MODULE 2

8086 INSTRUCTION SET & ASSEMBLER DIRECTIVES

ADDRESSING MODES OF 8086

- Indicate the way of locating data or operands
- Describe the type of operands
- The different ways in which a source operand is denoted in an instruction is known as addressing modes.

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Categorization of instructions based on Flow of instruction execution

- Sequential control transfer instructions
- >Transfer control to next instruction immediately after it eg: Arithmetic , logical, data transfer, processor control instructions
- Control transfer instructions
- >Transfer control to some predefined address/ address specified in the instruction

eg: INT(Interrupt), CALL, RET (Return from CALL), JUMP

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ADDRESSING MODES FOR SEQUANTIAL CONTROL TRANSFER INSTRUCTIONS:

 Immediate : Immediate data is a part of instruction MOV AX , 0005H

Immediate data(8 bit or 16 bit size)

2. Direct: 16 bit memory address(offset/displacement) is directly specified in the instruction.

MOV AX, [5000H]

Here data resides in a memory location in the data segment Effective address= offset address + segment address (content of DS) 10H*DS+5000H

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Example:

Given DS=1000H

Shifting a number 4 times is equivalent to multiplying it by 16D or 10H

DS:OFFSET ⇔ 1000H: 5000H

10H* DS ⇔ 10000

Offset ⇔ + 5000

15000H - Effective address

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3. Register: Data is stored in register. All the registers except IP can be used.

Eg: MOV BX, AX

4. Register Indirect: offset of data is in either BX or SI or DI registers. The default segment is either DS or ES

Eg: MOV AX, [BX]

Here data is in DS whose offset address is in BX

Effective address= 10H * DS+[BX]

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• Example:

Given DS=1000H and BX=2000H

DS:BX ⇔ 1000H:2000H

10H*DS ⇔ 10000

[BX] ⇔ + 2000

12000H - Effective address

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5. Indexed: offset of the operand is stored in one of the index registers.

For SI (source index), default segment is DS

For DI(destination index), default segment is ES

Eg: MOV AX, [SI]

Effective address= 10H*DS+[SI]

6. Register relative: Data is available by adding the displacement with the content of any one of the register BX, BP, SI and DI

Default segment is DS or ES

Eg: MOV AX, 50H [BX]

Effective address= 10H*DS+50H+[BH]

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• Example:

MOV AX, 5000 [BX]

Given DS=1000H and BX=2000H

DS: [5000 + BX]

10H*DS ⇔ 10000

Offset ⇔ + 5000

[BX] ⇔ + 2000

17000H - Effective address

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7. Based Indexed: effective address is sum of base register (BX or BP) and Index register (SI or DI)

Default segment register may be ES or DS

Eg: MOV AX, [BX] [SI]

Effective address= 10H*DS+[BX]+[SI]

Example:

Given DS=1000H, BX=2000H and SI=3000H

15000H - Effective address

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8. Relative Based Indexed: effective address is formed by adding displacement with the sum of content of any of base registers (BX or BP) and any one of the index registers

Eg: MOV AX, 50H [BX] [SI]

Effective address= 10H*DS+50H+[BX]+[SI]

Example:

Given DS=1000H, BX=2000H and SI=3000H

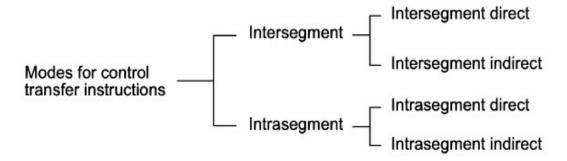
MOV AX, 5000 [BX] [SI]

DS: [BX + SI + 5000]10H*DS ⇔ 10000 [BX] ⇔ + 2000 [SI] ⇔ + 3000 Offset ⇔ + 5000

1A000 - effective address

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ADDRESSING MODES FOR CONTROL TRANSFER INSTRUCTIONS:



Intersegment: Destination location is in different segment. Intrasegment: Destination location is in same segment.

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• Intersegment Direct:

- ➤ Destination is in different segment
- ➤ Provides branching from one code segment to another code segment
- ➤CS and IP of destination address are specified directly in the instruction. Example:

JPM 5000H : 2000H;

Jump to effective address 2000H in segment 5000H.

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- Intersegment Indirect
- ➤ Destination lies in different segment
- ➤ Destination location is passed to the instruction indirectly.

Example:

JMP [2000H];

Jump to an address in the other segment specified at effective address 2000H in DS

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- Intrasegment Direct:
- ➤ Destination lies in same segment
- ➤ Displacement is computed using the content of the IP
- Intrasegment Indirect:
- ➤ Destination lies in same segment
- Destination location is passed to the instruction indirectly.
- ➤ Branch address is found as the content of a register
- **≻**Example

JMP [BX]; Jump to effective address stored in BX.

