# Tiefe Neuronale Netze für die bildbasierte Segmentierung und Lokalisierung chirurgischer Instrumente

Bachelorarbeit - Amelie Wagner

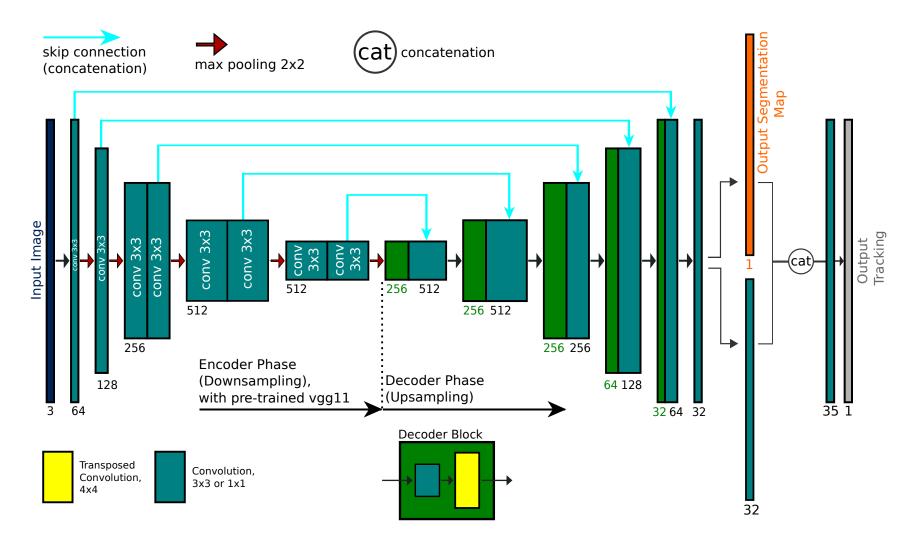


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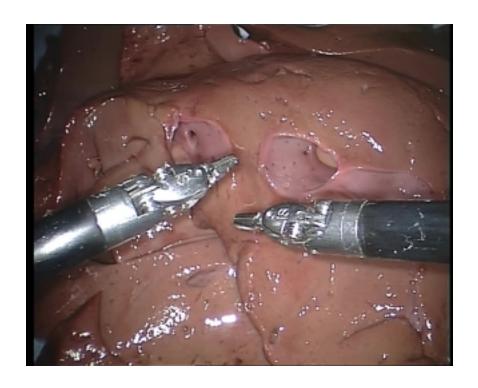
German Cancer Research Center University Hospital Carl Gustav Carus Dresden Carl Gustav Carus Faculty of Medicine, TU Dresden Helmholtz-Zentrum Dresden-Rossendorf

