

Assignment: Solving a Non-Linear Equation

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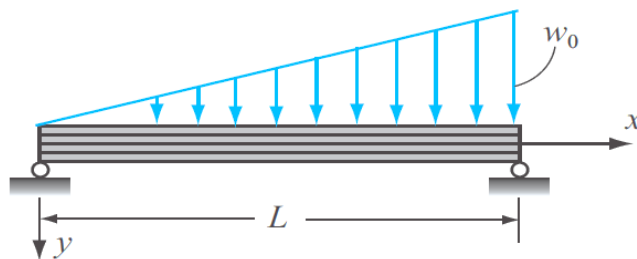
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Instructions:

You must submit, report file and program file: “myNM.h”, “myNM.c”, “Assignment_nonlinear.c” on Hisnet.

Problem: Solve the following non-linear equation [30pt]

A simply supported I-beam is loaded with a distributed load, as shown. The deflection, y , of the center line of the beam as a function of the position, x , is given by the equation:



From the solution of the equation of motion for this model, the steady-state up-and-down motion of the car (mass) is given by $x(t)$, due to the wheel motion of $y(t)$. The ratio between amplitude X and amplitude Y is given by:

$$y = \frac{w_0 x}{360 L E I} (7 L^4 - 10 L^2 x^2 + 3 x^4)$$

where $L=4\text{m}$ is the length, $E=70\text{ GPa}$ is the elastic modulus, $I=52.9 \times 10^{-6} \text{ m}^4$ is the moment of inertia, and $w_0=20\text{ kN/m}$.

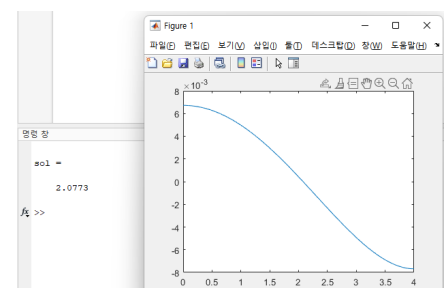
Find the position x where the deflection at the point where the deflection of the beam is maximum and determine the deflection at this point.

HINT: The maximum deflection is at the point where $dy/dx=0=f(x)$. First, find $dy/dx=f(x)$. Then solve for $f(x)$.

a. Solve for the solution using MATLAB's functions of `fzero()` [5pt]

b. Use your defined Newton-Raphson method to solve for the solution. [20pt]

c. Compare the result with MATLAB's solution [5pt]



```
clc; clear; close all;

L=4;
E=70*10^9;
I=52.9*10^-6;
w0=20*10^3;
x=0:0.001:L;

y=(w0.*(360*L*E*I)).*(7*(L^4)-10*(L^2).*(x.^2)+3.*x.^4);
F=inline('(20000.*x)/(360*4*70*10^9*52.9*10^-6)).*(7*(4^4)-10*(4^2).*(x.^2)+3.*x.^4)',x);
dF=inline('(20000)/(360*4*70*10^9*52.9*10^-6)).*(7*(4^4)-10*(4^2).*(x.^2)+3.*x.^4)+(20000.*x)/(360*4*70*10^9*52.9*10^-6)).*(-2*10*(4^2).*x+3.*4*x.^3)',x);
% F'

plot(x,dF(x));
x0=3;           %initial x
sol=fzero(dF,x0) %dy/dx=0=f(x)
```

Procedure:

You need to create the main source file ('Assignment_nonlinear.c'). You should fill in your codes on the main source file and in your library. Show the output results on the report.

Upload (1) Assignment_nonlinear.c, (2) myNM.h, (3) myNM.c) as a zip file

- Create newtonRaphson function to solve a non-linear equation.

```
double newtonRaphson (double func(double x), double dfunc(double x),
                     double x0, double tol)
```

- The declaration of the function must be in “myNP.h”
- The definition of the function must be in “myNP.cpp”

- User defined non-linear function, f(x), and the derivative function f'(x) must be defined in main source file (e.g. .Assignment_nonlinear.c)

```
double func(double x);
double dfunc(double x);
```

- Show the output results by capturing the output screen by running the main source. Display the output value of x(n), iteration number, and the relative error or tolerance.

