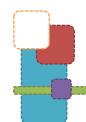


#### Index Construction

Younghoon Kim

(nongaussian@gmail.com)





#### Index construction

- How do we construct an index?
- What strategies can we use with limited main memory?

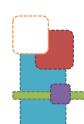




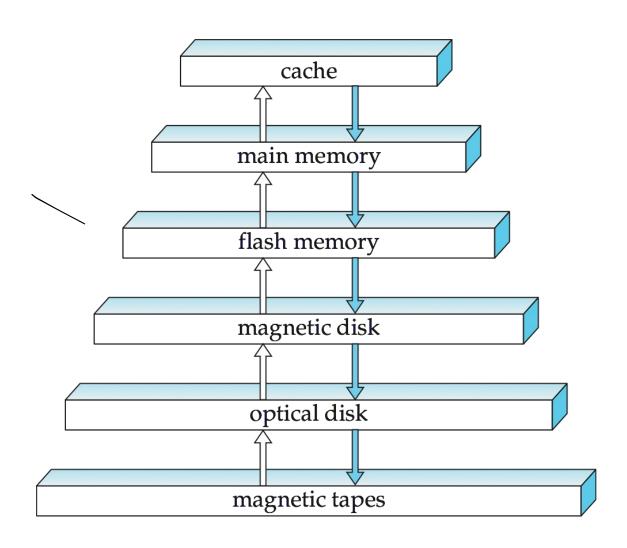
#### Hardware basics

- Many design decisions in information retrieval are based on the characteristics of hardware
- We begin by reviewing hardware basics

#### DISK I/O



# Storage Hierarchy





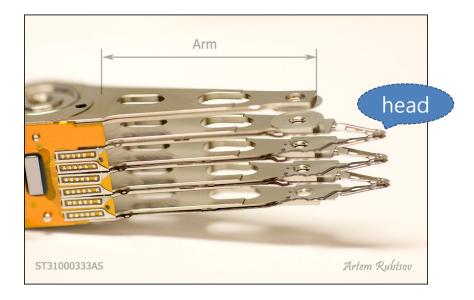
# Storage Hierarchy (Cont.)

- primary storage: Fastest media but volatile (cache, main memory).
- secondary storage: next level in hierarchy, non-volatile, moderately fast access time
  - also called on-line storage
  - E.g. flash memory, magnetic disks
- tertiary storage: lowest level in hierarchy, non-volatile, slow access time
  - also called off-line storage
  - E.g. magnetic tape, optical storage

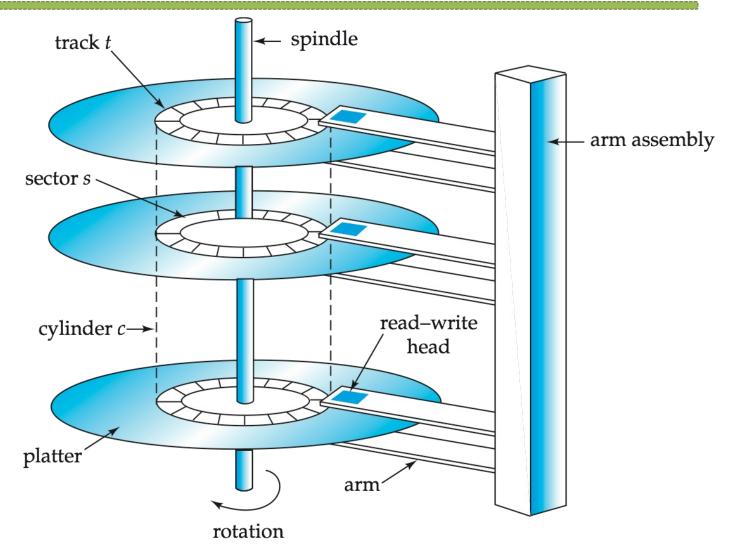
#### Magnetic Hard Disk Mechanism



© CanStockPhoto.com - csp7646757



#### Magnetic Hard Disk Mechanism



NOTE: Diagram is schematic, and simplifies the structure of actual disk drives



#### Magnetic Disks

#### Read-write head

- Positioned very close to the platter surface (almost touching it)
- Reads or writes magnetically encoded information.
- Surface of platter divided into circular tracks
  - Over 50K-100K tracks per platter on typical hard disks
- Each track is divided into sectors.
  - A sector is the smallest unit of data that can be read or written.
  - Sector size typically 512 bytes
  - Typical sectors per track: 500 to 1000 (on inner tracks) to 1000 to 2000 (on outer tracks)
- To read/write a sector
  - disk arm swings to position head on right track
  - platter spins continually; data is read/written as sector passes under head
- Head-disk assemblies
  - multiple disk platters on a single spindle (1 to 5 usually)
  - one head per platter, mounted on a common arm.



