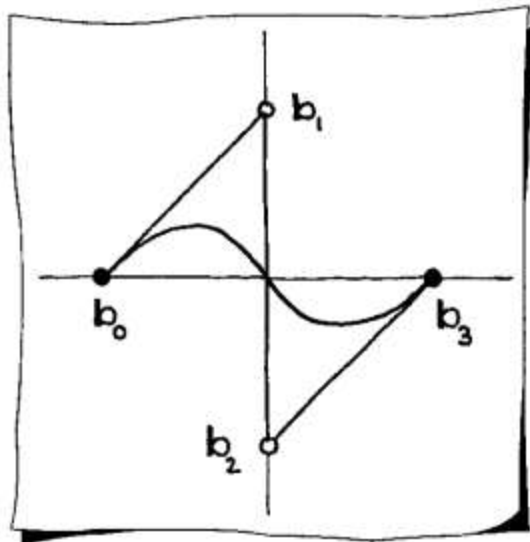


Cubic Bezier Polynomial (Added)



$$\mathbf{x}(t) = (1 - t)^3 \mathbf{b}_0 + 3(1 - t)^2 t \mathbf{b}_1 + 3(1 - t) t^2 \mathbf{b}_2 + t^3 \mathbf{b}_3$$

Example $\mathbf{x}(t) = \begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = \begin{bmatrix} -(1 - t)^3 + t^3 \\ 3(1 - t)^2 t - 3(1 - t) t^2 \end{bmatrix}$



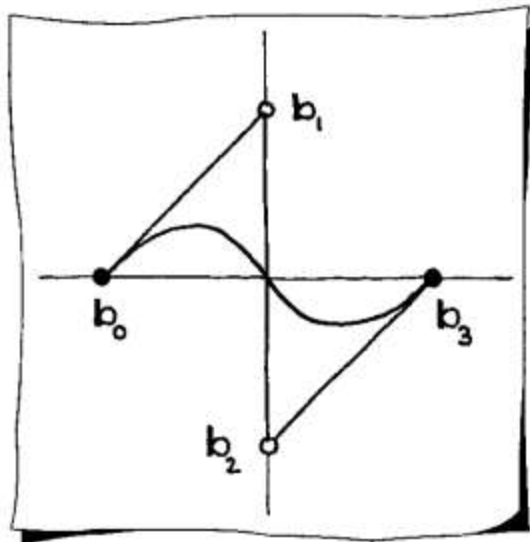
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$$\text{Example } \mathbf{x}(t) = \begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = \begin{bmatrix} -(1 - t)^3 + t^3 \\ 3(1 - t)^2 t - 3(1 - t) t^2 \end{bmatrix}$$

$$\Rightarrow \mathbf{x}(t) = \begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = (1 - t)^3 \begin{bmatrix} -1 \\ 0 \end{bmatrix} + 3(1 - t)^2 t \begin{bmatrix} 0 \\ 1 \end{bmatrix} + 3(1 - t) t^2 \begin{bmatrix} 0 \\ -1 \end{bmatrix} + t^3 \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

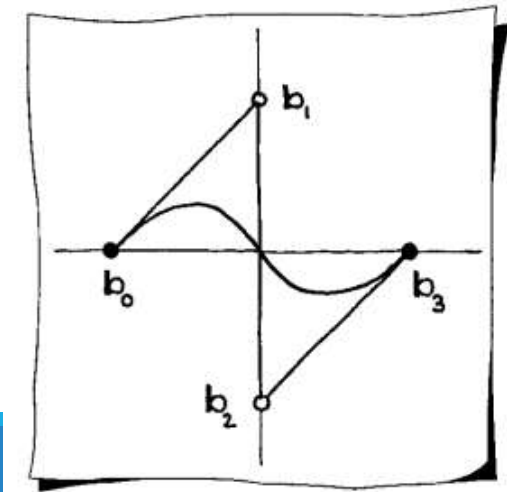


Derivative of Cubic Bezier Polynomial (Added)



