# Pan tracking webcam using OpenCV and Arduino

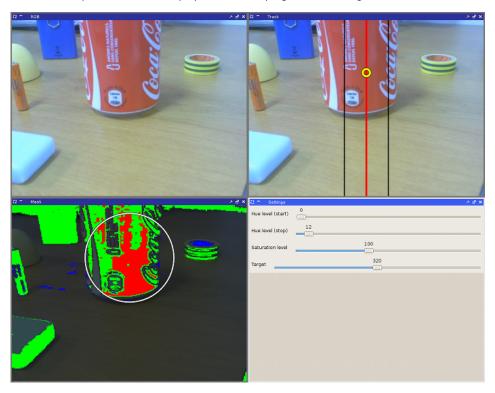
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## 1. Overview

## 1.1. OpenCV

The various  $\mbox{\sc OpenCV}$  windows displayed while the program is running:

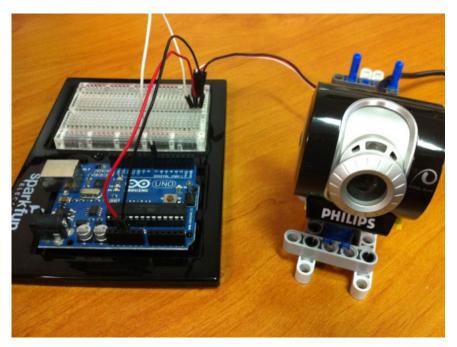


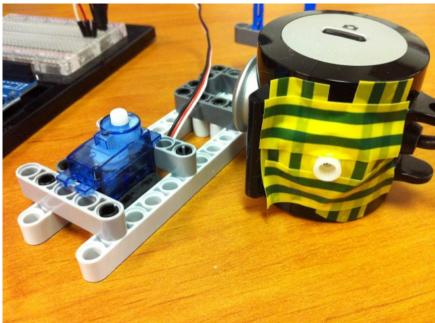
(That's Linux, using the Sawfish window manager with mxflat theme.)

#### 1.2. Arduino

I'm using a Philips SPC900NC webcam (from which I removed the part used to fix it on a monitor). I used adhesive tape to bind the motor support to the webcam.

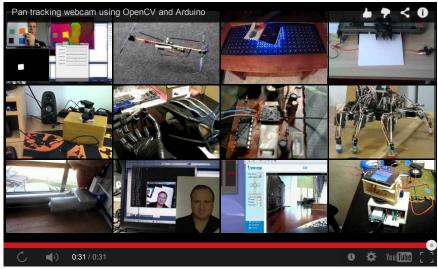
The Arduino board and the motor come from the Arduino kit prepared by Sparkfun. See <a href="http://www.sparkfun.com/products/10173">http://www.sparkfun.com/products/10173</a>.





# 1.3. Example

A video showing how the webcam is controlled accordingly to the object to track:



(You need Javascript or a HTML5 capable browser to play the video.)

## 2. Source code

#### There are 2 programs:

- 1. the OpenCV program which track the object from the webcam and send orders to Arduino to position the servo motor. You can download it from <a href="http://doc.tuxee.net/tracking.cc">http://doc.tuxee.net/tracking.cc</a>.
- 2. the Arduino program which receive orders from the OpenCV program. You can download it from <a href="http://doc.tuxee.net/tracking-arduino.cc">http://doc.tuxee.net/tracking-arduino.cc</a>.

The protocol is very simple between OpenCV and Arduino: the program transmit one integer per line through the serial connection (using the USB connection or a RS232 port). Each integers gives the position (in microseconds) of the servo motor to set.

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