JMP [BX + 5000H]

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INSTRUCTION SET OF 8086

- 1. Data copy/ transfer instruction:
- >Transfer data from source operand to destination operand
- ➤ Eg: store, move , load, exchange, I/O instructions
- 2. Arithmetic & Logical instructions
- 3. Branch instructions:
- Transfer control of execution to a specified address
- ➤ Eg: jump, interrupt, call, return instruction
- 4. Loop instructions:
- >Implement loop structure
- ➤ Eg: LOOP, LOOPNZ, LOOPZ instructions

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- 5. Machine control instructions:
- ➤ Control machine status
- ➤ Eg: NOP, HLT, WAIT, LOCK
- 6. Flag manipulation instructions:
- ➤ Affect flag registers
- ► Eg: CLD, STD, CLI, STI
- 7. Shift & Rotate instructions:
- For bitwise shifting or rotation in either side
- 8. String instructions:
- ➤ String manipulation operations
- Eg: load, move, scan, compare store

1. DATA COPY /TRANSFER INSTRUCTIONS

1. MOV (move)

- Transfer data from one register/memory to another register/memory
- Source general purpose /special purpose register or memory location
- Destination register or memory location
- Syntax: MOV destination, source
- Eg: MOV AX, BX
- Direct loading of segment register with immediate data is not permitted
 MOV DS, 5000H (not permitted)

correct procedure is

MOV AX, 5000H

MOV DS, AX

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2. PUSH (push to stack)

- ▶ Push content of specified register on to the stack.
- ➤ Store a word (2 bytes) on to the stack

➤ Syntax: PUSH source

Eg: PUSH AX

PUSH DS

PUSH [5000H] – content of location 5000H and 5001H in DS are pushed on to the stack.

3. POP (pop from stack)

➤Get a word from the stack to the provided location.

➤ Syntax: POP destination

Eg: POP AX

POP DS

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4. XCHG (exchange)

- Exchange the contents of source and destination operands
- Exchange of data content of two memory locations is not permitted

```
Syntax: XCHG destination, source
```

```
Eg: XCHG [5000H], AX;
```

XCHG BX; (exchange data between AX and BX)

5. IN (input the port)

- ➤ Used for reading an input port
- ► AL and AX are destinations
- >DX is the only register which is allowed to carry the port address
- Eg: IN AL, 0300H; read data from port address 0300H and store in AL

IN AX; - read data from port whose address is in DX and store in AX

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6. OUT (output to the port)

- ➤ Used for writing to an output port
- ➤ AL and AX are the source operands
- >Address of output port may be specified in the instruction or in DX

Eg: OUT 0300H, AL; - send data available in AL to the port whose address is 0300H

7. XLAT (translate)

Finding the code in code conversion problem

Eg: translate the code of the key pressed to 7-segmented code

8. LEA (Load Effective Address)

- ➤ Load offset of an operand in specified register
- ➤ Used to save pointer(address) of a value

Eg: LEA BX, ADR; - offset of label ADR will be transferred to register BX

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9. PUSHF (push Flag to stack)

- ➤ Pushes the flag register on to the stack
- First the upper byte then the lower byte will push on to the stack
- >SP is decremented by 2, for each push operation

10. POPF (pop Flag from stack)

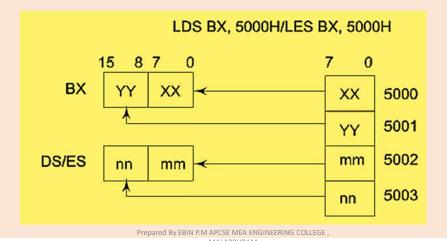
- ➤ Used to copy a word at the top of the stack to the flag register.
- >SP is incremented by 2, for each pop operation

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11. LDS/LES (Load pointer to DS/ES)

➤ It loads DS or ES register & destination register with the content of memory location(source)



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2. ARITHMETIC INSTRUCTIONS

1. ADD (add)

- ➤ Source and destination may be registers
- ➤ Memory to memory addition not possible
- ➤ Syntax: ADD Destination, Source

≻Eg: ADD AX, 0100H

ADD AX, BX

ADD AX, [SI]

ADD AX, [5000H]

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2. ADC (Add with carry)

Same as ADD instruction but add the carry flag

➤ Syntax: Destination ← Source + Destination + CF

Eg: ADC 0100H

ADC AX, BX

ADC AX, [SI]

ADC AX, [5000H]

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3. INC (Increment)

➤ Increment the content of the register or memory location by 1

➤Syntax: INC Destination

≽Eg: INC AX

INC [BX]

INC [5000H]

4. DEC (Decrement)

Subtract 1 from the content of the specified register or memory location

➤Syntax: **DEC Destination**

➤ Eg: DEC AX

DEC [5000H]

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5. SUB (Subtract)

- Subtract source operand from the destination operand
- > Result is stored in destination operand
- ➤ Syntax: Destination ← Destination Source

