

## Assignment VII - Modal Analysis

- Computer Projects:

1. Write a code to complete the shielded microstrip problem to obtain the first  $TM_{01}$  mode. Assume  $h = w/2 = 2$  mm,  $\epsilon_r = 4$ ,  $a = 40h$  and  $b = 2.5h$ .  $M_h$  should be even and no less than 10.
2. Start with  $f = 2$  GHz and demonstrate the following two solution observations:
  - (a) Within the substrate space under the trace,  $E_z$  will indeed articulate  $TM_{01}$  behavior.
  - (b) Throughout the cross-section, however, substrate region will have limited effect on where the peak  $E_z$  location(s) are, whereas the trace will cause the field distribution to mimic a  $TM_{21}$  mode as far as the  $a \times b$  metal enclosure is concerned.
3. Repeat the analysis at 40 GHz and demonstrate the increased role of the substrate on field distribution.
4. Calculate, at 40 GHz, the energy percentage contained within the substrate, compared to the total energy in the microstrip's cross-section.

### Theory

#### Gauss-Seidel Iterative Method with Over-Relaxation

The Gauss-Seidel (G-S) method is a classical iterative technique for solving systems of linear equations, particularly those arising from finite-difference (FD) approximations of partial differential equations (PDEs). It is especially effective for sparse systems and large-scale numerical simulations such as electromagnetic field problems in waveguides or microstrip lines.

##### 1. Finite Difference Formulation

For a second-order differential equation such as:

$$f''(x) - 2f(x) = 0, \quad f(0) = 1, \quad f'(1) = 0$$

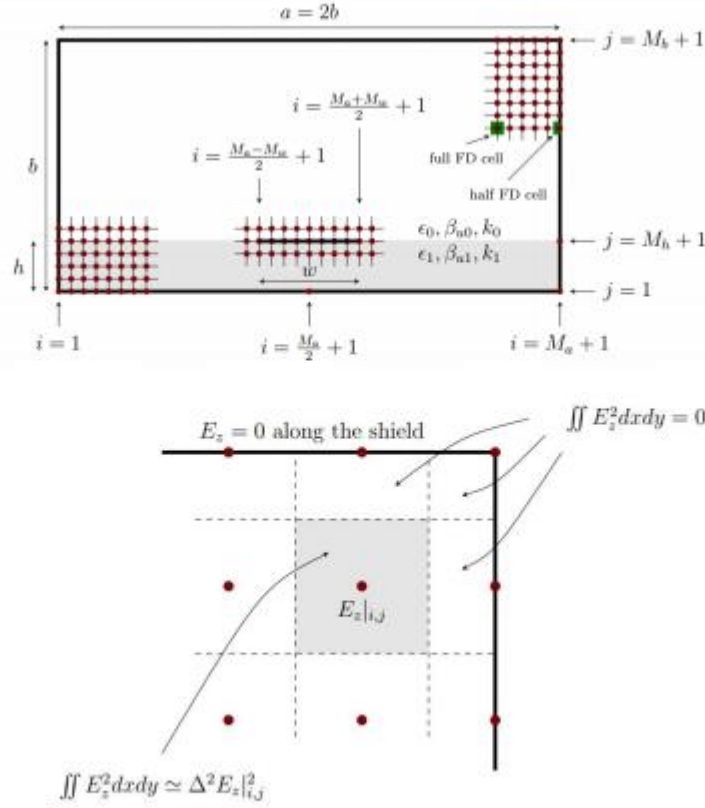
we discretize the domain into a grid and apply finite differences. The central difference approximation gives:

$$\frac{f_{i+1} - 2f_i + f_{i-1}}{\Delta^2} - 2f_i = 0$$

which rearranges to the Gauss-Seidel update formula:

$$f_i^{(n)} = \frac{f_{i+1}^{(n-1)} + f_{i-1}^{(n)}}{2(1 + \Delta^2)}$$

Here,  $f_i^{(n)}$  is the updated value at iteration  $n$ , using the most recent values of neighboring points.



