

# Question #1

## Buck Converter DCM

### Conditions

$$V_g = 5[\text{V}]$$

$$R_{load} = 4[\Omega]$$

$$freq = 250[\text{kHz}]$$

$$L = 2.2[\mu\text{H}]$$

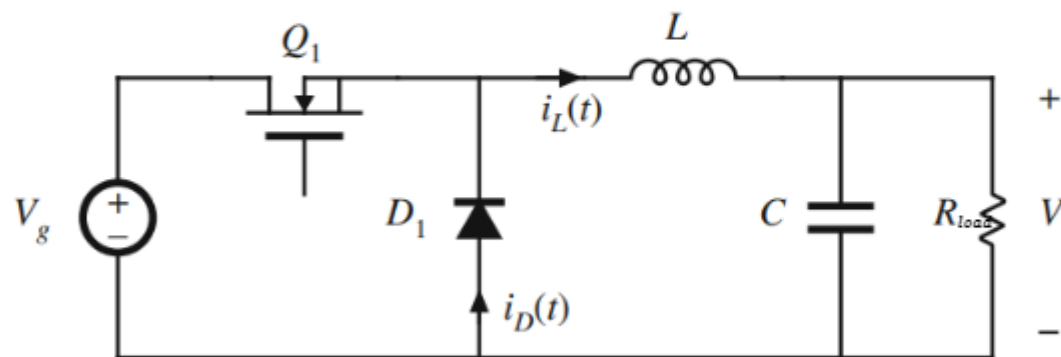
$$C = 47[\mu\text{F}]$$

$$K = \frac{2L}{RT_s}$$

### Problems

아래 회로가 DCM으로 동작할 때 왼쪽의 조건을 고려하여 문제를 푸시오

- 1)  $K_{crit}(D)$  & 입출력 관계식  $V/V_g$
- 2)  $D_1 = 0.3$  일때 출력전압  $V$  계산
- 3) 2)의 결과를 PSIM simulation 결과와 비교
- 4) PSIM simulation으로 인덕터 리플 전류  $\Delta i_L$ , 평균전류  $I$ , 시간  $D_3$  확인



$$I_L = \frac{V}{R} = \frac{DV_g}{R} \dots \textcircled{1}$$

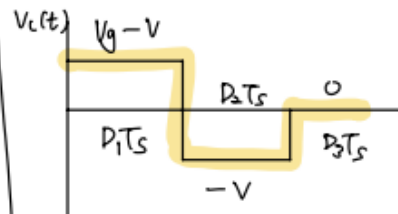
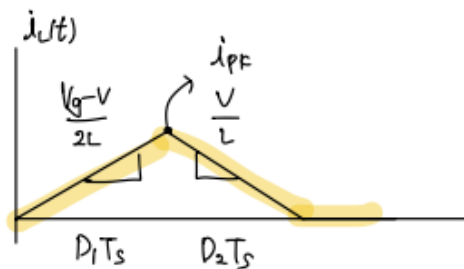
$$\Delta i_L = \frac{(V_g - V)}{2L} DT_s \quad V = DV_g \dots \textcircled{2}$$