➤ Eg: SUB AX, BX

SUB AX, [5000H]

SUB [5000H], 0100

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6. SBB (Subtract with borrow)

> Syntax: Destination ← Destination – Source – CF

≽Eg: SBB AX, BX

SBB AX, [5000H]

SBB [5000H], 0100

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7. CMP (Compare)

- Compare the source operand with a destination operand
- >Source register, immediate data or memory location
- Destination register or memory location
- For comparison, it subtract the source operand from destination operand (Destination Source) but does not store the result.
- ➤ Both operands equal Zero flag is set
- ➤ Source operand > Destination operand Carry flag is set
- ➤ Otherwise carry flag is reset
- **≻Eg:** CMP BX, 0100H

CMP BX, CX

CMP BX, [SI]

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8. MUL (Unsigned multiplication)

- ➤ Multiplies unsigned byte/word with the content of AL/AX
- unsigned byte/word may be in general purpose register or memory location
- MSB of result is stored in DX & LSB is stored in AX
- \triangleright Eg: MUL CX { (DX)(AX) ← AX * CX }
- 9. IMUL (Signed multiplication)
- ➤ Multiplies signed byte/word in source operand with the content of AL/AX
- ➤ Source can be general purpose register , index register or base register
- ►Eg: IMUL BH

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10. DIV (Unsigned Division)

- ➤ Divides unsigned word / double word by 16 bit/8 bit operand
- ➤ Quotient will be stored in AL
- ➤ Reminder will be stored in AH

11. IDIV (Signed Division)

- ➤ Same as DIV instruction but signed
- ➤ Result will also be signed number

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- >AAA ASCII ADJUST AFTER ADDITION
- > AAS ASCII ADJUST AFTER SUBTRACTION
- ► AAM ASCII ADJUST FOR MULTIPLICATION
- >AAD ASCII ADJUST FOR DIVISION
- ➤ DAA DECIMAL ADJUST ACCUMULATOR
- > DAS DECIMAL ADJUST AFTER SUBTRACTION
- ➤ NEG NEGATE (To find 2's complement)

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3. LOGICAL INSTRUCTIONS

- 1. AND (Logical AND)
- >ANDs the source operand to the destination operand
- ➤ Result stored in destination operand
- Source operand: immediate, register or memory location
- ➤ Destination operand: register or memory location
- ≽Eg: AND AX, 0008H

If content of AX is 3F0FH, Then

4		0	0	1	1	1	1	1	1	0	0	0	0	1	1	1	1	= 3F0F H [AX]
		1	1	1	1	1	1	1	1	\	1	\downarrow	1	1	1	1	1	AND
		0	0	0	0	0	0	0	0	0	0	0	0	1	0	0	0	= 0008 H
		0	0	0	0	0	0	0	0	0	0	0	0	1	0	0	0	= 0008 H [AX]
-	The	e resi	ılt (000	8H	will be i	n A	X.	repare	ed By EBIN P.M A			A ENG	GINEERING CO		Ε,		32

2. OR (Logical OR)

➤ Carries out the OR operation

≻Eg: OR AX, 0098H

If the content of AX is 3F0FH, then

0 0 1 1	1 1 1 1	0 0 0 0 1 1 1 1	= 3F0F H
$\downarrow\downarrow\downarrow\downarrow\downarrow$	$\downarrow\downarrow\downarrow\downarrow\downarrow$	$\downarrow\downarrow\downarrow\downarrow\downarrow$ $\downarrow\downarrow\downarrow\downarrow$	OR
0 0 0 0	0 0 0 0	1 0 0 1 1 0 0 0	= 0098 H
0 0 1 1	1 1 1 1	1 0 0 1 1 1 1 1	= 3F9F H

Thus the result 3F9FH will be stored in the AX register.

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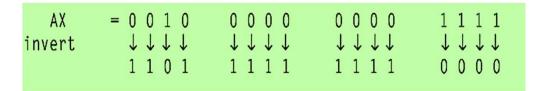
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3. NOT (Logical Invert)

➤ Complement the content of an operand register/ memory location.

►Eg: NOT AX

If the content of AX is 200FH, then



The result DFF0 will be stored in AX

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4. XOR (Logical Exclusive OR)

- ➤ When two inputs are different , XOR gives high output
- ➤ When two inputs are same , XOR gives low output
- **≻**Eg: XOR AX, 0098H

If the content of AX is 3F0FH, then

Result is stored in AX

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5. TEST (Logical Compare instruction)

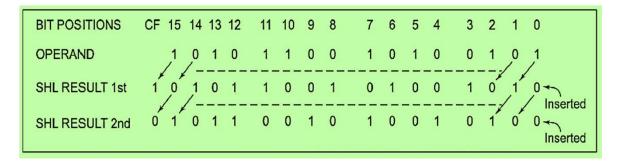
- ➤ Performs bit by bit logical AND operation
- >If both the operands are 1, result is set to 1 else 0
- The result is not available for further use
- ➤ Affected flags are CF, SF, ZF and PF