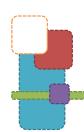
#### Performance Measures of Disks

- Access time (=seek time) the time it takes from when a read or write request is issued to when data transfer begins. Consists of:
  - Seek time time it takes to reposition the arm over the correct track.
    - Average seek time is 1/2 the worst case seek time.
    - 4 to 10 milliseconds on typical disks
  - Rotational latency time it takes for the sector to be accessed to appear under the head.
    - Average latency is 1/2 of the worst case latency.
    - 4 to 11 milliseconds on typical disks (5400 to 15000 r.p.m.)
- Data-transfer rate the rate at which data can be retrieved from or stored to the disk.
  - 25 to 100 MB per second max rate, lower for inner tracks
  - Multiple disks may share a controller, so rate that controller can handle is also important
    - E.g. SATA: 150 MB/sec, SATA-II 3Gb (300 MB/sec)
    - Ultra 320 SCSI: 320 MB/s, SAS (3 to 6 Gb/sec)



#### Optimization of Disk-Block Access

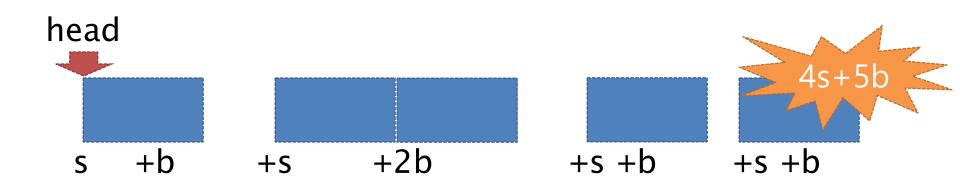
- **Block** a contiguous sequence of sectors from a single track
  - data is transferred between disk and main memory in blocks
  - sizes range from 512 bytes to several kilobytes
    - Smaller blocks: more transfers from disk
    - Larger blocks: more space wasted due to partially filled blocks
    - Typical block sizes today range from 4 to 16 kilobytes

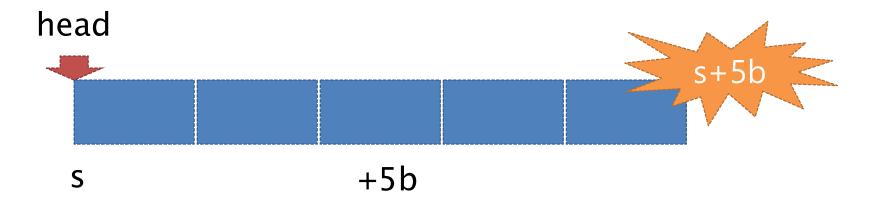


#### Optimization of Disk Block Access

- File organization optimize block access time by organizing the blocks to correspond to how data will be accessed
  - E.g. Store related information on the same or nearby cylinders.
  - Files may <u>get fragmented</u> over time
    - E.g., if data is inserted to/deleted from the file
    - Or free blocks on disk are scattered, and newly created file has its blocks scattered over the disk
    - Sequential access to a fragmented file results in increased disk arm movement
  - Some systems have utilities to defragment the file system, in order to speed up file access

#### Optimization of Disk Block Access





# SORT-BASED INDEX CONSTRUCTION



#### **Index Construction**

- Grouping postings with term
  - $-\rightarrow$  sort
- Scaling sort for large data
  - → external merge-sort

#### Scaling Index Construction

Grouping postings

Term	docID
1	1
did	1
enact	1
julius	1

```
dic = dict()

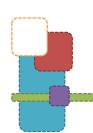
for token, docid in postings:
   if token not in dic:
      dic[token] = list()

dic[token].append(docid)
```

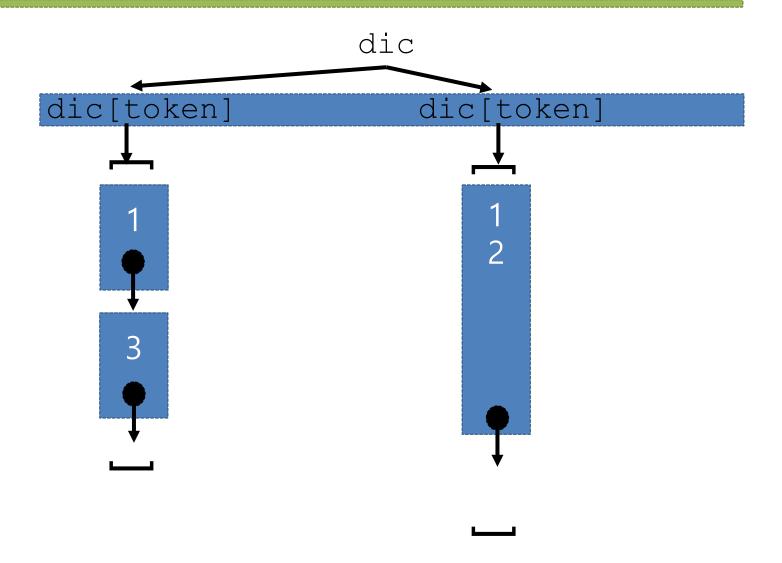


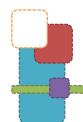






#### Scaling Index Construction





#### Scaling Index Construction

- In-memory index construction does not scale
  - Can't stuff entire collection into memory, sort, then write back
- How can we construct an index for very large collections?
  - Considering the hardware constraints we just learned about . . .
  - Memory, disk, speed, etc.