$$= \frac{V_g D D' T_s}{2L}$$

$$\textcircled{1} = \textcircled{2}$$

$$\frac{DV_g}{R} < \frac{V_g D D' T_s}{2L}$$

$$\frac{2L}{RT_s} < D' \quad \therefore K_{crit} = D'$$



$$V = V_g \frac{D_1}{D_1 + D_2}$$



$$i_L(t) = i_c(t) + \frac{V}{R}$$

$$\langle i_c(t) \rangle = 0$$

$$\langle i_L \rangle = \frac{V}{R}$$

$$i_{peak} = \frac{V_g - V}{L} D_1 T_s$$

삼각형의 넓이

$$\langle i_L \rangle = \frac{1}{2} (D_1 + D_2) T_s \cdot \frac{V_g - V}{L}$$

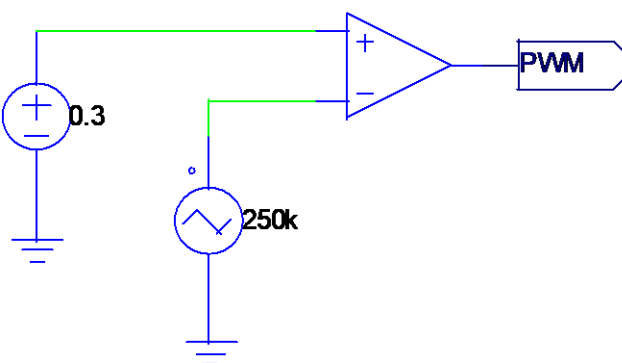
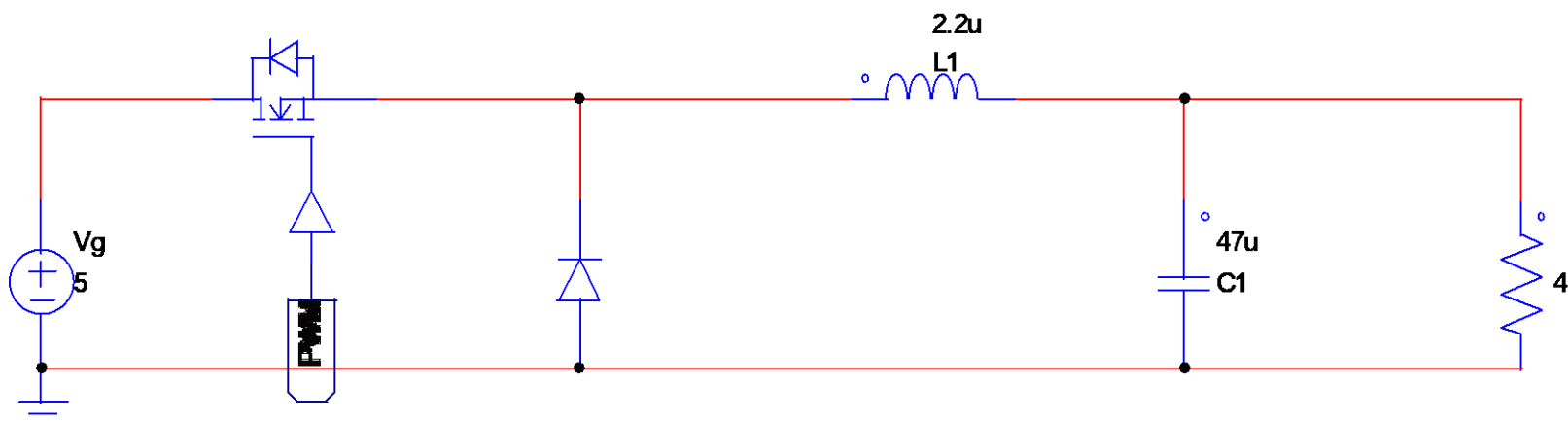
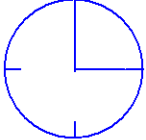
$$\frac{V}{R} = \frac{T_s}{2L} (D_1 + D_2) (V_g - V)$$

$$V = \frac{1}{K} (D_1 + D_2) (V_g - V)$$

$$\frac{V}{V_g} = \frac{2}{1 + \sqrt{1 + \frac{4K}{D_1^2}}}$$

$$D_1 = 0.3, K = 0.275$$

$$\rightarrow \frac{V}{V_g} = \frac{2}{1 + \sqrt{1 + \frac{4 \times 0.275}{0.3^2}}} = 0.4314 \quad \therefore V = 2.157 \text{ [V]}$$



Simulation Control

PSIM | SPICE | SimCoder | Color

Solver Type

☒ Fixed-step ☐ Variable-step (dual) [Help](#)