Eg: TEST AX, BX

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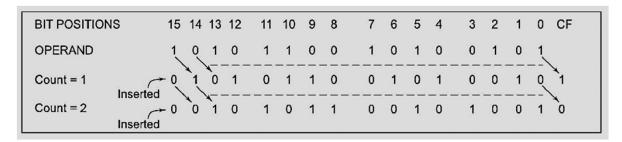
6. SHL/ SAL (Shift Logical / Arithmetic Left)

- ➤ Shift the operand bit by bit to the left and insert 0 in LSB
- The count is either 1 or specified by register CL

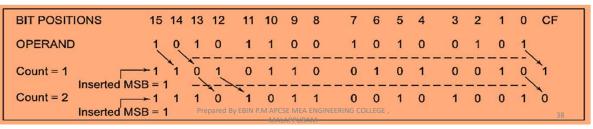


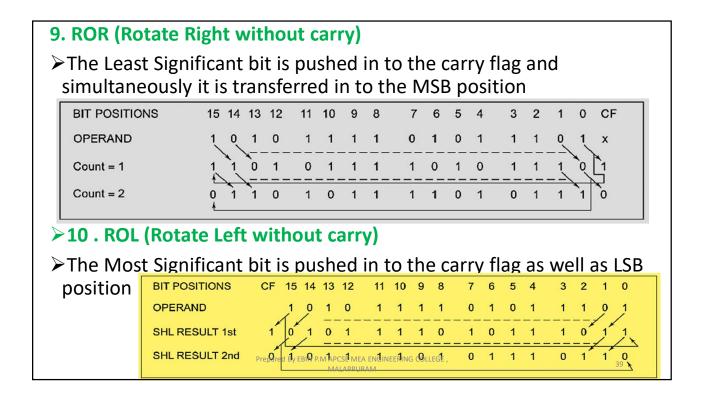
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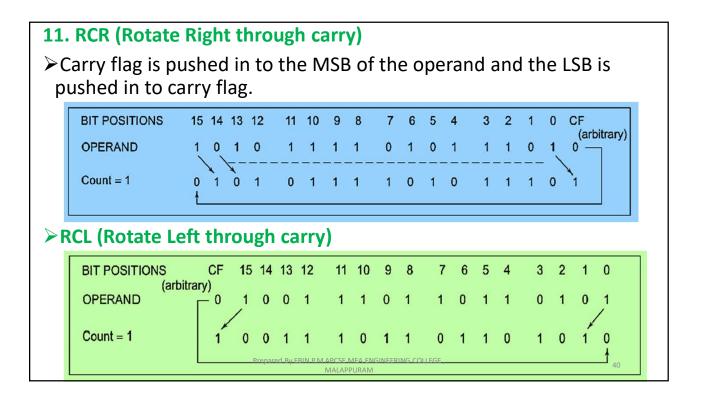
7. SHR (Shift Logical Right)



8. SAR (Shift Arithmetic Right)







4. FLAG MANIPULATION INSTRUCTIONS

- ➤ CLC CLEAR CARRY
- >CLD CLEAR DIRECTION
- ➤ CLI CLEAR INTERRUPT
- >STC SET CARRY
- >STD SET DIRECTION
- ➤ STI SET INTERRUPT
- > CMC COMPLEMENT CARRY

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5. PROCESSOR CONTROL INSTRUCTIONS

- ➤ WAIT Wait for TEST input pin to go Low
- ➤ HLT Halt the processor
- ➤ NOP No operation
- ➤ ESC Escape to external devices
- ► Lock Bus lock instruction

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6. STRING MANIPULATION INSTRUCTIONS

- ❖A string is a series of data bytes or words available in memory at consecutive locations
- ❖To refer a string 2 parameters are needed
 - 1. start/ end address of string
 - 2. Length of string (stored as a count in CX register)

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1. REP (Repeat)

- ➤ Used as a prefix to other instruction
- ➤ Repeat the given instruction till CX != 0
- ➤ When CX become zero , execution proceeds to the next instruction in sequence
- ➤ REPE/REPZ: Repeat operation while Equal/Zero
- >REPNE/REPNZ: Repeat operation while Not Equal/ Not Zero

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2. MOVSB/MOVSW (Move String Byte/ Move String Word)

- ➤ Move a string of byte/word from DS:SI (source) to ES:DI (destination)
- ➤ Starting address of source string is 10H* DS+[SI]
- ➤ Starting address of destination string is 10H* ES+[DI]

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3. CMPS (Compare string)

- ➤ Used to compare the strings
- ➤ Length of string must be stored in CX register
- ➤ If both the byte/word string are equal, Zero flag is set.
- ➤ CMPSB Compare String Byte
- CMPSW Compare String Word