Let's talk about straightforward methods



## Sort using disk as "memory"?

Can we use the same index construction algorithm for larger collections, but by using disk instead of memory?

head



 No: Sorting on disk is too slow due to too many disk seeks.

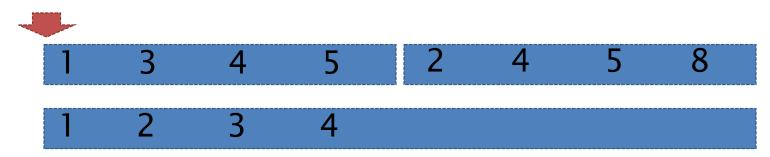


### Sort using disk as "memory"?

Block-based disk I/O



head

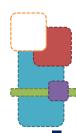


#### **BLOCK-BASED DISK I/O**

### Example: Join Operation

#### Join

- Two relations 'student' and 'takes' on student IDs
- E.g., SELECT r.id FROM student as r JOIN takes as s ON r.id = s.studentID
- Examples use the following information
  - Number of records of student. 5,000 takes. 10,000
  - Number of blocks of student. 100 takes. 400
  - That is,
    - A block can hold 50 student records and 25 takes records respectively
    - $n_r = 5,000$
    - $n_s = 10,000$
    - $b_r = 100$
    - $b_s = 400$

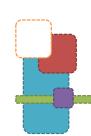


#### Nested-Loop Join

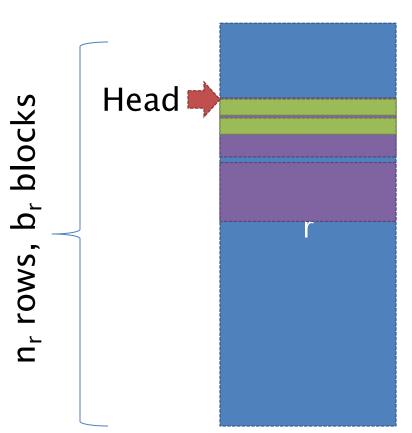
To compute the theta join  $r \bowtie_{\theta} s$  ( $\theta$ : join condition)

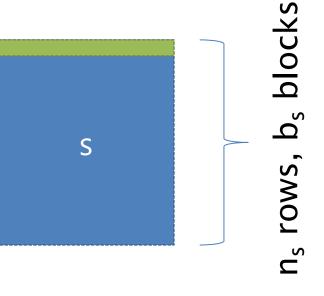
```
for each tuple t_r in r do begin for each tuple t_s in s do begin test pair (t_r,\ t_s) to see if they satisfy \theta if they do, add (t_r,\ t_s) to the result end end
```

- r is called the outer relation and s the inner relation of the join
- Assume that no indices can be used with any kind of join condition



#### Nested-Loop Join





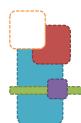
# of block transfers:  $b_r$  +  $n_r * b_s$  # of disk seeks:  $b_r$  +  $n_r$ 

### Nested-Loop Join (Cont.)

 In the worst case, if there is enough memory only to hold one block of each relation, the estimated cost is

$$n_r * b_s + b_r$$
 block transfers, plus  $n_r + b_r$  seeks

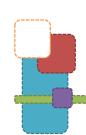
- Assuming worst case memory availability cost estimate is
  - with student as outer relation:
    - 5000 \* 400 + 100 = 2,000,100 block transfers,
    - 5000 + 100 = 5100 seeks
  - with takes as the outer relation
    - 10000 \* 100 + 400 = 1,000,400 block transfers and 10,400 seeks
- Block nested-loops algorithm (next slide) is preferable.



#### Block Nested-Loop Join

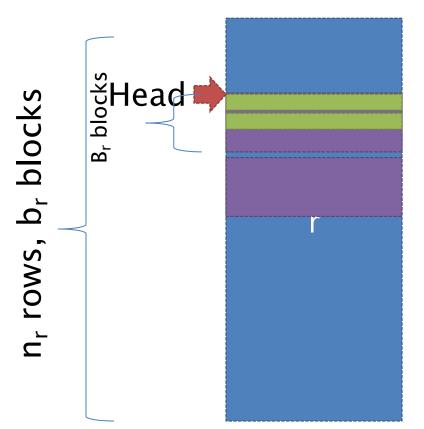
 Variant of nested-loop join in which every block of inner relation is paired with every block of outer relation.