Example)

```
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Newton-Raphson Method Results
-----
Newton-Raphson Method Result:
Iteration:0      X(n): -10.000000      Tolerance: 1.0000000000
Iteration:1      X(n): -5.764706      Tolerance: 0.7346938776
Iteration:2      X(n): -3.661663      Tolerance: 0.5743407933
Iteration:3      X(n): -2.638657      Tolerance: 0.3876993534
Iteration:4      X(n): -2.179107      Tolerance: 0.2108892813
Iteration:5      X(n): -2.023619      Tolerance: 0.0768367851
Iteration:6      X(n): -2.000533      Tolerance: 0.0115399761
Iteration:7      X(n): -2.000000      Tolerance: 0.0002662004
Final Solution: -2.000000
계속하려면 아무 키나 누르십시오 . . .
```

Pseudo Code

```
Double NewtonRaphson ()
while (K < N_max And E > tol)
{
    h = -dfunc(xn) / func(xn)
    xn = xn + h
    E = |dfunc(xn)|
    K++
}
```

- Paste your code of `newtonRaphson()`

```
// your code goes here
double newtonRaphson(double dfunc(double x), double d2func(double x), double x0, double _tol)
{
    double xn = x0;
    double ep = 1000;
    int Nmax = 1000;
    int k = 0;
    double h = 0;

    do {
        if (d2func(xn) == 0)
        {
            printf("[ERROR] d2F == 0 !!\n");
            break;
        }
        else
        {
            // get h=f/df @ x(k)
            h = -dfunc(xn) / d2func(xn);
            printf("Xf%X\n", xn);
            printf("Xf%X\n", dfunc(xn), d2func(xn));

            // update x(k+1)=x(k)+h(k)
            xn = xn + h;

            // check tolerance
            ep = fabs(dfunc(xn));

            k++;

            printf("k:%d\n", k);
            printf("X(k): %f\n", xn);
            printf("Tol: %10f\n", ep);
        }
    } while (k < Nmax && ep > _tol);

    return xn;
}

double dfunc(double x)
{
    double L = 4;
    double E = 70 * pow(10, 9);
    double I = 52.9 * pow(10, -6);
    double v0 = 20 * pow(10, 3);

    double dF = 0;
    dF = (v0 / (360 * L * E * I)) * (7 * pow(L, 4) - 30 * pow(L, 2) * pow(x, 2) + 15 * pow(x, 4));

    return dF;
}

double d2func(double x)
{
    double L = 4;
    double E = 70 * pow(10, 9);
    double I = 52.9 * pow(10, -6);
    double v0 = 20 * pow(10, 3);

    double d2F = 0;
    d2F = (v0 / (360 * L * E * I)) * (-60 * pow(L, 2) * x + 60 * pow(x, 3));

    return d2F;
}
```

Newton-Raphson Method Results					
Newton-Raphson Method Result:					
-0.004925	-0.004726	k:1	X(k): 1.957937	Tol: 0.0006464362	
0.000646	-0.005361	k:2	X(k): 2.078523	Tol: 0.0000065774	
-0.000007	-0.005463	k:3	X(k): 2.077319	Tol: 0.0000000005	
Final Solution: 2.077319					
계속하려면 아무 키나 누르십시오 . . .					

HINT:

- Need to select `MaxItr` to prevent infinite loop errors
- Calculate for $f'(x)$ analytically. If it is too complex to find $f'(x)$, then use the secant method technique to estimate $f'(x)$.
- Try to make a fail-safe program with error-handling techniques.
 - Check(Try-Catch) for possible errors such as $f'(x) == 0$
- Example code for using MATLAB `fzero(function, x0)`

```
FUN = @(x) 8-4.5*(x-sin(x));
x0=2;
x=fzero(FUN,x0)
```

- Examples of defining functions in C.

Eg. $y = x^2 - x$

```
double func(x) {
    return x*x-x;
}

double dfunc(x) {
    return 2*x-1;
}
```