4. SCAS (Scan string)

- ➤ Used to scan a string
- >SCASB scan string byte
- >SCASW Scan string word

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5. LODS (Load String)

- ➤ It loads the AL/AX register by the content of a string pointed to by DS : SI register pair.
- ► LODSB Load string byte
- ► LODSW Load string word

6. STOS (Store string)

- ➤ It store the AL/AX register contents to a location in the string pointed by ES:DI register pair
- >STOSB Store String Byte
- >STOSW Store string word

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ASSEMBLER DIRECTIVES

➤ An Assembler is a program used to convert an Assembly Language Program in to machine code

Assembler directives

- Assembler directives are statements that direct the assembler to do a task
- ➤ It control the organization of the program
- ➤ Provide necessary information to the assembler to understand ALPs
- ➤ It consist of 2 type of statements
- 1. Instructions→Translated to the machine code by the Assembler
- 2. Directives → Not translated to the machine code

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I. Data declaration directives

➤ DB, DW, DQ and DT are data declaration directives

1.DB (Define Byte)

- ➤ Used to declare a byte or 2- byte variable
- ➤ It reserve a byte or bytes of memory locations in the available memory

Eg: RANKS DB 01H, 02H, 03H, 04H

Assembler reserve 4 memory locations for an array named RANKS and initialize them with the above specified 4 values.

Eg: VALUE DB 50H

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Eg: MESSAGE DB 'GOOD MORNING'

- Reserve the number of bytes of memory equal to the number of characters in the string.
- Name of the string is MESSAGE and initialize the location by the ASCII values of these characters

2. DW (Define Word)

➤ Used to declare a word type variable (a word = 16 bit)

Eg: WORDS DW 1234H, 4567H, 78ABH, 045CH

- Declare an array of 4 words and initialize them with above value.
- Array name is WORDS

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> We can use DUP operator with DW directive

Eg: WDATA DW 5 DUP (6666H)

 This statement reserve 5 words,ie,10 bytes of memory for a word label WDATA and initialize all the word location with 6666H

3. DQ (Define Quad word)

➤ Used to reserve 4 words (8 bytes) of memory for a specified variable and Initialize it with specified value

4. DT (Define Ten bytes)

➤ Declare a variable which is 10 bytes in length and initialize with a specified value

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II. ASSUME

- This directive is used to name the logical segment
- ≥8086 works directly with 4 physical segment; ie,

Code segment

Data segment

Stack segment

Extra segment

➤In assembly language , each segment is given a name.

Code segment may be given the name CODE

Data segment may be given the name DATA

► ASSUME statement is must at starting of each program.

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Eg: ASSUME DS: DATA

Data items related to the program are available in a logical segment DATA

Eg: ASSUME CS: CODE

Machine codes are available in a segment named CODE; and hence the CS register is to be loaded with the address allotted by the operating system for the label CODE

III. END (end of program)

- ➤ End of an assembly language program
- >It should be the last statement in the file

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IV. ENDP (end of procedure)

- ➤ It indicate end of a procedure(subroutines)
- >A procedure has a name or label
- **▶**Syntax: procedure_name ENDP

Eg:

PROCEDURE STAR : STAR ENDP

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```
V. ENDS (end of segment)

> End of logical segment

> Syntax: segment_name ENDS

ASSUME CS: CODE, DS: DATA
CODE SEGMENT
:
:
CODE ENDS
```

VI. SEGMENT

- ➤ To indicate the start of a logical segment
- ➤ Syntax: segment_name SEGMENT
- ➤ Segment may be assigned a type like PUBLIC or GLOBAL
- **PUBLIC** → can be used by other modules of the program while linking
- ➤ GLOBAL → can be accessed by any other modules

