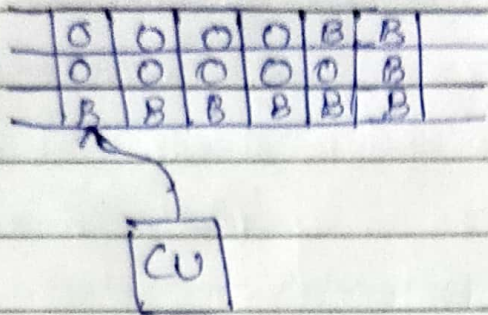
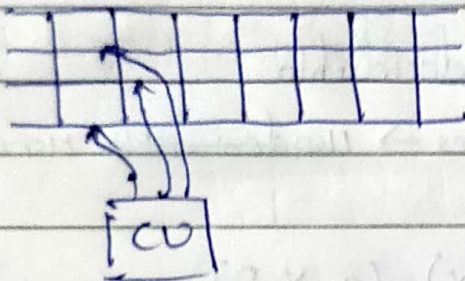


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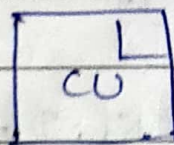
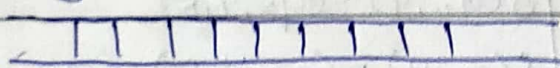
Various of Turing Machine
a) Multiplex TM



iii) Multiple Tape TM



iv) Storage in CU



$$(q_0, [0, 0, B])$$

$$(q_0, [0, 0, B], R)$$

$$q_0, [B, B, B]$$

$$(q_0, [B, B, B]) = (q_1, [B, B, 0], R)$$

$$\delta(q_0, [0, 0, B]) = (q_0, [0, 0, B], R)$$

$$\delta(q_0, [0, B, B]) = (q_0, [0, B, 0], R)$$

$$\delta([q_0, B], 0) = ([q_0, 0], 0, R)$$

$$\delta([q_0, 0], 1) = ([q_0, 0], 1, R)$$

$$\delta([q_0, 0], B) = ([q_1, B], B, R)$$

TM as transducer $\rightarrow m+n \rightarrow 0^m 1 0^n$

$$(q_0, 0) = (q_1, B, R)$$

$$(q_0, 0) = (q_1, 0, L)$$

$$(q_1, 0) = (q_1, 0, R)$$

$$(q_0, 1) = (q_1, 1, L)$$

$$(q_1, 1) = (q_2, 1, R)$$

$$(q_4, 0) = (q_1, 0, L)$$

$$(q_2, 0) = (q_2, 0, R)$$

$$(q_1, B) = (q_0, B, R)$$

$$(q_2, B) = (q_3, 0, L)$$

$m \times n \rightarrow 0^m 1 0^n 1$

$$(q_0, 0) = (q_1, X, R)$$

$$(q_1, 0) =$$

$$(q_1, 1) = (q_2, 1, R)$$

$$(q_2, 0) = (q_3, 0, R)$$

$$(q_3, 0) = (q_4, 0, L)$$

$$(q_4, X) = q_0$$

$$(q_5, X) = (q_5, 0, L)$$

m x n

$$\delta(q_0, 0) = (q_1, X, R)$$

$$\delta(q_1, 0) = (q_1, 0, R)$$

$$\delta(q_1, 1) = (q_2, 1, R)$$

$$\delta(q_2, 0) = (q_3, Y, R)$$

$$\delta(q_3, 0) = (q_3, 0, R)$$

$$\delta(q_3, 1) = (q_4, 1, R)$$

$$\delta(q_4, Y) = (q_5, Y, R)$$

$$(q_3, 1) = (q_4, 1, R)$$

$$(q_4, B) = (q_5, 0, L)$$

$$(q_5, 1) = (q_6, 1, L)$$

$$(q_6, 1) = (q_7, 1, L)$$

$$(q_7, 1) = (q_8, 1, L)$$

$$(q_8, B) = (q_0, B, R)$$

$$\delta(q_4, B) = (q_5, 0, L)$$

$$\delta(q_5, 1) = (q_6, 1, L)$$

$$\delta(q_6, 0) = (q_6, 0, L)$$

$$\delta(q_6, Y) = (q_6, Y, L)$$

$$\delta(q_6, 1) = (q_7, 1, L)$$

$$\delta(q_7, 0) = (q_7, 0, L)$$

$$\delta(q_7, X) = (q_0, X, R)$$

Recursive Languages

Whenever we can design a TM with acceptance in final state & non-acceptance in non-final state.

TM — YES

— NO

For every string Recursive lang has TM o/p YES/NO

Recursively Enumerable lang

RE lang $\begin{cases} \text{YES (Accepting with final state)} \\ \text{NO loop (Non-accepting with non-final state)} \end{cases}$

∞ loop \rightarrow Never halt \rightarrow Undecidable

Halting problem of TM \rightarrow Undecidable problem

TM \rightarrow Determinism

\rightarrow Non-determinism

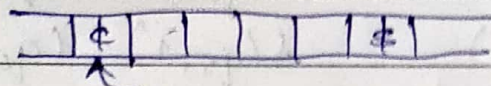
We always design DTM.

Linear Bounded Automata (LBA)

$M = (Q, \Sigma, \Gamma, \delta, q_0, \phi, \$, F)$

$\phi \rightarrow$ Left end marker

$\$ \rightarrow$ Right end marker



ϕ & $\$$ instead of \square
(Blank)

q_0

It is fixed size; No i/p symbol appears after $\$$.

Context-Sensitive Lang

$\alpha\beta \rightarrow \gamma$ (Done only when LHS format is as specified)

$\alpha \rightarrow \beta \Rightarrow$ RE lang (No restriction on no. of symbols in α & β)