- Let us consider the eigenvalue problem of the open microstrip line in Fig. 7.3, where  $w = 2h = 4$  mm.
- We are interested in isolating the first TM mode underneath the trace (TM<sub>01</sub>) which signifies a half cycle change vertically and a variation across the trace's width which is governed by its expected U-shaped current density distribution.
- The corresponding wave equation is

$$(\nabla^2 + \beta_u^2)E_z(x, y) e^{-\gamma z} = 0 \rightarrow \underbrace{\left( \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \beta_u^2 + \gamma_z^2 \right)}_{\nabla_T^2 = k^2} E_z = 0$$

where  $\beta_u^2 = \omega^2 \mu_0 \epsilon_0$  in air and  $\omega^2 \mu_0 \epsilon_0 \epsilon_r$  within the substrate, with the corresponding boundary condition  $E_z = 0$  along the two conductors.

- To truncate the discrete model, we will enclose the open microstrip structure with an  $a \times b$  PEC box where  $a = 10w$  and  $b = a/2$  and the ground plane forming the base of this box.
- We will then divide the cross-section into square FD cells such that we have  $M_h$  cells between trace and ground plane. The other cell counts of import are  $M_w = 2M_h$ ,  $M_a = 20M_h$  and  $M_b = 10M_h$ , as defined in Fig. 7.4. (Figure is not fully to scale,  $a = 5w$  was used.)
- Thus divided, we can approximate the wave equation with the following FD equation for every node not lying on a PEC occupied space within the shielded enclosure

$$\frac{\overbrace{E_z|_{i+1,j} + E_z|_{i-1,j} + E_z|_{i,j+1} + E_z|_{i,j-1}}^{S_{i,j}} - 4E_z|_{i,j}}{\Delta^2} + k^2 E_z|_{i,j} = 0$$

- Re-arranging as an update equation renders our first of two leap-frog equations

$$\begin{aligned}
E_z|_{i,j} &= \frac{S_{i,j}}{\alpha_j} \\
\alpha_j &= 4 - (k_j \Delta)^2 \\
k_j^2 &= \begin{cases} k_1^2 & , 2 \leq j \leq M_h \\ (k_1^2 + k_0^2)/2 & , j = M_h + 1 \\ k_0^2 & , M_h + 2 \leq j \leq M_b \end{cases}
\end{aligned} \tag{7.1}$$

- The exception is  $E_z$  must be zero at the trace;

$$E_z|_{i,M_h+1} = 0 \quad \text{when} \quad \frac{M_a - M_w}{2} + 1 \leq i \leq \frac{M_a + M_w}{2} + 1$$

- Furthermore,  $k_0$  and  $k_1$  are related to the unchanging  $\gamma_z$  throughout the *waveguide's* cross-section;

$$\gamma_z^2 = k^2 - \beta_u^2 \rightarrow k_1^2 - \beta_{u1}^2 = k_0^2 - \beta_{u0}^2,$$

leading to

$$\begin{aligned}
k_1^2 &= k_0^2 + \beta_{u1}^2 - \beta_{u0}^2 = k_0^2 + \beta_{u0}^2(\epsilon_r - 1) \\
\frac{k_0^2 + k_1^2}{2} &= k_0^2 + \beta_{u0}^2 \frac{\epsilon_r - 1}{2}
\end{aligned}$$