```
EXE.CODE SEGMENT GLOBAL; Start of Segment named EXE.CODE,
; that can be accessed by any other module.
EXE.CODE ENDS ; END of EXE.CODE logical segment.
```

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VII. EQU (Equate)

- ➤ Used to give a name to some value or to a symbol.
- Each time the assembler finds the name in the program, it will replace the name with the value or symbol you given to that name.
- ► Eg: LABEL EQU 0500H → Assigns the constant 0500H with the label LABEL

►Eg: FACTOR EQU 03H

You has to write this statement at the starting of your program. Later in the program you can use this as follows

ADD AL, FACTOR

When it codes this instruction, the assembler will code it as

ADD AL, 03H

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VIII. PROC (procedure)

- >Used to identify the start of a procedure
- The term **NEAR** or **FAR** is used to specify the type of the procedure
- ➤ NEAR → Procedure is located with in same segment (ie, with in 64K)
- ➤ FAR → Procedure is located in different segment
- ►Eg: RESULT PROC NEAR

IX. ORG (origin)

- >It changes the starting offset address of the data in the data segment
- ➤ Eg: The statement ORG 2000H tells the assembler to set the location counter to 2000H
- ➤ORG directive allows you to set the location counter to a desired value at any point in the program.

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X. EXTRN (external) & PUBLIC (public)

- >PUBLIC directive is used along with EXTRN directive
- The directive EXTRN informs the assembler that the names, procedures and labels declared after this directive have already been defined in some other assembly language modules
- ➤ While in other module , the names, procedures and labels must be declared public using PUBLIC directive

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Eg: If one wants to call a procedure FACTORIAL appearing in module 1 from module 2, in module1, it must be declared public using the statement PUBLIC FACTORIAL, and in module2 it must be declared external using the statement EXTRN FACTORIAL

MODULE1	SEGMENT	
PUBLIC	FACTORIAL	FAR
MODULE1	ENDS	
MODULE2	SEGMENT	
EXTRN	FACTORIAL	FAR
MODULE2	ENDS	

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XI. GROUP (group the related segments)

➤This directive form a logical group of segments with similar purpose or type

►Eg: PROGRAM GROUP CODE, DATA, STACK

- ❖Here CODE, DATA and STACK segment must lie with in a 64Kbytes memory segment, that is named as PROGRAM
- ❖ For the ASSUME statement, one can use the label PROGRAM rather than CODE, DATA and STACK. ie,

ASSUME CS: PROGRAM DS: PROGRAM SS: PROGRAM

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XII. PTR (pointer)

- ➤ Used to specify the data type byte or word
- ➤ If the prefix is BYTE, then the particular label, variable or memory operand is an 8- bit quantity.
- ➤If word is the prefix, then it is 16-bit quantity

Eg: MOV AL, BYTE PTR [SI] → Moves content of memory location addressed by SI (8 bit) to AL

Eg: MOV BX, WORD PTR [2000H] → Moves 16 bit content of memory location 2000H to BX . ie, [2000H] to BL , [2001H] to BH

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XIII. OFFSET (Offset of a Label)

- ➤ When the assembler comes across the OFFSET operator along with a label, It first compute the 16 bit displacement of the label and replaces the string 'OFFSET LABEL' by the computed displacement
- This operator is used with arrays, strings, labels and procedures to decide their offsets in their default segments.

```
CODE SEGMENT
MOV SI, OFFSET LIST
CODE ENDS
DATA SEGMENT
LIST DB 10H
DATA ENDS
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```

```
Assembly Language Program to add two 16 -bit numbers
ASSUME CS:CODE, DS:DATA
DATA SEGMENT
OPR1 DW 1234H
                                       ; 1st operand
         DW 0002H
OPR2
                                       ; 2nd operand
RESULT DW 01 DUP(?)
                                        ; A word of memory reserved for re-
                                          sult
DATA
         ENDS
CODE
         SEGMENT
START: MOV AX, DATA
                                      : Initialize data segment
         MOV DS, AX
         MOV AX, OPR1
                                      ; Take 1st operand in AX
         MOV BX, OPR2
                                      ; Take 2nd operand in BX
         CLC
                                      ; Clear previous carry if any
         ADD AX, BX ; Add BX to AX 
MOV DI, OFFSET RESULT ; Take offset of RESULT in DI 
MOV [DI], AX ; Storetheresultatmemory address in DI
         MOV AH, 4CH
                                       ; Return to DOS prompt
         INT 21H
                             Prepared By EBIN P.M APCSE MEA ENGINEERING COLLEGE ends
CODE
         ENDS
         END START
                                      MALAP PUROgram ends
```

- Some data may be required for the program. So DATA segment is needed
- ➤ CODE segment contains actual instruction . It is compulsory
- >If stack facility is used we need STACK segment
- ➤In the first line of program, ASSUME directive declares that the label CODE refers to the code segment & the label DATA refers to the data segment
- ➤ CODE = Logical name of code segment
- ➤ DATA = Logical name of data segment
- ➤ OPR1 is first operand & OPR2 is second operand
- ➤ RESULT DW 01H DUP (?) → It reserve 01H words of memory for storing the result of the program and leaves it undefined due to the directive DUP (?)

