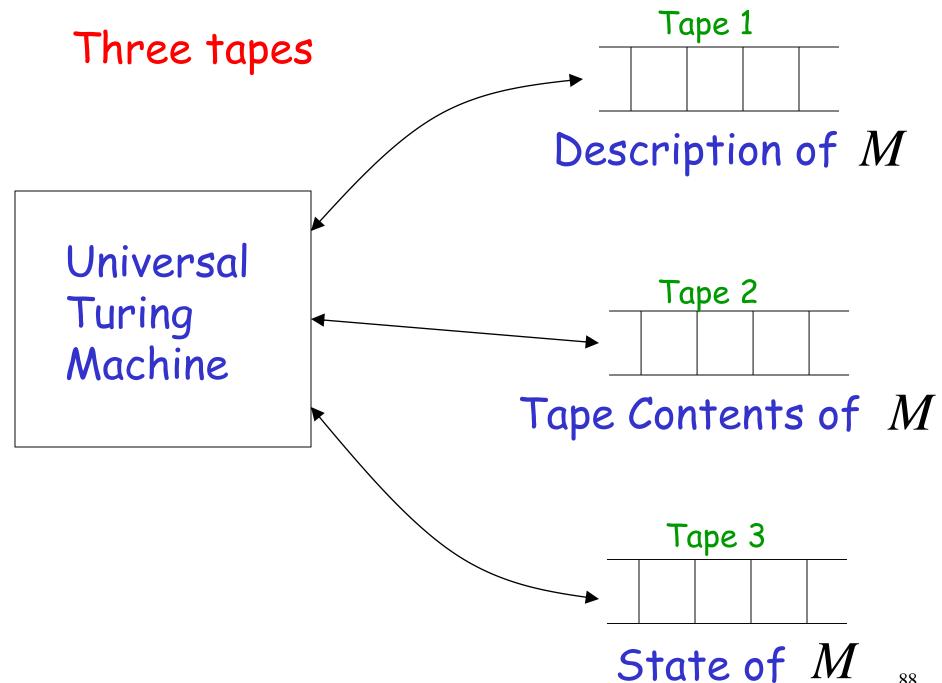
- · Reprogrammable machine
- · Simulates any other Turing Machine

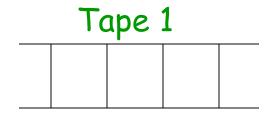
Universal Turing Machine simulates any other Turing Machine M

Input of Universal Turing Machine:

Description of transitions of M

Initial tape contents of M



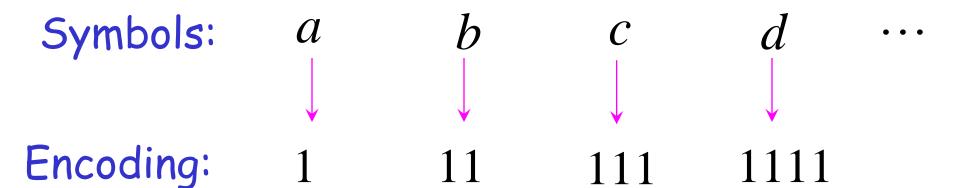


Description of M

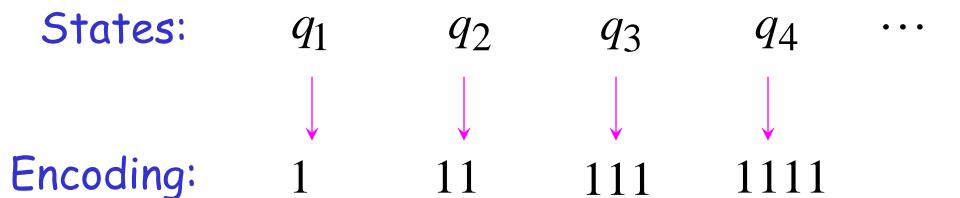
We describe Turing machine M as a string of symbols:

We encode M as a string of symbols

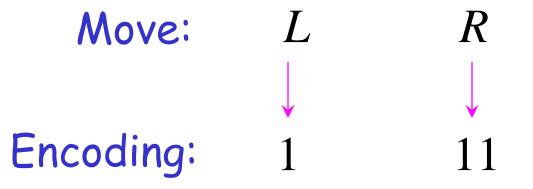
Alphabet Encoding



State Encoding



Head Move Encoding



Transition Encoding

Transition:
$$\delta(q_1,a)=(q_2,b,L)$$

Encoding: 10101101101
separator

Machine Encoding

Transitions:

$$\delta(q_1, a) = (q_2, b, L) \qquad \delta(q_2, b) = (q_3, c, R)$$

Encoding:

10101101101 00 1101101110111011

separator

Tape 1 contents of Universal Turing Machine:

encoding of the simulated machine $_{\it M}$ as a binary string of 0's and 1's

A Turing Machine is described with a binary string of 0's and 1's

Therefore:

The set of Turing machines forms a language:

each string of the language is the binary encoding of a Turing Machine

Language of Turing Machines

```
(Turing Machine 1)
L = \{ 010100101,
     00100100101111,
                           (Turing Machine 2)
     111010011110010101,
     ..... }
```