- The second leap-frog equation is obtained from the following chosen inner product

$$\begin{aligned}
\langle E_z, \mathcal{L}E_z \rangle &= \int_{\Omega_x} \int_{\Omega_y} E_z (\nabla_T^2 + k^2) E_z dx dy = 0 \\
\underbrace{\int_{\Omega_x} \int_{\Omega_y} E_z \nabla_T^2 E_z dx dy}_{= I_1} &+ \underbrace{\int_{\Omega_x} \int_{\Omega_y} k^2 E_z^2 dx dy}_{= I_2} = 0
\end{aligned}$$

$$I_1 \simeq \sum_{i=2}^{M_a} \sum_{j=2}^{M_b} E_z|_{i,j} [S_{i,j} - 4E_z|_{i,j}] \tag{7.2}$$

$$I_2 \simeq \Delta^2 \sum_{i=2}^{M_a} \left\{ \sum_{j=2}^{M_h} k_1^2 E_z^2|_{i,j} + \sum_{j=M_h+2}^{M_b} k_0^2 E_z^2|_{i,j} + \frac{k_0^2 + k_1^2}{2} E_z^2|_{i,M_h+1} \right\} \tag{7.3}$$

$$\begin{aligned}
&\simeq k_0^2 \underbrace{\Delta^2 \sum_{i=2}^{M_a} \sum_{j=2}^{M_b} E_z^2|_{i,j}}_{= I_{2a}} + \underbrace{\beta_{u0}^2(\epsilon_r - 1) \Delta^2 \sum_{i=2}^{M_a} \left[ \frac{1}{2} E_z^2|_{i,M_h+1} + \sum_{j=2}^{M_h} E_z^2|_{i,j} \right]}_{= I_{2b}} \\
&\tag{7.4}
\end{aligned}$$

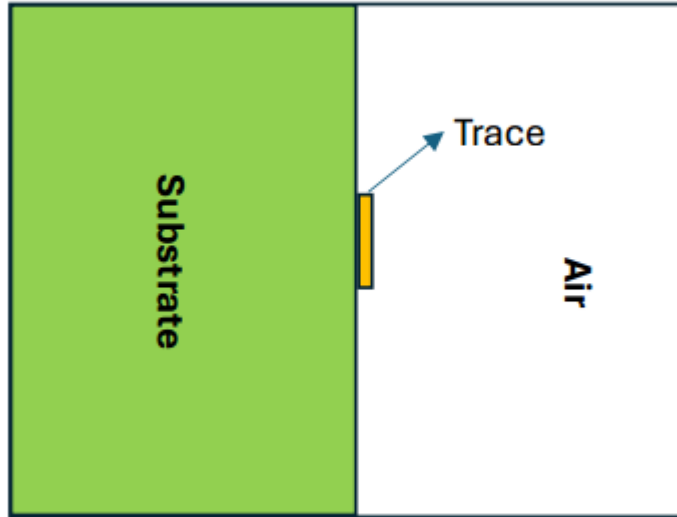
- The following is resulting second iterative update equation

$$k_0^2 = -\frac{I_1 + I_{2b}}{I_{2a}} \tag{7.5}$$

- To capture the TM<sub>01</sub> mode under the trace we can start leap-frogging equations (7.1–7.5) with the following initial guess

$$E_z|_{i,j} = \sin \frac{\pi(j-1)}{M_h}, \quad j = 2, 3, \dots, M_h \tag{7.6}$$

with zero values everywhere else.



## 2. Gauss-Seidel Algorithm

The algorithm proceeds by sweeping through all interior points of the domain and updating each value based on the latest available neighboring values. The boundary conditions are applied explicitly and remain fixed throughout the iterations.

## 3. Over-Relaxation

To accelerate convergence, a **relaxation factor**  $R$  is introduced:

$$f_i^{(n)} = R \cdot \tilde{f}_i^{(n)} + (1 - R) \cdot f_i^{(n-1)}$$

where  $\tilde{f}_i^{(n)}$  is the updated value from the standard Gauss-Seidel step. This technique is known as **Successive Over-Relaxation (SOR)**. For over-relaxation,  $R > 1$ ; the optimal value of  $R$  is problem-specific but typically lies in the range  $1.2 \leq R \leq 1.5$ .

## 4. Convergence Criteria

The iteration continues until the solution converges, typically defined by:

$$\max_i |f_i^{(n)} - f_i^{(n-1)}| < \epsilon$$

for some small threshold  $\epsilon$  (e.g.,  $10^{-6}$ ).