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- The label STARTS is the starting point of the execution sequence
- ASSUME directive just inform the assembler that the label CODE is used for code segment and the label DATA is used for data segment. It does not put the address of CODE in code segment register (CS) and address of DATA in data segment register (DS)
- The process of putting the actual segment address value in to the corresponding segment register is called Segment register initialization
- ➤ CS is automatically initialize by the loader. So we should initialize DS
- ≻le, MOV AX, DATA MOV DS, AX

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- The instruction **MOV DI, OFFSET RESULT** take offset of RESULT in DI. Ie, it store the offset of the label RESULT into DI register.
- ➤ MOV [DI], AX → This instruction stores the result available in AX into the address pointed to by DI. Ie, address of the RESULT.
- ➤ MOV AH, 4CH → 4CH is a function call for return back to DOS prompt, after executing the program.
- ➤INT 21H → DOS function calls available under INT 21H instruction.
- ➤In DOS, the hardware like memory, keyboard, CRT display, hard disk can be handled with the help of the instruction INT 21H

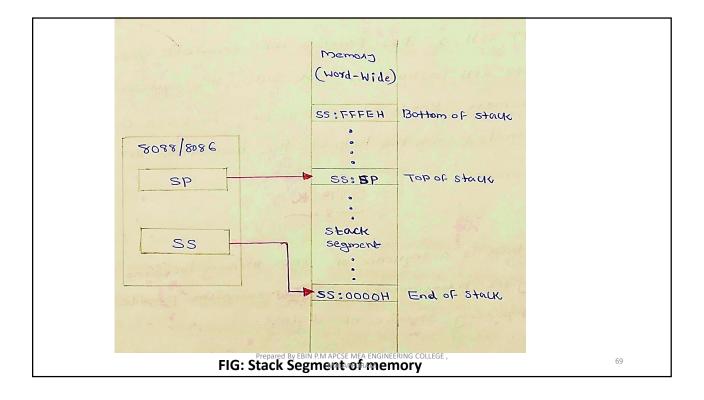
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STACK

- Stack is a sequence of RAM memory locations defined by the programmer. Stack mechanism provide a temporary storage of data.
- ➤ Stack is a block of memory locations which is accessed using the SP and SS registers.
- ➤ Stack is a Last In First Out (LIFO) data segment.
- ➤In the case of subroutine and interrupt, the address of re-entry in to the main program (return address) may be stored in the stack.
- The process of storing the data in the stack is called Pushing into the stack.
- The process of transferring the data back from the stack to the CPU register is called popping off the stack.

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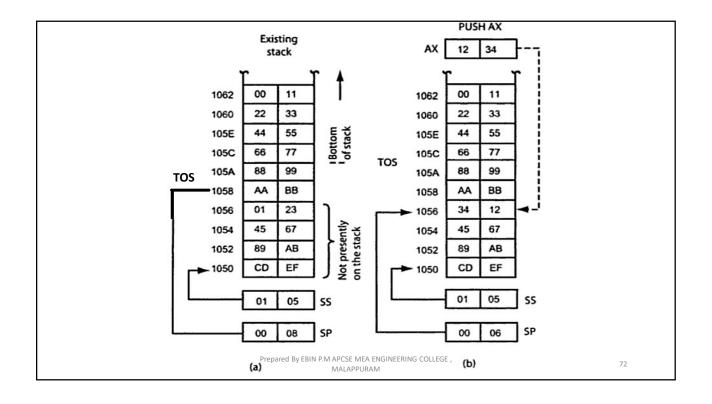


- ➤ Top of stack → Physical address of the last storage location in the stack to which data were pushed. This address is obtained from the content of SS and SP (SS: SP)
- ➤ Bottom of stack → At the microcomputer's startup, the value in SP is initialized to FFFEH. Combining this value with the current value in SS gives the highest address word location in the stack (SS: FFFEH), called bottom of the stack.
- ➤ 8086 can push data and address information on to the stack from its internal register or a storage location in memory.
- ➤ Data transferred to and from the stack are word-wide, not bytewide

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- ➤ Each time a word is to be pushed on to the stack, the value in SP is automatically decremented by two
- Therefore, stack grows down in memory from the bottom of the stack (SS: FFFEH) towards the end of the stack (SS: 0000H)
- ➤ Each time a word is popped from the top of stack, the value in SP is automatically incremented by two

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- Figure (a), is the state of stack prior to execution of the PUSH AX instruction.
- The stack segment register contains 105H. Bottom of stack address is derived from SS and offset FFFEH

Bottom of stack address = 1050H + FFFEH = 1104EH

➤ SP contains 0008H. Top of stack can be derived from SS and SP

Top of stack = 1050H + 0008H= 1058H

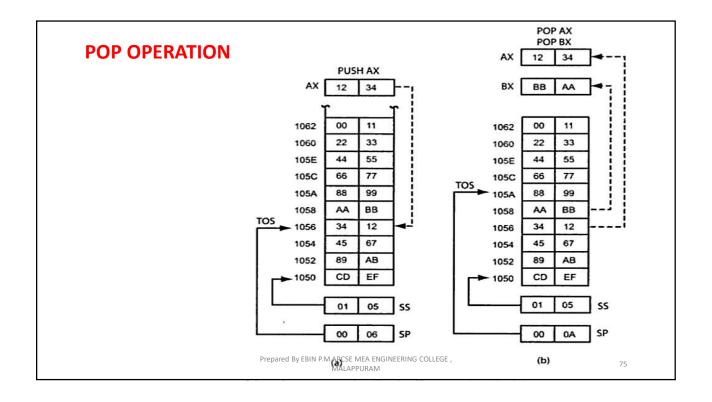
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PUSH OPERATION