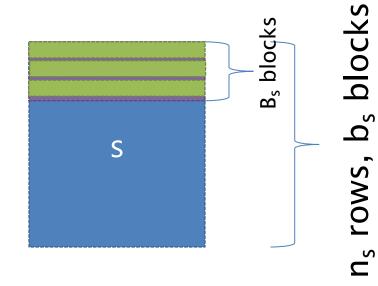
```
for each block B_r of r do begin
for each block B_s of s do begin
for each tuple t_r in B_r do begin
for each tuple t_s in B_s do begin
Check if (t_p, t_s) satisfy the join condition
if they do, add (t_p, t_s) to the result
end
end
end
```



#### Block Nested-Loop Join

Available blocks:  $B_r + B_s$ 





# of block transfers:

$$b_r$$

+

$$b_S \cdot \left[\frac{b_r}{B_r}\right]$$

# of disk seeks:

$$\left[\frac{b_r}{B_r}\right]$$

+

$$\left[\frac{b_r}{B_r}\right]$$

## Block Nested-Loop Join (Cont.)

Available memory: B<sub>r</sub> + B<sub>s</sub> blocks

Block transfers: 
$$b_r + b_s \cdot \left[\frac{b_r}{B_r}\right]$$

Disk seeks:  $2\left[\frac{b_r}{B_r}\right]$ 

- In the worst case:  $B_r = 1$  and  $B_s = 1$ 
  - $-b_r * b_s + b_r$  block transfers + 2 \*  $b_r$  seeks
    - 100 \* 400 + 100 = 40,100 block transfers
    - 2 \* 100 = 200 seeks

#### **Nested-loop Join:**

2,000,100 block transfers + 5,100 seeks

## Block Nested-Loop Join (Cont.)

I/O costs

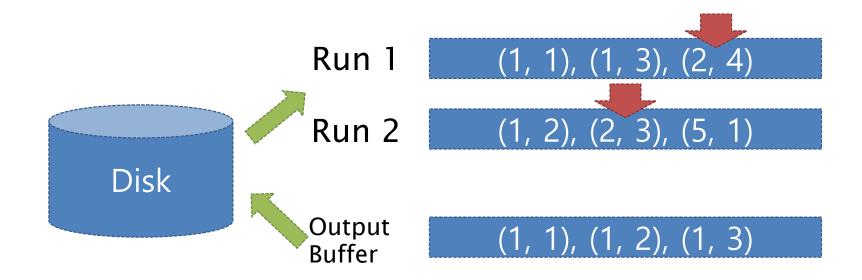
Block transfers: 
$$b_r + b_s \cdot \left[ \frac{b_r}{B_r} \right]$$
  
Disk seeks:  $2 \left[ \frac{b_r}{B_r} \right]$ 

- Improvements to nested loop and block nested loop algorithms:
  - In block nested-loop, use (M-2) memory blocks as the buffer for outer relations, where M= memory size in blocks; use remaining two blocks to buffer inner relation and output
    - Cost =  $b_r + b_s \cdot \left[ \frac{b_r}{M-2} \right]$  block transfers +  $2 \left[ \frac{b_r}{M-2} \right]$  seeks

#### **EXTERNAL MERGE SORT**

# BSBI: Blocked sort-based Indexing (Sorting with fewer *disk seeks*)

- 12-byte (4+4+4) records (termID, docID, pos).
- Run(Block aligned): Already sorted list of records
- Basic idea of algorithm:
  - Accumulate postings for each block, sort, write to disk.
  - Then merge the blocks into one long sorted order.

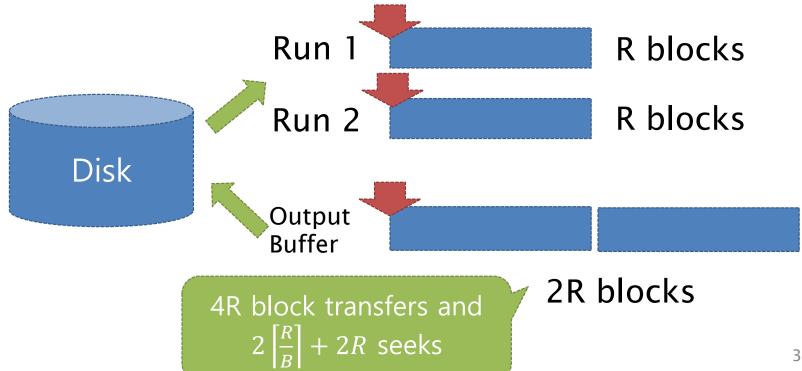




#### I/O Cost of Merging Two Runs

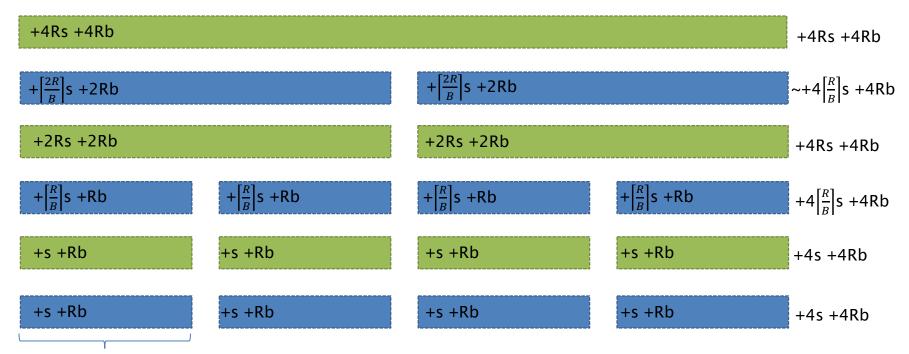
#### Assume

- We merge two runs and write the intermediated sorted run on disk
- We are available M (=2B + 1) blocks of memory



