SI 211: Numerical Analysis

Solution of Homework 1

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1. (a) $x = \pi$

Exact solution is: 0 and Matlab solution is: -1.54597494809480e-13.

So the numerical approximation error is: -1.54597494809480e-13.

The reason for this error is that π is stored with finite precision in the computers.

(b)

Here, we can use Taylor Expansion at $x_0 = 0$ to approaximate to exact value of $\sin(10^4 * x)$.

By using first order approximation of Taylor expansion, we have

$$f(x) = \frac{10^4 x + o(x^2)}{x} = 10^4 + o(x)$$

Thus the numerical evaluation error calculated by Julia is

$$Julia > h(x) = \sin(1e4*x)/x$$

Julia > abs(h(1e-10)-1e4)

By using fourth order approximation of Taylor expansion, we have

$$f(x) = \frac{10^4 x - 10^{12} x^3 + o(x^5)}{x} = 10^4 + 10^{12} * x^2 + o(x^4)$$

Thus the numerical evaluation error calculated by Julia is

Julia>
$$h(x)=\sin(1e4*x)/x$$

Julia> abs(h(1e-10)-1e4-1e-8)

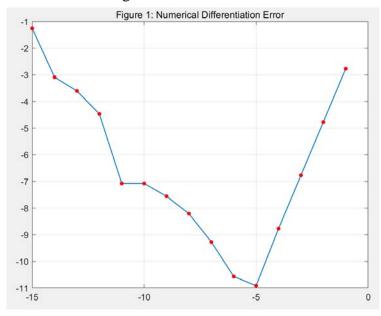
we eventually get the error $\approx 10^{-8}$

2. (a) Function *diff* code in Matlab:

(b) Evaluate the derivative of the function f(x) = exp(x) at x = 0, and $h \in [10^{-15}, 10^{-1}]$

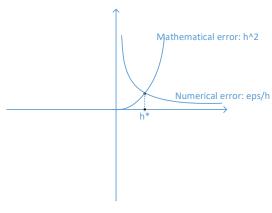
```
x = log10(h);
y = log10(e);
plot(x,y);hold on
plot(x,y,'r.','MarkerSize',10);
```

The result is shown in the figure 1



Interpret the result:

The numerical differentiation error is produced by numerical error and mathematical error together, the error dominated by h^2 when h is greater than h^* , in the other hand, the error dominated by $\frac{eps}{h}$ when h is less than h^* .



error(h)
$$\approx h^2 + \frac{eps}{h}$$

$$\frac{d}{dh}error(h^*) = 2h^* - \frac{eps}{h^{*2}} = 0$$

$$h^* = \sqrt[3]{eps} \approx 10^{-5}$$

3. Algorithmic differentiation

$$b_0 = 1$$

$$b_1 = -\sin(a_0) * b_0$$

$$b_2 = a_1 * b_1 + b_1 * a_1$$

$$b_3 = \cos(a_1) * b_1$$

$$b_4 = a_2 * b_3 + b_2 * a_3$$

$$f'(x) = b_4$$

The derivative of f(x) at x = 0 is: 0 using AD code, the actual derivative is 0, so the numerical error is 0, and the order of magnitude of the numerical error also is 0.

Julia Code

```
import Base.*
import Base.sin
import Base.cos
mutable struct ADV
      а
     b
end
function *(A::ADV,B::ADV)
    return ADV(A.a*B.a,A.a*B.b+A.b*B.a);
end
function sin(A::ADV)
    return ADV(sin(A.a),cos(A.a)*A.b)
end
function cos(A::ADV)
    return ADV(cos(A.a),-sin(A.a)*A.b)
end
function f(x)
    return sin(cos(x))*cos(x*x)
end
```

Get the Result

```
x = ADV(0,1)

f(x)

ADV(0.8414709848078965, -0.0)
```