#### Netzwerkstruktur: modifiziertes U-Net [1]



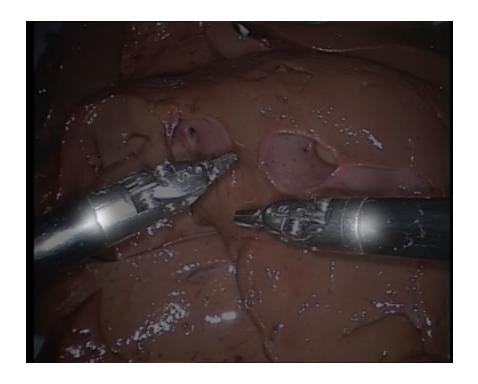


#### 2 Instrumente, EndoVis15 subchallenge [1]



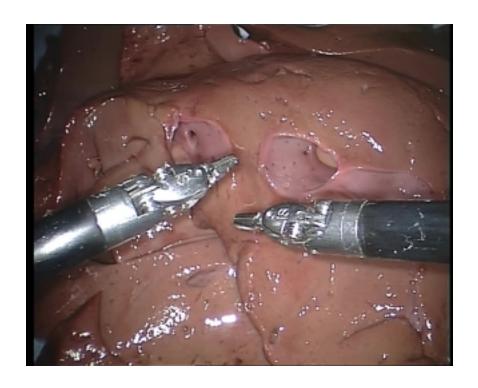


2 Instrumente,EndoVis15 subchallenge [1]+ Ground truth Lokalisierung





#### 2 Instrumente, EndoVis15 subchallenge [1]





2 Instrumente,EndoVis15 subchallenge [1]+ Ground truth Segmentierung

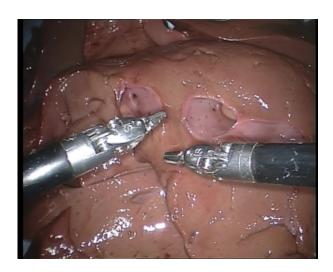




Training mit 100 Epochen

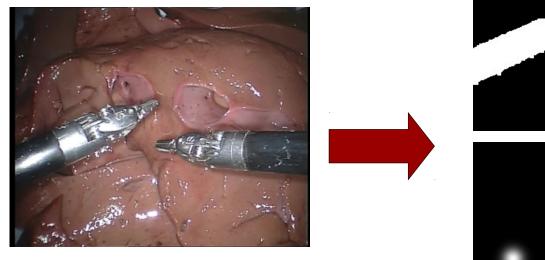


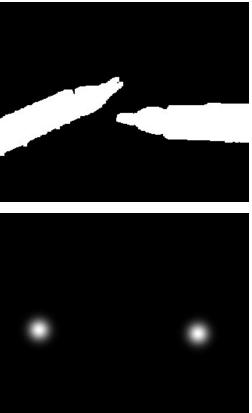
- 2 Instrumente, EndoVis15 tracking subchallenge [2]
- Training: 100 Epochen





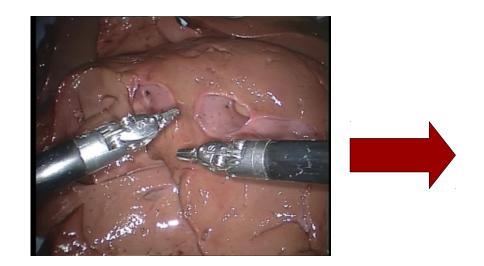
- 2 Instrumente, EndoVis15 tracking subchallenge [2]
- Training: 100 Epochen

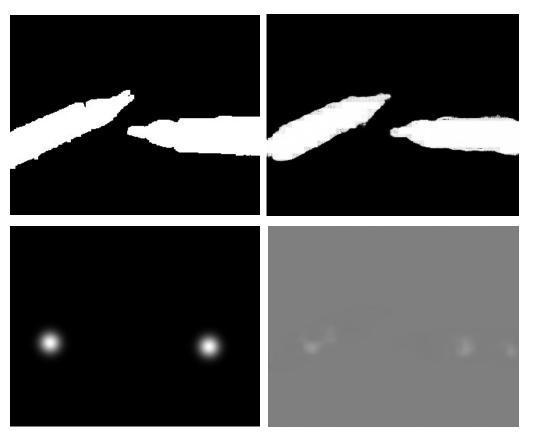






- 2 Instrumente, EndoVis15 tracking subchallenge [2]
- Training: 100 Epochen

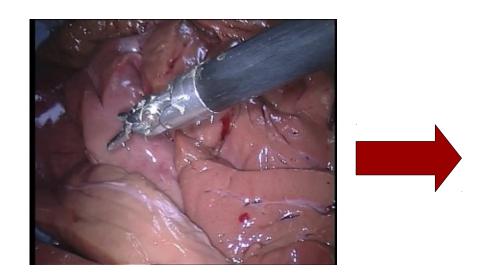


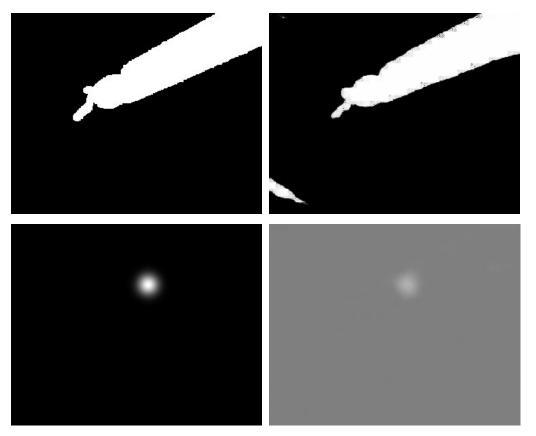




• 1 Instrument, EndoVis15 tracking subchallenge [2]