## 5. Application in Waveguide/Microstrip Problems

In solving Helmholtz or Poisson equations for waveguide cross-sections or electrostatic problems, the Gauss-Seidel method iteratively updates the scalar field (e.g.,  $E_z$  or potential  $\phi$ ) across the 2D mesh. Over-relaxation significantly improves convergence speed, especially for high-resolution meshes.

**CODE:**

```
1 % format and initialization
2 format long
3 clearvars
4 close all
5
6 % Constants
7 frequencies = [2e9, 40e9]; % Frequencies in Hz
8 er = 4;
9 u0 = 4 * pi * 1e-7;
10 e0 = 8.8542e-12;
11
12 % Geometry
13 w = 4e-3;
14 h = w / 2;
15 a = 40 * h; % horizontal length
16 b = 2.5 * h; % vertical length
17
18 % Mesh parameters
19 Mh = 10; % cells in height
20 Mw = 2 * Mh; % width
21 Ma = 40 * Mh; % horizontal resolution
22 Mb = 2.5 * Mh; % vertical resolution
23
24 del_a = a / Ma;
25 del_b = b / Mb;
26
27 % Loop over frequencies
28 for f = frequencies
29     omega = 2 * pi * f;
30     Bu0 = omega * sqrt(u0 * e0);
31
32     % Initialization
33     s = zeros(Ma + 1, Mb + 1);
34     Ez = zeros(Ma + 1, Mb + 1);
35     Ez_previous = Ez;
36     alpha = zeros(Mb + 1, 1);
37     k_sq = zeros(Mb + 1, 1);
38
39     % Initial guess for Ez
40     for i = 2:Ma
41         for j = 2:Mh
42             Ez(i, j) = sin((pi * (j - 1)) / Mh);
43         end
44     end
45
46     % Iterative FDFD solver
47     iteration = 0;
```

```

48 convergence = 0;
49 tol = 1e-4;
50
51 while ~convergence
52     Ez_previous = Ez;
53     iteration = iteration + 1;
54
55     % Calculate s
56     for i = 2:Ma
57         for j = 2:Mb
58             s(i, j) = Ez(i, j + 1) + Ez(i, j - 1) + Ez(i + 1, j) + Ez(i - 1, j);
59         end
60     end
61
62     % I1 term
63     I1 = 0;
64     for i = 2:Ma
65         for j = 2:Mb
66             I1 = I1 + (Ez(i, j) * s(i, j) - 4 * Ez(i, j)^2);
67         end
68     end
69
70     % I2a term

```

```

71     I2a = sum(sum(Ez(2:Ma, 2:Mb).^2)) * del_a * del_b;
72
73     % I2b term (substrate region only)
74     I2b = sum(sum(Ez(2:Ma, 2:Mh).^2));
75     for i = 2:Ma
76         I2b = I2b + 0.5 * Ez(i, Mh + 1)^2;
77     end
78     I2b = I2b * (Bu0^2 * (er - 1) * del_a * del_b);
79
80     % Compute k^2
81     k0_sq = - (I1 + I2b) / I2a;
82     k1_sq = k0_sq + Bu0^2 * (er - 1);
83
84     for j = 2:Mb
85         if j <= Mh
86             k_sq(j) = k1_sq;
87         elseif j == Mh + 1
88             k_sq(j) = (k1_sq + k0_sq) / 2;
89         else
90             k_sq(j) = k0_sq;
91         end
92         alpha(j) = 4 - k_sq(j) * del_a * del_b;
93     end

```

```

94
95     % Over-relaxation update
96     R = 1.3;
97     for relaxation = 1:5
98         for i = 2:Ma
99             for j = 2:Mb
100                 Ez(i, j) = R * (Ez(i, j + 1) + Ez(i, j - 1) + Ez(i + 1, j) + Ez(i - 1, j)) / alpha(j) ...
101                     + (1 - R) * Ez(i, j);
102             end
103             % Enforce trace (center line) Ez = 0
104             if i >= ((Ma - Mw)/2 + 1) && i <= ((Ma + Mw)/2 + 1)
105                 Ez(i, Mh + 1) = 0;
106             end
107         end
108     end