Time Step  ☐ Time Step Ratio  ☐ Smaller Time Step

Total Time  ☐ Free Run

Print Time

Print Step

Load Flag  ☐

Save Flag  ☐

Engine Default Values

R\_switch\_on

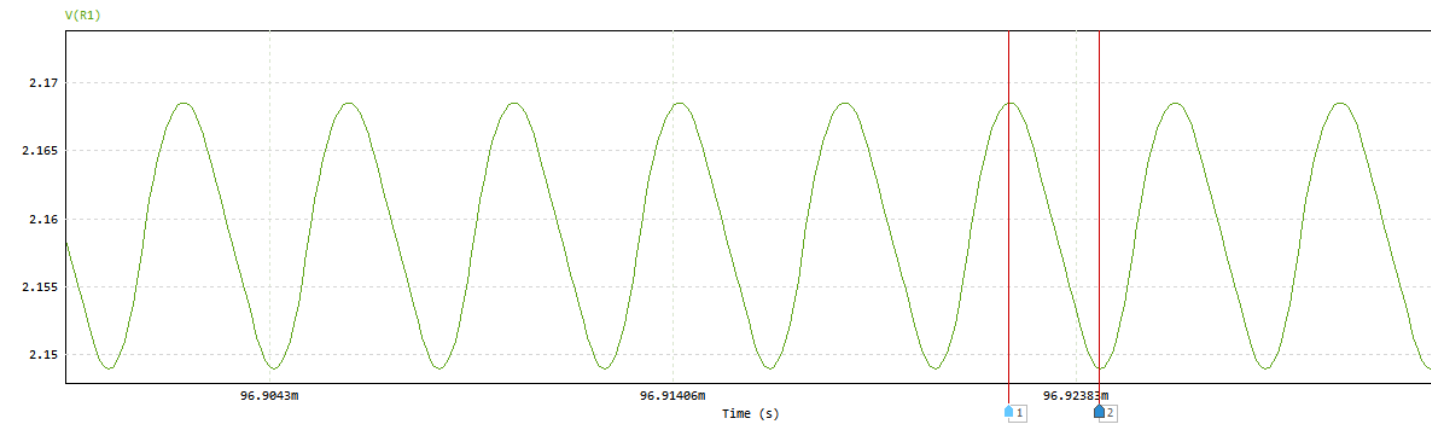
R\_switch\_off

Triangular : VTRI1

Parameters | Color

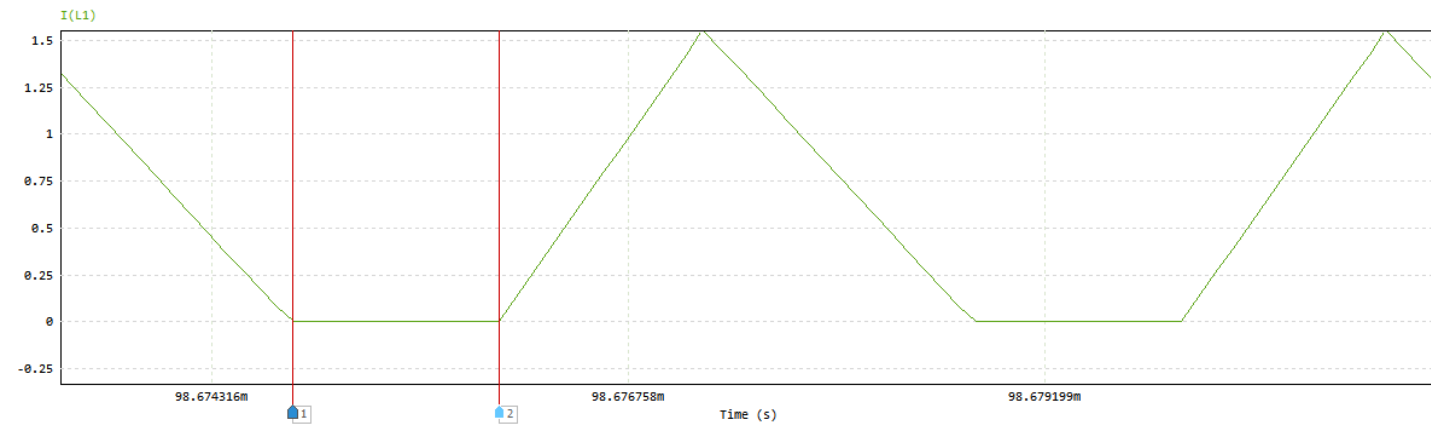
Triangular-wave voltage source [Help](#)

		Display
Name	VTRI1	<input type="checkbox"/>
V_peak_to_peak	1	<input type="checkbox"/>
Frequency	250k	<input checked="" type="checkbox"/>
Duty Cycle	1	<input type="checkbox"/>
DC Offset	-0	<input type="checkbox"/>
Tstart	0	<input type="checkbox"/>
Phase Delay	0	<input type="checkbox"/>



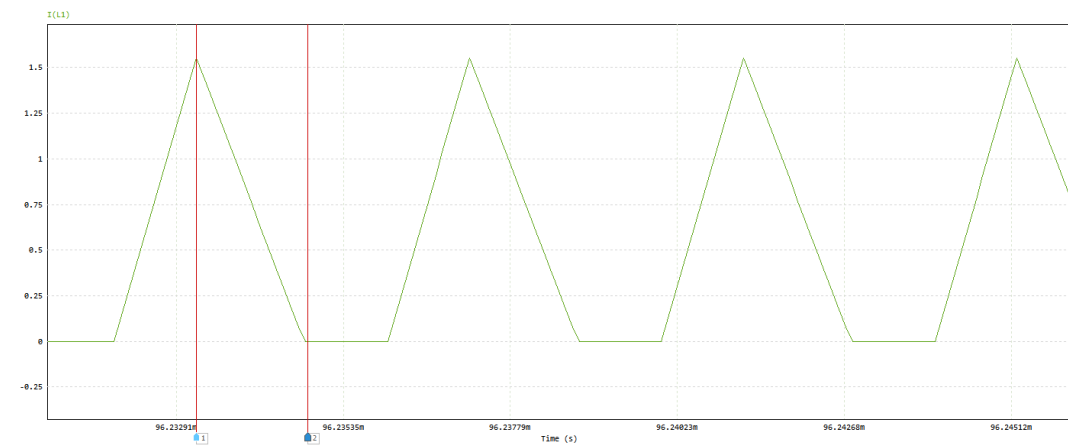
Measure					
		X1	X2	$\Delta$	Average
Time		9.69222e-02	9.69244e-02	2.20000e-06	
V(R1)		2.16853e+00	2.14896e+00	-1.95726e-02	2.15919e+00

$$\text{Average } V_{out} = 2.1519[V]$$



Measure					
		X1	X2	$\Delta$	Average
Time		9.86748e-02	9.86760e-02	1.20358e-06	
I(L1)		2.76892e-03	-7.53132e-06	-2.77646e-03	2.97256e-03

$$D_3 = X2 - X1 = 1.2 * 10^{-6} = 1.2[\mu s]$$



Measure					
		X1	X2	$\Delta$	Average
Time		9.90612e-02	9.90640e-02	2.80000e-06	
I(L1)		1.55396e+00	-7.51737e-06	-1.55397e+00	4.38583e-01