• Training: 100 Epochen



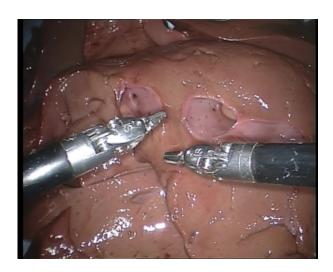




Training mit 900 Epochen



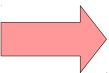
- 2 Instrumente, EndoVis15 tracking subchallenge [2]
- Training: 900 Epochen

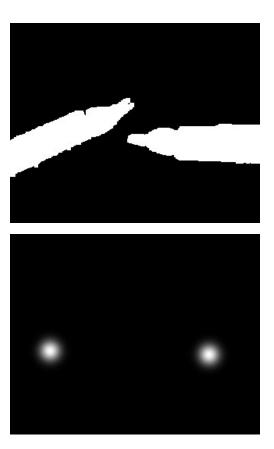




- 2 Instrumente, EndoVis15 tracking subchallenge [2]
- Training: 900 Epochen

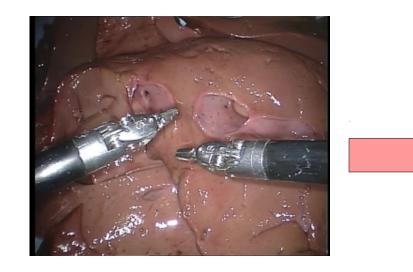


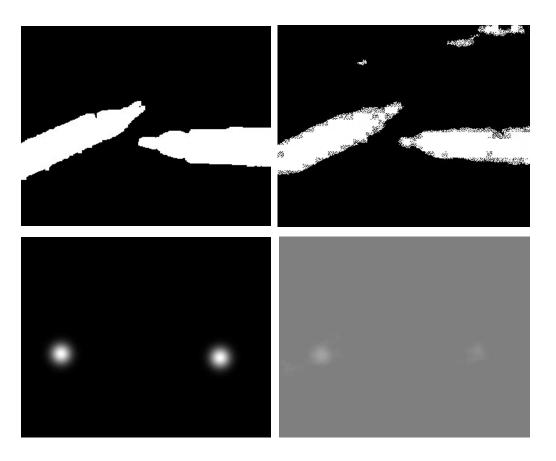






- 2 Instrumente, EndoVis15 tracking subchallenge [2]
- Training: 900 Epochen

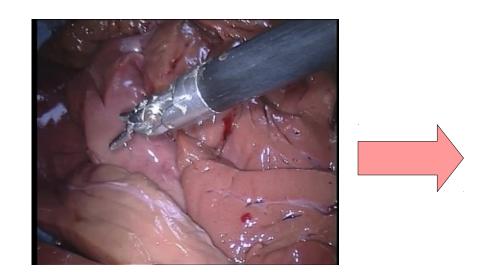


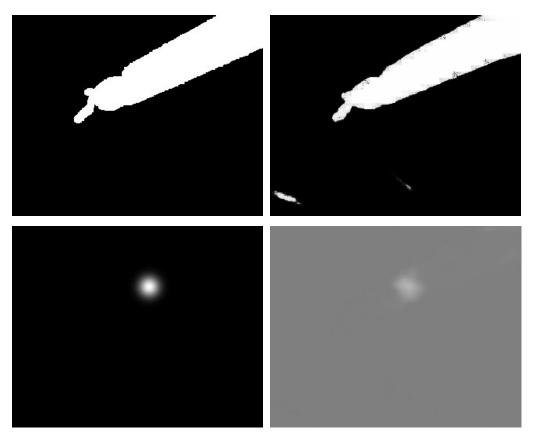




• 1 Instrument, EndoVis15 tracking subchallenge [2]

• Training: 900 Epochen







#### Quellen

- [1] A. Shvets, A. Rakhlin, A. A. Kalinin, and V. Iglovikov, "Automatic Instrument Segmentation in Robot-Assisted Surgery Using Deep Learning"
- [2] https://endovissub-instrument.grand-challenge.org/Data/