# Sorting N blocks of records

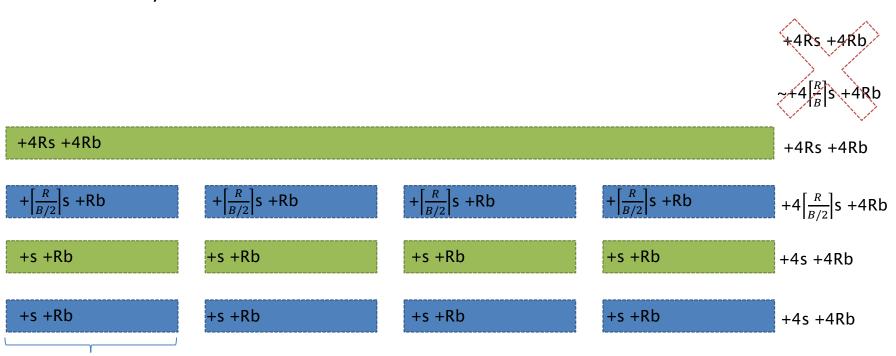
- Mergesort do binary merges, with a merge tree of log<sub>2</sub>N depth where N = the number of smallest runs
- During each level, read into memory runs, merge, write back to disk
- Assume M (=2B + 1) blocks of memory available and the initial run size is R blocks





#### Binary Merge vs. Multi-way Merge

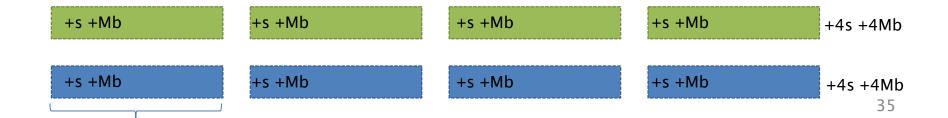
- But it is more efficient to do <u>a multi-way merge</u>, where you are reading from all blocks simultaneously
- Assume M (=2B + 1) blocks of memory available and the initial run size is R blocks
  - Use B/2 blocks for each run





#### Multi-way Merge: Determine R

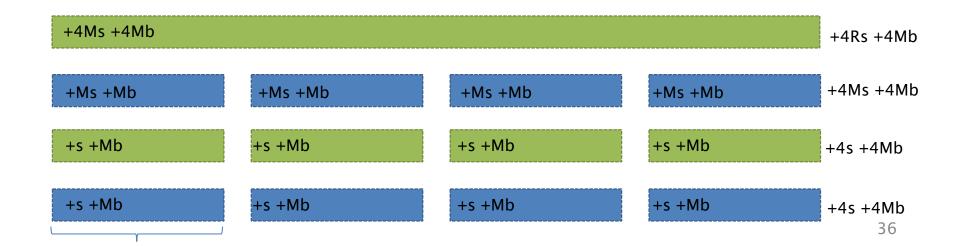
- Given
  - M blocks of available memory
  - m: m-way merge
- The depth of merge tree
  - log<sub>m</sub>n<sub>R</sub> where n<sub>R</sub> is the number of initial runs
  - To reduce n<sub>R</sub>, we use M blocks for sorting each initial run and generate M-blocks long initial runs





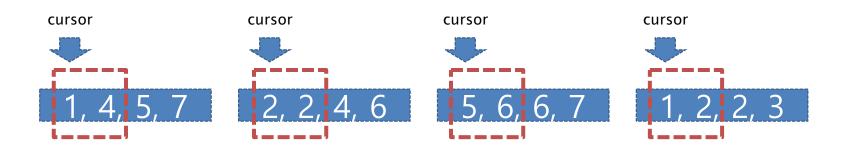
#### Multi-way Merge: Determine m

- Given
  - M blocks of available memory
  - m: m-way merge
- The depth of merge tree
  - log<sub>m</sub>n<sub>R</sub> where n<sub>R</sub> is the number of initial runs
  - To increase m, we perform (M-1)-way merge: use 1-blocks for the read buffer for each run



- Access m runs
  - Use a block of memory for read buffer for each run
  - Use a block of memory for output buffer
  - Among the head of m runs, takes the smallest and put into output buffer

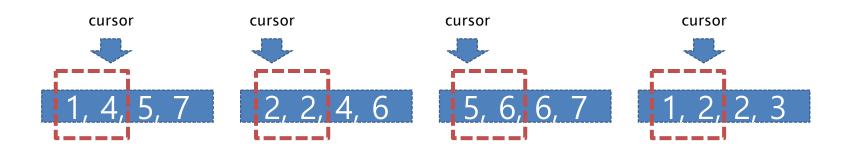
Output buffer: 1 1



- Access m runs
  - Use a block of memory for read buffer for each run
  - Use a block of memory for output buffer
  - Among the head of m runs, takes the smallest and put into output buffer