$$I_L = 0.43858[A]$$

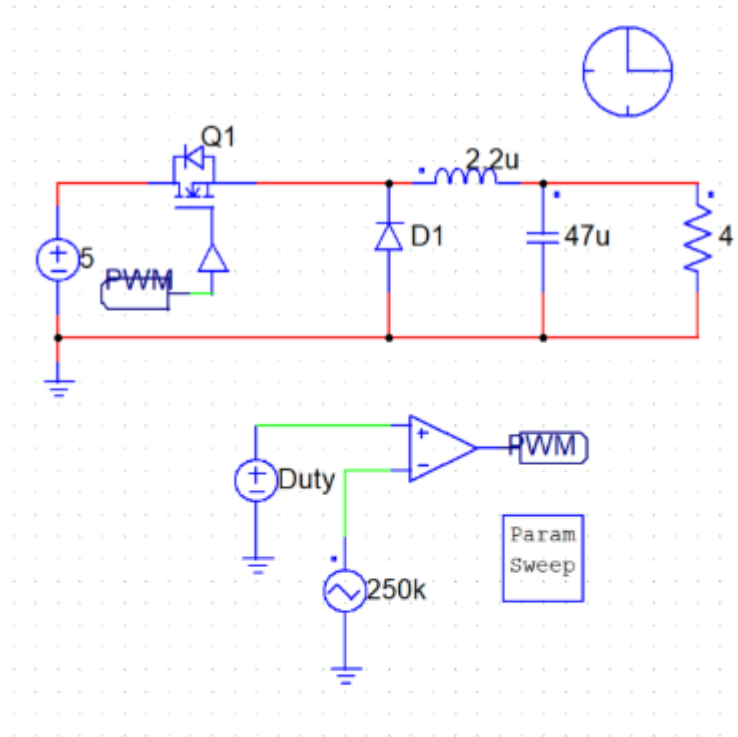
$$\Delta i_L = 1.55397[A]$$

# Question #2

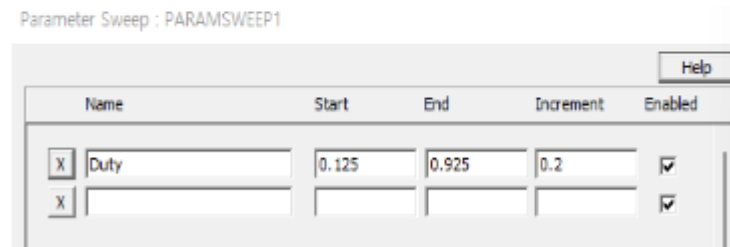
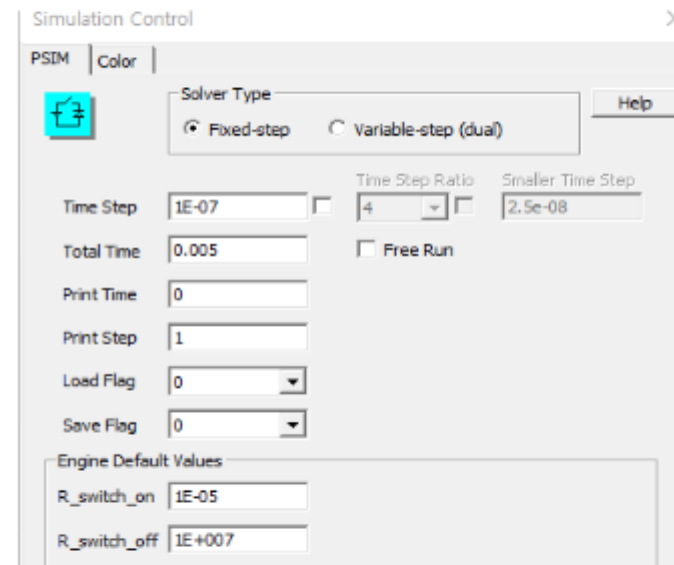
## Buck converter DCM