- >AX initially contains the number 1234H.
- Execution of push instruction causes the stack pointer to be decremented by two.
- Therefore the next stack access is to the location corresponding to address 1056H. This location is where the value in AX is pushed.
- ➤ The MSB of AX (ie,12H) resides in memory address 1057H and LSB of AX (ie, 34H) is held in memory address 1056H

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- The execution of the first instruction POP AX, causes the 8086 to read the value from the Top of the stack and put it in to AX register as 1234H
- ➤ SP is incremented to give 0008H and the other read operation POP BX, causes the value BBAAH to be loaded into the BX register.
- ➤SP is incremented once more and now equals 000AH. Therefore, the new top of stack is at address 105AH

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MACROS

- Suppose a number of instructions are appearing again and again in the main program, the listings become lengthy.
- ➤ So a macro definition (i.e. a Label) is assigned with the repeatedly appearing string of instructions.
- ➤ The process of assigning a label or macro-name to the string is called defining a macro
- The macro name or macro definition is then used through out the main program to refer to that string of instructions.
- >A macro with in a macro is called nested macro

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- ➤ When a group of instructions are to be used several times to perform the same task in a program and they are too small to be written as a procedure , then they can be defined as a macro.
- ➤ Macro is a small group of instructions, and is called by its name.
- The process of replacing the macro with the instructions it represent is called expanding the macro.

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```
Macro can be defined anywhere in a program using the directives
 MACRO and ENDM
```

≻Eg: DISPLAY MACRO

MOV AX, SEG MSG

MOV DS, AX

MOV DX, OFFSET MSG

MOV AH, 09H

INT 21H

ENDM

- ❖SEG is used to substitute the segment address of the label MSG
- ❖If AH contains 09H ,then CRT display is to be used for displaying a message.

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- ➤ DISPLAY is the macro name, which should be used in the actual program
- ➤ The above macro DISPLAY displays the messge MSG on the CRT screen
- A macro may also be used to represent statements and directives. The following example shows a macro containing statements.

```
STRING MACRO
```

MSG1 DB 0AH, 0DH, "Programs", 0AH, "\$"

MSG2 DB OAH, ODH, "Retry, Abort, Fail", OAH, "\$"

ENDM

Calling a macro means, inserting the statements and instructions represented by the macro directly at the place of the macro name in the program.

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PROCEDURE

- ➤ When a group of instructions are to be used several times to perform a same task in the program, then we can write them as a separate subprogram called procedure or subroutine.
- ➤ Procedure can be call in a program using CALL instruction
- ➤ Procedures are written and assembled as separate program modules and stored in memory.
- ➤ When a procedure is called in the main program, the program control is transferred to procedure and after executing the procedure the program control is transferred back to main program.
- > RET is used to return the control to main program

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- ➤If the processor encounters a CALL instruction , then it save the content of PC (Program Counter) in stack and load the subroutine address in PC.
- The content of the PC that is saved in the stack is the address of the instruction next to CALL in the main program
- ➤ When the subroutine address is loaded in PC , the processor start executing the subroutine. The last instruction in the subroutine will be RET instruction.
- ➤ When RET is executed, the processor move the top of the stack memory to program counter (PC). Now the execution control is returned to main program.

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Advantages:

- 1. Modular programming → The various task in the program can be developed as separate modules and called in the program.
- 2. Reduction in the amount of work and program development time
- 3. Reduces memory requirement for program storage

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PROCEDURE	MACRO
Accessed by CALL and RET mechanism	Accessed with name given to macro when defined
Machine codes for instructions are stored in memory once	Machine codes are generated for instructions in the macro each time it is called
Parameters are passed in registers, memory locations or stack	Parameters are passed as part of statement which calls macro
Executes slower than macro	Executes faster than procedure
Used for more instruction operation	Used for less instruction operation

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PARAMETER PASSING TECHNIQUES

1. Passing parameters through registers

➤ Here the data is placed in registers by the main program, and these registers are used by procedure.

```
Solve S = (A+B) - (C+D)

MOV AX, [1100]

MOV BX, [1102]

MOV CX, [1104]

MOV DX, [1106]

CALL SL-EQ

MOV [1200], AX

HLT

SL-EQ

ADD AX, BX

ADD CX, DX

SUB AX, CX

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RET MALAPPURAM
```

2. Passing parameters through memory

```
MOV SI, 2000
MOV CX, 0AH

LI: CALL SQ
    MOV [DI], AL
    INC DI
    LOOP LI
    HLT

SQ
    MOV AL, [SI]
    MOV BL, AL
    MUL BL
    INC SI
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```

MOV DI, 2500