```



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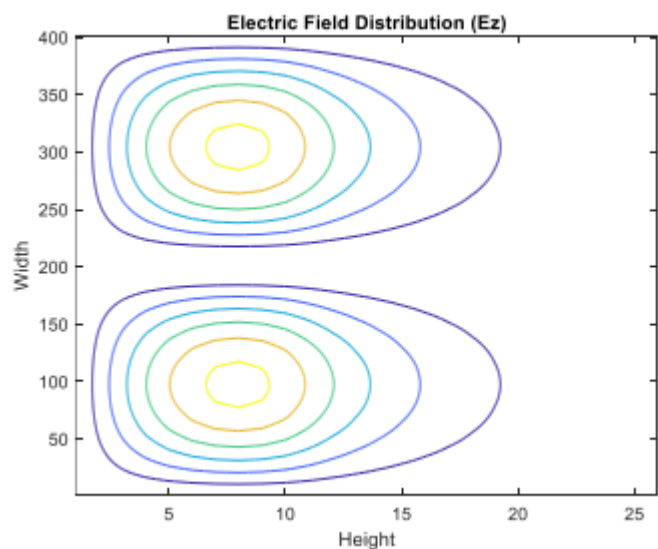
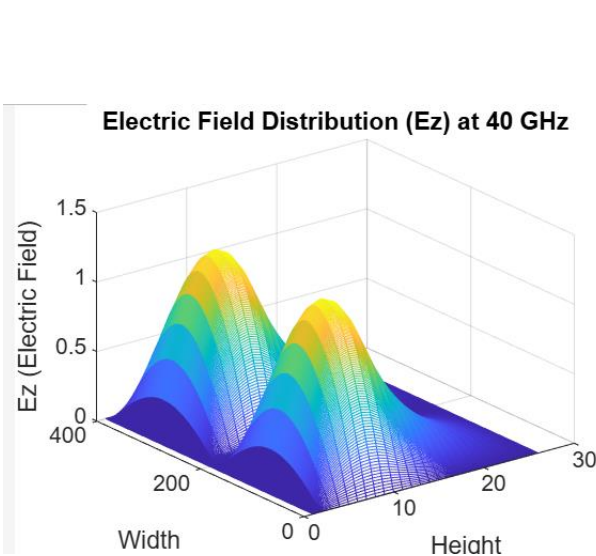
109
110     % Check convergence after 100 iterations
111     if iteration >= 100
112         if max(abs(Ez(:) - Ez_previous(:))) <= tol
113             convergence = 1;
114         end
115     end
116 end
117
118 % Energy computation
119 energy_substrate = sum(sum(Ez(2:Ma, 2:Mh).^2)) * del_a * del_b;
120 energy_substrate = 0.5 * e0 * er * energy_substrate;
121
122 Air_energy = sum(sum(Ez(2:Ma, Mh+1:Mb).^2)) * del_a * del_b;
123 Air_energy = 0.5 * e0 * Air_energy;
124
125 total_energy = energy_substrate + Air_energy;
126
127 energy_percent = (energy_substrate / total_energy) * 100;
128
129 % Display result
130 fprintf('\nEnergy within the substrate when frequency = %.1f GHz is %.2f%%\n', f / 1e9, energy_percent);
131
132 % Plot for each frequency
133 figure;
134 mesh(Ez)
135 xlabel('Height')
136 ylabel('Width')
137 zlabel('Ez (Electric Field)')
138 title(['Electric Field Distribution (Ez) at ', num2str(f/1e9), ' GHz'])
end

```

Energy within the substrate when frequency = 2.0 GHz is 59.90%

Energy within the substrate when frequency = 40.0 GHz is 92.46%

>>



**When Frequency = 2GHz, energy contained within the substrate = 59.9%**