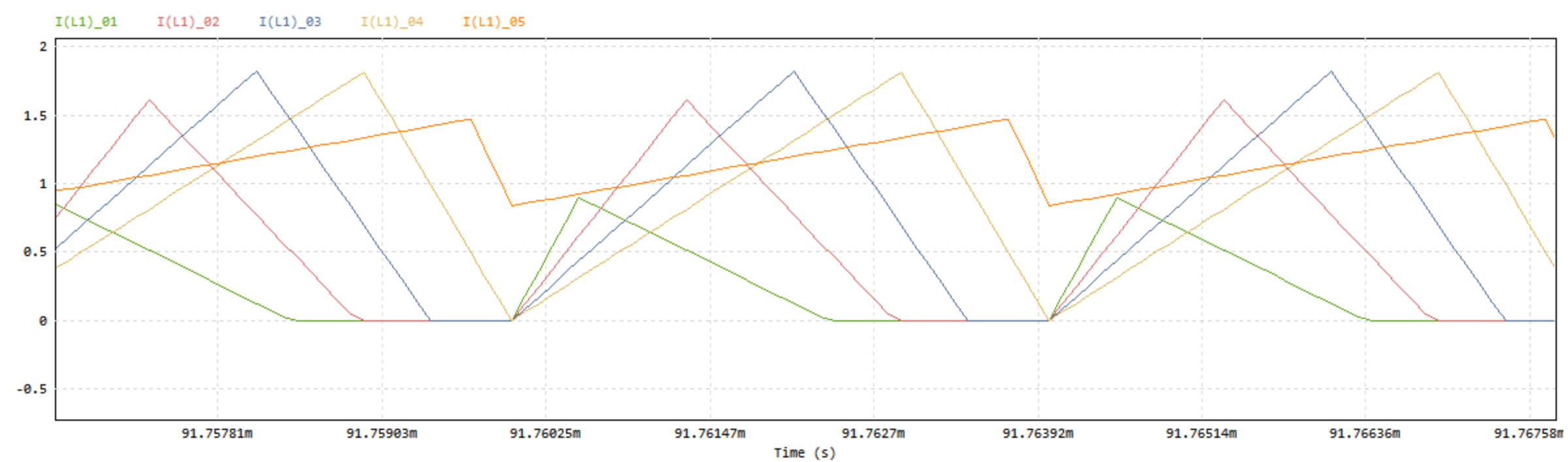
### Problems

Question #1에 대해 PSIM의 Parameter Sweep을 이용하여 (Duty를 변경하여) CCM에서 DCM으로 변경되는 구간을 확인하시오 (DCM:  $\Delta i_L > I$ )



$$K = 0.275, \quad K_{crit} = (1 - D)$$





$K_{crit} = (1 - D) = 0.275$ 가 되는 지점인  $I(L1)_{04}$ 부터 CCM 모드가 시작되는 것을 확인

# Question #3

## Boost Converter DCM

### Conditions

$$V_g = 100[\text{V}]$$

$$R_{load} = 100[\Omega]$$

$$freq = 5[\text{kHz}]$$

$$L = 1[\text{mH}]$$

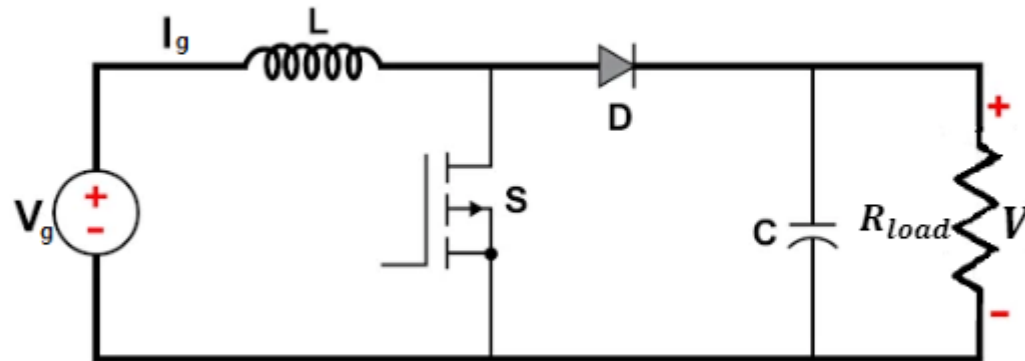
$$C = 100[\mu\text{F}]$$

$$K = \frac{2L}{RT_s}$$

### Problems

아래 회로가 DCM으로 동작할 때 왼쪽의 조건을 고려하여 문제를 푸시오

- 1)  $K_{crit}(D)$  & 입출력 관계식  $V/V_g$
- 2)  $D_1 = 0.25$  일때 출력전압  $V$  계산
- 3) 2)의 결과를 PSIM simulation 결과와 비교
- 4) PSIM simulation으로 인덕터 리플 전류  $\Delta i_L$ , 평균전류  $I$ , 시간  $D_3$  확인



$$I = \frac{V_g}{D'^2 R}, \quad \Delta i_L = \frac{V_g}{2L} DT_s$$

$$\frac{V_g}{D'^2 R} < \frac{V_g}{2L} DT_s$$

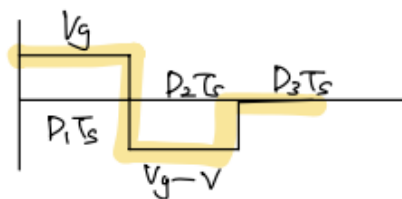
$$\frac{2L}{RT_s} > D'^2 D \quad K = \frac{2L}{RT_s}$$

$$K_{crit}(D) = D D'^2$$

$$\textcircled{1} \quad \begin{aligned} V_L(t) &= V_g \\ i_c(t) &= \frac{V}{R} \end{aligned}$$

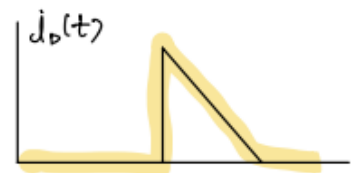
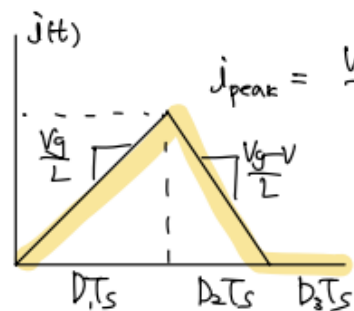
$$\textcircled{2} \quad \begin{aligned} V_L(t) &= V_g - V \\ i_c(t) &= i(t) - \frac{V}{R} \end{aligned}$$

$$\textcircled{3} \quad \begin{aligned} V_L(t) &= 0 \\ i_c(t) &= -\frac{V}{R} \end{aligned}$$