$$\text{Example } \mathbf{x}(t) = \begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = \begin{bmatrix} -(1-t)^3 + t^3 \\ 3(1-t)^2t - 3(1-t)t^2 \end{bmatrix}$$

$$\Rightarrow \mathbf{x}(t) = \begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = (1-t)^3 \begin{bmatrix} -1 \\ 0 \end{bmatrix} + 3(1-t)^2t \begin{bmatrix} 0 \\ 1 \end{bmatrix} + 3(1-t)t^2 \begin{bmatrix} 0 \\ -1 \end{bmatrix} + t^3 \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$



Derivative of Cubic Bezier Polynomial (Added)

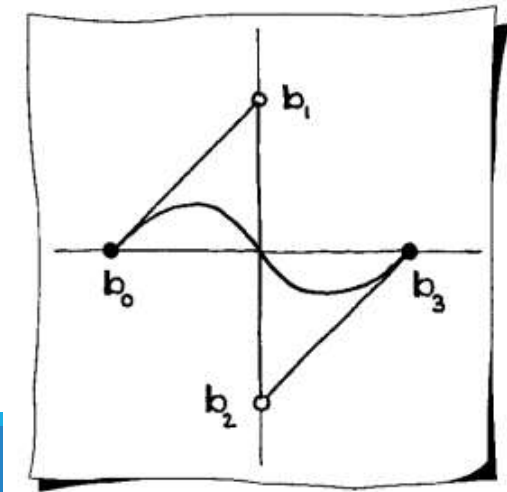


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- Find the first derivative of $\mathbf{x}(t)$

$$\mathbf{x}'(t) = \begin{bmatrix} x'(t) \\ y'(t) \end{bmatrix} = 3 \begin{bmatrix} 1 \\ 1 \end{bmatrix} (1-t)^2 + 6 \begin{bmatrix} 0 \\ -2 \end{bmatrix} (1-t)t + 3 \begin{bmatrix} 1 \\ 1 \end{bmatrix} t^2$$



Uniform Quadratic B-Spline (Added)



9. (15pt)

$$\mathbf{p}_0 = \begin{bmatrix} -1 \\ 0 \end{bmatrix}, \quad \mathbf{p}_1 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \quad \mathbf{p}_2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \quad \mathbf{p}_3 = \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \quad \mathbf{p}_4 = \begin{bmatrix} 2 \\ 2 \end{bmatrix}$$

를 control points로 가지는 2차원 uniform 2차 B-spline 곡선 $\mathbf{f}(t)$ 는 다음과 같이 쓸 수 있다.

$$\mathbf{f}(t) = \sum_{i=0}^4 \mathbf{p}_i N_i^2(t), \text{ where } N_i^2(t) = \begin{cases} \frac{1}{2}r^2, & r = t - \tau_i, \text{ if } t \in [\tau_i, \tau_{i+1}) \\ -r^2 + r + \frac{1}{2}, & r = t - \tau_{i+1}, \text{ if } t \in [\tau_{i+1}, \tau_{i+2}) \\ \frac{1}{2}(1-r)^2, & r = t - \tau_{i+2}, \text{ if } t \in [\tau_{i+2}, \tau_{i+3}) \\ 0, & \text{otherwise.} \end{cases}$$

- (a) (4pt) $\tau_0 = 0, \tau_1 = 1$ 일 때, $\mathbf{f}(t)$ 의 knot sequence를 적으시오.
- (b) (3pt) (a)의 knot sequence를 이용할 때, $\mathbf{f}(3.5)$ 의 값의 계산에 영향을 미치는 (즉, 0이 아닌) $N_i^2(t)$ 를 모두 쓰시오.
- (c) (8pt) (a)의 knot sequence를 이용하여, $\mathbf{f}(3.5)$ 를 계산하시오.