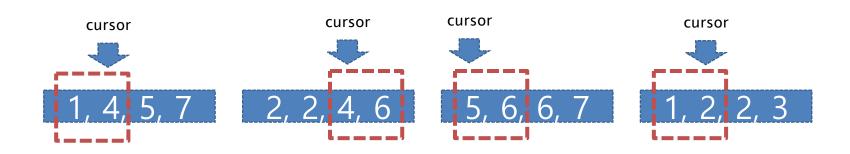
Output buffer: 2 2



- Access m runs
  - Use a block of memory for read buffer for each run
  - Use a block of memory for output buffer
  - Among the head of m runs, takes the smallest and put into output buffer

### 1 1 2 2

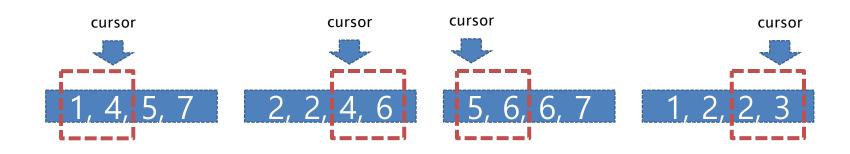
Output buffer: 2 2



- Access m runs
  - Use a block of memory for read buffer for each run
  - Use a block of memory for output buffer
  - Among the head of m runs, takes the smallest and put into output buffer

### 1 1 2 2 2 2

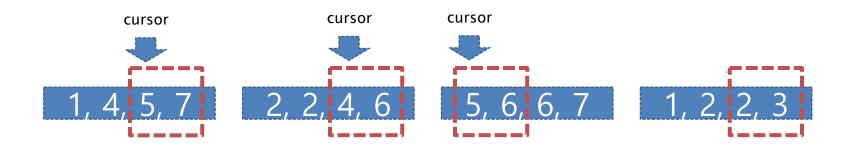
Output buffer: 3 4



- Access m runs
  - Use a block of memory for read buffer for each run
  - Use a block of memory for output buffer
  - Among the head of m runs, takes the smallest and put into output buffer

1122234

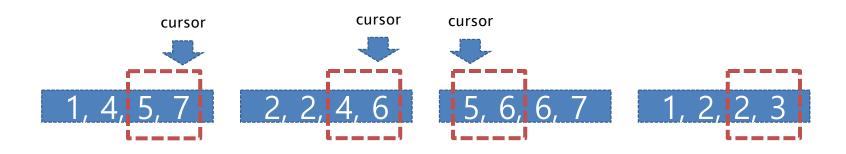
Output buffer: 4 5



- Access m runs
  - Use a block of memory for read buffer for each run
  - Use a block of memory for output buffer
  - Among the head of m runs, takes the smallest and put into output buffer

1 1 2 2 2 2 3 4 4 5

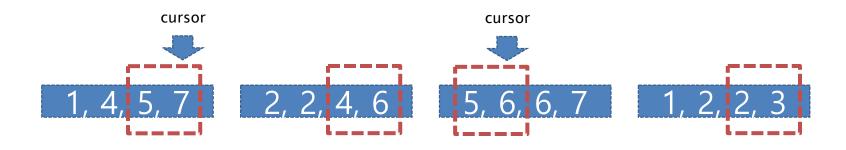
Output buffer: 5 6



- Access m runs
  - Use a block of memory for read buffer for each run
  - Use a block of memory for output buffer
  - Among the head of m runs, takes the smallest and put into output buffer

1 1 2 2 2 2 3 4 4 5 5 6

Output buffer: 6 6

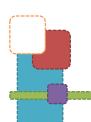


- Access m runs
  - Use a block of memory for read buffer for each run
  - Use a block of memory for output buffer
  - Among the head of m runs, takes the smallest and put into output buffer

1122234455666

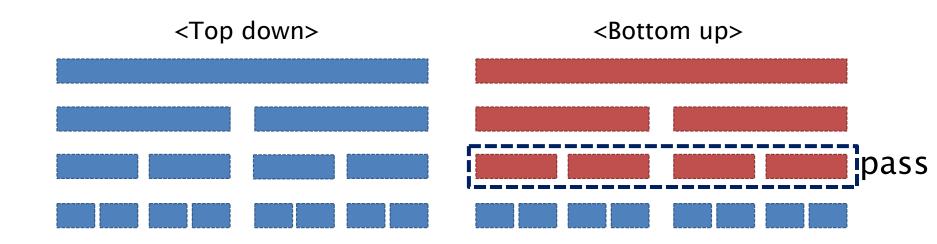
Output buffer: 7 7





### Top Down vs. Bottom Up

- Traditional memory-based binary merge sort algorithm
  - Top down is easier to implement
- External m-way merge sort algorithm
  - Bottom up is better





- Create sorted initial runs. Let i be 0 initially.

  Repeatedly do the following till the end of the data:
  - (a) Read **M blocks** of postings into memory
  - (b) Sort the in-memory blocks using quick sort.
  - (c) Write sorted data to run R<sub>i</sub> on disk; increment i.

### Let the final value of i be N

Merge the runs (next slide).....