$$D_1 V_g + D_2 (V_g - V) = 0$$

$$V = \frac{(D_1 + D_2) V_g}{D_2}$$



Average Diode Current

$$I_D = \frac{1}{T_s} \int_0^{T_s} i_D(t) dt$$

$$\int_0^{T_s} i_D(t) dt = \frac{1}{2} i_{peak} D_2 T_s$$

$$\langle i_D \rangle = \frac{1}{2} \cdot \frac{V_g}{L} D_1 D_2 T_s$$

$$\frac{V}{R} = \frac{V_g D_1 D_2 T_s}{2L}$$

$$D_2 V = D_1 V_g + D_2 V_g$$

$$D_2 (V - V_g) = D_1 V_g$$

$$D_2 = \frac{D_1 V_g}{V - V_g}$$

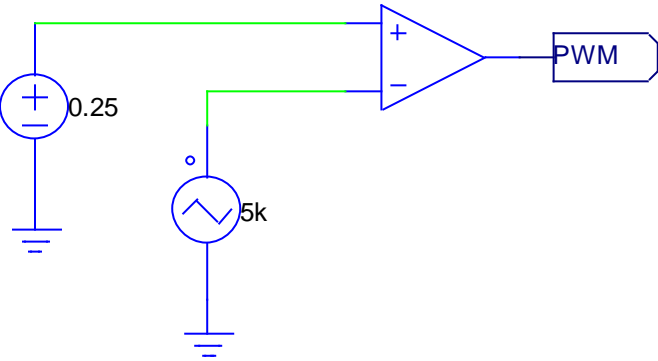
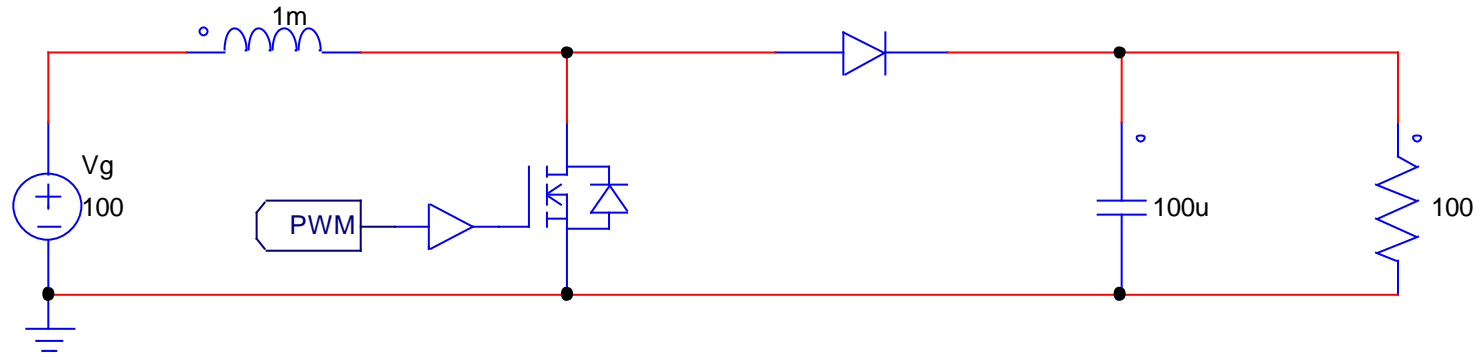
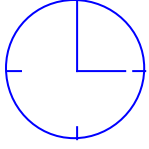
$$V^2 - V V_g - \frac{V_g^2 D_1^2}{K} = 0$$

$$\frac{V}{V_g} = \frac{1 + \sqrt{1 + 4 D_1^2 / K}}{2}$$

$$\frac{V}{V_g} = \frac{1 + \sqrt{1 + 4 \cdot 0.25^2 / 0.1}}{2} = 1.4354$$

$$V = 143.5414 \text{ CV}$$





Simulation Control

PSIM | SPICE | SimCoder | Color

Solver Type: ☒ Fixed-step ☐ Variable-step (dual) [Help](#)

Time Step:  ☐ Time Step Ratio:  ☐ Smaller Time Step:

Total Time:  ☐ Free Run

Print Time:

Print Step:

Load Flag:  ☐

Save Flag:  ☐

Engine Default Values

R\_switch\_on:

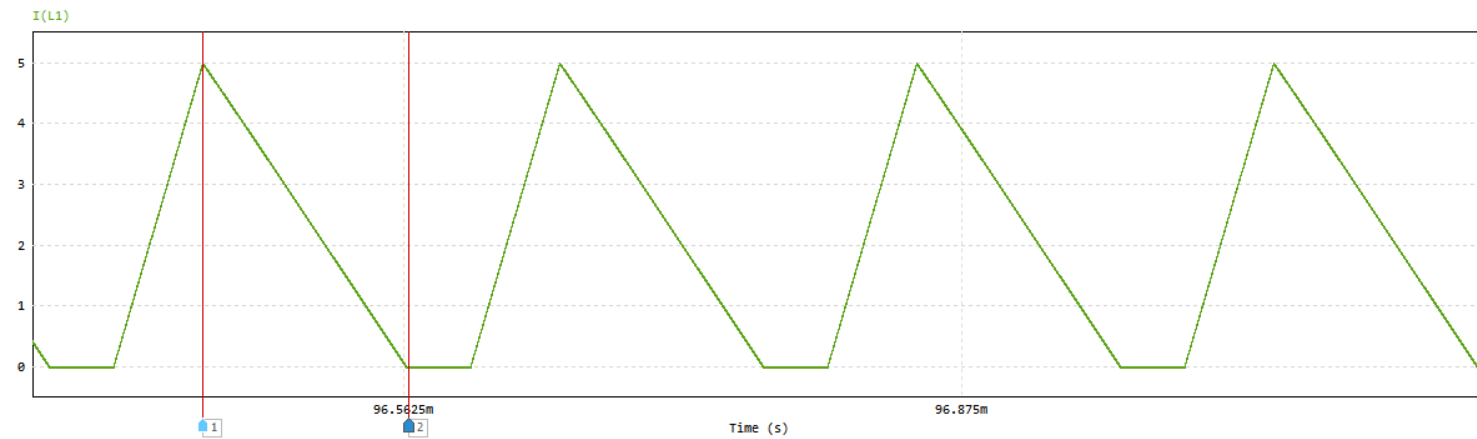
R\_switch\_off:

Triangular : VTRI1

Parameters | Color

Triangular-wave voltage source [Help](#)

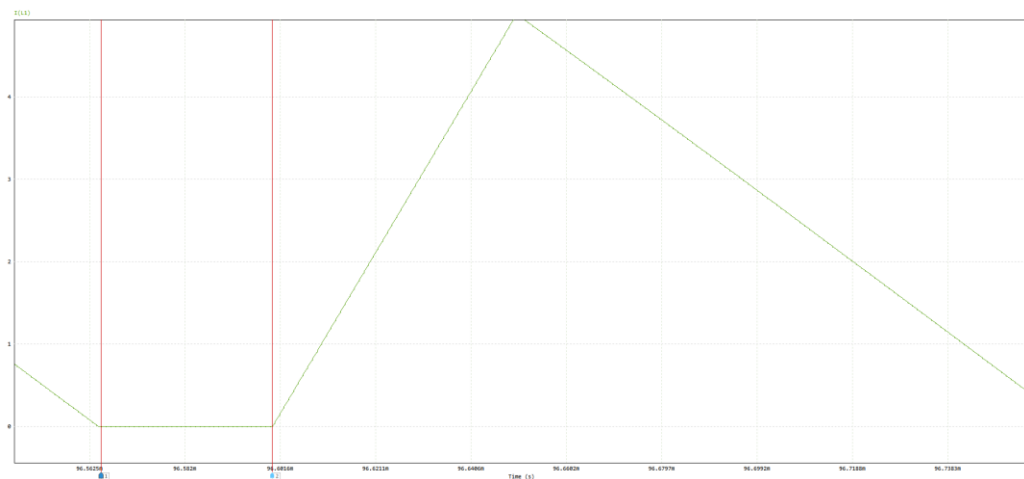
		Display
Name	<input type="text" value="VTRI1"/>	<input type="checkbox"/> <input type="text" value="V"/>
V_peak_to_peak	<input type="text" value="1"/>	<input type="checkbox"/> <input type="text" value="V"/>
Frequency	<input type="text" value="5k"/>	<input checked="" type="checkbox"/> <input type="text" value="Hz"/>
Duty Cycle	<input type="text" value="1"/>	<input type="checkbox"/> <input type="text" value="V"/>
DC Offset	<input type="text" value="0"/>	<input type="checkbox"/> <input type="text" value="V"/>
Tstart	<input type="text" value="0"/>	<input type="checkbox"/> <input type="text" value="s"/>
Phase Delay	<input type="text" value="0"/>	<input type="checkbox"/> <input type="text" value="s"/>



Measure					
		X1	X2	$\Delta$	Average
Time		9.64500e-02	9.65658e-02	1.15758e-04	
I(L1)		4.99940e+00	0.00000e+00	-4.99940e+00	2.47899e+00

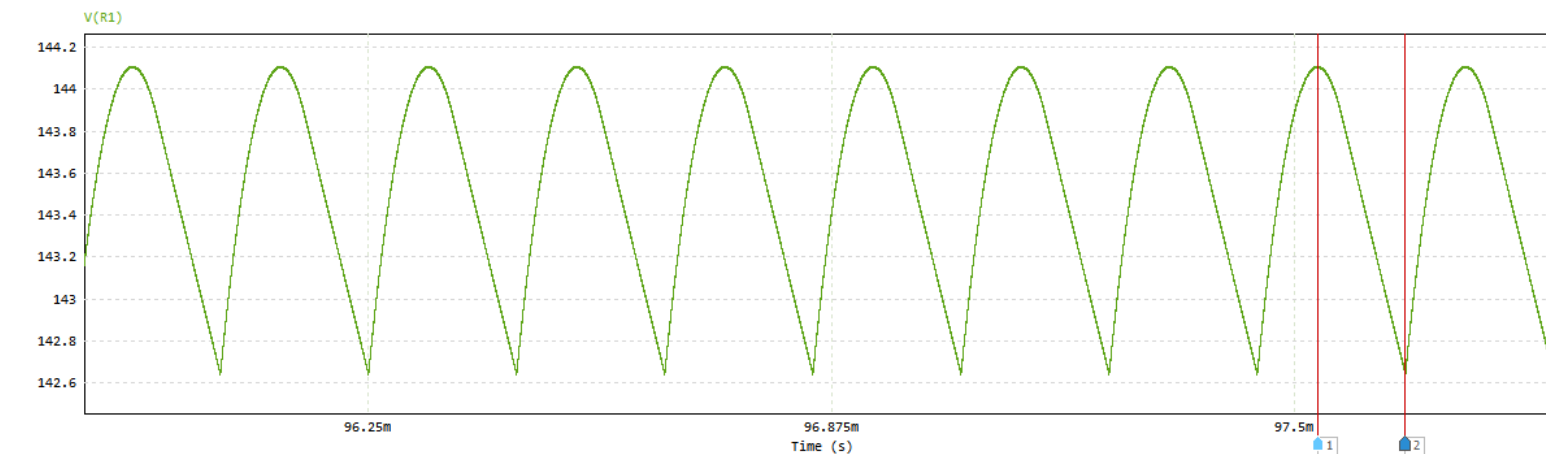
$$I_L = 1.915[A]$$

$$\Delta i_L = 5[A]$$



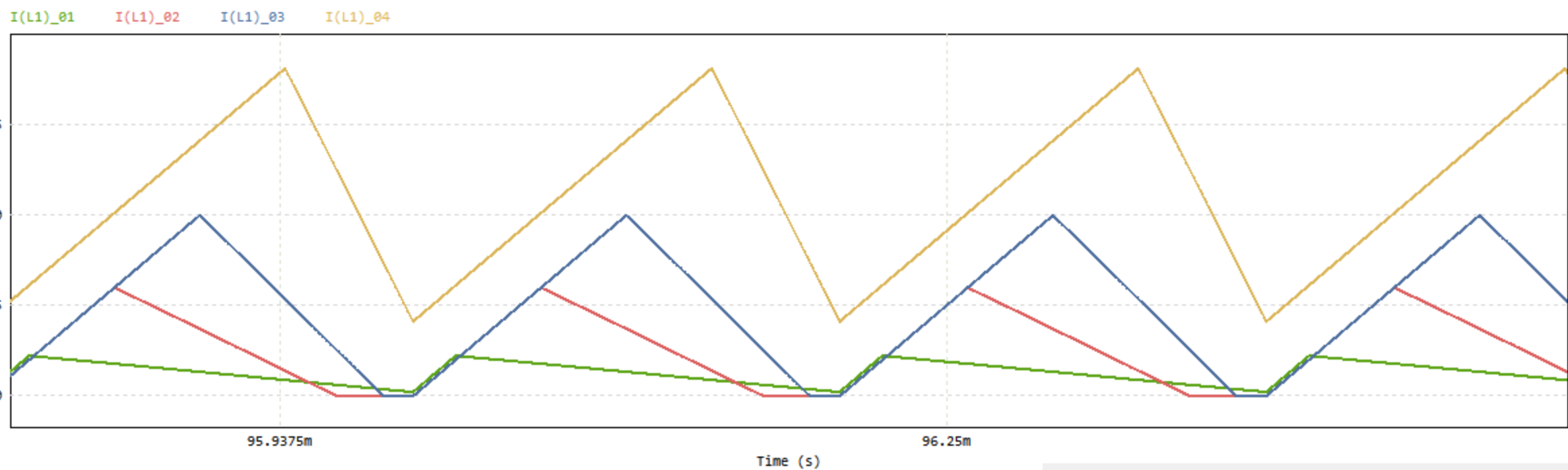
Measure					
		X1	X2	$\Delta$	Average
Time		9.65648e-02	9.65999e-02	3.51000e-05	
I(L1)		0.00000e+00	0.00000e+00	0.00000e+00	0.00000e+00

$$D_3 = 0.351[\mu s]$$



Measure					
		X1	X2	$\Delta$	Average
Time		9.75316e-02	9.76500e-02	1.18400e-04	
V(R1)		1.44109e+02	1.42645e+02	-1.46345e+00	1.43471e+02

$$V_R = 143.47[V]$$



$I(L_1)01, D = 0.1$ 로 CCM으로 동작  
 $I(L_2)02, D = 0.3$ 로 DCM으로 동작  
 $I(L_3)03, D = 0.5$ 로 DCM으로 동작  
 $I(L_4)014 D = 0.7$ 로 CCM으로 동작

왜 boost는 CCM과 DCM이 섞여서 나오는가?

$K = 0.1$ 을 기준으로 Duty에 따라 CCM으로 동작하다가 DCM으로 동작하다 다시 CCM으로 동작한다.

즉 boost converter는 buck convert와 달리  $K_{crit}$ 는  $D(1 - D)^2$ 로 3차 방정식이므로 K값을 기준으로 두 번 바뀌기 때문이다.