Let M denote AVAILABLE

Blocks in main memory



## External Merge-Sort (Cont.)

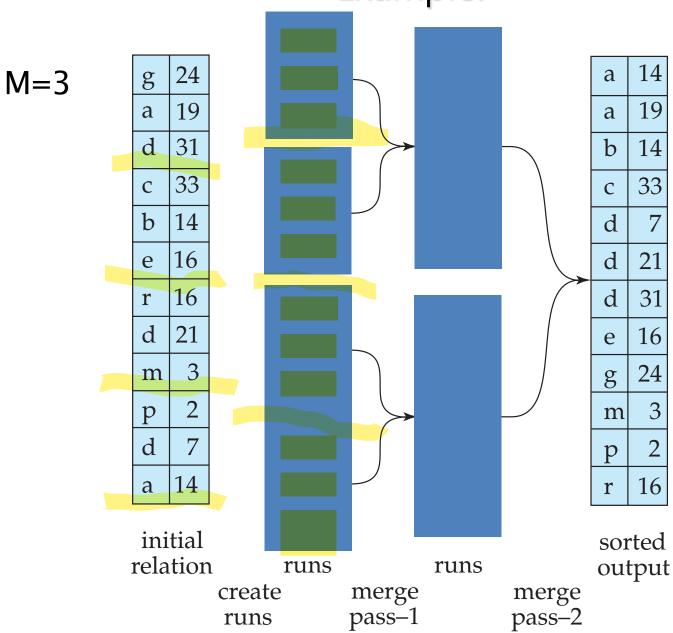
- 2. Merge the runs (N-way merge). If N < M (N < = M-1),
  - 1. Use <u>N blocks of memory to buffer input runs</u>, and <u>1 block to buffer output</u>. Read the first block of each run into its buffer page
  - 2. repeat
    - 1. Select the first record (in sort order) among all buffer pages
    - 2. Write the record to the output buffer. If the output buffer is full write it to disk.
    - 3. <u>If the buffer page becomes empty then</u> read the next block (if any) of the run into the buffer.
  - 3. until all input buffer pages are empty:



## External Merge-Sort (Cont.)

- If N ≥ M, several merge passes are required.
  - In each pass, contiguous groups of M 1 runs are merged using the previous procedure.
  - A pass reduces the number of runs by a factor of M-1 and creates runs longer by the same factor.
    - E.g. If there are 90 runs and M=11, one pass reduces the number of runs to 9 and each generated run is 10 times as long as the initial run
  - Repeated passes are performed till all runs have been merged into one.

### Example:



### **Cost Estimation**

### Cost analysis:

- M blocks(=pages) are available in main memory
- Postings on  $\mathbf{b_r}$  blocks  $\rightarrow \left[\frac{b_r}{M}\right]$  runs are generated!
- Total number of **merge passes** required:  $\left[\log_{M-1}\left[\frac{b_r}{M}\right]\right]$
- COST: Block transfers (read/write) for initial run creation as well as in each pass is  $2b_r$ 
  - for final pass, we don't count write cost
    - we ignore final write cost for all operations since the output of an operation may be sent to the parent operation without being written to disk
  - Thus, total number of block transfers for external sorting:

$$2b_r + 2b_r \left( \left\lceil \log_{M-1} \left\lceil \frac{b_r}{M} \right\rceil \right\rceil \right) - b_r$$

Seeks: next slide

### Cost Estimation (Cont.)

### Cost of seeks

- During run generation: one seek to read each run and one seek to write each run
  - $2\left[\frac{b_r}{M}\right]$  seeks
- During the merge phase
  - Need 2b<sub>r</sub> seeks for each merge pass
    - except the final one which does not require a write
  - Total number of seeks:

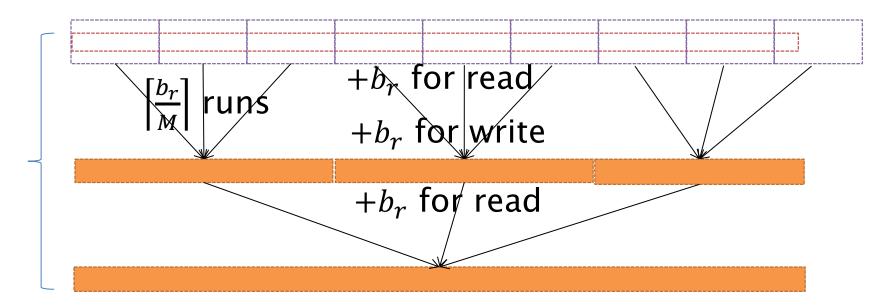
$$2\left[\frac{b_r}{M}\right] + 2b_r\left[\log_{M-1}\left[\frac{b_r}{M}\right]\right] - b_r$$

# Cost Estimation: Block Transfers

Cost analysis:

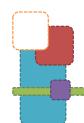
M blocks

 $2b_r$  for initial run generation



$$\left[\log_{M-1}\left[\frac{b_r}{M}\right]\right]$$
 passes

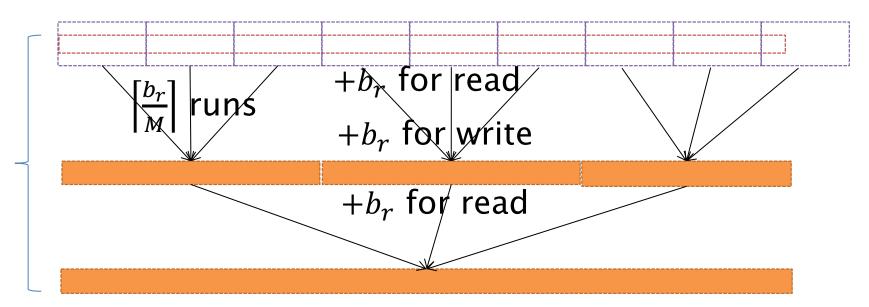
$$2b_{r} + 2b_{r} \left( \left\lceil \frac{\log_{M-1}}{M} \right\rceil \right) - \frac{b_{r}}{M}$$



### Cost Estimation: Disk Seeks

Cost analysis:

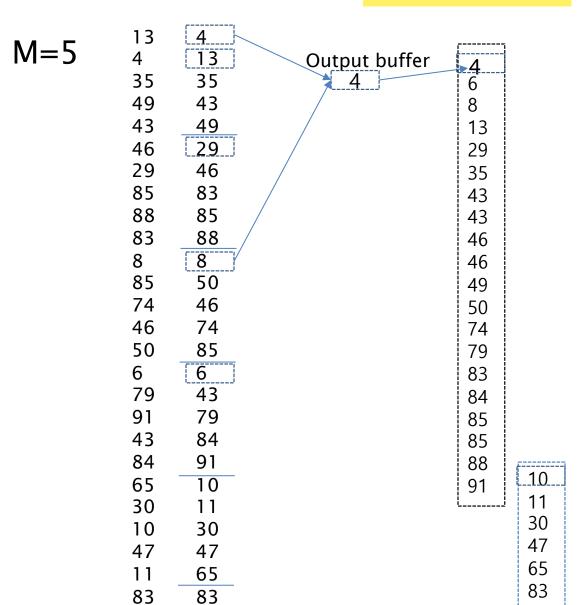
 $2\left|\frac{b_r}{M}\right|$  for initial run generation



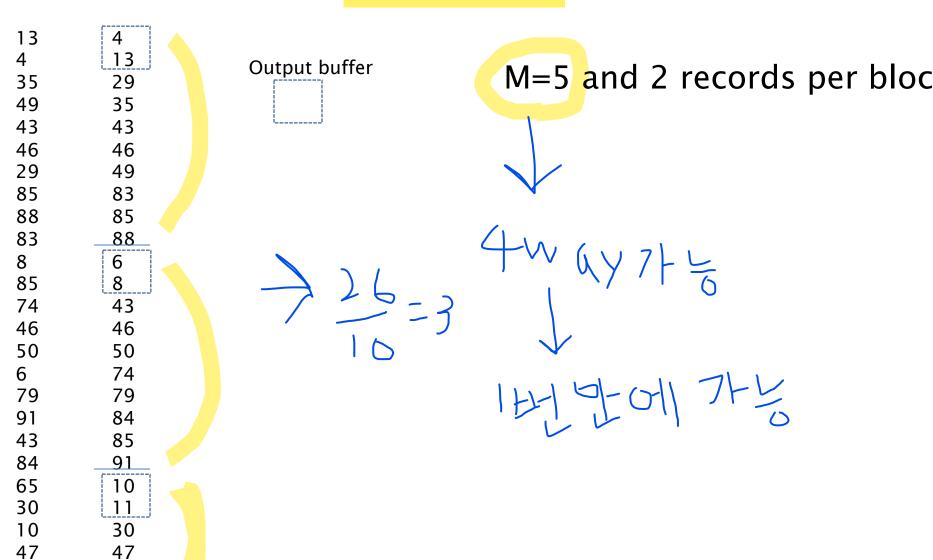
$$\left[\log_{M-1}\left[\frac{b_r}{M}\right]\right]$$
 passes

$$\left[\log_{M-1}\left[\frac{b_r}{M}\right]\right]$$
 passes  $2\left[\frac{b_r}{M}\right] + 2b_r\left(\left[\log_{M-1}\left[\frac{b_r}{M}\right]\right]\right) - b_r$ 

### Exercise:

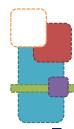


### Exercise:



### Exercise

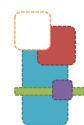
M=3 and 1 records per block



### Quiz

- Sort the postings using external merge-sort algorithm
  - 30 postings
  - 3 blocks of memory are available
  - Each block(a page) can hold up to 3 postings
  - A block is used for the read buffer of each run
- How many blocks to read/write?
- How many disk seeks occurs?

Term Term	Doc#
	1
lid	1
enact	1
ulius	1
aesar	1
	1
vas	1
illed	1
•	1
he	1
apitol	1
orutus	1
illed	1
ne	1
60	2
et	2
t	2
ре	2
vith	2
aesar	2
he	2
oble	2
orutus	2
nath	2
old	2
ou	2
aesar	2
vas	2
mbitious	2
vas	2



### Distributed Indexing

- External merge-sort is the best choice using a single computer
- Nonetheless, web-scale indexing must use a distributed computing cluster
- How do we exploit such a pool of machines for indexing? → MapReduce